

## Description

The F1456 is a High Gain / High Linearity 2100 MHz to 2950 MHz TX Digital Variable Gain Amplifier used in transmitter applications.

The F1456 TX DVGA provides 32.1 dB maximum gain with +38 dBm OIP3 and 3.9 dB noise figure. Up to 31.5 dB gain control is achieved using the combination of a digital step attenuator (DSA) and a  $K_{LIN}^{TM}$  RF Digital Gain Amplifier. This device uses a single 5 V supply and 215 mA of  $I_{CC}$ .

This device is packaged in a 6 mm x 6 mm, 28-pin QFN with 50  $\Omega$  single-ended RF input and RF output impedances for ease of integration into the signal-path.

## Competitive Advantage

In typical Base Stations, RF VGAs are used in the TX traffic paths to drive the transmit power amplifier. The F1456 TX DVGA offers very high reliability due to its construction from a monolithic silicon die in a QFN package. The F1456 is configured to provide an optimum balance of noise and linearity performance consisting of a  $K_{LIN}^{TM}$  RF amplifier, digital step attenuator (DSA) and a PA driver amplifier. The  $K_{LIN}^{TM}$  amplifier maintains the OIP3 and output P1dB performance over an extended attenuation range when compared to competitive devices.

## Typical Applications

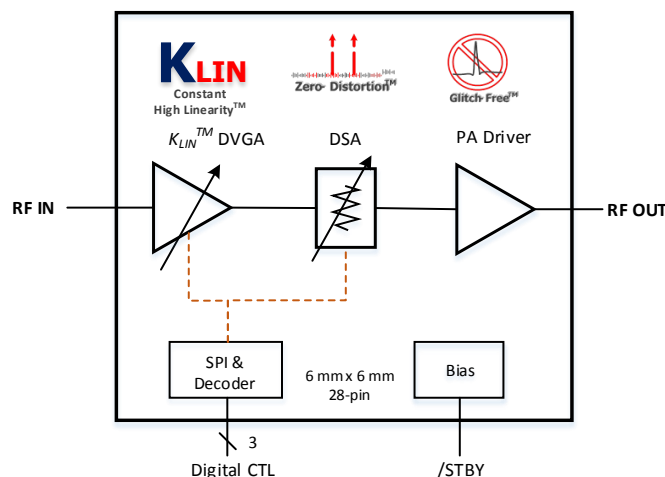
- Multi-mode, Multi-carrier Transmitters
- WiMAX and LTE Base Stations
- UMTS/WCDMA 3G Base Stations
- PHS/PAS Base Stations
- Public Safety Infrastructure

## Features

- Broadband 2100 MHz to 2950 MHz
- 32.1 dB max gain
- 3.9 dB NF @ max gain (2650 MHz)
- 31.5 dB total gain control range, 0.5 dB step
- < 2 dB overshoot between gain transitions
- Maintains flat +21.5 dBm OP1dB for more than 13 dB gain adjustment range
- Maintains flat +38 dBm OIP3 for more than 15 dB gain adjustment range
- SPI interface for DSA control
- Single 5 V supply voltage
- $I_{CC} = 215$  mA
- Up to +105  $^{\circ}\text{C}$   $T_{CASE}$  operating temperature
- 50  $\Omega$  input and output impedance
- Standby mode for power savings
- Pin compatible 700 MHz and 2100 MHz versions
- 6 mm x 6 mm, 28-pin QFN package

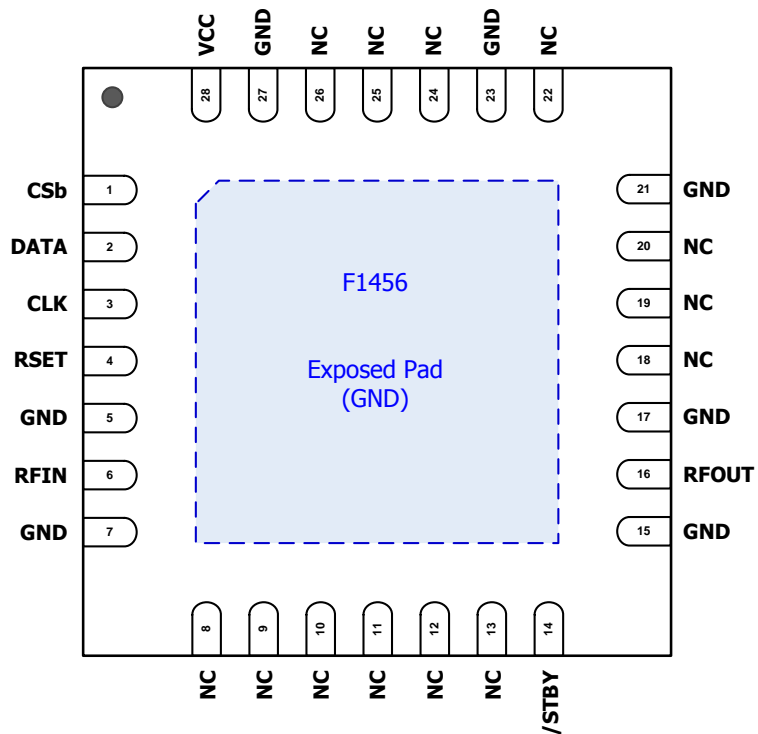
## Block Diagram

Figure 1. Block Diagram



## Pin Assignments

**Figure 2. Pin Assignments for 6 mm x 6 mm x 0.9 mm QFN Package – Top View**



## Pin Descriptions

**Table 1. Pin Descriptions**

Number	Name	Description
1	CSb	Chip Select Input: 1.8 V or 3.3 V logic compatible.
2	DATA	Data Input: 1.8 V or 3.3 V logic compatible.
3	CLK	Clock Input: 1.8 V or 3.3 V logic compatible.
4 [a]	RSET	Connect 2.2 k $\Omega$ external resistor to GND to set amplifier bias.
5, 7, 15, 17, 21, 23, 27	GND	Pins internally tied to exposed paddle. Connect to ground on PCB.
6	RFIN	RF input internally matched to 50 $\Omega$ . Must use external DC block.
8, 9, 10, 11, 12, 13, 18, 19, 20, 22, 24, 25, 26	NC	No internal connection. These pins can be left unconnected, voltage applied, or connected to ground (recommended).
14	/STBY	Standby pin. Device will be placed in standby mode when pin 14 is set to a logic low or when pin 14 is left floating (pulled low via internal high impedance to GND). In standby mode, SPI circuitry is still active. With a logic high applied to pin 14 the part is set to full operation mode.
16	RFOUT	RF output internally matched to 50 $\Omega$ . Must use external DC block.
28	VCC	5 V Power Supply. Connect to V <sub>cc</sub> and use bypass capacitors as close to the pin as possible.
	— EP	Exposed Pad. Internally connected to GND. Solder this exposed pad to a PCB pad that uses multiple ground vias to provide heat transfer out of the device into the PCB ground planes. These multiple ground vias are also required to achieve the noted RF performance.

- a. External resistor on pin 4 used to optimize the overall device for DC current and linearity performance across the entire frequency band.

## Absolute Maximum Ratings

Stresses above those listed below may cause permanent damage to the device. Functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

**Table 2. Absolute Maximum Ratings**

Parameter	Symbol	Minimum	Maximum	Units
V <sub>CC</sub> to GND	V <sub>CC</sub>	-0.5	5.5	V
DATA, CSb, CLK, /STBY	V <sub>Cntrl</sub>	-0.5	V <sub>CC</sub>	V
RSET	I <sub>RSET</sub>		+1.5	mA
RFIN externally applied DC voltage	V <sub>RFIN</sub>	+1.4	+3.6	V
RFOUT externally applied DC voltage	V <sub>RFOUT</sub>	V <sub>CC</sub> - 0.15	V <sub>CC</sub> + 0.15	V
RF Input Power (RFIN) applied for 24 hours max. [a]	P <sub>max_in</sub>		+12	dBm
RF Output Power (RFOUT) present for 24 hours maximum [a]	P <sub>max_out</sub>		+26	dBm
Continuous Power Dissipation	P <sub>diss</sub>		1.75	W
Junction Temperature	T <sub>j</sub>		150	°C
Storage Temperature Range	T <sub>st</sub>	-65	150	°C
Lead Temperature (soldering, 10s)			260	°C
ElectroStatic Discharge – HBM (JEDEC/ESDA JS-001-2012)			2000 (Class 2)	V
ElectroStatic Discharge – CDM (JEDEC 22-C101F)			1000 (Class C3)	V

- a. Exposure to these maximum RF levels can result in significantly higher I<sub>CC</sub> current draw due to overdriving the amplifier stages.

## Recommended Operating Conditions

**Table 3. Recommended Operating Conditions**

Parameter	Symbol	Condition	Minimum	Typical	Maximum	Units
Power Supply Voltage	$V_{CC}$		4.75		5.25	V
Operating Temperature Range	$T_{CASE}$	Exposed Paddle	-40		+105	°C
RF Frequency Range [a]	$F_{RF}$	High Linearity Bandwidth	2100		2700	MHz
		Extended band for DPD	2700		2950	
Maximum Operating Average RF Output Power		$Z_S = Z_L = 50 \Omega$			14	dBm
RFIN Port Impedance	$Z_{RFI}$	Single Ended		50		$\Omega$
RFOUT Port Impedance	$Z_{RFO}$	Single Ended		50		$\Omega$

- a. Device linearity is optimized over the range from 2100 MHz to 2700 MHz. Gain flatness is optimized up to 2950 MHz to account for systems with extended DPD bandwidth requirements.

## Electrical Characteristics - General

See Typical Application Circuit. Unless otherwise stated, specifications apply when operated as a TX VGA,  $V_{CC} = +5.0\text{ V}$ ,  $F_{RF} = 2.65\text{ GHz}$ ,  $T_{CASE} = +25\text{ }^{\circ}\text{C}$ ,  $/STBY = \text{High}$ ,  $Z_S = Z_L = 50\text{ }\Omega$ , maximum gain setting. Evaluation Kit trace and connector losses are de-embedded.

**Table 4. Electrical Characteristics**

Parameter	Symbol	Condition	Minimum	Typical	Maximum	Units
Logic Input High Threshold	$V_{IH}$	JEDEC 1.8V or 3.3V logic	<b>1.1</b> <sup>[a]</sup>		$V_{CC}$	V
Logic Input Low Threshold	$V_{IL}$	JEDEC 1.8V or 3.3V logic	<b>-0.3</b>		<b>0.8</b>	V
Logic Current	$I_{IH}, I_{IL}$	SPI	<b>-1</b>		<b>+1</b>	$\mu\text{A}$
	$I_{STBY}$	/STBY	<b>-10</b>		<b>+10</b>	
DC Current	$I_{CC}$			215	<b>245</b>	mA
Standby Current	$I_{CC\_STBY}$	/STBY = Low		1	<b>2</b>	mA
Standby Switching Time	$T_{STBY}$	50% /STBY control to within 0.2 dB of the on state final gain value		250		ns
Gain Step	$G_{STEP}$	Least Significant Bit		0.5		dB
Maximum Attenuator Glitching	$ATTN_G$	Any state to state transition		2		dB
Maximum Step Error (DNL) [over voltage, temperature and attenuation states]	$ERROR_{STEP}$	$F_{RF} = 2.10\text{ GHz}$	-0.27 <sup>[b]</sup>		+0.24	dB
		$F_{RF} = 2.30\text{ GHz}$	-0.32		+0.26	
		$F_{RF} = 2.50\text{ GHz}$	-0.36		+0.29	
		$F_{RF} = 2.65\text{ GHz}$	-0.36		+0.31	
		$F_{RF} = 2.80\text{ GHz}$	-0.36		+0.33	
		$F_{RF} = 2.95\text{ GHz}$	-0.37		+0.36	
Maximum Absolute Error (INL)	$ERROR_{ABS}$			0.8		dB
Gain Settling Time <sup>[c]</sup>	$G_{ST}$	50% of CSb to 10% / 90% RF		200		ns
SPI <sup>[d]</sup>						
Serial Clock Speed	$F_{CLOCK}$				<b>25</b>	MHz
CSb to CLK Setup Time	$T_{LS}$		<b>5</b>			ns
CLK to Data Hold Time	$T_H$		<b>5</b>			ns
CSb Trigger to CLK Setup Time	$T_{LC}$		<b>5</b>			ns

- Items in min/max columns in **bold italics** are Guaranteed by Test.
- Items in min/max columns that are not bold/italics are Guaranteed by Design Characterization.
- Excludes SPI write time.
- SPI 3 wire bus (refer to serial Control Mode Timing diagram).

