

Description

The ZMID520x Evaluation Kit enables evaluation of the IDT ZMID520x Family of Inductive Position Sensor ICs via IDT's ZMID520x Application Modules (available separately). It can be used for the sensor calibration for the following ICs:

- ZMID5201: analog interface
- ZMID5202: PWM interface
- ZMID5203: SENT interface

The main purpose of the ZMID520x Evaluation Kit is communication between the user's computer and the ZMID520x. The user's computer sends commands and data via its USB port to the ZMID Communication Board (ZMID-COMBOARD).

The microcontroller on the ZMID-COMBOARD interprets these commands and relays them to the ZMID520x located on the ZMID520x Application Module using the one-wire interface (OWI) communication interface.

The microcontroller also forwards data bytes from the ZMID520x back to the computer via the USB connection. These bytes can be sensor readings, ZMID520x internal registers values, or ZMID520x EEPROM contents.

The ZMID520x EVKIT Application Software is a graphical user interface (GUI) that is provided online for the kit. It supports all ZMID520x configurations and enables the user to understand the functionality of the ZMID520x as well as perform measurements.

Features

- USB "plug and play" no driver installation needed
- Small ZMID-COMBOARD: 4 cm × 7.3 cm
- One-wire communication interface (OWI) enables quick and easy configuration and calibration of the ZMID520x using the user's computer
- PWM, analog, or SENT reading of the output depending on product code
- The modular design allows easy swapping in different ZMID520x Application Modules (available separately) for evaluation using the same ZMID-COMBOARD and ZMID520x EVKIT Application Software
- The kit software is available for download from the IDT product page for the ZMID-COMBOARD: <u>www.IDT.com/ZMID-COMBOARD</u>

Kit Contents

- ZMID-COMBOARD
- Micro-USB cable

Figure 1. ZMID520x Evaluation Kit and ZMID520x Application Modules



Important Notes

Disclaimer

Integrated Device Technology, Inc. and its affiliated companies (herein referred to as "IDT") shall not be liable for any damages arising out of defects resulting from

- (i) delivered hardware or software
- (ii) non-observance of instructions contained in this manual and in any other documentation provided to user, or
- (iii) misuse, abuse, use under abnormal conditions, or alteration by anyone other than IDT.

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Restrictions in Use

IDT's ZMID520x Evaluation Kit, consisting of the ZMID-COMBOARD and micro-USB cable used in combination with the ZMID520x Application Module and the ZMID520x AID EVKIT Application Software, is designed for evaluation and configuration of the ZMID520x product family only. IDT's ZMID520x Evaluation Kit hardware and software must not be used for characterization measurements in terms of replacing calibrated laboratory environment and measurement devices.



Important Safety Warning: These procedures can result in high currents, which can cause severe injury or death and/or equipment damage. Only trained professional staff should connect external equipment and operate the software.



Important Equipment Warning: Ensure the correct connection of all cables. Supplying the board using the wrong polarity could result in damage to the board and/or the equipment.

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1. Setup

1.1 Required User Equipment

A Windows®-based computer is required for interfacing with the kit and configuring the ZMID520x.

1.2 User Computer Requirements and Setup

1.2.1 Computer Requirements

The user must have administrative rights on the computer to download and install the ZMID520x EVKIT Application Software for the kit.

The computer must meet the following requirements:

- Windows® Vista SP1 or later, 7 (including SP1), 8, 8.1, or 10.
 Note: Touch screens are not supported.
 Note: Windows® XP is no longer supported. Contact IDT for assistance. See contact information on the last page.
- Supported architecture: x86 and x64.
- Available USB port.
- Internet access for downloading the ZMID520x EVKIT Application Software.
- Microsoft® .NET Framework 4.0

1.2.2 Software Installation and Setup

The ZMID520x EVKIT Application Software is not included with the kit. To ensure use of the latest version of the software, it is available for download free of cost in zip file format from the IDT web site on the web page given on page 1.

Follow these procedures to install the ZMID520x EVKIT Application Software:

- 1. After downloading the zip file to the user's computer, extract the contents of the zip file.
- 2. Double-click on the extracted setup.exe file to activate the installation.
- 3. Follow the standard installation instructions displayed on the screen and change the installation path if required. If the default path settings have been used, the software automatically completes the installation and creates an access link on the user's computer under *Start > All Programs > IDT > ZMID520x EVKIT*. The installation dialog offers the option to create a desktop short-cut icon for the software.

1.3 Hardware Setup

This section describes the basic hardware setup of the ZMID520x Evaluation Kit boards and provides a brief overview on the components. Refer to the user manual for the specific ZMID520x Application Module for the setup required for the target holder, which is shown in Figure 1, and for further details for the module such as schematics and BOMs. The application module user manuals are available on the IDT product web pages for the modules: See section 6 for the IDT product web pages for the application modules to download the manuals.

1.3.1 Overview of the Hardware

Figure 2 shows the board connections for the ZMID520x Evaluation Kit using the ZMID5201 Arc Application Module (ZMID520xMARC18001) as an example.



Figure 2. ZMID520x Evaluation Kit Connections – ZMID520x Arc Application Module Example





Table 1. ZMID-COMMBOARD Key Components and Connector Descriptions

Note: See Figure 3 for the components referenced in this table.

Label	Description
P2	Connector to the ZMID520x Application Module Sensor Board. Note: The same signals are on the adjacent 4-pin header P1, which has silkscreen labels for the pin signals: NC (no connection), GND, OUT, and VDD.
P4	Alternative connection for the ZMID520x Application Module Sensor Board instead of P2 or for an optional connection for a second Application Module Sensor Board. If connecting to two modules at the same time, the ZMID520x ICs on the modules must have the same output option (e.g., 2 x ZMID5201). Note that the same signals are available on the adjacent 4-pin header P3, which has labels for the pin signals: NC (no connection), GND, OUT, and VDD.
P5	USB connector to the host PC.
P8	Boot pins.
Reset	Reset board button.
LED1 (Red)	Fault indicator LED: ON indicates an error.
LED2 (Green)	Information LED: ON indicates normal operational status.
LED3 (Blue)	Information LED: ON indicates initialization/communication.
LED4 (Red)	Board power indicator.

Figure 4, Figure 5, and Figure 6 give an overview of the different ZMID520x Application Module Sensor Boards before installation of the target holder for each type of board. The three boards have the same connectors and components given in Table 2 and identified in the figures. Each board has a silkscreen checkbox that indicates which ZMID520x IC is mounted on the Application Module Sensor Board: ZMID5201, ZMID5202, or ZMID5203, depending on the order code for the module.

Label	Description
P1	4-pin Molex Picoflex header for cable to the ZMID-COMBOARD.
P2	PCB 4-pin header for de-bugging purposes. If the user's microcontroller is used instead of the ZMID-COMBOARD, P2 can be used to connect the microcontroller to the Application Module.
D1	Power Indicator LED for the VDD.

Table 2. ZMID520x Application Module: Key Components and Connector Descriptions

Figure 4. ZMID520x Rotary 360° Application Module – Overview



Figure 5. ZMID520x Arc 130°Application Module – Overview





Figure 6. ZMID520x Linear Application Module – Overview

1.3.2 Connecting the Kit

Important Equipment Warning: Ensure the correct connection of all cables. Supplying the board using the wrong polarity could result in damage to the board and/or the equipment.

