

## FEATURES

**Fast and flexible output rate—5 SPS to 250 kSPS**

**Fast settling time—20  $\mu$ s**

**Channel scan data rate of 50 kSPS/channel**

**Performance specifications**

17 noise free bits at 250 kSPS

20 noise free bits at 2.5 kSPS

22 noise free bits at 5 SPS

INL  $\pm 2.5$  ppm of FSR

**85 dB rejection of 50 Hz and 60 Hz with 50 ms settling**

**User-configurable input channels**

2 fully differential or 4 pseudo differential

**Crosspoint multiplexer**

**On-chip 2.5 V reference (drift 2 ppm/ $^{\circ}$ C)**

**Internal oscillator, external crystal, or external clock**

**Power supply**

Single supply: 5 V AVDD1, 2 V to 5 V AVDD2 and IOVDD

Optional split supply: AVDD1 and AVSS  $\pm 2.5$  V

**Current: 7.8 mA**

**Temperature range:  $-40^{\circ}$ C to  $+105^{\circ}$ C**

**3- or 4-wire serial digital interface (Schmitt trigger on SCLK)**

CRC error checking

SPI, QSPI, MICROWIRE, and DSP compatible

## APPLICATIONS

**Process control: PLC/DCS modules**

Temperature and pressure measurement

**Medical and scientific multichannel instrumentation**

**Chromatography**

## GENERAL DESCRIPTION

The AD7176-2 is a fast settling, highly accurate, high resolution, multiplexed  $\Sigma$ - $\Delta$  analog-to-digital converter (ADC) for low bandwidth input signals. Its inputs can be configured as two fully differential or four pseudo differential inputs via the integrated crosspoint multiplexer. An integrated precision, 2.5 V, low drift (2 ppm/ $^{\circ}$ C), band gap internal reference (with an output reference buffer) adds functionality and reduces the external component count.

The maximum channel scan data rate is 50 kSPS (with a settling time of 20  $\mu$ s), resulting in fully settled data of 17 noise free bits. User-selectable output data rates range from 5 SPS to 250 kSPS. The resolution increases at lower speeds.

The AD7176-2 offers three key digital filters. The fast settling filter maximizes the channel scan rate. The Sinc3 filter maximizes the resolution for single-channel, low speed applications. For 50 Hz and 60 Hz environments, the AD7176-2 specific filter minimizes the settling times or maximizes the rejection of the line frequency. These enhanced filters enable simultaneous 50 Hz and 60 Hz rejection with a 27 SPS output data rate (with a settling time of 36 ms).

System offset and gain errors can be corrected on a per channel basis. This per channel configurability extends to the type of filter and output data rate used for each channel. All switching of the crosspoint multiplexer is controlled by the ADC and can be configured to automatically control an external multiplexer via the GPIO pins.

The specified operating temperature range is  $-40^{\circ}$ C to  $+105^{\circ}$ C. The AD7176-2 is housed in a 24-lead TSSOP package.

## FUNCTIONAL BLOCK DIAGRAM

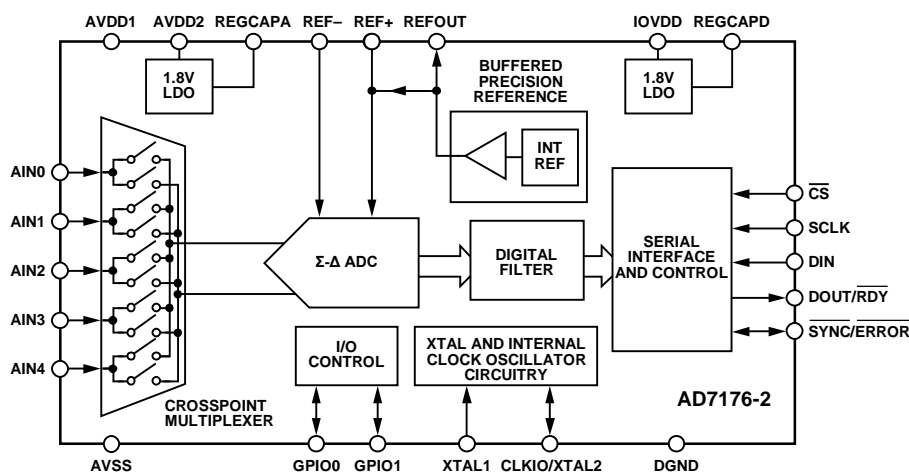


Figure 1.