## Electrical Characteristics - RF

See Typical Application Circuit. Unless otherwise stated, specifications apply when operated as a TX VGA,  $V_{CC} = +5.0\text{ V}$ ,  $F_{RF} = 2.65\text{ GHz}$ ,  $T_{CASE} = +25\text{ }^{\circ}\text{C}$ , /STBY = High,  $Z_S = Z_L = 50\text{ }\Omega$ , maximum gain setting. Evaluation Kit trace and connector losses are de-embedded.

**Table 5. Electrical Characteristics**

Parameter	Symbol	Condition	Minimum	Typical	Maximum	Units
RF Input Return Loss	$RL_{RFIN}$			12		dB
RF Output Return Loss	$RL_{RFOUT}$			12		dB
Gain - Max Gain Setting	$G_{MAX}$		<b>30.6</b>	32.1	<b>33.6</b>	dB
Gain - Min Gain Setting	$G_{MIN}$	Max attenuation	<b>-1.5</b>	0	<b>1.5</b>	dB
Gain Flatness [c]	$G_{FLAT}$	$F_{RF} = 2100\text{ MHz to }2700\text{ MHz}$ any 400 MHz BW		0.5		dB
Noise Figure	NF	0 dB attenuation		3.9		dB
		10 dB attenuation		5.9		
		20 dB attenuation		10.9		
		29.5 dB attenuation		19.5		
		31.5 dB attenuation		21.5		
Output Third Order Intercept Point	OIP3	0 dB attenuation Pout = +7 dBm / tone 5 MHz tone separation		41.9		dBm
		6 dB attenuation Pin = -21 dBm / tone 5 MHz tone separation		45.4		
		10 dB attenuation Pin = -21 dBm / tone 5 MHz tone separation	<b>35.5</b>	43.6		
		20 dB attenuation Pin = -21 dBm / tone 5 MHz tone separation		36.1		
		29.5 dB attenuation Pin = -21 dBm / tone 5 MHz tone separation		27.4		
		31.5 dB attenuation Pin = -21 dBm / tone 5 MHz tone separation		25.7		
Output 1dB Compression Point	OP1dB	0 dB attenuation		21.9		dBm
		0 dB attenuation, $T_{CASE} = +105\text{ }^{\circ}\text{C}$		21.4		
		6 dB attenuation	<b>20.9</b>	21.9		

- Items in min/max columns in **bold italics** are Guaranteed by Test.
- Items in min/max columns that are not bold/italics are Guaranteed by Design Characterization.
- Includes a positive slope feature over the noted RF range to compensate for typical system roll-off.

## Thermal Characteristics

**Table 6. Package Thermal Characteristics**

Parameter	Symbol	Value	Units
Junction to Ambient Thermal Resistance.	$\theta_{JA}$	40	°C/W
Junction to Case Thermal Resistance. (Case is defined as the exposed paddle)	$\theta_{JC}$	4	°C/W
Moisture Sensitivity Rating (Per J-STD-020)		MSL 1	

## Typical Operating Conditions (TOC)

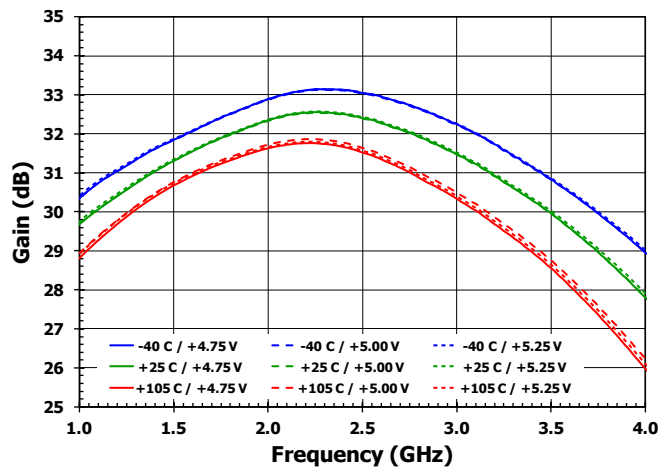
Unless otherwise stated the typical operating graphs were measured under the following conditions:

- $V_{CC} = 5.0 \text{ V}$
- $Z_L = Z_S = 50 \text{ Ohms}$  Single Ended
- $F_{RF} = 2.65 \text{ GHz}$
- $T_{CASE} = +25 \text{ °C}$
- /STBY = High
- 5 MHz Tone Spacing
- Gain setting = Maximum Gain
- All temperatures are referenced to the exposed paddle
- ACLR measurements used with a Basic LTE FDD Downlink 20 MHz TM1.2 Test signal
- EVM measurements used with a Basic LTE FDD Downlink 20 MHz TM3.1 Test signal
- Note TN1: Atten  $\leq 4 \text{ dB}$  Fixed Pout = 7 dBm per waveform or per tone, Atten  $> 4 \text{ dB}$  Fixed Pin = -21 dBm per waveform or per tone
- Note TN2: Atten  $\leq 7 \text{ dB}$  Fixed Pout = 10.5 dBm per waveform or per tone, Atten  $> 7 \text{ dB}$  Fixed Pin = -14.5 dBm per waveform or per tone
- Evaluation Kit traces and connector losses are de-embedded

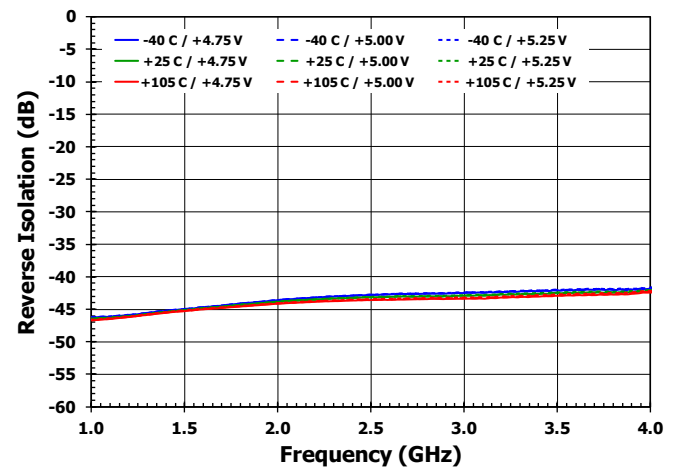


## Typical Performance Characteristics

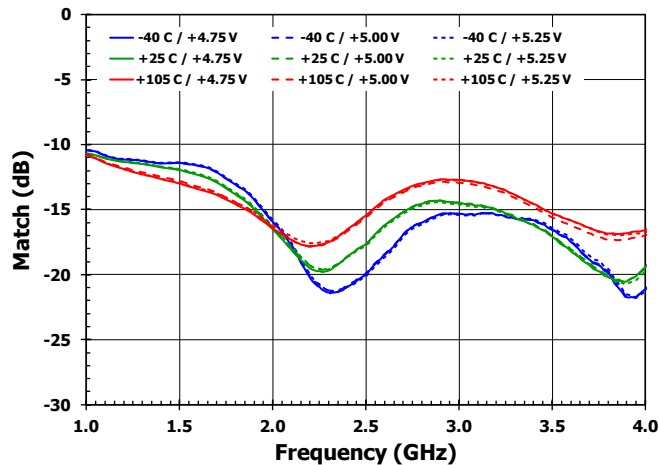
**Figure 3. Maximum Gain vs. Frequency over Temp and Voltage [Attn = 0.0 dB]**



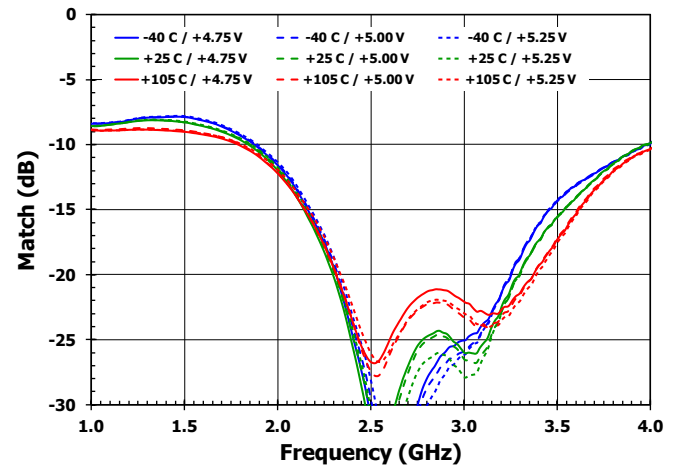
**Figure 4. Reverse Isolation vs. Frequency over Temp and Voltage [Attn = 0.0 dB]**



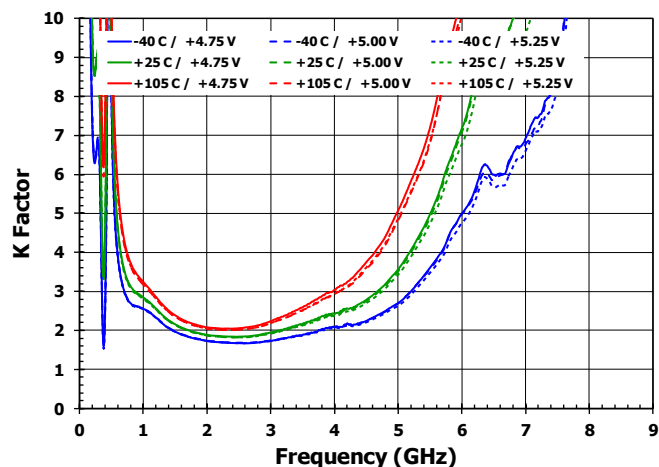
**Figure 5. Input Return Loss vs. Frequency over Temp and Voltage [Attn = 0.0 dB]**



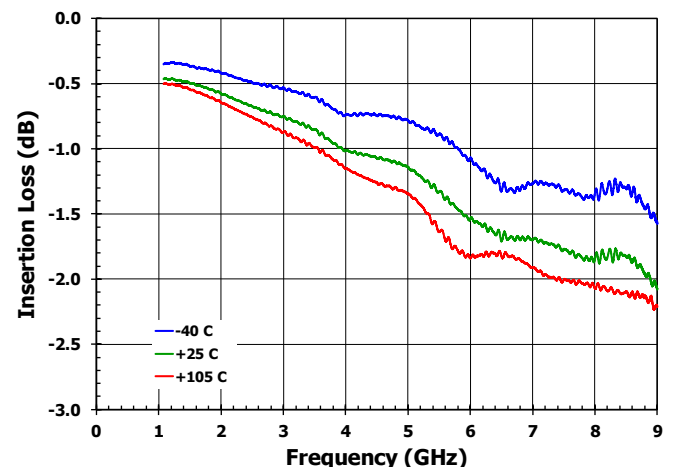
**Figure 6. Output Return Loss vs. Frequency over Temp and Voltage [Attn = 0.0 dB]**



