

# STHVDAC-256MTG

Datasheet - production data

# Antenna tuning circuit with turbo and glide

# Lead-free, Flip Chip (20 bumps)

# Features

- Dedicated controller to bias BST tunable capacitors
- Operation compliant with cellular systems requirements
- Turbo and glide modes for optimal system performance
- Integrated boost converter with 6 programmable outputs (from 0 to 24 V)
- Low power consumption
- MIPI RFFE serial interface 1,8 V
- Available in WLCSP for stand-alone or SiP module integration

# Applications

- Cellular antenna tunable matching network in multi-band GSM/WCDMA/LTE handsets
- Compatible for open loop antenna tuner application

#### **Benefits**

RF tunable passive implementation in mobile phones to optimize the radiated performance.

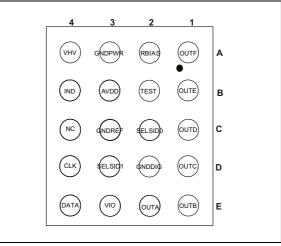
#### Description

The ST high voltage BST capacitor controller STHVDAC-256MTG is a high voltage digital to analog converter (DAC), specifically designed to control and meet the wide tuning bias voltage requirement of the BST tunable capacitors.

It provides 6 independent high voltage outputs, thus having the capability to control 6 different capacitors. It is fully controlled through an RFFE serial interface.

BST capacitors are tunable capacitors intended for use in mobile phone application and dedicated to RF tunable application. These tunable capacitors are controlled through a bias voltage ranging from 0 to 24 V. The implementation of BST tunable capacitor in mobile phones enables significant improvement in term of radiated performance, making the performance almost insensitive to external environment.

#### Figure 1. Pin configuration



November 2015

DocID028369 Rev 1

This is information on a product in full production.

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# **1** Electrical characteristics

Symbol	Parameter	Rating	Unit
AV <sub>DD</sub>	Analog supply voltage	-0.3 to +5.5	V
V <sub>I/O</sub>	Digital supply voltage	-0.3 to +3.3	V
V <sub>LOG</sub>	Input voltage logic lines (DATA, CLK, SEL_ID0, SEL_ID1)	-0.5 to V <sub>I/O</sub> + 0.5	V
V <sub>ESD (HBM)</sub>	Human body model, JESD22-A114-B, All I/O	2	kV
T <sub>stg</sub>	Storage temperature	-55 to +150	°C
Тj	Maximum junction temperature	150	°C

#### Table 1. Absolute maximum ratings (limiting value)

Table 2. Recommended operating conditio	ons

Symbol	Parameter		Unit		
Symbol	raiametei	min.	typ.	max.	onit
T <sub>AMB_OP</sub>	Operating ambient temperature	-30	-	+85	°C
AV <sub>DD</sub>	Analog supply voltage	2.3	-	5	V
V <sub>I/O</sub>	Digital supply voltage	1.65	-	1.95	V
VIH	Input voltage logic level High (DATA, CLK, SEL_ID0, SEL_ID1)	0.7*V <sub>I/O</sub>	-	V <sub>I/O</sub> + 0.3	V
VIL	Input voltage logic level Low (DATA, CLK, SEL_ID0, SEL_ID1)	-0.3	-	0.3*V <sub>I/O</sub>	V



Conditior	ns: AV <sub>DD</sub> 3.3V, VI/O from 1.65		from -30 °C to +85 °C,L <sub>BOOST</sub> = ecified	15 µH	unless	s other	wise	
Symbol	Symbol Parameter Conditions						Uni	
		Low Power mo	ode or shutdown		0.28	1		
		1	Active mode, 1 output steady state 2V		130			
I <sub>LBOOST</sub>	Boost inductor supply current	ILBOOST_SS2	Active mode, 6 outputs steady state 2V			700	μA	
	L=15µH, AV <sub>DD</sub> = 3.3 V		Active mode, 1 output steady state 20V		150			
		ILBOOST_SS20	Active mode, 6 outputs steady state 20V			800		
	AV <sub>DD</sub> supply current AV <sub>DD</sub> = 3.3 V	Low Power mode or shutdown			1.55	5		
		I <sub>AVDD_SS2</sub>	Active mode, 1 output steady state 2V		600			
I <sub>AVDD</sub>			Active mode, 6 outputs steady state 2V			1200	μA	
			Active mode, 1 output steady state 20V		600			
		IAVDD_SS20	Active mode, 6 outputs steady state 20V			1200		
		Low Power mo	de or shutdown		1.8	5	μA	
I <sub>I/O</sub>	V <sub>I/O</sub> supply current	Active mode: (6 outputs active) No activity on CLK, VI/O=1.8V FCLK = 13MHz FCLK = 26MHz			28 560 1100	50 800 1500	μA	
I <sub>IH</sub>	Input current logic level high	Any mode, DA pins	-1		+1	μA		
Ι <sub>ΙL</sub>	Input current logic level low	Any mode, DA pins	-1		+1	μA		
V <sub>IORST</sub>	VIO low threshold					0.5	V	