Rev. 0

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One Technology Way, P.O. Box 9106, Norwood, MA 02062-9106, U.S.A.  
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**REVISION HISTORY**

11/12—Revision 0—Initial Version

## SPECIFICATIONS

AVDD1 = 4.5 V to 5.5 V, AVDD2 = 2 V to 5.5 V, IOVDD = 2 V to 5.5 V, AVSS = DGND = 0 V, REF+ = 2.5 V, REF− = AVSS, internal master clock = 16 MHz,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.

Table 1.

Parameter	Test Conditions/Comments	Min	Typ	Max	Unit
ADC SPEED AND PERFORMANCE					
Output Data Rate (ODR)		5		250,000	SPS
No Missing Codes <sup>1</sup>		24			Bits
Resolution	See Table 6				
Noise	See Table 6				
Noise Free Resolution	250 kSPS, REF+ = 5 V		17		Bits
	2.5 kSPS, REF+ = 5 V		20		Bits
	5 SPS, REF+ = 5 V		22		Bits
ACCURACY					
Integral Nonlinearity (INL)	2.5 V reference		±2.5	±7	ppm of FSR
	5 V reference		±7		ppm of FSR
Offset Error <sup>2</sup>			±40		μV
Offset Drift			±110		nV/°C
Offset Drift vs. Time <sup>3</sup>			±450		nV/500 hours
Gain Error <sup>2</sup>	25°C		±10	±50	ppm/FSR
Gain Drift vs. Temperature <sup>1</sup>			±0.5	±1	ppm/FSR/°C
Gain Drift vs. Time <sup>3</sup>			±3		ppm/FSR/500 hours
REJECTION					
Power Supply Rejection	AVDD1, AVDD2 $V_{IN} = 1$ V		90		dB
Common-Mode Rejection					
At DC	$V_{IN} = 0.1$ V	95			dB
At 50 Hz and 60 Hz <sup>1</sup>	20 SPS ODR (post filter) (50 Hz ± 1 Hz and 60 Hz ± 1 Hz)	130			dB
Normal Mode Rejection <sup>1</sup>	50 Hz ± 1 Hz and 60 Hz ± 1 Hz				
	Internal clock, 20 SPS ODR (post filter)	71	90		dB
	External clock, 20 SPS ODR (post filter)	85	90		dB
ANALOG INPUTS					
Differential Input Voltage Range			± $V_{REF}$		V
Absolute AIN Voltage Limits <sup>1</sup>		AVSS − 0.050		AVDD1 + 0.05	V
Analog Input Current			±48		μA/V
Input Current			±0.75		nA/V/°C
Input Current Drift	External clock		±4		nA/V/°C
	Internal clock (±2.5 % clock)		±4		nA/V/°C
Crosstalk	1 kHz input		−120		dB
INTERNAL REFERENCE					
Output Voltage	100 nF external capacitor on REFOUT to AVSS		2.5		V
Initial Accuracy <sup>1</sup>	REFOUT with respect to AVSS	− 0.16%		+ 0.16%	V
Temperature Coefficient	$T_A = 25^\circ\text{C}$				
	0°C to +105°C		±2	±5	ppm/°C
	−40°C to +105°C		±3	±10	ppm/°C
Reference Load Current, $I_{LOAD}$	$I_L$	−10		+10	mA
Power Supply Rejection (Line Regulation)	AVDD1 and AVDD2		93		dB
Load Regulation	$\Delta V_{OUT}/\Delta I_L$		32		ppm/mA
Voltage Noise	$e_N$ , 0.1 Hz to 10 Hz		4.5		μV rms
Voltage Noise Density	$e_N$ , 1 kHz		215		nV/√Hz