**Figure 7. Stability vs. Frequency over Temperature and Voltage [Attn = 0.0 dB]**

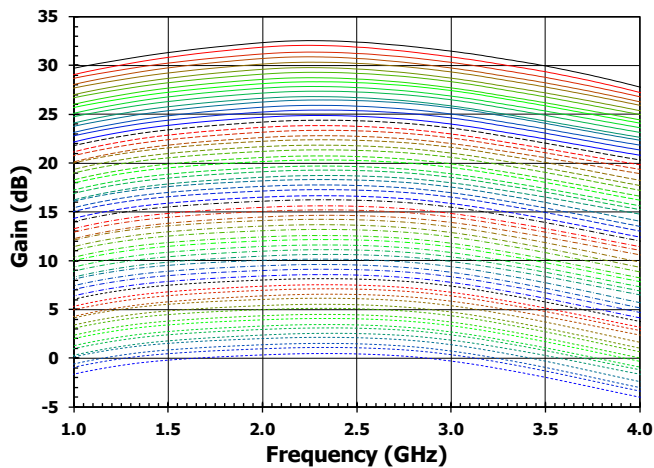


**Figure 8. EvKit Insertion Loss vs. Frequency over Temperature**

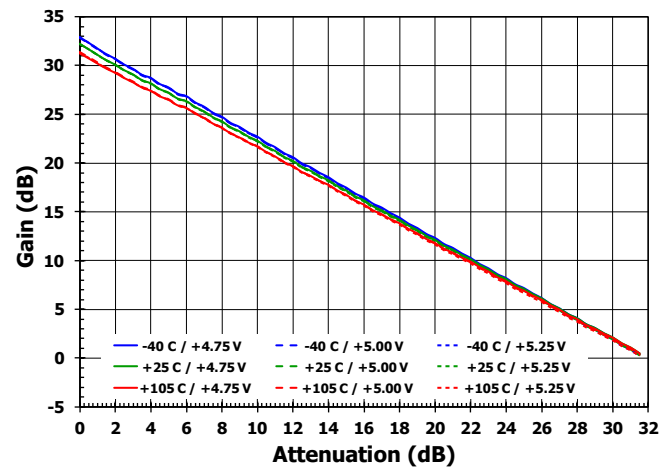


## Typical Performance Characteristics

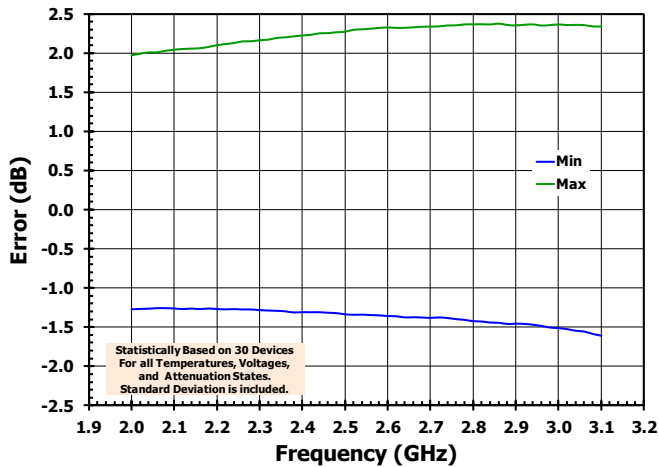
**Figure 9. Gain vs. Frequency [+25 °C, All States]**



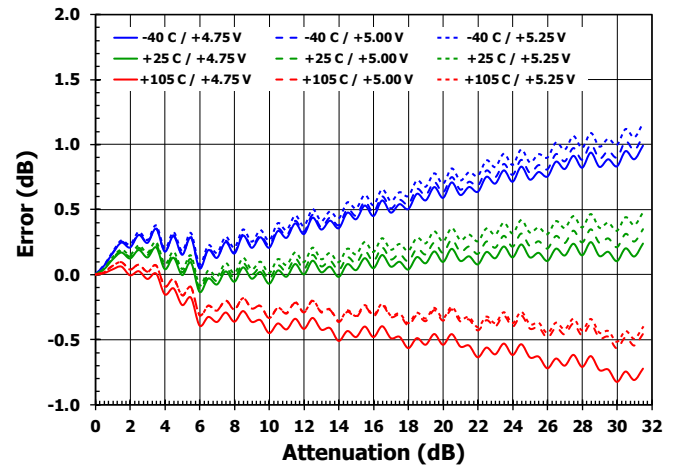
**Figure 10. Gain vs. Attenuation over Temperature and Voltage [2.65 GHz]**



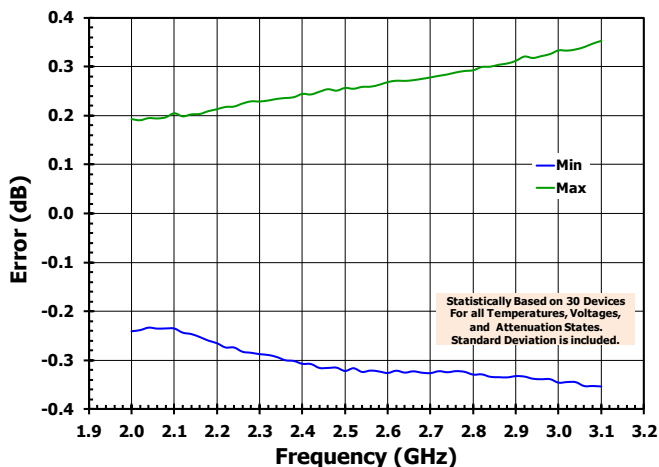
**Figure 11. Worst Case Attenuator Absolute Accuracy vs. Freq [All parameters]**



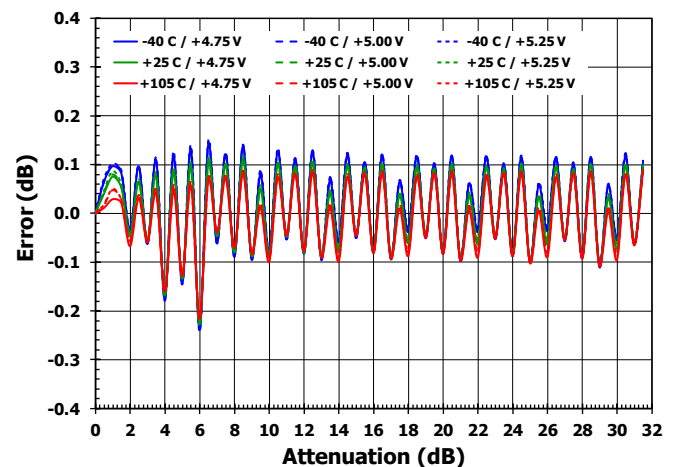
**Figure 12. Attenuator Absolute Accuracy vs. Atten over Temp and Voltage [2.65 GHz]**



**Figure 13. Worst Case Step Accuracy vs. Freq [All parameters]**

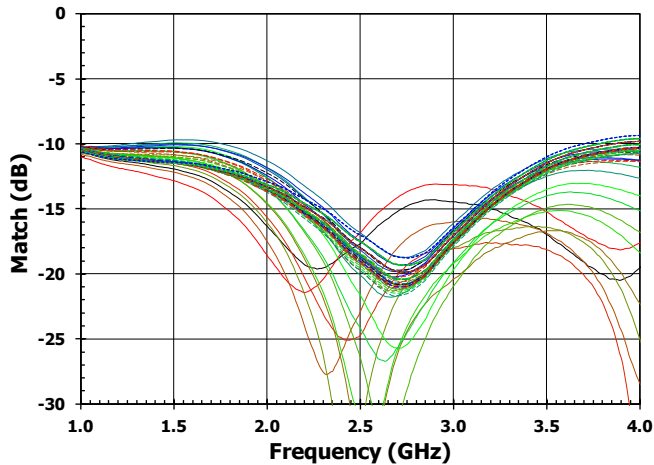


**Figure 14. Step Accuracy vs. Attenuation over Temperature and Voltage [2.65 GHz]**

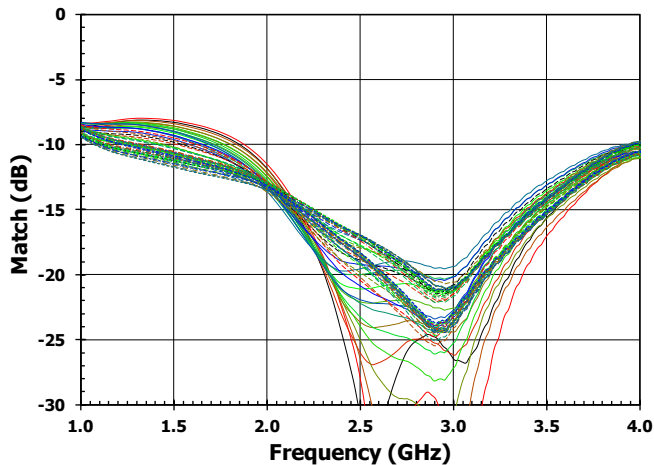


## Typical Performance Characteristics

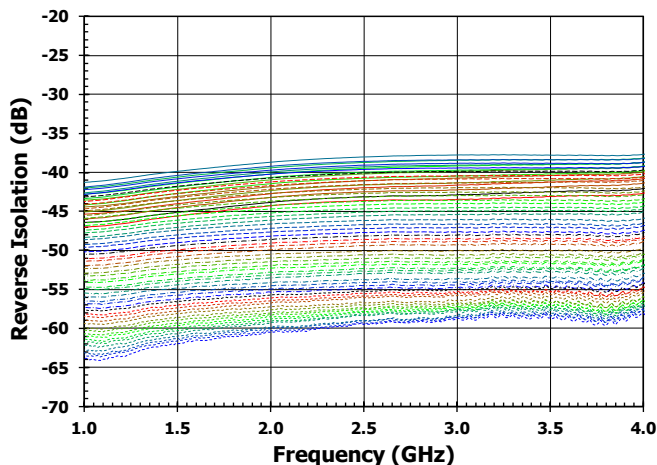
**Figure 15. Input Return Loss vs. Frequency**  
[+25 °C, All states]



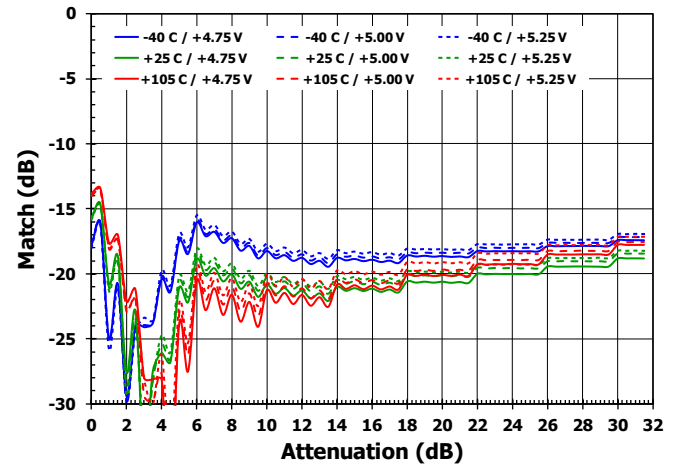
**Figure 17. Output Return Loss vs. Frequency**  
[+25 °C, All states]



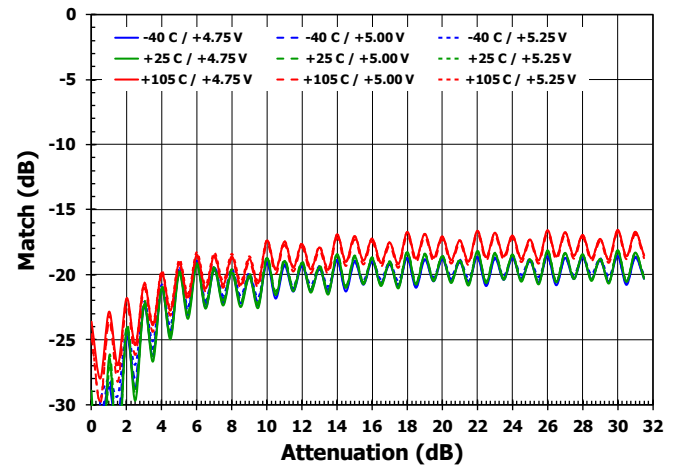
**Figure 19. Reverse Isolation vs. Frequency**  
[+25 °C, All states]



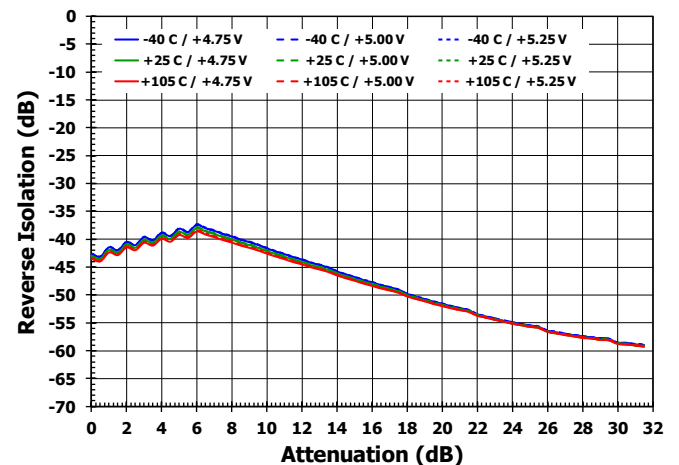
**Figure 16. Input Return Loss vs. Attenuation**  
over Temperature and Voltage [2.65 GHz]