#### Table 3. DC characteristics



Conditio	Conditions: AV <sub>DD</sub> from 2.3 to 5V, VI/O from 1.65 to 1.95 V, T <sub>amb</sub> from -30 °C to +85 °C, OUTA-C, unless otherwise specified										
Symbol	Parameter	Min.	Тур.	Max.	Unit						
LOW POW	ER MODE										
Z <sub>out</sub>	OUTA-OUTF output impedance		6			MΩ					
ACTIVE MO	DDE										
V <sub>OH</sub>	OUTA-OUTF maximum output voltage	DAC = 7Fh, ILOAD < 1 $\mu$ A	23.17	23.88		V					
V <sub>OL</sub>	OUTA-OUTF minimum output voltage	DAC = 0Ah, ILOAD < 1 μA		1.88	1.94	V					
Resolution	Voltage resolution / OUTA- OUTF	7 bits DAC, 01h to 7Fh range		188		mV					
INL	Integral Non Linearity	DAC A – DAC F from 0Ah to 7Fh	-3		+3	LSB					
DNL	Differential non Linearity	DAC A – DAC F from 0Ah to 7Fh	-0.5		+0.5	LSB					
Error	DACs error	DAC A – DAC F from 0Ah to 7Fh	-3		+3	% V <sub>out</sub>					
lsc	Over Current Protection	Any DAC output			50	mA					

#### Table 4. High voltage DAC output characteristics



# 2 Functional block diagram

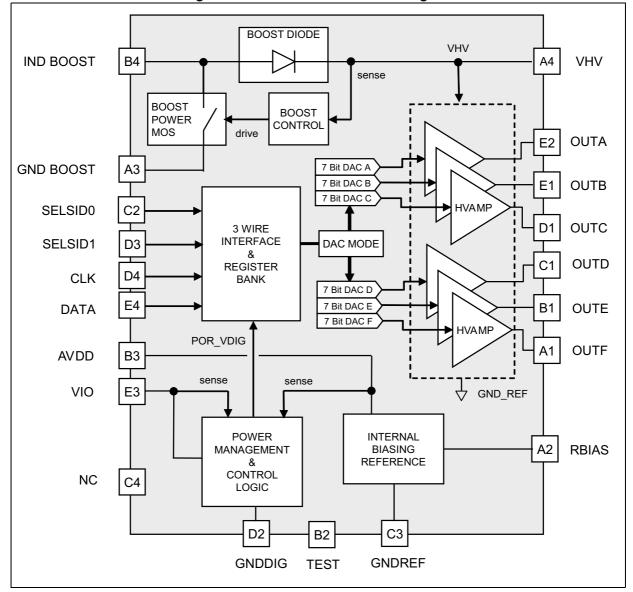


Figure 2. HVDAC functional block diagram



Pin number	Pin name	Description
A1	OUTF	High voltage output F
A2	RBIAS	Biasing reference resistance
A3	GND_BOOST	Power ground
A4	VHV	Boost High voltage output
B1	OUTE	High voltage output E
B2	TEST	Reserved for test, leave unconnected or connected to GND in application PCB
B3	AVDD	Analog supply
B4	IND_BOOST	Boost inductance
C1	OUTD	High voltage output D
C2	SELID0	RFFE interface / SELID0
C3	GND_REF	Analog ground
C4	NC	Not connected
D1	OUTC	High voltage output C
D2	GND_DIG	Digital ground
D3	SELID1	RFFE interface / SELID1
D4	CLK	RFFE interface / Serial clock
E1	OUTB	High voltage output B
E2	OUTA	High voltage output A
E3	VIO	Digital supply
E4	DATA	RFFE interface / Serial data

Table 5. Signals description



# 3 Theory of operation

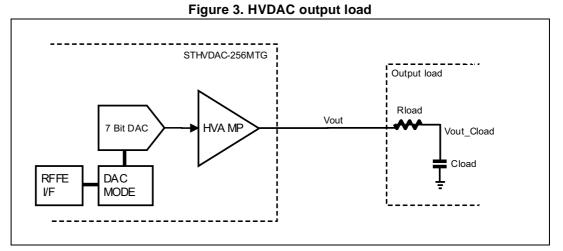
#### 3.1 HVDAC output voltages

The HVDAC outputs are directly controlled by programming the 7 bits DAC (DAC A to DAC F) through the RFFE interface.

The DAC stages are driven from a reference voltage, generating an analog output voltage driving a high voltage amplifier supplied from the boost converter (see HVDAC block diagram *Figure 2*).

The HVDAC output voltages are scaled from 0 to 24 V, with 127 steps of 188 mV. If DAC value is set to 00h, then the corresponding output is setup to be in high impedance state (6 M $\Omega$ ).

STHVDAC-256MTG has been specifically designed to drive BST tunable capacitors, equivalent to RC output loads as shown in *Figure 3*.



Each DAC output can be operated either in normal, turbo or glide mode. The DAC mode is set by controlling turbo mode bit of each DAC register (MSB of registers 2, 3, 4, 6, 7, 8), and Glide enable bits (defined in registers#1 and #5).

#### 3.1.1 DAC operation in normal mode -- glide\_enable = 0b, turbo\_mode = 0b

In normal mode, the DAC output directly switches from old to new output voltage after programming. The DAC output is controlled to ensure the output voltage ( $V_{out}$ , see *Figure 3*) reaches its final value within 10µs typical after valid RFFE command.