- 1. Ensure that the ZMID-COMBOARD is not connected to the computer.
- 2. Assemble the ZMID520x Application Module with the target holder as described in the user manual for the specific application module.
- Connect the ZMID520x Application Module via the flat cable to the ZMID-COMBOARD as shown in the example for the ZMID520x Arc Application Module in Figure 2. See Figure 1 for the connections for the ZMID520x Linear Application Module and ZMID520x Rotary Application Module.
- 4. Connect the ZMID-COMBOARD to the computer using the micro-USB cable provided in the ZMID-COMBOARD. Power is provided from the computer via the USB connection. No external power source is required.
- 5. The indicator LED2 on the ZMID-COMBOARD will light (see Figure 3) if conditions are normal. This indicates that the board is ready to communicate with the *ZMID520x EVKIT Application Software*. The D1 LED on the ZMID520x Application Module (see Figure 4, Figure 5, or Figure 6) also lights when the board is powered on.

2. ZMID520x EVKIT Application Software User Guide

2.1 Sections of the Display

The ZMID520x EVKIT Application Software provides a graphic user interface (GUI) for communicating with the kit. The GUI is displayed when the application is started. Figure 7 identifies the various sections of the display.



	ZMID520x EVKIT Application FILE SETTINGS TOOLS HELP		
2	ZMID5203	6	www.IDT.com
3-	CONNECTION Disconnect	BRATION COMMAND CONSOLE MEMORY EDIT	ACTIVE DEVICES
4-	IC STATUS Powered Busy CAPP mode CMD mode SW parity error Read Status	Raw 60% 40% -	Device: E: Name: ZMID5203 FW: 00.06.0009
5-	I/O FUNCTIONS Read EEPROM Write EEPROM Copy SWR To EEPROM Reset IC Create Log Enable Create Log	20% 	
			9
	 Menu bar: Contains settings and to Information label: Displays the nar "CONNECTION" section: Displays "IC STATUS" section: Displays statement 	ools. me of the connected device. s connection-related options. atus information from the connected device.	

- 5) "I/O FUNCTIONS" section: Displays options to perform READ and WRITE actions on the connected device.
- 6 Navigation tabs: Used to switch between the different main window tabs.
- 7) "ACTIVE DEVICES" section: Displays a list of the currently connected communication boards.
- ⁸ Main window area: Displays options and information about the connected device.
- 9) Status bar: Displays status messages during operation.

2.2 Getting Started

The following steps describe how to establish a connection to the ZMID520x Application Module and perform measurements. The combination of a ZMID-COMBOARD and its connected ZMID520x Application Module is referred to as the "device" in the GUI.

2.2.1 Connecting to a Device

- 1. Ensure that the ZMID520x Application Module is properly connected to the ZMID-COMBOARD. See section 1.3.2.
- 2. Connect the ZMID-COMBOARD to the user's computer using the micro-USB cable provided in the kit.
- 3. Start the GUI application. See Figure 8 for the start-up screen.
- 4. The device will appear in the "Active Devices" section. If there are no other devices on the list, it will be automatically selected; otherwise select it by clicking on it.
- 5. If the device shows as unknown, manually identify the device first. For a description of how to manually identify a device, refer to section 2.6.
- 6. Click on the "Connect" button to initialize the connection.
- 7. After a successful connection, the GUI will display the contents of the main window area.
- 8. Two sensor boards can also be connected to the ZMID-COMBOARD at the same time; see Figure 10 for an example. Data are displayed according to the selection made through the drop down menu on the top left side (Module 1 or Module 2). When connecting to two modules at the same time, both ZMID520x ICs on the modules must have the same output option (e.g., 2 x ZMID5201).

Figure 8. Start-up Screen





Figure 9. Display When Connected to a Device – ZMID5203 Example





2.2.2 Reading Measurements

- After connecting to a device, select the "MAIN" tab from the navigation menu. Two sub-tabs "OUTPUT" and "INTERNAL VALUES" are displayed. For the ZMID5203, the "SENT" sub-tab is also displayed and provides a SENT interface decoder. The "OUTPUT" tab displays the reading at the ZMID520x output pin SOUT.
- The readings can be displayed as scaled values in percent or as raw (decimal/hexadecimal) values. Use the "Component 1" radio buttons ("%" or "Raw") to select the desired method for presenting the values. If there are two devices, repeat the selection for the second device using the "Component 2" radio buttons.

The "OUTPUT" tab readings in percent represent

- a. Analog values for the ZMID5201 Percent of VDD
- b. PWM values for the ZMID5202 Duty cycle of the signal
- c. SENT values for the ZMID5203 Percent of the maximum position SENT value (4095)

The "OUTPUT" tab readings in raw data represent

- a. Analog values for the ZMID5201 –12-bit value from the ZMID COMBOARD's ADC with VDD for reference voltage
- b. PWM values for the ZMID5202 -12-bit value from the duty cycle calculation
- c. SENT values for the ZMID5203 12-bit position value decoded from the SENT stream
- Clicking the "Start" button will activate the measurements and change this button to the "Stop" button. The GUI disables some of its buttons and options while the measurement is active. Clicking the "Stop" button will deactivate the measurement and reactivate all options and buttons again.
- 4. At the bottom of each measurement tab, the "Enable Create Log" check box can be checked to log the measured values into a *.csv file. The filename and its location are specified with the "Select File" entry field.

The "OUTPUT" tab displays the physical values by using either the ADC or digital inputs of the ZMID-COMBOARD. Figure 11 shows an example of SENT interface readings. For the PWM or analog interface, the values are captured using an analog-to-digital conversion by the microcontroller located on the ZMID-COMBOARD. Hence, the accuracy of the measured values is limited due to the setup. The ZMID Evaluation Kit is a configuration tool – it is not intended to act as a measurement device.



Figure 11. "OUTPUT" Tab – ZMID5203 Example

The "INTERNAL VALUES" tab displays measurements that are only accessible via OWI (see Figure 12). Therefore, all the readings are digital register contents and not limited in terms of hardware accuracy.



Figure 12. "INTERNAL VALUES" Tab – ZMID5203 Example

There are three controls that can be used to view and change settings on the device:

- **AGC Mode:** Gain and integration time control used to enable or disable the Automatic Gain Control (AGC) and the Integration Time Control of the device. The following standard options are available in the drop-down menu:
 - · Gain adaptation and integration time adaptation off
 - · Gain adaptation and integration time adaptation on

Two additional options are available for the AGC Mode that are for advanced testing only. Note: Before using either of these options, contact IDT support (see the last page for the contact information).

- · Gain adaptation off and integration time adaptation on
- · Gain adaptation on and integration time adaptation off
- AGC Gain Stage. Depending on the AGC Mode, this control has different behaviors:
 - When the AGC is active ("Gain and integration time adaptation" is on), the value in the "ACG Gain Stage" entry field specifies the maximum gain for gain regulation. During measurements, the box becomes read-only and displays the existing gain stage setting that the ZMID520x is using.
 - When the AGC is disabled ("Gain and integration time adaptation" is off), the value in the input field specifies the selected gain stage.
- Over Sampling Rate (OSR). This parameter defines the number of averaging samples per receiving channel and reduces the noise level on the signal.

The "SENT" tab is only available when the ZMID5203 Application Module is connected to the ZMID-COMBOARD. It displays the decoded SENT data information as shown in Figure 13.



Figure 13. "SENT" Tab (ZMID5203 only)

2.3 Changing the Configuration Settings

The "CONFIGURE" tab (see Figure 14) is designed to provide the user with an easy way of viewing and editing the IC configuration. Each value represents a register or a part of a register from the internal memory of the device. The displayed memory type can be either the ZMID520x EEPROM or the SWR memory. SWR refers to shadow registers used as the working memory for the ZMID520x, which can be temporarily written via the GUI to the ZMID520x for development purposes.