**Figure 18. Output Return Loss vs. Attenuation**  
over Temperature and Voltage [2.65 GHz]

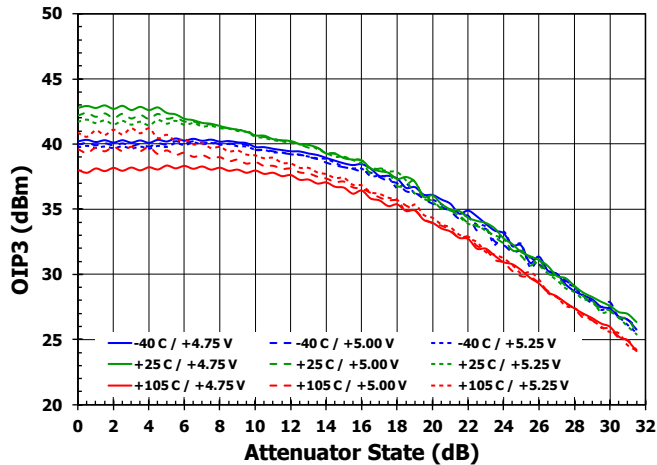


**Figure 20. Reverse Isolation vs. Attenuation**  
over Temperature and Voltage [2.65 GHz]

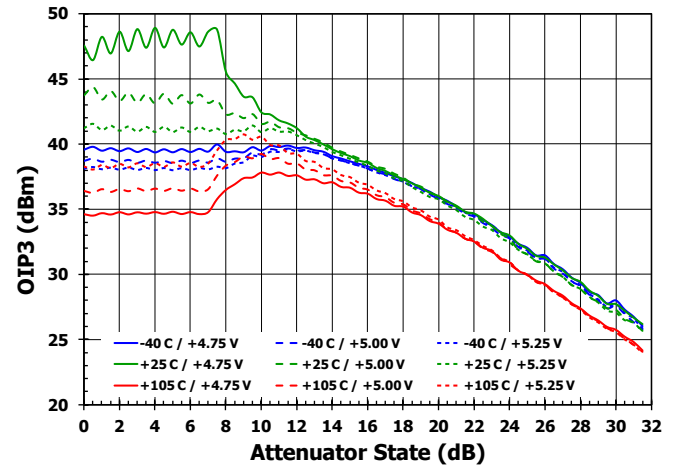


## Typical Performance Characteristics

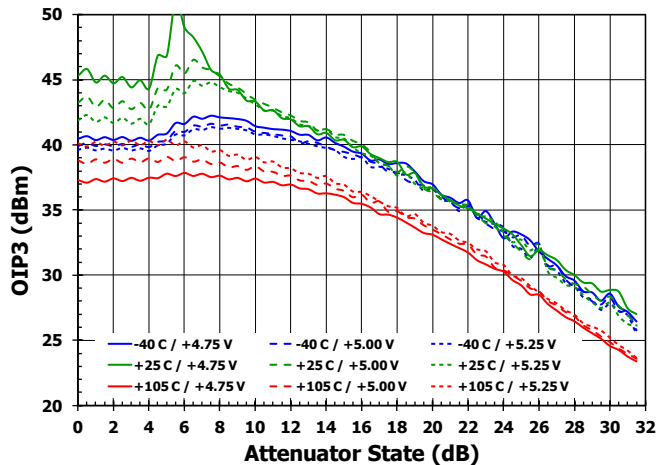
**Figure 21. Output IP3 vs. Attn over Temp and Voltage [2.3 GHz] (Test Note TN1)**



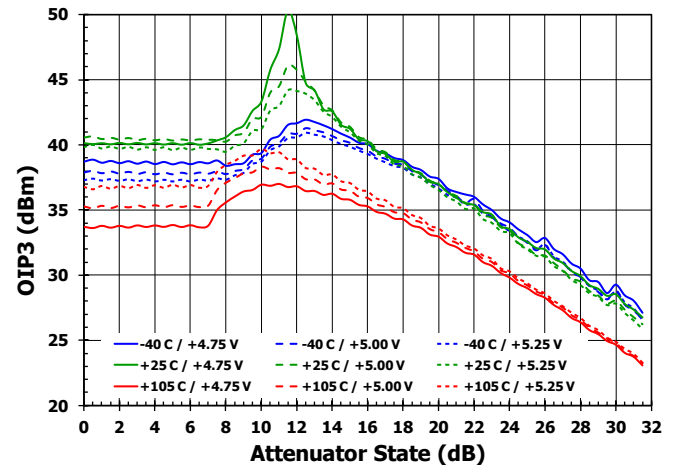
**Figure 22. Output IP3 vs. Attn over Temp and Voltage [2.3 GHz] (Test Note TN2)**



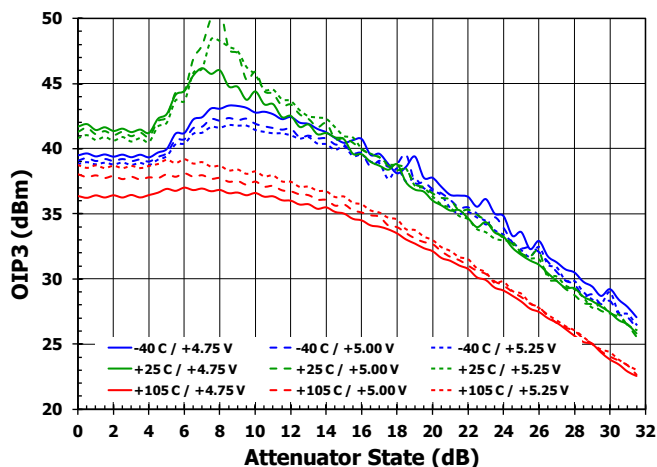
**Figure 23. Output IP3 vs. Attn over Temp and Voltage [2.5 GHz] (Test Note TN1)**



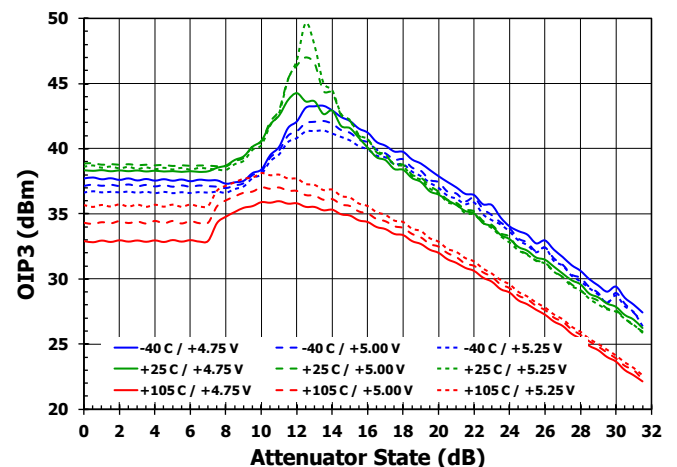
**Figure 24. Output IP3 vs. Attn over Temp and Voltage [2.5 GHz] (Test Note TN2)**



**Figure 25. Output IP3 vs. Attn over Temp and Voltage [2.65 GHz] (Test Note TN1)**

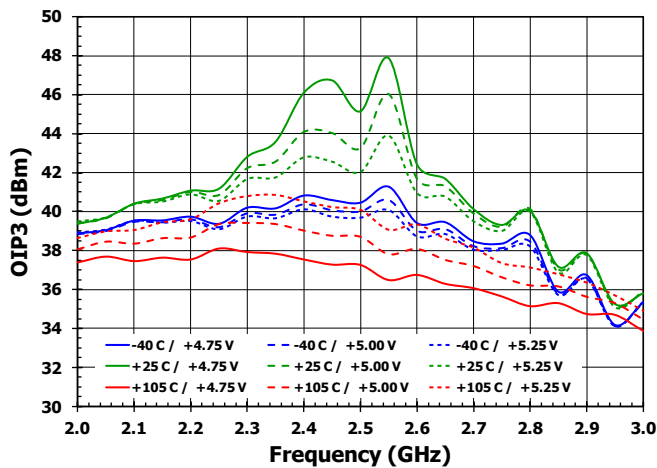


**Figure 26. Output IP3 vs. Attn over Temp and Voltage [2.65 GHz] (Test Note TN2)**

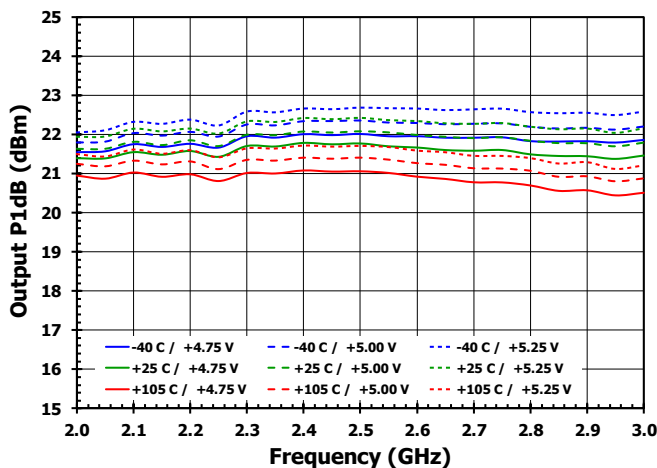


## Typical Performance Characteristics

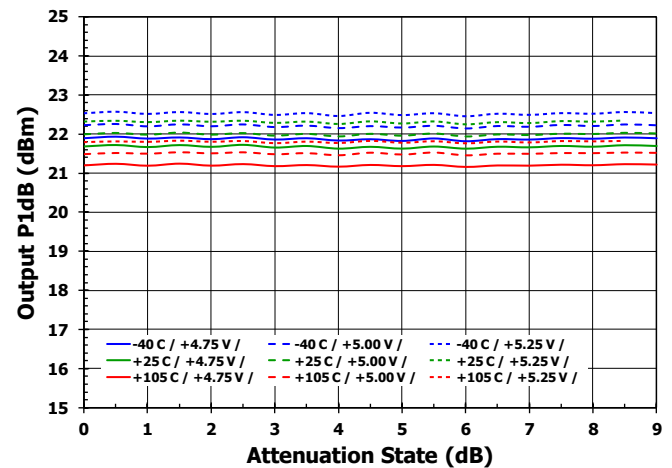
**Figure 27. Output IP3 vs. Frequency over Temperature and Voltage [Attn = 0.0 dB]**



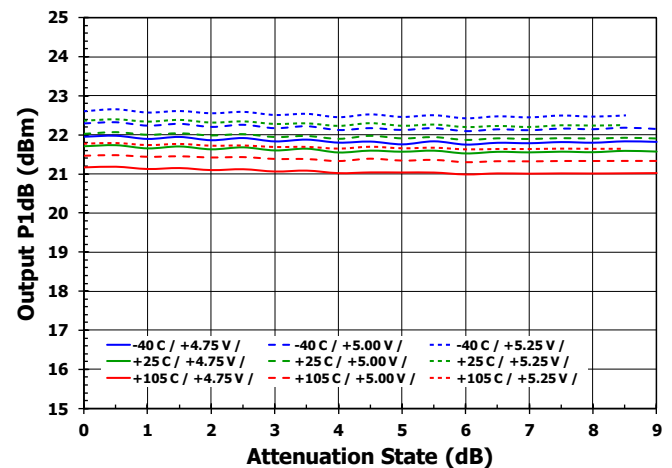
**Figure 29. Output P1dB vs. Frequency over Temp and Voltage [Attn = 0.0 dB]**



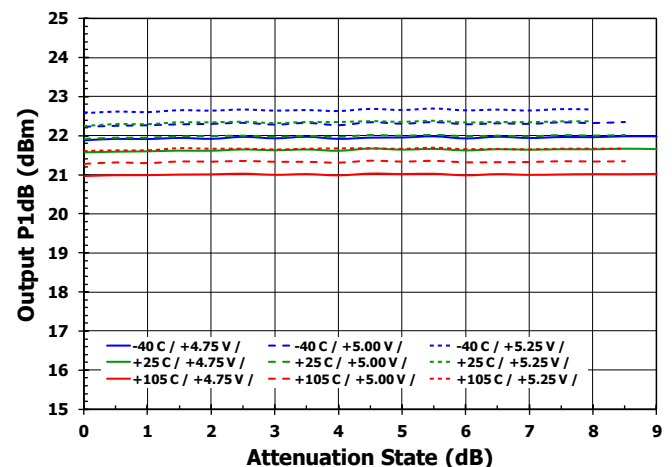
**Figure 28. Output P1dB vs. Attenuation over Temperature and Voltage [2.3 GHz]**