Typical timing diagram in Normal mode is shown on *Figure 4*.



#### 3.1.2 DAC operation in turbo mode -- glide\_enable = 0b, turbo\_mode = 1b

A specific turbo mode is implemented in the STHVDAC-256MTG to ensure a fast system settling time.

In this mode, the DAC voltage outputs are optimized to minimize the settling time on the output capacitor load (Vout\_Cload, see *Figure 3*). Once enabled, the output voltage on the output capacitor reaches its final value within 55µs typical.

In turbo mode, STHVDAC-256MTG has been optimized to support up to 4 different output RC loads, as defined in *Table 6*. The RC loads can be selected for each output independently, by controlling PTIC\_selection bits in registers#9 to #11.

Typical timing diagram in turbo mode is shown on *Figure 4*.

#### 3.1.3 DAC operation in glide mode - glide\_enable = 1b, turbo\_mode = x

Glide mode has been implemented to smooth DAC output voltage transition, and to minimize the impact of tunable capacitor changes on RF system performance (especially to meet 3GPP phase discontinuity requirements).

In this mode, the DAC output voltage transitions from old to new voltage value, in a period of time equal to the glide\_delay defined as:

Glide\_delay = glide\_step\_delay \* 256 (programmable from 512 µs up to 16.84 ms)

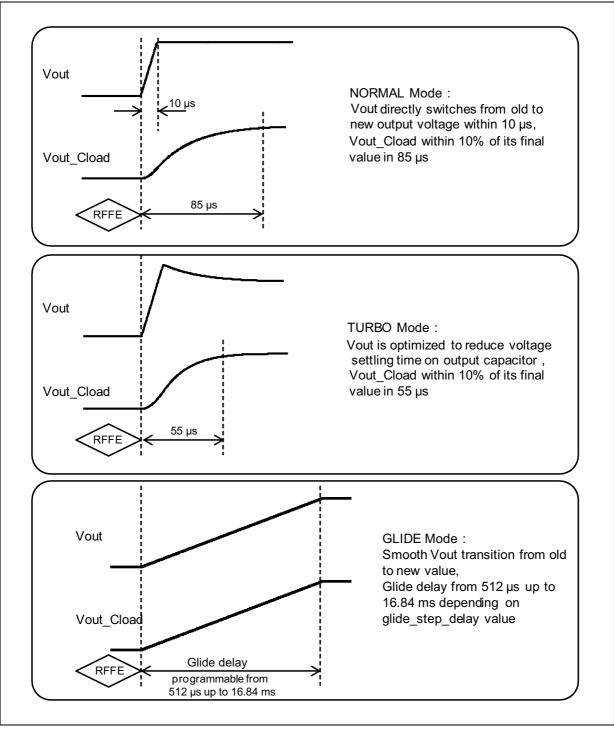
glide\_step\_delay defined in registers#1 and #5 as per Table 11.

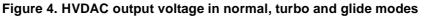
Typical timing diagram in glide mode is shown on Figure 4.

PTIC_sele	ection bits	Rload	Cload
0	0	12 kΩ	2.7 nF
0	1	17 kΩ	2.7 nF
1	0	22 kΩ	2.7 nF
1	1	27 kΩ	2.7 nF

Table 6. Supported output RC loads (turbo mode only)









# 4 Devices operating modes

The following operating modes are accessible through the serial interface:

#### 4.1 Shutdown mode:

The HVDAC is switched OFF, and all the blocks in the control ASIC are switched OFF. Power consumption is almost zero in this mode, the DAC outputs are in high Z state. The shutdown mode is set by driving VIO to LOW level.

#### 4.2 Active mode:

The device is directly set into this mode after startup, or by driving PWR\_MODE bits to 00b in register #0 or #28.

Active mode is further controlled through reg#0 bit D5:

D5 = 0b (default): Idle mode:  $V_{HV}$  = OFF

the device is switched OFF except the RFFE interface. Power consumption is almost zero in this mode, the DAC outputs are in high Z state (same as Low power mode).

This is the default state when  $AV_{DD}$  and VIO are supplied to the device.

D5 = 1b: Operating mode:  $V_{HV}$  = 27 V

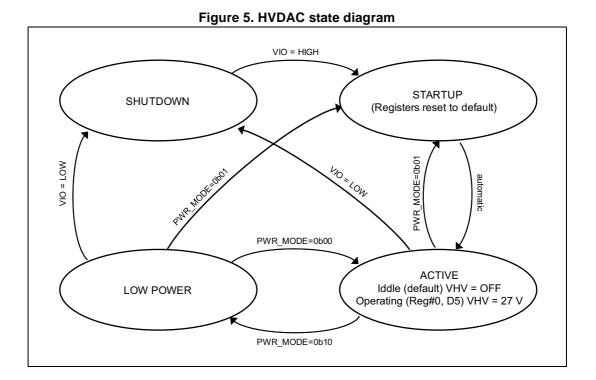
The HVDAC is switched ON and the DAC outputs are fully controlled through the RFFE serial interface. The DAC settings can be dynamically modified and the outputs will be adjusted according to the specified timing diagrams. Each DAC can be individually controlled and/or pulled down according to application requirements.