2 ZWID 520X EVKIT Applicat	aon	
ILE SETTINGS TOOLS	HELP	
ZMID5203		www.IDT.co
CONNECTION	MAIN CONFIGURE CALIBRATION COMMAND CONSOLE MEMORY EDIT	ACTIVE DEVICES
Disconnect	INPUT OUTPUT DIAGNOSTICS	Refresh
	Shown memory type EEPROM ~	Devices Fr
IC STATUS Powered Busy APP mode CMD mode SW parity error Read Status	Lc_cal 16 Vddt_trim 3 Sampl_cycle 4 Ext 3 Gain_stage 8 Swap_rc_pol On > Swap_rc_amp On > Invppr2 Off > Invppr1 On > Osr 32 samples > Agc_interlink Gain adaptat > Agc_mode Gain off & Ir >	Name:ZMID5203 FW:00.06.0009
I/O FUNCTIONS Read EEPROM Write EEPROM	Agc_sat_mode Off v	
Reset IC		

Figure 14. "CONFIGURE" Tab – Selection of Memory Type to be Displayed

If parameters in the EEPROM memory selection have been changed, the ZMID520x must be reset after the writing process is finished for the changes to take effect. This is done automatically after pressing the "Write EEPROM" button in the "I/O FUNCTIONS" section (see Figure 15). This can be disabled via the "SETTINGS" menu > "Reset on Memory Write." In the case of the SWR selection, by default, changes are immediately written to the SWR memory of the ZMID520x. This option can be disabled via the "SETTINGS" menu > "Enable Automatic SWR Write" (see Figure 16). Clicking the "Write SWR to EEPROM" button in the "I/O FUNCTIONS" section copies all of the current SWR settings to the EEPROM memory of the device. This section also provides the "Reset IC" button for manually resetting the ZMID520x. The reset power cycles the device and puts it in Command Mode. After reset, the contents of the EEPROM of the device are copied to its working memory SWR.

Figure 15. Buttons in the "I/O FUNCTIONS" Section



Figure 16. Options on the "SETTINGS" Menu



There are three different data types shown on the "CONFIGURE" tab:

- 1. Numerical values are displayed in a white field (see Figure 17). If they are hexadecimal, "0x" is automatically inserted at the beginning of the value.
- 2. Values with predefined multiple choices are displayed in a drop-down menu (see Figure 18).
- 3. Read-only values are displayed with a light blue background. They can only be selected and copied (see Figure 19).

Figure 17. Example of Numerical Values That Can be Edited

|--|

Figure 18. Example of a Drop-Down Menu with Multiple Choice Values

2023Hz	•
1011Hz	
758Hz	
506Hz	
253Hz	
126Hz	

Figure 19. Example of Read-Only Values

3	0x0122	Positive

Changing a value will change the font color to red (see Figure 20). This indicates that the change has not yet been applied to the actual memory (EEPROM or SWR) of the IC. To apply the change, click the corresponding "Write..." button in the "I/O FUNCTIONS" section. If the "Reset IC" or one of the "Read" buttons is pressed, the values will be set to represent the current settings of the device.

Figure 20. Example of a Modified Value that is Not Yet Saved to Memory



Context-sensitive pop-ups (see Figure 21), referred to as "tooltips," provide additional information that appears briefly as the cursor hovers over an element on the screen. The tooltips for entry fields include a brief description of the setting and the address of the internal memory register.

Figure 21. Example of Tooltip Information

Pwm_freq	2023Hz •
	PWM frequency (Bits on address: 0x000A)

2.4 Calibration

There are three sub-tabs under the "CALIBRATION" tab: COIL OFFSET, OUTPUT RANGE, and CALIBRATION AND LINEARIZATION.

2.4.1 "COIL OFFSET" Sub-tab

The "COIL OFFSET" sub-tab is located under the "CALIBRATION" tab (see Figure 22). It is used to compensate the offset of the signal acquired from coils R1 and R2 connected to the ZMID520x.

Figure 22. "COIL OFFSET" Tab – ZMID5203 Example

ZMID520x EVKIT Application	n	– 🗆 X
FILE SETTINGS TOOLS H	ELP	www.IDT.com
CONNECTION Disconnect IC STATUS Powered Busy APP mode CMD mode SW parity error Read Status I/O FUNCTIONS Read EEPROM Write EEPROM Copy SWR To EEPROM Reset IC	MAIN CONFIGURE CALIBRATION COMMAND CONSOLE MEMORY EDIT COL OFFSET OUTPUT RANGE CALIBRATION AND LINEARIZATION R1 Offset (Cosine 26 R2 Offset (Sine) -30 Read Start Offset Groupensation Warning: In order to use Offset Calibration option, automatic gain control has to be turned off. If you start calibration, this option will be turned off automatically. (Agc_mode = 0) Sine Max Cosine Max Cosine Min Cosine	ACTIVE DEVICES Refresh Device: E: Name: ZMID5203 FW: 00.06.0009

For each of the coils, the following are displayed:

- 1. R1 Offset Offset applied to the signal from the R1 coil.
- 2. R2 Offset Offset applied to the signal from the R2 coil.

The GUI automatically determines which of the coils is the sine and cosine signal based on the current configuration settings. The two signals are color coded in red and green. When the "Read" button is pressed, the current sine and cosine and their maximal and minimal values are displayed next to the graph.



Figure 23. Receiver Coil (ABS Value) Offset Example with Offset Compensation = $\alpha/2$

To start the automatic calibration for amplitude offset, click the "Start Offset Compensation" button. The GUI will guide the user through a sequence of instructions for performing the calibration procedure.

- 1. Remove the target from the coil, and press "Ok."
- 2. Wait for a few seconds for the GUI to measure the offset. It will automatically continue to the next step.
- 3. Values for the Offset will be updated (see Figure 24).
- 4. Use the "Write EEPROM" button from the "I/O FUNCTIONS" section to save the new values to the EEPROM.



Figure 24. Coil Offset Calibration Completed – ZMID5203 Example

2.4.2 "OUTPUT RANGE" Sub-tab

The "OUTPUT RANGE" sub-tab (see Figure 25) is used to configure the output behavior of the ZMID520x. For a detailed description of output settings, refer to the ZMID520x Datasheet.



Figure 25. "OUTPUT RANGE" Tab - ZMID5201 Example

There are four values that can be edited on the "OUTPUT RANGE" sub-tab for subsequent use during the calibration procedure:

- The "Output Start Point [%]" field defines the desired output value when the target is at the mechanical start point.
- The "Output End Point [%]" field defines the desired output value when the target is at the mechanical end point.
- The "Apply Clamps" checkbox is available only for the ZMID5201 (analog interface) and the ZMID5202 (PWM interface). If activated, the output is clamped between the specified start and end points if the target goes beyond these mechanical positions. Due to the low resolution of the clamps register, the available clamping values might not match the selected output start and end points exactly. See Figure 28 and Figure 29 for examples of the output without clamping and the output with clamping, respectively.
- Out MOD: Defines the output mode.
 - Linear: The Linear Output Mode is a non-repeating output mode in which the sensor output signal is clamped at the mechanical end points (see Figure 26).
 - Modulo 360: The Modulo Output (saw tooth output) Mode is a repeating output mode in which the sensor output signal is not clamped at the mechanical end points, but it is switched back to its origin (see Figure 27).



Figure 26. Linear Output Mode Example with Slope = 2, Offset = 90°





The results from the calibration procedure are displayed in two fields on the "OUTPUT RANGE" tab. They are direct representations of the *Offset* and *Slope* registers in the ZMID520x. The values can also be manually entered by the user.