**Figure 30. Output P1dB vs. Attenuation over Temp and Voltage [2.5 GHz]**

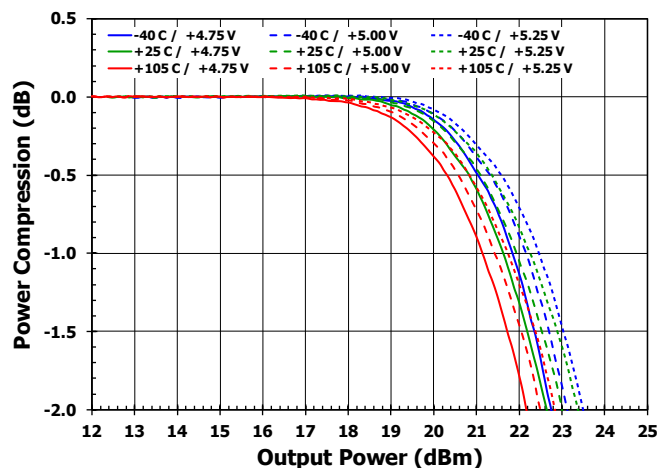


**Figure 31. Output P1dB vs. Attenuation over Temp and Voltage [2.65 GHz]**

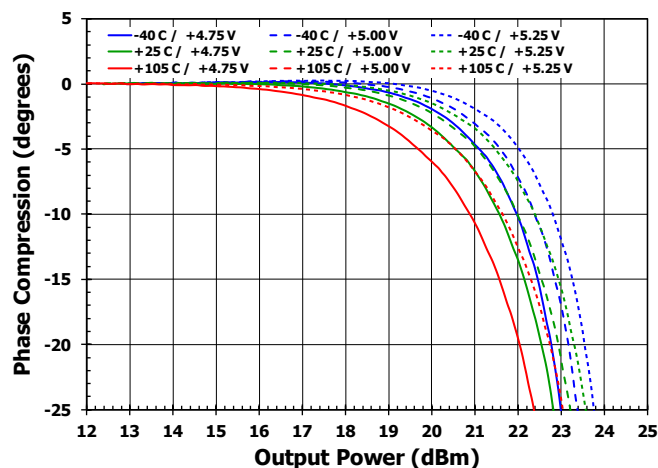


## Typical Performance Characteristics

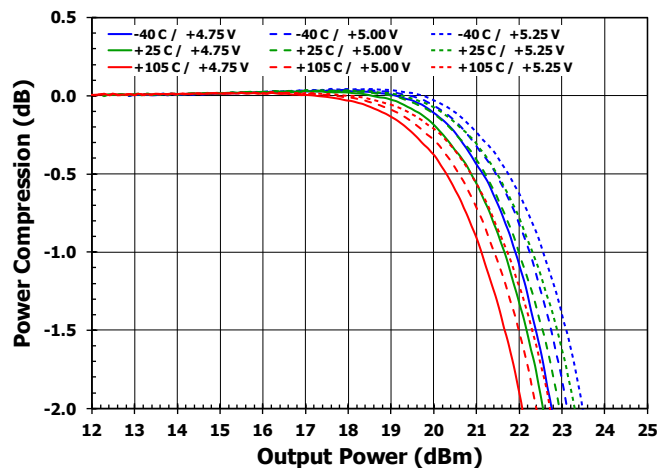
**Figure 32. Gain Compression vs. Pout over Temperature and Voltage [2.3 GHz]**



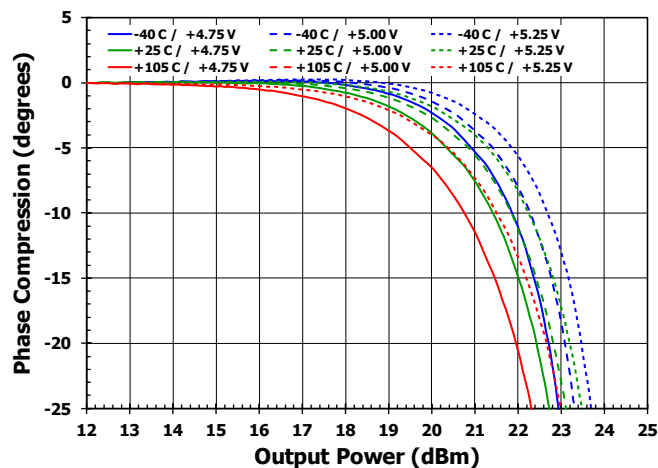
**Figure 33. Phase Compression vs. Pout over Temperature and Voltage [2.3 GHz]**



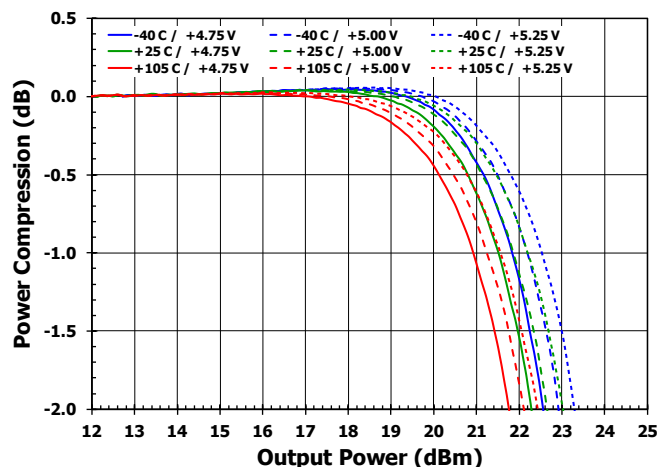
**Figure 34. Gain Compression vs. Pout over Temperature and Voltage [2.5 GHz]**



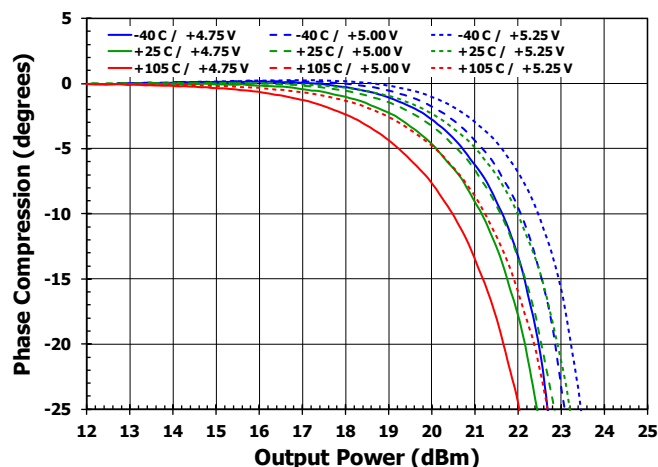
**Figure 35. Phase Compression vs. Pout over Temperature and Voltage [2.5 GHz]**



**Figure 36. Gain Compression vs. Pout over Temperature and Voltage [2.65 GHz]**

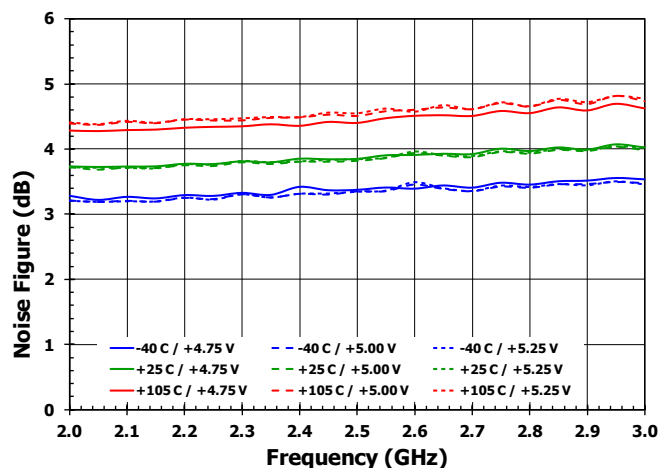


**Figure 37. Phase Compression vs. Pout over Temperature and Voltage [2.65 GHz]**

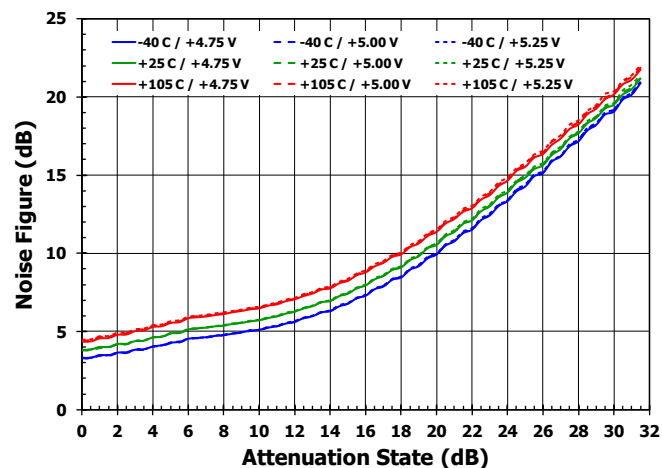


## Typical Performance Characteristics

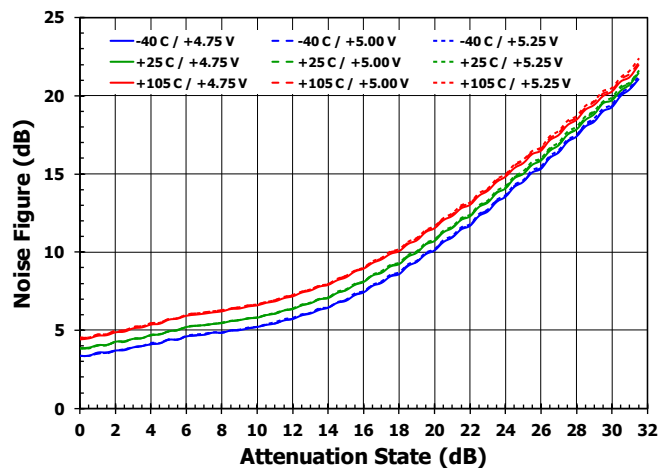
**Figure 38. Noise Figure vs. Frequency over Temperature and Voltage [Attn = 0.0 dB]**



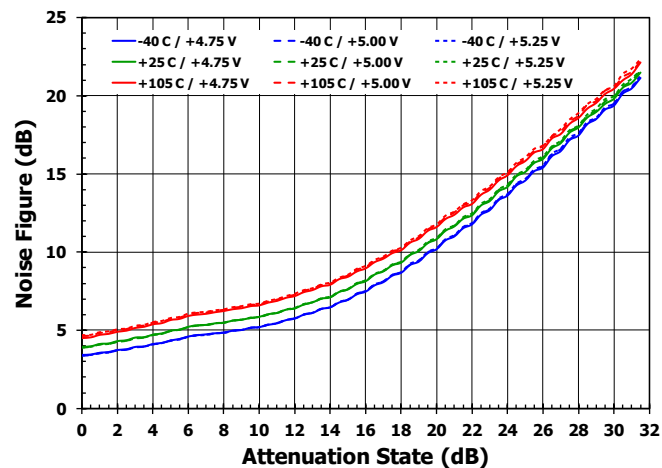
**Figure 39. Noise Figure vs. Attenuation over Temperature and Voltage [2.3 GHz]**



**Figure 40. Noise Figure vs. Attenuation over Temperature and Voltage [2.5 GHz]**



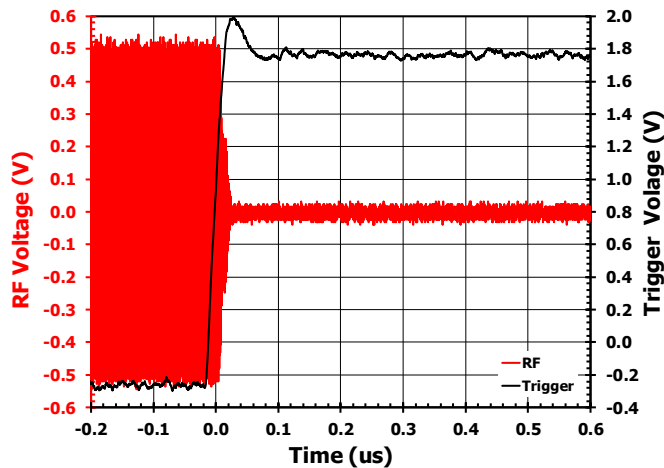
**Figure 41. Noise Figure vs. Attenuation over Temperature and Voltage [2.65 GHz]**