#### 4.3 Low power mode:

The HVDAC is switched OFF except the RFFE interface. Power consumption is almost zero in this mode, the DAC outputs are in high Z state.

The device is set into this mode by driving PWR\_MODE bits to 10b. All registers can be controlled and accessed in low power mode.





4.4 Device reset

Power-On Reset is implemented on the VI/O supply input, ensuring the HVDAC will be reset to default mode once VI/O supply line rises above a given threshold (typically 1V). This trigger will force all registers to their default value.

Device Reset is also implemented as defined in the MIPI RFFE specification. Setting PWR\_MODE bits to 01b will force the device to reset all registers to their default value, and then automatically switch the device into low power mode.

A Soft Reset is implemented using register #26 MSB. Setting this bit will reset all registers to their default values, except PM\_TRIG register (reg #28) and device USID (reg #31).

#### 4.5 **RFFE serial interface**

The HVDAC is fully controlled through RFFE serial interface (DATA, VIO, CLOCK).

This interface is further described in the next sections of this document and is made compliant to the MIPI Alliance Specification for RF Front End control Interface version 1.10 - 26 July 2011 (see *Figure 12* and *Figure 13*).

Sequence Start Condition (SSC): One rising edge followed by falling edge on DATA while CLK remains at logic level low. This is used by the Master to identify the start of a Command frame.

Parity (P): Each frame shall end with a single parity bit. The parity bit shall be driven such that the total number of bits in the frame that are driven to logic level one, including the parity bit, is odd.



Bus park cycle (BP): The slave releasing DATA will drive the DATA to logic level zero during the first half of the CLK clock cycle. This is used by the master as the indication of the end of Frame.

#### 4.6 **RFFE serial interface extended mode**

All the registers in the device can be addressed in extended mode, by sending appropriate command sequences as per MIPI RFFE specification (see *Figure 14*).

#### 4.7 RFFE serial interface broadcast capability

Registers#28 to #31 can be addressed in broadcast mode, by sending appropriate command sequences as per MIPI RFFE specification.

#### 4.8 **RFFE interface - command and data frame structure**

The STHVDAC-256MTG RFFE interface has been implemented to support the following command sequences:

- Register WRITE
- Register READ
- Extended register write

These supported command sequences are described in Figure 6.

		SSC	)		Co	mm	and	Frame	D				Data frame						Τ	
Register WRITE	0	1	0	USID	0	1	0	REG Address[4,0]	Ρ	DATA[7,0]	Ρ	ΒP				_		+	+	_
Register READ	0	1	0	USID	0	1	1	REG Address[4,0]	Ρ	BP DATA[7,0]		Ρ	BР		_			7	+	-
Extended Register WRITE	0	1	0	USID	0	0	0	0 0 0 0 0 BC[3,0] 1 1 1 1	Ρ	Address[7,0]	Ρ	ι	Jp to	04 b	ytes par		data	with	в	P
	USID : Unique Slave Identifier P : Parity Bit BC : Byte Count SSC : Sequence Start Condition BP : Bus Park Cycle																			

#### Figure 6. Supported command sequences

All frames are required to end with a single parity bit. The parity bit shall be driven such that the total number of bits in the frame that are driven to logic level 1, including the parity bit, is odd. In case the device detects a parity error, the frame is considered not valid and is ignored.

#### 4.9 Power-up/down sequence

*Table 7* and *Figure 8* are describing the HVDAC settling time requirements and recommended timing diagrams.

Switching from Shutdown to Active mode is triggered by setting VIO to HIGH level.

Switching from Low Power to Active mode will occur setting PWR\_MODE bits to 00b (REGISTER#28 or REGISTER#0).

Switching from active to low power mode will occur setting PWR\_MODE bits to 10b (REGISTER#28 or REGISTER#0).



Following active mode command (from Low power), the HVDAC will be operational after  $t_{active}$  (typ. 100 µs). Once in active mode, a settling time of 10 µs typ (Tset) is required following each DAC command in active mode. During this settling time the HVDAC output voltages will vary from the initial to the updated DAC command.

#### 4.10 Power supply sequencing

No specific power supply sequencing is required on the STHVDAC-256MTG.

The STHVDAC-256MTG is fully functional only once both VIO and AV<sub>DD</sub> are supplied.

#### 4.11 Trigger mode

To meet precise timing requirements and avoid RFFE interface traffic congestion at critical timing, trigger mode has been implemented in the RFFE interface.

Three triggers (TRIG0, TRIG1 and TRIG2) are available and can be controlled through the RFFE interface.

By default, registers #2 to #4 (DAC A, DAC B and DAC C) are associated to TRIG0 and registers #6 to #8 (DAC D, DAC E and DAC F) are associated to TRIG1. Each DAC can be independently mapped to TRIG0, TRIG1 or TRIG2 by controlling trigger configuration bits in registers #9 and #10.

#### Trigger mode enabled (default mode):

By default, the different triggers are enabled and the device is running in triggered mode.

In this case, once in ACTIVE mode, the following sequence must be followed to control the HVDAC outputs:

- Send any valid write command sequence to Register#0 Register#11. The new DAC register values will be temporarily stored in shadow registers.
- Send a register#28 write command sequence, setting trigger bits (D2 to D0) and keeping trigger mask bits (D5 to D3) low. The shadow registers will be loaded to destination registers and this will trigger the corresponding DAC outputs to their new values.