- Slope: The slope of the transfer function of the output signal.
- Offset: The zero-offset of the output signal referenced to the mechanical position in degrees.

Figure 28. Output without Clamping



Figure 29. Output Clamped from 20% to 80%



Automatic Output Calibration Procedure:

To start the automatic calibration, click the "Start Calibration" button. The GUI will guide the user through a sequence of instructions for performing the calibration procedure.

- 1. Move the sensing target to the start position, and click "OK" in the dialog box. The graph will start displaying the internal reading of the position.
- 2. Move the sensing target to the end position, and click OK. The GUI will automatically attempt to determine if the slope polarity of the values is positive (values ascending) or negative (values descending). If this cannot be determined, the GUI will ask the user to specify the polarity of the slope. For the example provided in Figure 30, the slope is negative.

- 3. Based on the acquired data, the GUI will attempt to calculate the best values for the Slope, Offset, and Clamps registers. If the calibration is not possible with the currently selected "Out MOD" setting, the GUI will ask the user to change to the other setting (see Figure 31). The calculated values will be prepared to be written to the memory, and the user will be directed to use the "Write EEPROM" button in the "I/O FUNCTIONS" section to write the new coefficients to the memory of the device. See Figure 32.
- 4. If the calculated values are out of range or the calibration is not possible, a message will inform the user which value is affected. The most common cause of unsuccessful calibration is setting the start and end target positions too close to each other since this could require a slope value larger than the valid range of slope values. See Figure 33.
- 5. A detailed log from the calibration function is available from the "TOOLS" menu > "Open Log File" > "Calibration."

Figure 30. Specify the Original Slope



Figure 31. Request for Changing the Out_Mod Setting



Figure 32. Successful Calibration Message



Figure 33. Unsuccessful Calibration Message

Calibration error	X
Calibration Failed! The calculated slope -6.7489 is not in th	e available range -4 to 4
	ОК

25

2.4.3 "CALIBRATION AND LINEARIZATION" Tab

The "CALIBRATION AND LINEARIZATION" tab contains two sub-tabs. The "AUTO CAL" sub-tab is used to perform the full output range calibration and linearization on a device by importing a *.csv* file with position measurements. The "MANUAL LINEARIZATION" sub-tab can be used to manually calculate the linearization register values for given target positions.

2.4.3.1 "AUTO CAL" Sub-tab

The "AUTO CAL"" sub-tab is located under the "CALIBRATION AND LINEARIZATION" tab (see Figure 34). It is used to do a full calibration of the ZMID520x by processing a .csv file with measurement data.