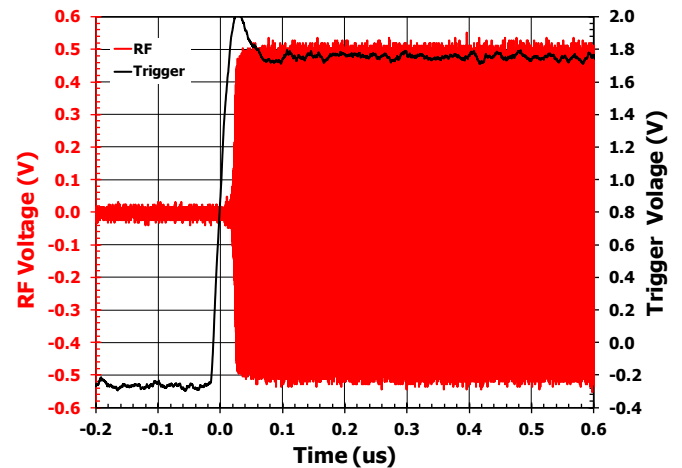


## Typical Performance Characteristics

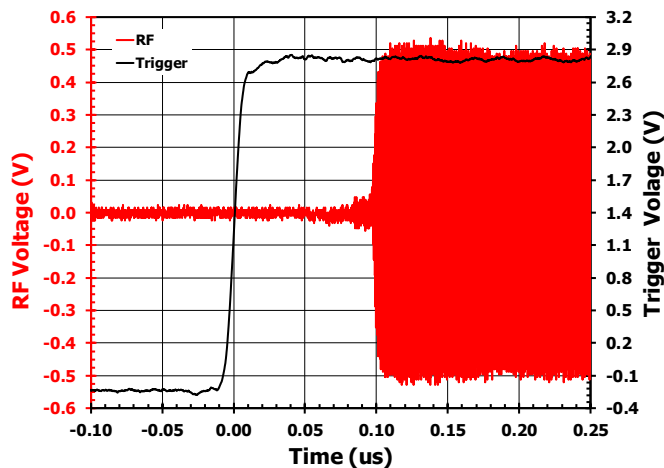
**Figure 42. Switching Speed 0.0 to 31.5 dB**



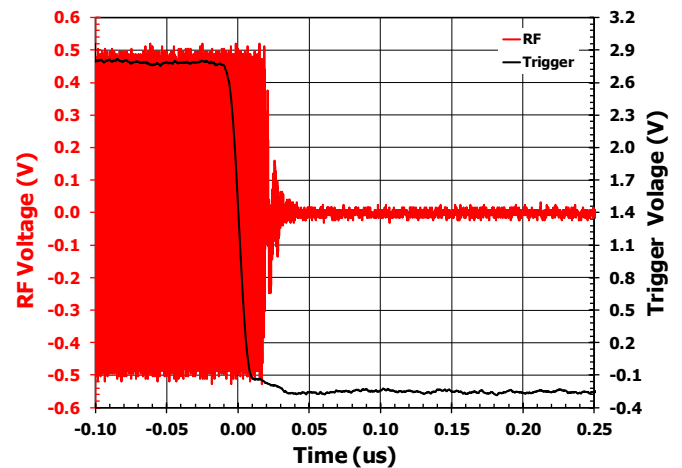
**Figure 43. Switching Speed 31.5 to 0.0 dB**



**Figure 44. Switching Speed Standby Mode to Full Operation Mode**



**Figure 45. Switching Speed Full Operation Mode to Standby Mode**





## Typical Performance Characteristics

Figure 46. ACLR vs. Attn [2.3 GHz]

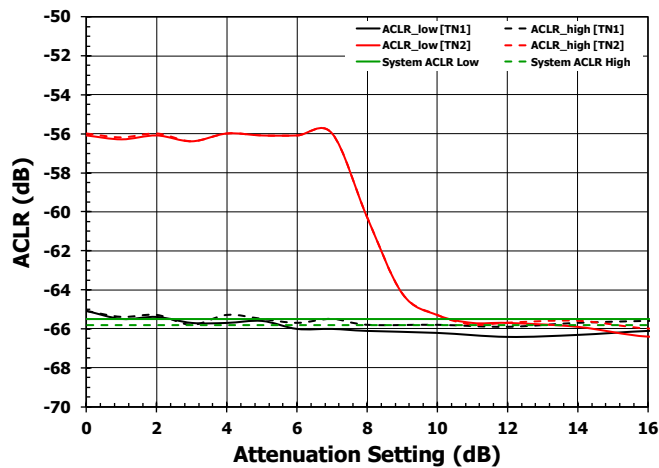


Figure 47. EVM (RMS) vs. Attn [2.3 GHz]

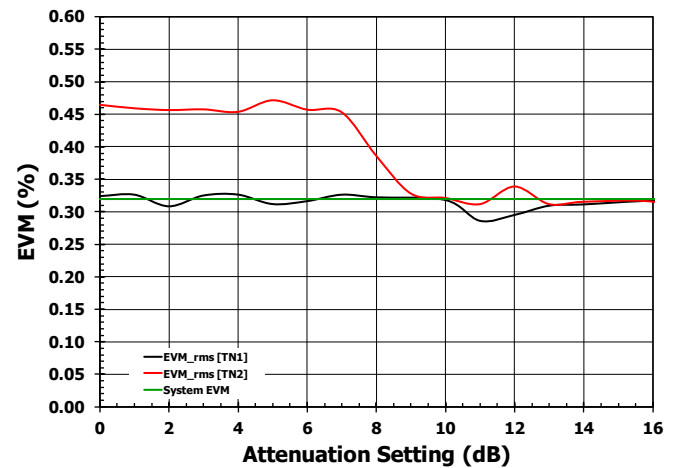


Figure 48. ACLR vs. Attn [2.5 GHz]

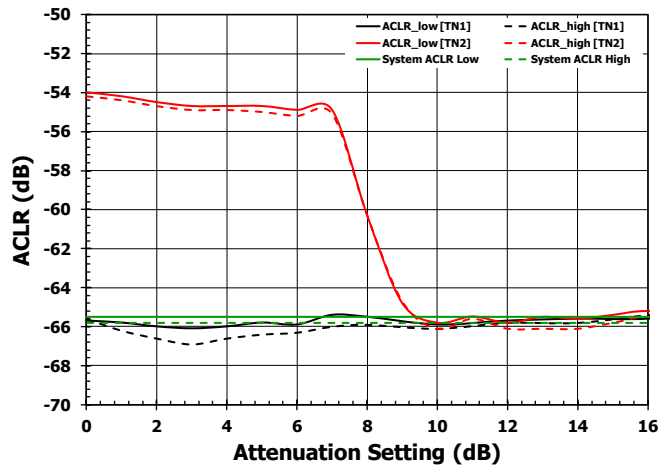


Figure 49. EVM (RMS) vs. Attn [2.5 GHz]

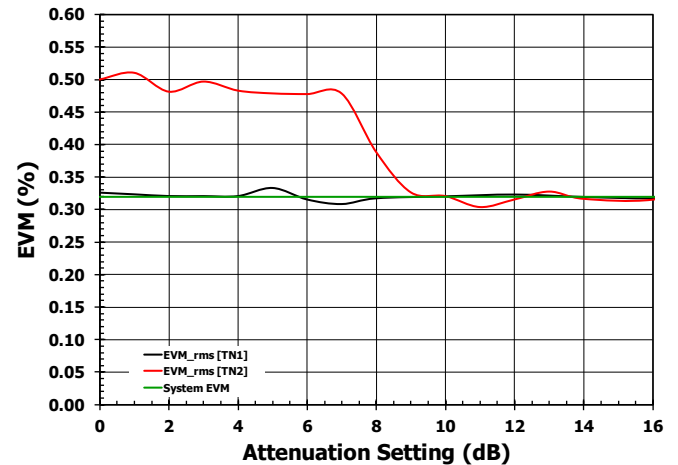


Figure 50. ACLR vs. Attn [2.65 GHz]

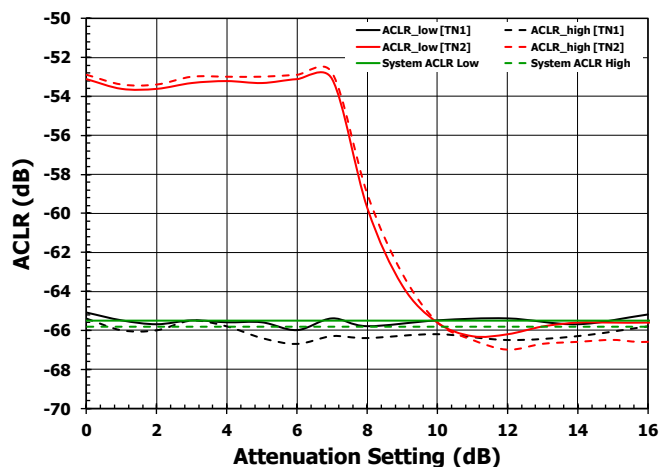
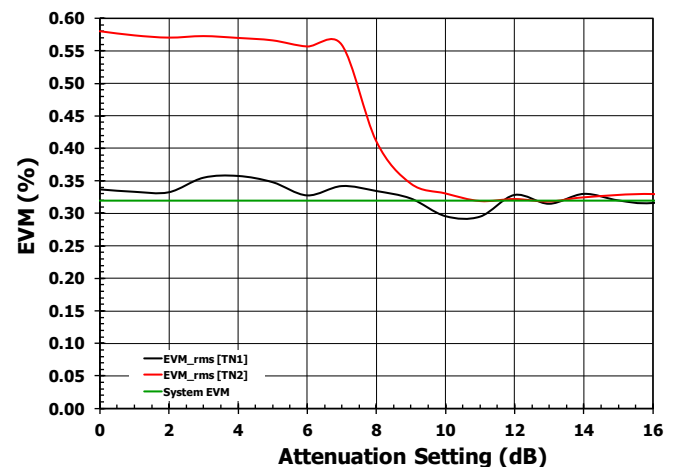


Figure 51. EVM (RMS) vs. Attn [2.65GHz]



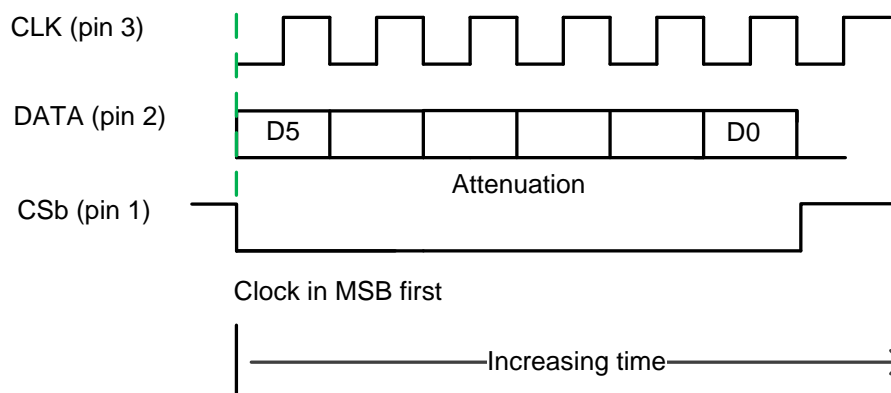
## Serial Port Interface

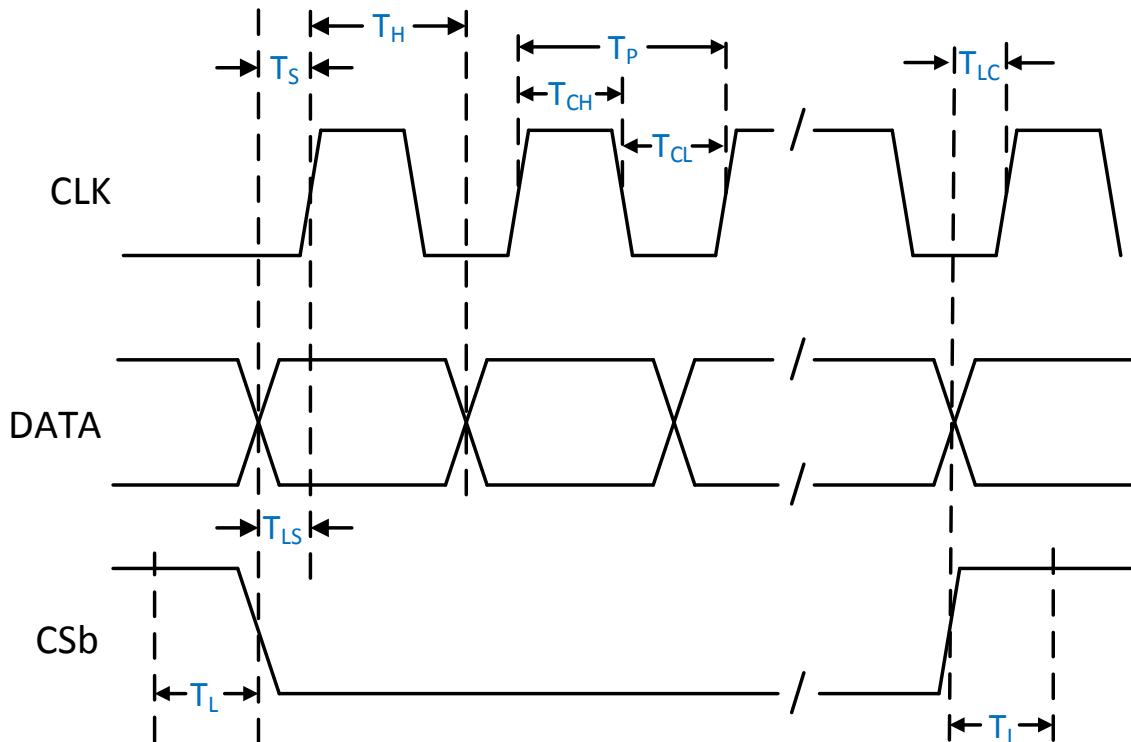
Serial data is formatted as a 6-bit word clocking data in MSB first.