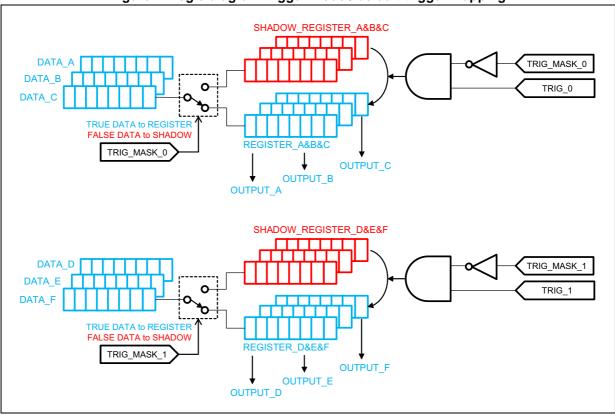
#### Trigger mode disabled:

The different triggers are disabled by setting corresponding trigger mask bits in register#28 (D5 to D3).

In this case, any valid DAC register write command sequence is directly loaded to the destination register, directly triggering the corresponding DAC output to its new value.

The following logic diagram illustrates the trigger mode function. By default the trigger mode is enabled and the DATA are first sent to SHADOW registers, then transferred into DAC register once valid trigger is sent to register#28.





#### Figure 7. Logic diagram trigger mode / default trigger mapping

#### 4.12 Settling time

The STHVDAC will set the bias voltage of the tunable capacitors within 10 µs typical after

- Bus Park (BP) of register #28 write sequence data frame if trigger mode is enabled.
- Parity Bit (P) of each data frame of register #1 to #8 extended write sequence if trigger mode is disabled.

Condition	Conditions: AV <sub>DD</sub> from 2.5 to 5 V, $V_{I/O}$ from 1.65 to 1.95 V, $T_{amb}$ from -30 °C to +85 °C, OUTA-OUTF unless otherwise specified											
Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit						
T <sub>active</sub>	Activation time	Internal voltages activation time from Low Power (or shutdown) to Active mode Chv=33 nF	-	100	250	μs						
T <sub>set+</sub>	Output positive setting time @ 95% of delta V	$V_{out}$ 2 V to 20 V, equivalent load of 12 k $\Omega$ and 2.7 nF / Normal mode	-	10	25	μs						
T <sub>set-</sub>	Output negative setting time @ 95% of delta V	$V_{out}$ 20 V to 2 V, equivalent load of 12 k $\Omega$ and 2.7 nF / Normal mode	-	10	25	μs						

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Table	7	Timing
Tubic	•••	i iii iii iii iii ii



# 4.13 Recommended operation with trigger and extended commands

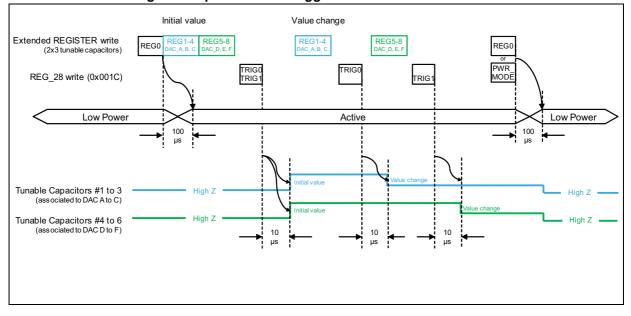
It is recommended to use trigger so that outputs will be activated by write to reg#28. By default the device is set in triggered mode.

PWR\_MODE bits from reg#28 have been duplicated in reg#0 to ensure the device can be setup from low power to active using one single extended mode RFFE command, as illustrated on *Figure 8*.

By default, DAC\_A, B and C are mapped to TRIG0 and DAC\_D, E and F to TRIG1. In this configuration, DAC values can be updated through RFFE extended commands, and DAC outputs for a given antenna synchronized through trigger control.

Each DAC output can be mapped to TRIG0, 1 or 2 through registers #9 to #11.

The timing diagram below represents recommended operation when default trigger mapping and extended write are in use.



#### Figure 8. Operation with trigger and extended commands



#### 4.14 Registers table

The STHVDAC is embedding 17 x 8 bits registers. Registers content is described in *Figure 9*, and registers default values are provided in *Figure 10*.