Figure 34. "AUTO CAL" Sub-tab – ZMID5201 Example

FILE SETTINGS TOOLS HELP Image: Construction of the provided state of the provided sta	ZMID520x EVKIT Application	tion					– 🗆 X
ZMID5201 ACTIVE DEVICES CONNECTION MAIN CONFIGURE CALIBRATION COMMAND CONSOLE MEMORY EDIT ACTIVE DEVICES Disconnect COLL OFFSET OUTPUT RANGE CALIBRATION AND LINEARIZATION Refresh Disconnect COLL OFFSET OUTPUT RANGE CALIBRATION AND LINEARIZATION Refresh C STATUS C:\AnalogData.csv Select File Refresh Devicer E: Sume: ZMID5201 Reme: ZMID5201 Refresh Devicer E: Sume: ZMID5201 Reme: ZMID5201 Reverse Busy Spatial Angle Slope Out Mod Out min % Config O No mode Spatial Angle Slope Out Mod Out max % Calculate V/O FUNCTIONS Reverse slope of Posto Ø ApplyClamps 90 Calculate V/O FUNCTIONS Reset IC Inint 4: 96 03 Inint 4: 96 03 Linint 4: 96 05 Inint 7: 000 Inint 7: 000 Inint 7: 000 Linint 7: 10 Inint 7: 10 Inint 7: 10 Inint 7: 000 Ininit 7: 10 Ininit 7: I	FILE SETTINGS TOOLS	HELP					
CONNECTION MAIN CONFIGURE CALIBRATION COMMAND CONSOLE MEMORY EDIT ACTIVE DEVICES Disconnect OUTO CAL MAINUAL LINEARIZATION Refresh Device: E: Name: ZMID5201 Provide Config Provide Config Device: E: Name: ZMID5201 Provide Config Provide Config Device: E: Name: ZMID5201 Provide Config ProvideC	ZMID5201						www.IDT.com
Disconnect COLL OFFSET OUTPUT RANGE CALIBRATION AND LINEARIZATION Refresh IC STATUS C:\AnalogData.csv Select File IC STATUS IUse Analog values instead of Spatial Angle VDD [V] Sware 2000 Busy APP mode Spatial Angle Slope Out Mod Out min % O Positive It inear 10 Calculate IVO FUNCTIONS Reverse slope of Posol ApplyClamps 90 IVO FUNCTIONS Clamp Hig: 90.5 0.5 Read Status Offset: 13.95576 2380 Vine EEPROM Linint 1: 64 0.2 Linint 1: 64 0.2 Linint 1: Inint 2: 96 0.3 Linint 1: Inint 1: 64 0.2 Linint 1: Linint 2: 96 0.3 Linint 3: Inint 1: 64 0.3 Linint 4: Linint 3: 0 0.0 Linint 4: Linint 4: 96 0.3 Linint 4: Linint 4: 9.3 0.5 Linint 4: Linint 4: 9.3 0.0 Linin	CONNECTION	MAIN CON		ALIBRATION COMM	MAND CONSOLE MEMORY EDIT		ACTIVE DEVICES
AUTO CAL MANUAL LINEARIZATION Nerresting IC STATUS C:\AnalogData.csv Select File Ø Use Analog values instead of Spatial Angle VDD [V] Swite IDT Output Config Ø Use Analog values instead of Spatial Angle VDD [V] Write IDT Output Config Ø Use Analog values instead of Spatial Angle VDD [V] Write IDT Output Config Ø Use Analog values instead of Spatial Angle VDD [V] Write IDT Output Config Ø Demode Spatial Angle Slope Out Mod Out min % Ø CMD mode Positive Uname: Modulo360 Out max % Ø Negative Modulo360 Out max % Calculate Ø Offset: 13.95676 2380 Slope: 100269 Slope: 1.00269 0402 Clamp Hig: 90.5 05 Clamp Hig: 90.5 05 Unint 1: 64 Unint 1: 64 02 Unint 1: 96 03 Unint 2: 96 03 Unint 4: 96 03 Unint 3: 0 00 Unint 5: 100 Unint 5: 10 Unint 1: 160 05	Disconnect	COIL OFFSE		CALIBRATION	N AND LINEARIZATION		Defrech
IC STATUS C:\AnalogData.csv Select File Name:ZMID5201 Powered Busy Use Analog values instead of Spatial Angle VDD [V] Write IDT Output Config Busy Spatial Angle Slope Out Mod Out min % Powered CMD mode Positive Elinear 10 Calculate Read Status Offset: 13.95676 2380 Sobs V/O FUNCTIONS Clamp Low: 9.5 0.5 Read EEPROM Linint 1: 64 02 Linint 1: 96 03 Linint 1: 64 Copy SWR To EEPROM Linint 4: 96 03 Linint 4: 96 Reset IC Linint 5: 10 Linint 4: 96 03 Linint 8: 512 10 Linint 4: 96 03 Linint 8: 512 10 Linint 8: 512 10 Linint 8: 512 10 Linint 8: 512 10		AUTO CAL	MANUAL LI	NEARIZATION			Refresh
IC STATUS Powered Busy APP mode CMD mode CMD mode Sw parity error Read Status VIO FUNCTIONS Read EEPROM Write EEPROM Uinint 1: 64 02 Linint 2: 96 03 Linint 2: 96 03 Linint 3: 100 Linint 4: 96 03 Linint 5: 160 05 Linint 5: 160 05 Linint 6: 640 14 Linint 5: 160 05 Linint 6: 640 14 Linint 7: 0 000 Linint 8: 512 10 Linint 9: -352 88		C:\AnalogDa	ita.csv			Select File	Device: E: Name: ZMID5201
APP mode Spatial Angle Slope Out Mod Out min % CMD mode Positive Linear 10 SW parity error Negative Modulo360 Out max % Calculate Read Status Offset: 13.95676 2380 90 I/O FUNCTIONS Clamp Low: 9.5 05 05 Read EEPROM Linnt 1: 64 02 Linnt 2: 96 03 Write EEPROM Linnt 3: 0 00 Linnt 4: 96 03 Copy SWR To EEPROM Linnt 4: 96 03 Linnt 7: 0 00 Linnt 8: 512 10 Linnt 8: 512 10 Linnt 9: -352 88	IC STATUS Powered Busy	Use Analo	og values insto ng the analog va	ead of Spatial Angle alues it is necessary to load	VDD [V] 5	Write IDT Output Config	FW:00.06.0009
O SW parity error ● Negative O Modulo360 Out max % Calculate Read Status Offset: 13.95676 2380 I/O FUNCTIONS Clamp Low: 9.5 05 Read EEPROM Clamp Hig: 90.5 05 Linht 1: 64 02 Linht 2: 96 03 Linht 3: 0 00 Linht 4: 96 03 Linht 5: 160 05 Linht 5: 160 05 Linht 6: 640 14 Linht 7: 0 00 Linht 8: 512 10 Linht 8: 512 10 Linht 9: -352 88	O APP mode CMD mode	Spatial Angle	Slope	Out Mod Einear	Out min % 10		
Read Status Offset: 13.95676 2380 Slope: 1.00269 0402 Slope: 1.00269 0402 Clamp Low: 9.5 05 Clamp Hig: 90.5 05 Clamp Hig: 90.5 05 LinInt 1: 64 02 LinInt 2: 96 03 LinInt 3: 0 00 LinInt 4: 96 03 LinInt 5: 160 05 LinInt 5: 160 05 LinInt 6: 640 14 LinInt 7: 0 00 LinInt 8: 512 10 LinInt 9: -352 88	O SW parity error	Negative Reverse s	lope of Pos0	 Modulo360 ApplyClamps 	Out max % 90	Calculate	
I/O FUNCTIONS Slope: 1.00269 0402 Clamp Low: 9.5 05 Clamp Hig: 90.5 05 Linint 1: 64 02 Linint 2: 96 03 Linint 3: 0 00 Linint 4: 96 03 Linint 5: 160 05 Linint 5: 160 05 Linint 6: 640 14 Linint 8: 512 10 Linint 9: -352 88	Read Status	Offset:	13,95676	2380			
I/O FUNCTIONS Clamp Low: 9.5 05 Read EEPROM Clamp Hig: 90.5 05 Write EEPROM LinInt 1: 64 02 LinInt 2: 96 03 LinInt 3: 0 00 LinInt 4: 96 03 LinInt 5: 160 05 LinInt 5: 160 05 LinInt 6: 640 14 LinInt 8: 512 10 LinInt 9: -352 88		Slope:	1.00269	0402			
Read EEPROM Clamp Hig: 90.5 05 Write EEPROM LinInt 1: 64 02 LinInt 2: 96 03 LinInt 3: 0 00 Copy SWR To EEPROM LinInt 4: 96 03 LinInt 5: 160 05 LinInt 5: 160 05 LinInt 6: 640 14 LinInt 7: 0 00 LinInt 8: 512 10 LinInt 9: -352 88	I/O FUNCTIONS	Clamp Low:	9.5	05			
Write EEPROM LinInt 1: 64 62 Write EEPROM LinInt 2: 96 03 Copy SWR To EEPROM LinInt 4: 96 03 LinInt 5: 160 05 LinInt 6: 640 14 LinInt 7: 0 00 LinInt 8: 512 10 LinInt 9: -352 88	Read FEPROM	Clamp Hig:	90.5	05			
Write EEPROM LinInt 3: 0 00 Copy SWR To EEPROM LinInt 4: 96 03 LinInt 5: 160 05 LinInt 6: 640 14 LinInt 7: 0 00 LinInt 8: 512 10 LinInt 9: -352 88		Linint 1:	96	03			
Copy SWR To EEPROM LinInt 4: 96 03 Reset IC LinInt 5: 160 05 LinInt 6: 640 14 LinInt 7: 0 00 LinInt 8: 512 10 LinInt 9: -352 88	Write EEPROM	LinInt 3:	0	00			
LinInt 5: 160 05 LinInt 6: 640 14 LinInt 7: 0 00 LinInt 8: 512 10 LinInt 9: -352 88	Copy SWR To EEPROM	LinInt 4:	96	03			
Keset IC LinInt 6: 640 14 LinInt 7: 0 00 LinInt 8: 512 10 LinInt 9: -352 88	Devet 10	LinInt 5:	160	05			
Linint 7: 0 00 Linint 8: 512 10 Linint 9: -352 8B	Reset IC	LinInt 6:	640	14			
LinInt 9: -352 8B		Linint /:	512	10			
		LinInt 9:	-352	8B			

The "AUTO CAL" sub-tab has the following input parameters:

The "Select File" button is used to specify the path to the .csv file with measurement data that will be used for the calibration. By default, the file should contain only raw Spatial Angle register readings taken at equal intervals during the whole movement range of the target. The header row in the .csv file is optional. The values are written as 16-bit unsigned integers [0 to 65535].

Figure 35. Example Contents of an Input .csv file with Spatial Angle Data

🧾 Spatial	AngleData	a.csv - N	lotepad		_	\times
File Edit	Format	View	Help			
Spa						~
64237						
63753						
63244						
62741						
62245						
61750						
61268						
60764						
60251						
59793						
59326						
58835						
58387						
57947						
57497						
57050						
56579						
56155						~
<						>

If the "Use Analog values instead of Spatial Angle" checkbox is selected, the input .csv file should contain only voltage readings from the
output of the ZMID5201 taken at equal intervals during the whole movement range of the target. The values are written as positive real
numbers in volts.

Note: This option is only available for ZMID5201.