Parameter	Test Conditions/Comments	Min	Typ	Max	Unit
Turn-On Settling Time	100 nF capacitor		60		μs
Long-Term Stability <sup>3</sup>	500 hours		460		ppm
Short Circuit	I <sub>SC</sub>		25		mA
EXTERNAL REFERENCE					
Reference Input Voltage	Reference input = (REF+) – (REF–)	1	2.5	AVDD1	V
Absolute Reference Input Voltage Limits <sup>1</sup>		AVSS – 0.05		AVDD1 + 0.05	V
Average Reference Input Current			±72		μA/V
Average Reference Input Current Drift	External clock		±1.2		nA/V/°C
	Internal clock		±6		nA/V/°C
Normal Mode Rejection <sup>1</sup>	See the Rejection parameter section of this table				
Common-Mode Rejection			83		dB
GENERAL-PURPOSE I/O (GPIO 0, GPIO 1)					
Output High Voltage, V <sub>OH</sub> <sup>1</sup>	I <sub>SOURCE</sub> = 200 μA	AVSS + 4			V
Output Low Voltage, V <sub>OL</sub> <sup>1</sup>	I <sub>SINK</sub> = 800 μA			AVSS + 0.4	V
Input Mode Leakage Current <sup>1</sup>		–10		+10	μA
Floating-State Output Capacitance			5		pF
Input High Voltage, V <sub>IH</sub> <sup>1</sup>		AVSS + 3			V
Input Low Voltage, V <sub>IL</sub> <sup>1</sup>				AVSS + 0.7	V
CLOCK					
Internal Clock					
Frequency			16		MHz
Accuracy		–2.5		+2.5	%
Duty Cycle			50:50		%
Output Low Voltage, V <sub>OL</sub>				0.4	V
Output High Voltage, V <sub>OH</sub>		0.8 × IOVDD			V
Crystal					
Frequency		14	16	16.384	MHz
Start-Up Time			50		μs
External Clock (CLKIO)			16	16.384	MHz
Duty Cycle <sup>1</sup>	Typical duty cycle 50:50 (max:min)	30	50:50	70	%
LOGIC INPUTS					
Input High Voltage, V <sub>INH</sub> <sup>1</sup>	2 V ≤ IOVDD ≤ 2.3 V	0.65 × IOVDD			V
	2.3 V ≤ IOVDD ≤ 5.5 V	0.7 × IOVDD			V
Input Low Voltage, V <sub>INL</sub> <sup>1</sup>	2 V ≤ IOVDD ≤ 2.3 V			0.35 × IOVDD	V
	2.3 V ≤ IOVDD ≤ 5.5 V			0.7	V
Hysteresis <sup>1</sup>	IOVDD > 2.7 V	0.08		0.25	V
	IOVDD < 2.7 V	0.04		0.2	V
Leakage Currents		–10		+10	μA
LOGIC OUTPUT (DOUT/RDY)					
Output High Voltage, V <sub>OH</sub> <sup>1</sup>	IOVDD ≥ 4.5 V, I <sub>SOURCE</sub> = 1 mA	0.8 × IOVDD			V
	2.7 V ≤ IOVDD < 4.5 V, I <sub>SOURCE</sub> = 500 μA	0.8 × IOVDD			V
	IOVDD < 2.7 V, I <sub>SOURCE</sub> = 200 μA	0.8 × IOVDD			V
Output Low Voltage, V <sub>OL</sub> <sup>1</sup>	IOVDD ≥ 4.5 V, I <sub>SINK</sub> = 2 mA			0.4	V
	2.7 V ≤ IOVDD < 4.5 V, I <sub>SINK</sub> = 1 mA			0.4	V
	IOVDD < 2.7 V, I <sub>SINK</sub> = 400 μA			0.4	V
Leakage Current	Floating state	–10		+10	μA
Output Capacitance	Floating state		10		pF