Reg #	Reg address hex	Reg address bin	D7 MSB	D6	D5	D4	D3	D2	D1	D0 LSB	Access type	Default Triggers
0	00h	[00000]	x	x	Active	0	1	0	PWR_	MODE	RW	no
1	01h	[00001]			glide step delay	/ ABC		Glide A EN	Glide B EN	Glide C EN	RW	no
2	02h	[00010]	TM_A				DAC A				RW	TRIG0
3	03h	[00011]	TM_B				DAC B				RW	TRIG0
4	04h	[00100]	TM_C				DAC C				RW	TRIG0
5	05h	[00101]			glide step delay DEF Glide D EN Glide E EN Glide F EN						RW	no
6	06h	[00110]	TM_D		DAC D							
7	07h	[00111]	TM_E		DAC E							TRIG1
8	08h	[01000]	TM_F				DAC F				RW	TRIG1
9	09h	[01001]	TRIG_CO	ONFIG_A	PTIC_S	elect_A	TRIG_CC	ONFIG_B	PTIC_S	Select_B	RW	no
10	0Ah	[01010]	TRIG_CO	ONFIG_C	PTIC_S	elect_C	TRIG_CC	DNFIG_D	PTIC_S	Select_D	RW	no
11	0Bh	[01011]	TRIG_CO	ONFIG_E	PTIC_S	elect_E	TRIG_CC	ONFIG_F	PTIC_S	Select_F	RW	no
26	1Ah	[11010]	SW reset				RFFE status				RW	no
28	1Ch	[11100]	PWR_	MODE	Trig mask 2	Trig mask 1	Trig mask 0	TRIG2	TRIG1	TRIG0	RW	no
29	1Dh	[11101]	SELSID1	SELSID0		PI	RODUCT ID	[xx000011	b]		R	no
30	1Eh	[11110]			MANUFACTURER ID [7,0] [00000100b]						R	no
31	1Fh	[11111]	0	0	MANUF_ID[9,8] [01b] USID [0111b]							no

Figure	9	Registers	table
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#### Figure 10. Registers default values

Reg #	Reg address hex	Reg address bin								
	Ř	Ř	D7	D6	D5	D4	D3	D2	D1	D0
0	00h	[00000]	0	0	0	0	1	0	0	0
1	01h	[00001]	0	0	0	0	0	0	0	0
2	02h	[00010]	0	0	0	0	0	0	0	0
3	03h	[00011]	0	0	0	0	0	0	0	0
4	04h	[00100]	0	0	0	0	0	0	0	0
5	05h	[00101]	0	0	0	0	0	0	0	0
6	06h	[00110]	0	0	0	0	0	0	0	0
7	07h	[00111]	0	0	0	0	0	0	0	0
8	08h	[01000]	0	0	0	0	0	0	0	0
9	09h	[01001]	0	0	0	0	0	0	0	0
10	0Ah	[01010]	0	0	0	0	0	1	0	0
11	0Bh	[01011]	0	1	0	0	0	1	0	0
26	1Ah	[11010]	0	0	0	0	0	0	0	0
28	1Ch	[11100]	0	0	0	0	0	0	0	0
29	1Dh	[11101]	SELSID1(*)	SELSID0(*)	0	0	0	0	1	1
30	1Eh	[11110]	0	0	0	0	0	1	0	0
31	1Fh	[11111]	0	0	0	1	0	1	1	1

Note:

(\*)Reg#29 - D7 and D6 (MSBs DEVICE ID) default values are directly tied to SELID1 and SELID0 pins, respectively. These bits are set to 1 if the corresponding pin is tied to  $V_{I/O}$ , and set to 0 if tied to GND. This will allow to have up to four HVDAC with different product ID connected to the same RFFE master.



#### 4.15 **RFFE interface - registers content description**

Registers content and control are further described in tables#8 to #14 and Figure 11.

D7	D6	Reg #0 D5	Comments							
PWR_	MODE	Active								
0	0	0	Active mode - idle							
0	0	1	Active mode - operating							
0	1	х	Start up / registers reset to default							
1	0	x	Low power							
1	1	х	N/A							

PWR\_MODE bits located in D7-D6 of reg#28, and duplicated in D1-D0 of reg#0.

D5	D4	D3	D2	D1	D0	Comments
Trig mask 2	Trig mask 1	Trig mask 0	Trig 2 Trig 1		Trig 0	
0	0	0	0	0	0	Triggers 2, 1, 0 are unmasked / triggers 2, 1, 0 are disabled (default)
0	0	0	1	1	1	Triggers 2, 1, 0 are unmasked / triggers 2, 1, 0 are enabled
1	1	1	0	0	0	Triggers 2, 1, 0 are masked

#### Table 9. STHVDAC trigger control register - reg#28

#### Table 10. HVDAC unique slave identifier control - reg#31

D7	D6	D5	D4	D3	D2	D1	D0	Comments
spa	spare MANUFACTURER_ID [9,8]		USID					
0	0	0	1	0	1	1	1	Default value
0	0	0	1	x	x	x	x	USID can be modified by RFFE master, see detailed programming procedure in MIPI RFFE specification



					<u>.</u>	
Address	D7	D6	D5	D4	D3	Comments
Address -		Glide st	Glide_step_delay value			
	0	0	0	0	0	2 µs
	0	0	0	0	1	4 µs
[00004]	0	0	0	1	0	6 µs
[00001]						
	1	1	1	1	0	62 µs
	1	1	1	1	1	64 µs
		Glide st				
[00101]	0	0	0	0	0	2 µs
	1	1	1	1	1	64 µs

#### Table 11. Glide step delay control - reg#1 - reg#5

 Table 12. Glide enable bits - reg#1 - reg#5

Address	D2	D1	D0	Comments
Address	Glide A EN	Glide B EN	Glide C EN	
[00001]	0	0	0	Glide enable = 0:DAC mode set by DAC register MSB
	1	1	1	Glide enable = 1:DAC in glide mode
	Glide D EN	Glide E EN	Glide F EN	
[00101]	0	0	0	Glide enable = 0:DAC mode set by DAC register MSB
	1	1	1	Glide enable = 1:DAC in glide mode