Figure 36. Example Contents of a .csv Input File with Output Voltage Data

analog	j.csv - Not	epad			-	×	
File Edit	Format	View	Help				
Analog							^
4.66308	5938						
4.62890	625						
4.59472	6563						
4.56054	6875						
4.52636	7188						
4.49218	75						
4.45800	7813						
4.42382	8125						
4.38476	5625						
4.35546	875						
4.32128	9063						
4.29199	2188						
4.25781	25						
4.22851	5625						
4.19921	875						
4.16503	9063						
4.13574	2188						
4.10644	5313						~
<						>	:

- The "VDD [V]" text box is used to specify the measured supply voltage of the ZMID5201 when the .csv data was gathered.
 Note: This option is only available for the ZMID5201.
- The "Write IDT Output Config" button writes a default configuration to the first 8 registers of the EEPROM to allow the analog measurements of the device to be converted to spatial angle values.
 Note: This option is only available for the ZMID5201.
- The "Spatial Angle Slope" radio buttons specify the polarity of the slope of the .csv input values. A positive slope means that the .csv input values are increasing; a negative slope means the values are decreasing.
- The "Reverse slope of Pos0" checkbox specifies whether the polarity of the slope of the calibrated values should be the same as the
 polarity of the Spatial Angle slope values or inverted.
- The "Out Mod" radio buttons specify the type of the calibration: Linear or Modulo360.
- The "Apply clamps" checkbox specifies whether the clamp register will be used to set clamp levels on the output that correspond to the minimal and maximal output calibration points.
 Note: This option is only available for the ZMID5201 and ZMID5202.
- The "Out min" and "Out max" text boxes are the desired output values in percent at the two mechanical movement end points. The
 minimal value should be less than the maximal value.
- The "Calculate" button calls the OneStepCalibration.dll library with the specified input parameters to calculate the calibration coefficients. After a successful calibration, the output fields are populated with the calculated calibration data. The left column shows the values in "human readable" format, and the right column shows the corresponding register data that will be written to the memory of the ZMID520x.
 - Offset: The zero-offset of the output signal referenced to the mechanical position in degrees.
 - Slope: The slope of the transfer function of the output signal.
 - Clamp Low and Clamp High: Actual output clamping levels.
 - LinInt 1 to 9: The correction coefficients at the 9 linear interpolation correction points.

A successful calibration will prepare the new values to be written to the EEPROM memory of the ZMID520x. To write the values, click the "Write EEPROM" button in the "I/O FUNCTIONS" section.

An unsuccessful calibration will only provide an error message.

Figure 37. Example of AUTO CAL Error Messages

Error	×	Error ×
Can't process the data! One or more of the inputs are invalio	d	Can't process the data! The calculated slope is out of range
ОК		ОК
Error	×	Error X
Can't process the data! The calculated offset is out of range		Can't read the CSV file!
ОК		ОК

A detailed report of the calibration can be viewed in the calibrationLogfile.txt log file, which is accessible through the Tools > Open Log File > Calibration menu.

2.4.3.2 "MANUAL LINEARIZATION" Sub-tab

The table on the "MANUAL LINEARIZATION" tab shows the nine points for which a value can be specified for application to a correction curve over the position range (see Figure 38).

The table has the following rows:

- Correction Point: Constraint points for linearization 1 to 9; below each correction point, the electrical position is shown in the next row (0 to 360 degrees in pre-calibration or 0 to 100% after calibration).
- Ideal Value: The ideal value (read-only) according to the motion range provided.
- Measured Value [mm] or [deg]: Entry field for values measured at the correction points ("mm" is not applicable to the ZMID520x Rotary 360° Application Module or the ZMID520x Arc 130° Application Module). These values are entered by the user.
- Correction: These read-only values (integers in the range of -127 to 127) will be added (after a multiplication x 32) to the "Spatial Angle" data if linearization is performed before calibration; in the case of linearization post-calibration, these values will be applied (after a multiplication x 32) to the Position 0 data, resulting in the Position 1 data. See the description of the "Start Reading" button below for an explanation of the "Position 0" and "Position 1" data fields.

Three additional controls are available on this tab.

- Motion Range [mm] or [deg]: Entry field for the linear motion range in mm (not applicable to the ZMID520x Rotary 360° Application Module and the ZMID520x Arc 130° Application Module) or the arc/rotation motion range in degrees. This user-selected value is used to calculate the ideal values.
- Correction Mode: This drop-down menu allows selecting whether the linearization is applied before or after calibration.
- Angle Offset: This drop-down menu offers the option to shift the linearization points if required. Whether the offset is applied or not is
 determined by the non-linearity error distribution. (Refer to the ZMID520x Datasheet for details).

Figure 38. "MANUAL LINEARIZATION" Sub-tab – ZMID5201 Example

ZMID520x EVKIT Applicat	ion										- 🗆 X
FILE SETTINGS TOOLS	HELP										
ZMID5201											www.IDT.com
CONNECTION	MAIN CON	IFIGURE	CALIBRAT	ΓΙΟΝ	COMMANE	CONSOLE	MEMO	ORY EDIT			ACTIVE DEVICES
Disconnect	COIL OFFSE		JT RANGE	CALIBR	ATION AN	D LINEARIZ	ATION				Defresh
	AUTO CAL	MANUA	L LINEARIZ	ATION							Daviews
IC STATUS		Me [m	otion Range im] or [deg]		Correctio	on Mode	A	ngle Offse	t		Device: E: Name: ZMID5201
O Powered			360		Post-calib	ration ~	0		~		
O APP mode	Correction	1	2	3	4	5	6	7	8	9	
CMD mode SW parity error	Point	0	12.5	25	37.5	50	62.5	75	87.5	100	
	Ideal Value	0	45	90	135	180	225	270	315	360	
Read Status	Measured Value [mm]or[deg]	0	0	0	0	0	0	0	0	0	
I/O FUNCTIONS	Correction	2	3	0	3	5	20	0	16	-11	
Read EEPROM							•	egrees (C Raw		
Write EEPROM		Calcu	ılate			Spatial Ang	le		0		
Copy SWR To EEPROM		Corre	ection				•	egrees (C Raw		
Reset IC						Position 0			0		
		Start F	Reading				•	egrees	C Raw		
						Position 1			0	J	

- The "Start Reading" button triggers a continuous reading of the three internal position registers of the ZMID520x (see Figure 38 for the corresponding measurement points in the calibration process). This is implemented to help the user measure the linearization error at the specific points.
- The "Spatial Angle" reading represents the CORDIC output angle before applying the slope and offset calibration. The "Position 0" reading is the position value after applying the slope and offset calibration but before applying the linear interpolation. The "Position 1" reading is the final value after the linear interpolation is applied (see Figure 39)
- The "Calculate Correction" button re-calculates the new correction values for the EEPROM registers based on the "Measured Value" cells.

To save changes to the device, use the corresponding "Write..." button in the "I/O FUNCTIONS" section.

Figure 39. Calibration Diagram



2.4.3.3 "MANUAL LINEARIZATION" Tab – Correction Values

Multiple strategies have been developed to obtain the set of correction values. For relevant information and procedures, contact IDT support. (See the contact information on the last page.)

2.5 Working with the Memory

2.5.1 "MEMORY EDIT" Tab

Information for all the memory types of the device and their values can be found on the "MEMORY EDIT" tab (see Figure 40). The data is organized in tables, and the register values are in hexadecimal format.

Figure 40. "MEMORY EDIT" Tab Contents – ZMID5201 Example

ZMID520x EVKIT Applicat	ion									- 🗆 ×
ILE SETTINGS TOOLS	HELP									
ZMID5201										www.IDT.co
CONNECTION	MAIN COI	NFIGURE	CALIBRATIC	ON COMM	MAND CONS	OLE MEN	IORY EDIT			ACTIVE DEVICES
Disconnect	EEPROM	0	1	2	3	4	5	6	7	Refresh
	0h	233F	0784	0000	0000	0000	0000	0000	0000	Device: E:
	8h	0000	0100	7002	B107	0837	0255	BFFF	0000	Name: ZMID5201
	10h	0000	00C2							FW:00.05.1000
Busy										
CMD mode	SWR	0	1	2	3	4	5	6	7	
SW parity error	0h	233F	0784	0000	0000	0000	0000	0000	0000	
Read Status	8h	0000	0100	7002	B107	0837	0255	BFFF		
	10h		00C2		0370	07CF	0F09	2709	1BEA	
I/O FUNCTIONS	18h	9384	E7D7	E7D7	0001					
Read EEPROM										
Write EEPROM										
Copy SWR To EEPROM										
Reset IC										
	Register values i	n red are differ	rent than actual	values in chip m	emory. You nee	d to write them	to chip memory	in order to take	e effect.	