**Table 7. Attenuation Word Truth Table**

Control Bit						Attenuator Setting
D5	D4	D3	D2	D1	D0	
1	1	1	1	1	1	0.0 dB
1	1	1	1	1	0	0.5 dB
1	1	1	1	0	1	1.0 dB
1	1	1	0	1	1	2.0 dB
1	1	0	1	1	1	4.0 dB
1	0	1	1	1	1	8.0 dB
0	1	1	1	1	1	16.0 dB
0	0	0	0	0	0	31.5 dB

**Figure 52. Serial Register Timing Diagram**



**Figure 53. SPI Timing Diagram**

**Table 8. SPI Timing Diagram Values for Figure 53**

Parameter	Symbol	Test Condition	Min	Typ	Max	Units
CLK Frequency	$F_C$				25	MHz
CLK High Duration Time	$T_{CH}$		20			ns
CLK Low Duration Time	$T_{CL}$		20			ns
DATA to CLK Setup Time	$T_S$		5			ns
CLK Period [a]	$T_P$		40			ns
CLK to DATA Hold Time	$T_H$		5			ns
CSb to CLK Setup Time	$T_{LS}$		5			ns
CSb Trigger Pulse Width	$T_L$		10			ns
CSb Trigger to CLK Setup Time [b]	$T_{LC}$		5			ns

a.  $(T_{CH} + T_{CL}) \geq 1/F_C$

b. Once all desired DATA is clocked in,  $T_{LC}$  represents the time a CSb high needs to occur before any subsequent CLK signals.

**Table 9. Standby Truth Table**

/STBY (pin 14)	Condition
0 V	Amplifier OFF with SPI powered ON
$V_{CC}$	Full operation

## Application Information

The F1456 has been optimized for use in high performance RF applications from 2100 MHz to 2950 MHz. The device maintains good performance outside of the optimized band as shown by the Typical Performance Characteristics.

### Power Up Attenuation Setting

When the part is initially powered up, the default VGA setting is the 31.5 dB [000000] attenuation state.

### Chip Select (CSb)

When CSb is set to logic high, the CLK input is disabled. When CSb is set to logic low, the CLK input is enabled and the DATA word can be programmed into the shift registers. The programmed word is then latched into the F1456 on the CSb rising edge (refer Figure 53). The operation of the SPI bus is independent of the /STBY pin setting (see Standby Mode section below).

### Standby Mode (/STBY)

The F1456 has a power down feature for power savings which is on Pin 14. For normal operation pin 14 must be set to a logic high. When a logic low is applied to pin 14 the amplifier is placed in standby mode. The Standby mode is a high isolation state. The level of this isolation is not specified and is dependent on the device and attenuation state. In Standby mode the SPI bus is operational and the device attenuation setting can be programmed. Therefore, the device will present the desired attenuation when it is enabled.

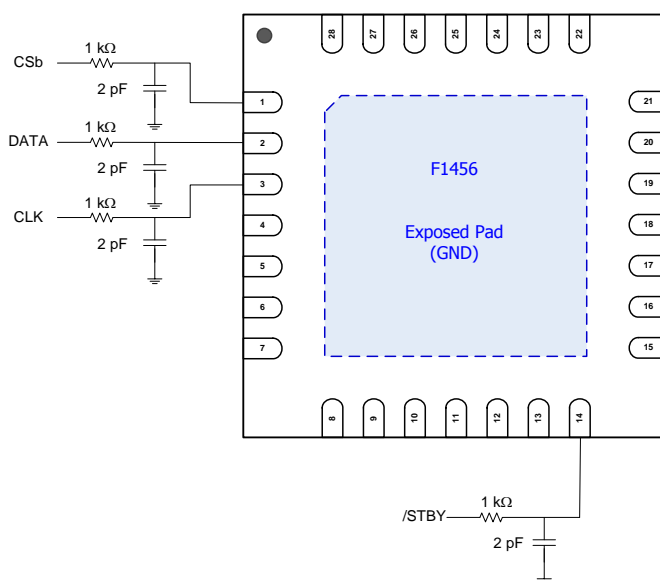
### Power Supplies

A common  $V_{CC}$  power supply should be used for all power supply pins. To minimize noise and fast transients de-coupling capacitors to all supply pins. Supply noise can degrade noise figure and fast transients can trigger ESD clamps causing them to fail. Supply voltage change or transients should have a slew rate smaller than  $1\text{ V} / 20\text{ }\mu\text{s}$ . In addition, all control pins should remain at 0 V ( $\pm 0.3\text{ V}$ ) while the supply voltage ramps or while it returns to zero.

### Control Pin Interface

If control signal integrity is a concern and clean signals cannot be guaranteed due to overshoot, undershoot, ringing, etc., the following circuit at the input of each control pin is recommended. This applies to SPI and control pins 1, 2, 3 and 14 as shown below. Note the recommended resistor and capacitor values do not necessarily match the EV kit BOM for the case of poor control signal integrity. For multiple devices driven by a single control line, the component values will need to be adjusted accordingly so as not to load down the control line.

**Figure 54. Control Pin Interface for Signal Integrity**



## Evaluation Kit Picture

Figure 55. Top View

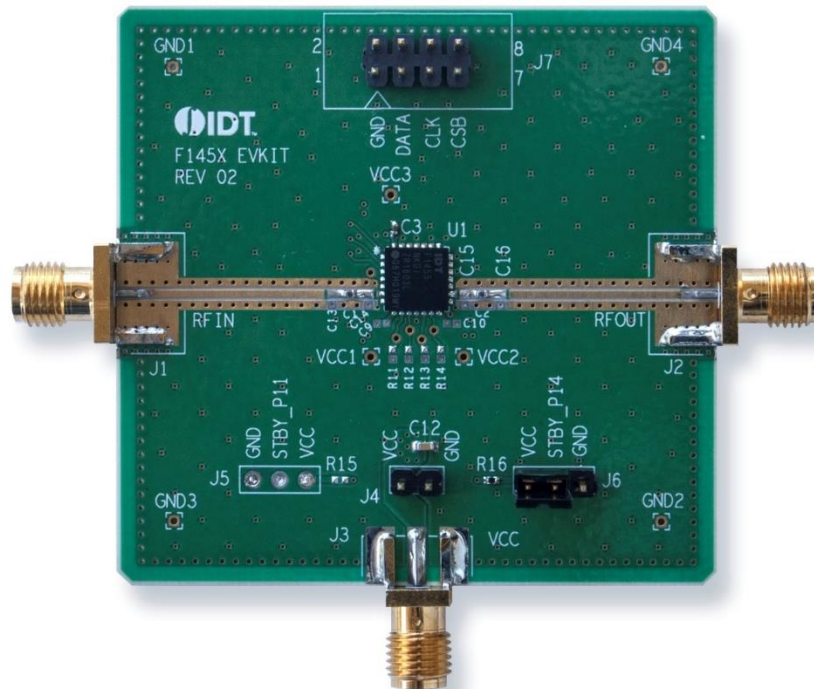
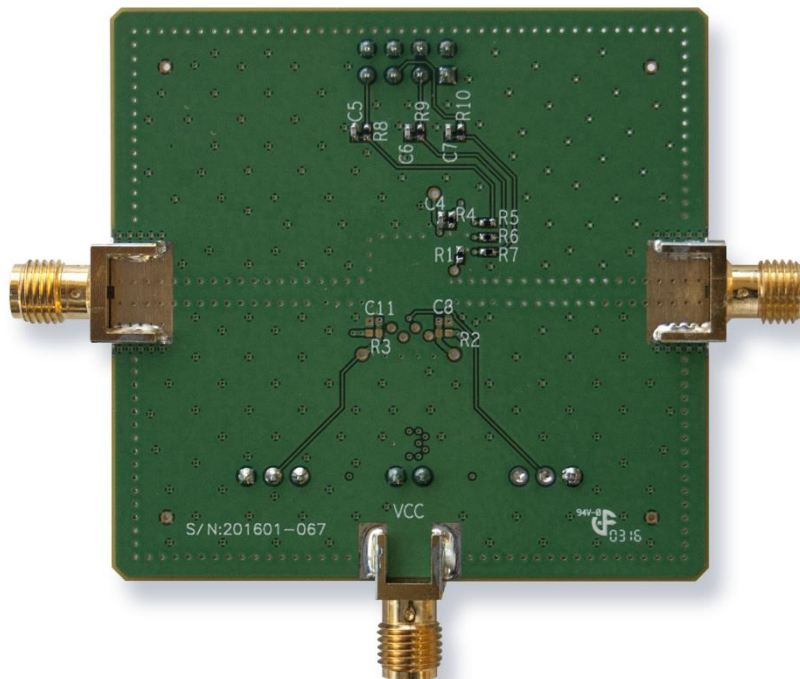
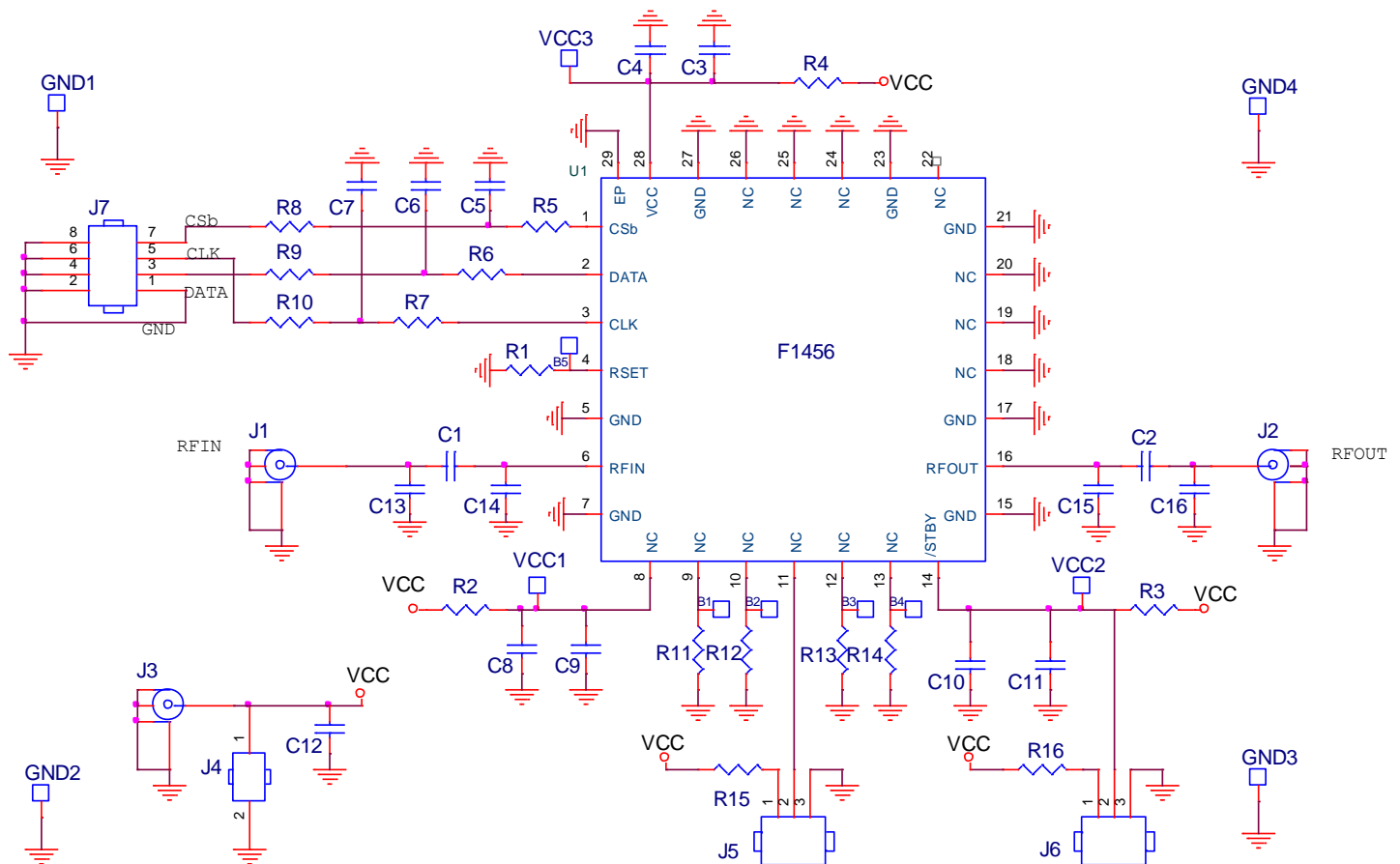


Figure 56. Bottom View



# Evaluation Kit / Applications Circuit

**Figure 57. Electrical Schematic**



Not All Components are used. Please check the Bill of Material (BOM) table.