#### Table 13. DAC control registers - reg#2, 3, 4, 6, 7, 8

Address	D7 MSB	D6	D5	D4	D3	D2	D1	D0 LSB	Comments
[00010]	TM_A				DAC	A			
[00011]	TM_B				DAC	В			D7:Turbo mode control:
[00100]	TM_C				DAC	С			0:Turbo OFF 1:Turbo ON
[00110]	TM_D				DAC	D			D7 is disregarded if glide mode is enabled
[00110]	TM_E				DAC	E			D6-D0:DAC output
[01000]	TM_F				DAC	F			



Reg#	Address	D7 MSB	D6	D5	D4	D3	D2	D1	D0 LSB	Access type	Triggered
26	[11010]	SW reset		RFFE status							no

Table 14. RFFE status register - reg#26

D7: Software reset:

- 0: Normal operation
- 1: Software reset all configurable registers are reset to their default values (except USID and reg#28)

D6-D0: RFFE status and error reporting

#### Figure 11. Trigger configuration and PTIC selection registers - reg#9, #10 and #11

Reg #	Reg address hex	Reg address bin	D7 MSB	D6	D5	D4	D3	D2	D1	D0 LSB	Access type	Default Triggers
9	09h	[01001]	TRIG_CO	ONFIG_A	PTIC_S	elect_A	TRIG_CO	ONFIG_B	PTIC_S	elect_B	RW	no
10	0Ah	[01010]	TRIG_CO	ONFIG_C	PTIC_S	elect_C	TRIG_CO	ONFIG_D	PTIC_S	elect_D	RW	no
11	0Bh	[01011]	TRIG_CO	ONFIG_E	PTIC_S	elect_E	TRIG_CO	ONFIG_F	PTIC_S	elect_F	RW	no

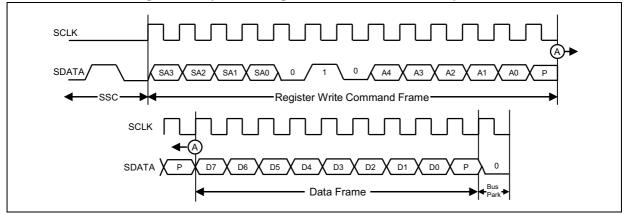


# 5 Serial interface specification

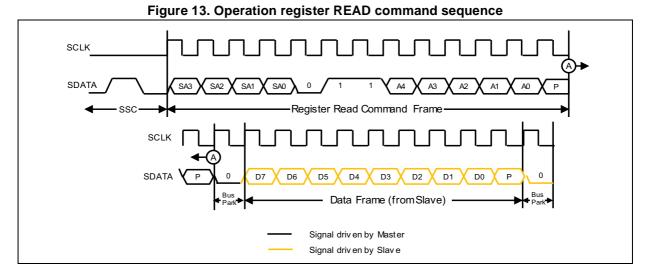
Conditions: AV <sub>DD</sub> from 2.3 to 5 V, VIO from 1.65 to 1.95 V, T <sub>amb</sub> from -30 °C to +85 °C, unless otherwise specified										
Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit				
F <sub>CLK</sub>	Clock Frequency			-	26	MHz				
T <sub>CLK</sub>	Clock Period		38.4	-		ns				
T <sub>HIGH</sub>	Clock High Time		11.25	-		ns				
T <sub>LOW</sub>	Clock Low Time		11.25	-		ns				
TD <sub>setup</sub>	DATA setup time	Relative to 30% of CLK falling edge	1	-		ns				
TD <sub>hold</sub>	DATA hold time	Relative to 70% of CLK falling edge	5	-		ns				
C <sub>CLK</sub>	CLK pin input capacitor			-	5	pF				
C <sub>DATA</sub>	DATA pin input			-	5	pF				