The read-only registers are marked with a light blue background. Modified register values will appear in red color until they are written to the device memory or re-read from it (see Figure 41).

Figure 41. Example of a Modified Value on the "MEMORY EDIT" Tab

000	0000	00
	0242	BF
FFE	OFFE	ЗF

Placing the cursor over a table cell displays a tooltip with additional information about the register (see Figure 42).

Figure 42. Example of "MEMORY EDIT" Tab Tooltip Inform	nation
--	--------

EEPRO	0 N	1	2	3	
0h	01EA	1683	0000	0000	0(
8h		0000	4803	Address: UXU	(10)
10h	0000]			

2.5.2 Saving and Loading Memory Dump Files

The current memory configuration can be saved to a file via the "FILE" menu > "Save Memory Dump." This is useful for providing a backup of the verified memory configuration or for copying a configuration to another device (see Figure 43).

The "Load Memory Dump" option loads a selected memory dump file into the "MEMORY EDIT" tab. The "Write EEPROM" button in the "I/O FUNCTIONS" section must be used to write the configuration into the memory of the ZMID520x.

The GUI provides a set of default memory dump files that can be used to easily return a device to its original settings.

The default memory dump files can be found in the "MemoryDumps" folder located in the main installation directory of the GUI.

Figure 43. Menu Options for Saving and Loading Memory Dump Files



2.5.3 Viewing Memory Dump Files without Connecting to a Device (Offline)

It is possible to load a memory dump file when no device is connected. This allows the user to view and edit the contents of a memory dump file. The "Save Memory Dump" menu option is used to save the changes to the same file or a new file. Since there is no device connected, only the "CONFIGURE" and "MEMORY EDIT" tabs are available (see Figure 44). The values that are different from the default values for the ZMID520x are displayed in red. Connecting to a device while viewing a memory dump file "offline" will cause the GUI to discard any unsaved changes to the memory dump file and switch to displaying the current settings from the connected device's memory.



ZMID520x EVKIT Applicat	ion	– 🗆 X
FILE SETTINGS TOOLS	HELP HELP	
CONNECTION	CONFIGURE MEMORY EDIT	ACTIVE DEVICES
IC STATUS Read Status I/O FUNCTIONS Reset IC	Shown memory type EEPROM Lc_cal 0 SampLcycle 0 Ext 0 Gain_stage 0 Swap_rc_pol On Invppr1 On On Osr Agc_interlink Gain adaptat Agc_sst_mode Off	
	Register values in red are different than actual values in chip memory. You need to write them to chip memory in order to take effect.	

2.6 Manually Identifying a Device

When a new device is connected to the computer, the GUI automatically recognizes it. If it is unable to identify the device, the user must manually identify it. There is also a menu option to re-identify a device (see Figure 45).

2.6.1 Identifying an Unknown Device

If the GUI is unable to automatically identify the device, it will be displayed as an unknown device in the "ACTIVE DEVICES" section, and the "Connect" button will be replaced by an "Identify Device" button.

Figure 45. GUI View if an Unknown Device is Selected

ZMID520x EVKIT Application	- 🗆 X
FILE SETTINGS TOOLS HELP	() IDT.
	www.IDT.com
CONNECTION	ACTIVE DEVICES
Identify Device	Refresh
	Device:
IC STATUS	Name: unknown FW: 00.05.1000
Read Status	
I/O FUNCTIONS	
Reset IC Please identify the device	
ricuse identity the device	
L	

Follow these steps to identify an unknown device:

- 1. Select the device by clicking on it in the "ACTIVE DEVICES" section.
- 2. Click on the "Identify Device" button in the "CONNECTION" section.
- In the resulting common file dialog, select the proper identification file based on the type of ZMID520x Application Module, and click "Open." The identification files can be found in the root directory in the *Profiles* folder (see Figure 46). Filenames with the suffix "_d" are used if two application modules are connected.
- 4. The GUI will identify the device and automatically connect to it.

Figure 46. File Dialog to Select an Identification File

Load Description File	e								×
	< Profiles		~	- 1	3	Search	Profiles		P
Organize 🔻 New	folder							•	?
💻 This PC	^	lame					Туре		Size
E. Desktop	E E	ZMID5201.xml					XML Docu	ment	
Documents	E	ZMID5201_d.xml					XML Docu	ment	
Downloads	E	ZMID5202.xml					XML Docu	ment	
Music	E	ZMID5202_d.xml					XML Docu	ment	
Pictures	E	ZMID5203.xml					XML Docu	ment	
	E	ZMID5203_d.xml					XML Docu	ment	
Videos									
	~ <								>
F	ile name	ZMID5201.xml			×	Suppo	rted Files (*ఎ	ml or *.ev	k) ~
						O	pen	Cance	el

2.6.2 Re-identifying a Device

- 1. Ensure the GUI is not connected to any device.
- 2. Select the device to identify from the "ACTIVE DEVICES" list by clicking on it.
- 3. Open the "TOOLS" menu, and select the "Identify Selected Device" menu option.
- 4. In the resulting common file dialog, select the proper identification file based on the type of ZMID520x Application Module, and click "Open." Filenames with the suffix "_d" are used if two application modules are connected.
- 5. The GUI will re-identify the device with the selected identification file and update the device information in the "ACTIVE DEVICES" section.

Figure 47. "Identify Selected Device" Menu Option

Image: ZMID520x EVKIT Application					
FILE SETTINGS	TOOLS HELP				
	Open Log File Open Log Folder	F			
CONNECT	Identify Selected Device	2			

3. Firmware Update

This section provides optional instructions for upgrading the firmware for the ZMID-COMBOARD if needed for special uses of the kit that might require additional features in the latest version of the firmware. Normally this is not needed since all versions of the firmware function properly with the GUI and hardware. To determine the existing version of the firmware on the board, see the "FW" version shown in the "ACTIVE DEVICES" section at the right of the display (see Figure 9).



Important Equipment Warning: Ensure the correct connection of all cables. Supplying the board using the wrong polarity could result in damage to the board and/or the equipment.

To perform a firmware update of the ZMID-COMBOARD, complete these steps:

- 1. Download the latest firmware file from the IDT website.
- 2. Disconnect the ZMID-COMBOARD from the USB port of the computer.
- 3. Install a jumper to short the two "BOOT" pins on the ZMID-COMBOARD as shown in Figure 3.
- 4. Connect the ZMID-COMBOARD to the USB port of the computer.
- 5. The ZMID-COMBOARD will show up as a removable drive named "CRP DISABLD." Open the drive to browse the files.

Figure 43. Locating the Removable Device

🔾 🗢 📑 🕨 Computer	•
Organize 🔻 System prop	erties Uninstall or change a program Map network drive Open Control Pan
★ Favorites ■ Desktop ● Downloads ● Recent Places	 Hard Disk Drives (1) SYSTEM (C:) Devices with Removable Storage (2)
ᇘ Libraries 📄 Documents	DVD RW Drive (D:) 0 bytes free of 256 KB FAT

- 6. Delete the "firmware.bin" file from the device. Recommendation: Store a copy of the file on the user's computer as a backup.
- 7. Copy the new firmware file to the device.
- 8. Disconnect the board from the USB port of the computer.
- 9. Remove the jumper from the "BOOT" pins.

To verify the firmware update, install a ZMID520x Application Module and connect to the computer. The GUI will now display the new version of the firmware on the board information in the "ACTIVE DEVICES" section.