**Table 10. Bill of Material (BOM)**

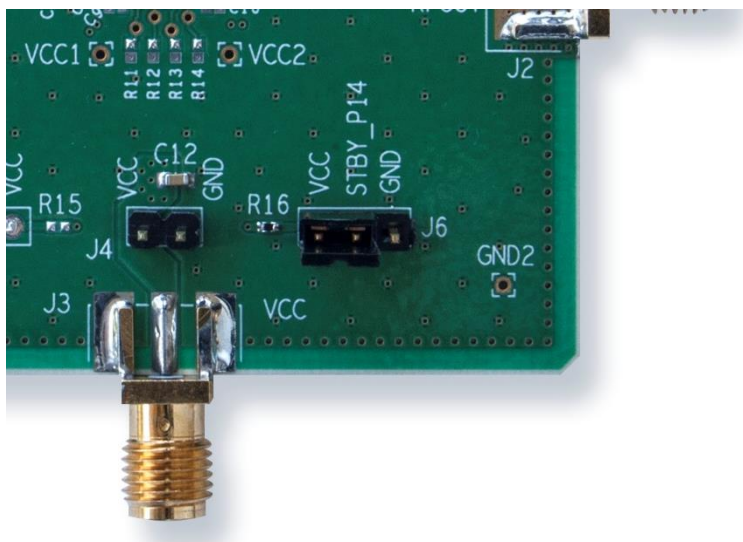
Part Reference	QTY	Description	Manufacturer Part #	Manufacturer
C1, C2	2	22 pF $\pm 5\%$ , 50V, C0G Ceramic Capacitor (0402)	GRM1555C1H220J	MURATA
C3	1	100 nF $\pm 10\%$ , 16V, X7R Ceramic Capacitor (0402)	GRM155R71C104K	MURATA
C4	1	1000 pF $\pm 5\%$ , 50V, C0G Ceramic Capacitor (0402)	GRM1555C1H102J	MURATA
C5, C6, C7	3	2 pF $\pm 0.1$ pF, 50V, C0G Ceramic Capacitor (0402)	GRM1555C1H2R0B	MURATA
C12	1	10 uF $\pm 20\%$ , 16V, X6S Ceramic Capacitor (0603)	GRM188C81C106M	MURATA
R1	1	2.2 k $\Omega$ $\pm 1\%$ , 1/10W, Resistor (0402)	ERJ-2RKF2201X	PANASONIC
R4 - R7	4	0 $\Omega$ Resistor (0402)	ERJ-2GE0R00X	PANASONIC
R8 - R10, R16	4	1 k $\Omega$ $\pm 1\%$ , 1/10W, Resistor (0402)	ERJ-2RKF1001X	PANASONIC
J4	1	CONN HEADER VERT SGL 2 X 1 POS GOLD	961102-6404-AR	3M
J6	1	CONN HEADER VERT SGL 3 X 1 POS GOLD	961103-6404-AR	3M
J7	1	CONN HEADER VERT DBL 4 X 2 POS GOLD	67997-108HLF	FCI
J1, J2	2	Edge Launch SMA (0.375 inch pitch ground, tab)	142-0701-851	Emerson Johnson
J3	1	Edge Launch SMA (0.250 inch pitch ground, round)	142-0711-821	Emerson Johnson
U1	1	VGA AMP	F1456NKGK	IDT
C8 - C11, C13 - C16, R2, R3, R11 - R15, J5		DNP		
	1	Printed Circuit Board	F145X EVKIT REV 02	

## Evaluation Kit Operation

### Standby

Connector J6 allows the F1456 to be put into the standby mode. Connecting J6 pin 2 (the center pin) to  $V_{cc}$  the amplifier will be placed in normal operating mode. To put the F1456 into standby mode for very low power consumption ground J6 pin 2 (the center pin). If J6 pin 2 (the center pin) is left open, then the F1456 will default to the standby mode.

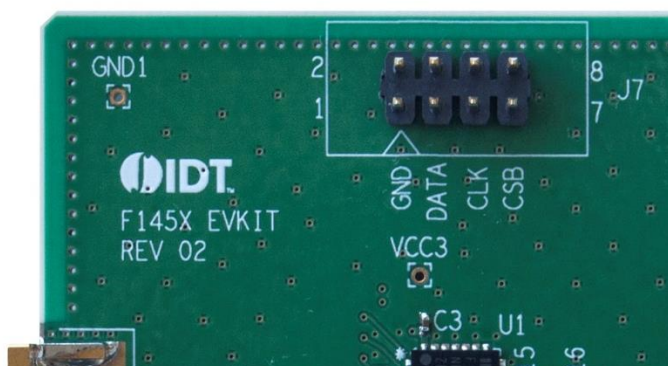
**Figure 58. Image of J6 connector for Standby mode control**



### Serial Programming Pins

Connector J7 pins 1, 2, 4, 6, 8 are ground. Pin 3 is DATA, pin 5 is Clock (CLK), pin 7 is Chip Select (CSB).

**Figure 59. Image of J7 connector for SPI**

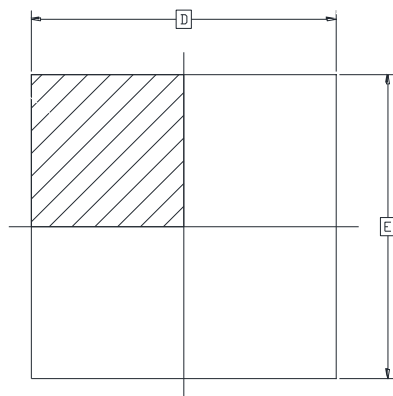




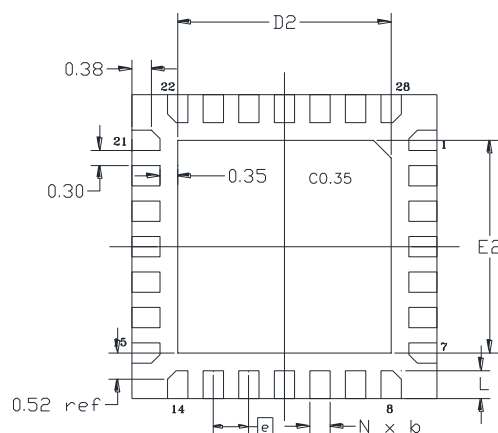
# Package Drawings

**Figure 60. Package Outline Drawing NKG28 PSC-4606**

INDEX AREA  
(D2/2 × E/2)



TOP VIEW



BOTTOM VIEW



SIDE VIEW

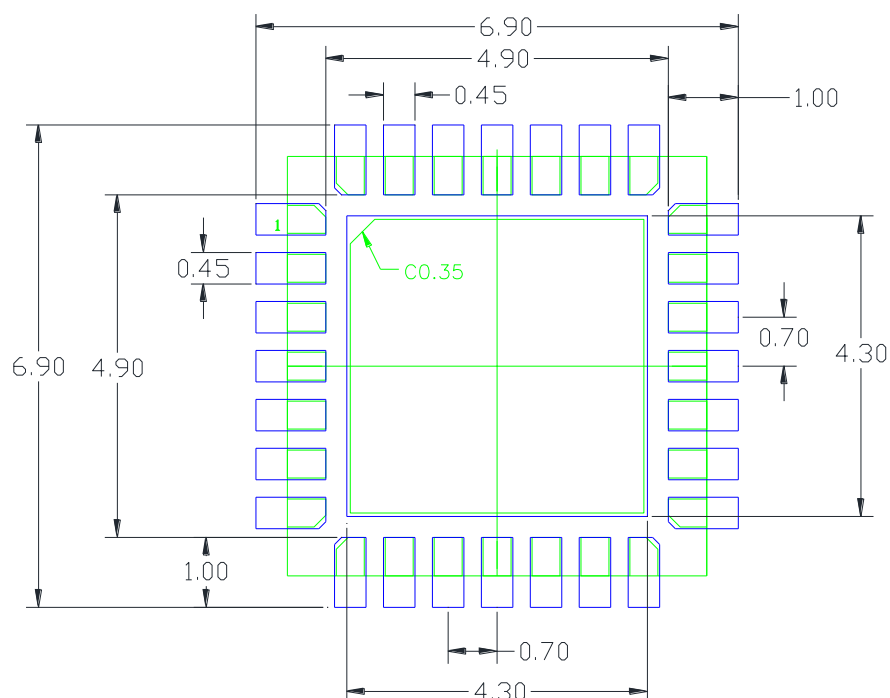
SYMBOL	DIMENSION		
	MIN	NOM	MAX
D2	4.10	4.20	4.30
E2	4.10	4.20	4.30
L	0.45	0.55	0.65
D	6.00 BSC		
E	6.00 BSC		
e	0.70 BSC		
A	0.80	0.90	1.00
A1	0.00	0.02	0.05
b	0.35	0.40	0.45
N	28		
aaa	0.15		
bbb	0.10		
ccc	0.10		
ddd	0.05		
eee	0.08		
fff	0.10		

## NOTES:

1. ALL DIMENSIONING AND TOLERANCING CONFORM TO ANSI Y14.5M-1982
2. ALL DIMENSIONS ARE IN MILLIMETERS.

## Recommended Land Pattern

**Figure 61. Recommended Land Pattern**



RECOMMENDED LAND PATTERN DIMENSION

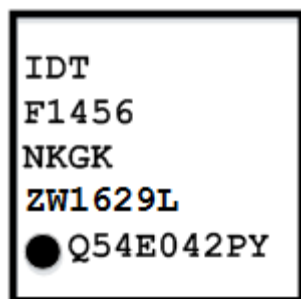
### NOTES:

1. ALL DIMENSIONS ARE IN mm. ANGLES IN DEGREES.
2. TOP DOWN VIEW, AS VIEWED ON PCB.
3. COMPONENT OUTLINE IS SHOWN FOR REFERENCE IN GREEN.
4. LAND PATTERN IN BLUE. NSMD PATTERN ASSUMED.
5. LAND PATTERN RECOMMENDATION PER IPC-7351B GENERIC REQUIREMENT FOR SURFACE MOUNT DESIGN AND LAND PATTERN.

## Ordering Information

Orderable Part Number	Package	MSL Rating	Shipping Packaging	Temperature
F1456NKGK	6 x 6 x 0.9 mm QFPN	1	Tray	-40° to +105°C
F1456NKGK8	6 x 6 x 0.9 mm QFPN	1	Tape and Reel	-40° to +105°C
F1456EVBK	Evaluation Board			
F1456EVSK	Evaluation Solution			

## Marking Diagram



1. Line 2 and 3 are the part number.
2. Line 4 "ZW" is Assembly Stepping.
3. Line 4 "yyww = 1629 has two digits for the year and week that the part was assembled.
4. Line 4 "L" denotes Assembly Site.
5. Line 5 "Q54E042PY" is the Assembly Lot number

## Revision History

Revision	Revision Date	Description of Change
0	2016-November 09	Initial Release



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