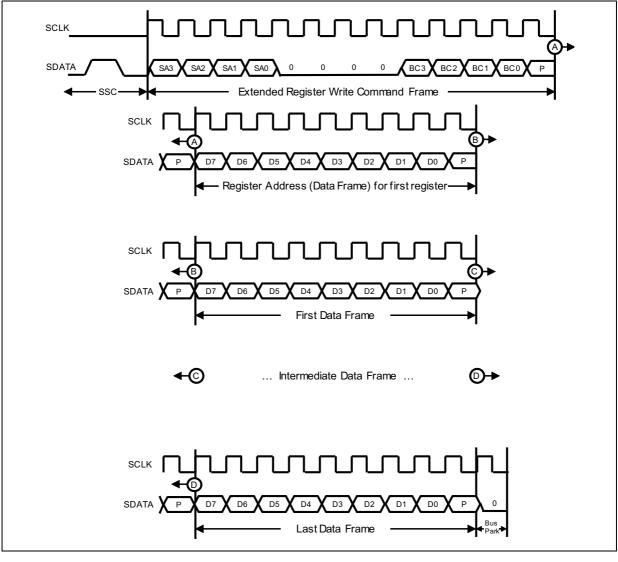
#### Table 15. Interface specifications

#### Figure 12. Operation register WRITE command sequence













# 6 Application schematic

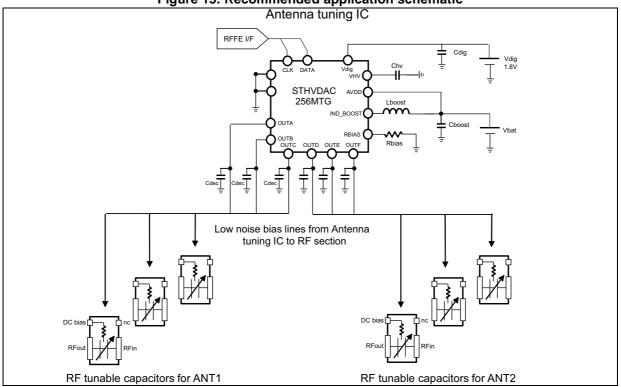
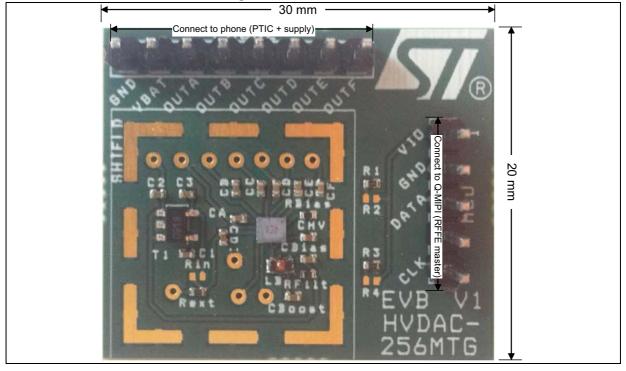


Figure 15. Recommended application schematic

Figure 16. Evaluation board



Components	Description	Nominal value	Package (inch)	Package (mm)	Recommended P/N
Cboost	Boost supply capacitor	1 µF	0201	0603	AVX: 02016D105MAT2A
Lboost	Boost inductance	15 µH	0603	1608	COILCRAFT: 0603LS-153XGL
Rbias	Reference bias resistor, 1%	110 kΩ	0201	0603	Multicomp: MC 0.0625W 0402 1%
Chv	Boost output capacitor, 50V	33 nF	0402	1005	Murata: GRM155R61H333KE19
Cdec	Decoupling capacitor, 50V	100 pF	0201	0603	TDK: C0603COG1H101J

#### Table 16. Recommended external BOM



# 7 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK<sup>®</sup> packages, depending on their level of environmental compliance. ECOPACK<sup>®</sup> specifications, grade definitions and product status are available at: *www.st.com*. ECOPACK<sup>®</sup> is an ST trademark.

# 7.1 Flip-chip package information

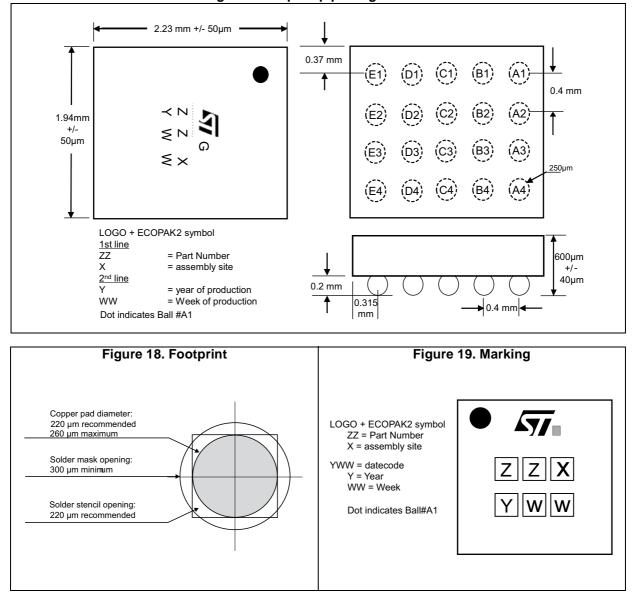


Figure 17. Flip-chip package outline



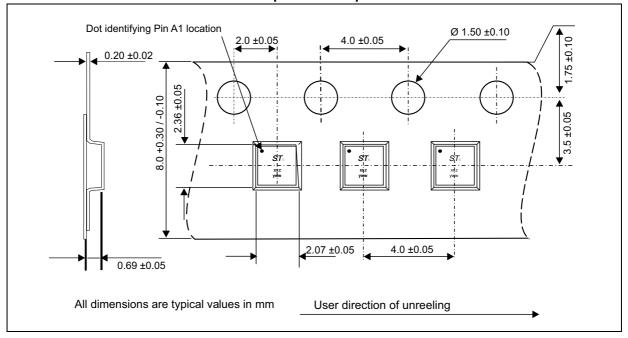


Table 17. Tape and reel specification



# 8 Ordering information

Part Number	Marking	Base Qty.	Delivery mode	
STHVDAC-256MTGF3	PT	5000	Tape & reel	

Table 18. Ordering information

Note: More information is available in the STMicroelectronics Application note: AN1235: "Flip Chip: Package description and recommendations for use"

# 9 Revision history

#### Table 19. Document revision history

Date	Revision	Changes
02-Nov-2015	1	Initial release.



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