4. ZMID-COMBOARD Schematics

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5. ZMID-COMBOARD BOM

Table 3. Bill of Materials for ZMID-COMBOARD Rev. 5.1

Note: DNP = Do not populate.

ltem	Designator	Value	Description	Footprint	Qty.
1	C1, C4, C5, C8, C9, C17, C19, C40, C36, C37, C25	100nF	100nF 16V X7R +-10%	0603	11
2	C2, C3, C12, C13, C16, C21, C22, C23	2.2nF	2.2nF 50V X7R +-10%	0603	8
3	C6, C7, C14	2.2µF	2.2uF 16V X7R +-10%	0805	3
4	C10, C11	22pF	22pF 50V C0G +-5%	0603	2
5	C15	4.7µF	4.7uF 25V X5R +-10%	0805	1
6	C18, C20, C26	10nF	10nF 50V X7R +-10%	0603	3
7	C24	820pF	820pF 50V C0G +-5%	0603	1
8	C65	10µF	10uF 25V X7R +-10%	1206	1
9	C89, C93	220nF	220nF 16V X7R +-10%	0603	2
10	C91	10µF	10uF 16V X5R +-10%	0805	1
11	C94	1nF	1.0nF 50V C0G +-5%	0603	1
12	D1	BAT54A	Schottky 30V 2x200mA 5ns 10pF, konf A	SOT23	1
13	D7	STPS1L40M	STMICROELECTRONICS - Schottky Rectifier, 40 V, 1 A, Single, DO-216AA, 2 Pins, 460 mV	DO216AA	1
14	IC2	LPC1549	NXP - ARM Microcontroller, LPC1500 ARM Cortex- M3 Microcontrollers, 32bit, 72 MHz, 256 KB, 36 KB, 100 Pins	LQFP-100	1
15	IC6	MCP6002-I/SN	2 OA,4.5mV,1pA,1.8-6V,100uA,1MHz	SOIC-8	1
16	IC8, IC10, IC12	SN74LVC1T45	Dual Supply Translating Transceiver 3-State	SC70	3
17	IC22	XC6204B332MR	LDO Voltage Regulators 300mA CMOS LDO 2.5V to 13.2V	SOT23-5	1
18	L1	EMI Bead 3A 50mR	Ferrite bead 0805, typ. 30Ohm@100MHz, 15mOhm@3.0A	0805	1
19	L2	10µH	inductor 10uH 60mA 0.5ohm 30%	0805	1
20	LED1, LED4	Red LED	2.0x1.25mm 150mcd/20mA 625nm Red 120°	0805	2
21	LED2	Green LED	2.0x1.25mm, 3.2-15mcd@20mA, 568nm Green, W.Clear, 120°	0805	1
22	LED3	Blue LED	2.0x1.25mm, 36-100mcd@20mA, 470nm Blue, W.Clear, 120°	0805	1
23	P1, P3	Header 1X4	Header, contact height 6.0mm, 1x4, straight PCB TH, P2.54mm	HS1X4M	2

ltem	Designator	Value	Description	Footprint	Qty.
24	P2, P4	DEV1, DEV2	Wire-To-Board Connector, 1.27 mm, 4 Contacts, Header, Picoflex 90325 Series, Through Hole, 1 Rows	molex 4pin	2
25	P5	USB_micro_B_Attend	MICRO USB 2.0; B-Type Receptacle; Right Angle; Shell DIP/Tail SMD	USB_micro_B_SMD	1
26	P8	Header 1X2	Header, contact height 6.0mm, 1x2, straight PCB TH, P2.54mm	HS1X2M	1
27	R1, R11	100Ω	RES SMD 0603 1% 200ppm 100R 1/10W	0603	2
28	R2, R3, R10, R39, R40, R42, R45, R47, R22, R23	10kΩ	RES SMD 0603 1% 100ppm 10K 1/10W	0603	10
29	R4, R5	680Ω	RES SMD 0603 1% 100ppm 680R 1/10W	0603	2
30	R15, R16	510Ω	RES SMD 0603 1% 100ppm 510R 1/10W	0603	2
31	R7, R8, R9,	1kΩ	RES SMD 0603 1% 100ppm 1.0K 1/10W	0603	3
32	R14	2.2kΩ	RES SMD 0603 1% 100ppm 2.2K 1/10W	0603	1
33	R24,R61,R73	820Ω	RES SMD 0603 1% 100ppm 820R 1/10W	0603	3
34	R25,R62,R74	1.3kΩ	RES SMD 0603 1% 100ppm 1.3K 1/10W	0603	3
35	R17, R18	DNP		0603	2
36	R28, R29	22Ω	RES SMD 0603 1% 200ppm 22R 1/10W	0603	2
37	R43	DNP			1
38	R44	DNP			1
39	R112, R113	5.1kΩ	RES SMD 0603 1% 100ppm 5.1K 1/10W	0603	4
40	R64, R65, R67	51kΩ	RES SMD 0603 1% 100ppm 51K 1/10W	0603	3
41	R66, R71, R21, R13, R6, R12	0Ω	RES SMD 0603 JUMPER MAX 50mOhm	0603	6
42	R117, R118, R119	22kΩ	RES SMD 0603 1% 100ppm 22K 1/10W	0603	3
43	RESET	DTSM-31Y	Tact sw. 2p SPST Mom. 50mA/12V 3.5x6mm SMD	3.5x6mm SMD	1
44	U1, U2	TS5a4624	Analog Switch, SPDT, 1 Channels, 0.7 ohm, 1.65V to 5.5V, SC-70, 6 Pins	SC-70	2
45	U3	TPS60150DRVR	5 V, Step-Up Charge Pump Regulator	WSON-6	1
46	Y1	12MHz QKT-3225	crystal Fund 12.000 MHz 3.2x2.5mm SMD (DFN) 15ppm 8pF -20+70°C	SMD-3.2X2.5	1

6. Sensors Boards

Refer to the following IDT product web pages for the manuals for specific ZMID520x Application Module manuals for a complete description of the sensors boards:

ZMID520x Linear Application Module

- www.IDT.com/ZMID5201MLIN
- www.IDT.com/ZMID5202MLIN
- www.IDT.com/ZMID5203MLIN
- ZMID520x Rotary 360° Application Module
- www.IDT.com/ZMID5201MROT
- www.IDT.com/ZMID5202MROT
- www.IDT.com/ZMID5203MROT

ZMID520x Arc 130° Application Module

- www.IDT.com/ZMID5201MARC
- www.IDT.com/ZMID5202MARC
- www.IDT.com/ZMID5203MARC

7. Glossary

Term	Definition
ADC	Analog-to-Digital Converter
AGC	Automatic Gain Control
CSV	Comma Separated Values – a file format that can be imported in spreadsheets.
EEPROM	Electrically Erasable Programmable Read-Only Memory – the storage memory of the ZMID520x IC
EVK	Evaluation Kit
GUI	Graphical User Interface – refers to the application used for communication with the kit
OWI	One-Wire Interface
PWM	Pulse Width Modulation
SENT	Single Edge Nibble Transmission
SWR	Shadow Register – used as working memory for the ZMID520x IC.
USB	Universal Serial Bus

8. Ordering Information

Refer to the product pages for the specific ZMID520x Application Module for the order codes for the module.

Orderable Part Number	Description
ZMID-COMBOARD	ZMID-COMBOARD, micro-USB cable

9. Revision History

Revision Date	Description of Change
September 25, 2018	 Updates for new version of software. Updates for addition of Auto Cal GUI tab. Updates for discontinuation of software support for Windows® XP. Minor edits.
December 10, 2017	Initial release.



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