Parameter	Test Conditions/Comments	Min	Typ	Max	Unit
SYSTEM CALIBRATION <sup>1</sup>					
Full-Scale Calibration Limit				$1.05 \times FS$	V
Zero-Scale Calibration Limit		$-1.05 \times FS$			V
Input Span		$0.8 \times FS$		$2.1 \times FS$	V
POWER REQUIREMENTS					
Power Supply Voltage					
AVDD1 – AVSS		4.5		5.5	V
AVDD2 – AVSS		2		5.5	V
AVSS – DGND		–2.75		0	V
IOVDD – DGND		2		5.5	V
IOVDD – AVSS	For AVSS < DGND			6.35	V
POWER SUPPLY CURRENTS	All outputs unloaded, digital inputs connected to IOVDD or DGND				
Full Operating Mode					
AVDD1 Current	External reference		1.5	1.75	mA
	Internal reference		1.75	2.1	mA
AVDD2 Current	External reference		4.3	4.9	mA
	Internal reference		4.5	5.1	mA
IOVDD Current	External clock		2	2.3	mA
	Internal clock		2.25	2.6	mA
	External crystal		2.5		mA
Standby Mode					
Standby (LDO On)	Internal reference off, total current consumption		22		μA
	Internal reference on, total current consumption		415		μA
Power-Down Mode	Full power-down, LDO, Internal reference		0.5	10	μA
POWER DISSIPATION					
Full Operating Mode	AVDD2 = 2 V, IOVDD = 2 V, external clock and reference		20.1	23.15	mW
	AVDD2 = 5 V, IOVDD = 5 V, external clock and reference		39	44.75	mW
	AVDD2 = 2 V, IOVDD = 2 V, internal clock and reference		22.25	25.9	mW
	AVDD2 = 5 V, IOVDD = 5 V, internal clock and reference		42.5	49	mW
Standby Mode	Internal reference off, all supplies = 5 V		110		μW
	Internal reference on, all supplies = 5 V		2.1		mW
Power-Down Mode	Full power-down		2.5	50	μW

<sup>1</sup> Specification is not production tested but is supported by characterization data at the initial product release.

<sup>2</sup> Following a system or internal zero-scale calibration, the offset error is in the order of the noise for the programmed output data rate selected. A system full-scale calibration reduces the gain error to the order of the noise for the programmed output data rate.

<sup>3</sup> The long-term stability specification is noncumulative.

## TIMING CHARACTERISTICS

IOVDD = 2 V to 5.5 V, DGND = 0 V, Input Logic 0 = 0 V, Input Logic 1 = IOVDD,  $C_{LOAD} = 20$  pF, unless otherwise noted.

Table 2.

Parameter	Limit at $T_{MIN}$ , $T_{MAX}$ (B Version)	Unit	Test Conditions/Comments <sup>1, 2</sup>
$t_3$	25	ns min	SCLK high pulse width
$t_4$	25	ns min	SCLK low pulse width
READ OPERATION			
$t_1$	0	ns min	$\overline{CS}$ falling edge to DOUT/ $\overline{RDY}$ active time
	15	ns max	IOVDD = 4.5 V to 5.5 V
	40	ns max	IOVDD = 2 V to 3.6 V
$t_2^3$	0	ns min	SCLK active edge to data valid delay <sup>4</sup>
	12	ns max	IOVDD = 4.5 V to 5.5 V
	25	ns max	IOVDD = 2 V to 3.6 V
$t_5^5$	2.5	ns min	Bus relinquish time after $\overline{CS}$ inactive edge
	20	ns max	
$t_6$	0	ns min	SCLK inactive edge to $\overline{CS}$ inactive edge
$t_7$	10	ns min	SCLK inactive edge to DOUT/ $\overline{RDY}$ high/low
WRITE OPERATION			
$t_8$	0	ns min	$\overline{CS}$ falling edge to SCLK active edge setup time <sup>4</sup>
$t_9$	8	ns min	Data valid to SCLK edge setup time
$t_{10}$	8	ns min	Data valid to SCLK edge hold time
$t_{11}$	5	ns min	$\overline{CS}$ rising edge to SCLK edge hold time

<sup>1</sup> Sample tested during initial release to ensure compliance.

<sup>2</sup> See Figure 2 and Figure 3.

<sup>3</sup> The time required for the output to cross the  $V_{OL}$  or  $V_{OH}$  limits.

<sup>4</sup> The SCLK active edge is the falling edge of SCLK.

<sup>5</sup>  $\overline{RDY}$  returns high after a read of the data register. In single conversion mode and continuous conversion mode, the same data can be read again, if required, while  $\overline{RDY}$  is high, although care should be taken to ensure that subsequent reads do not occur close to the next output update. If the continuous read feature is enabled, the digital word can be read only once.

## TIMING DIAGRAMS

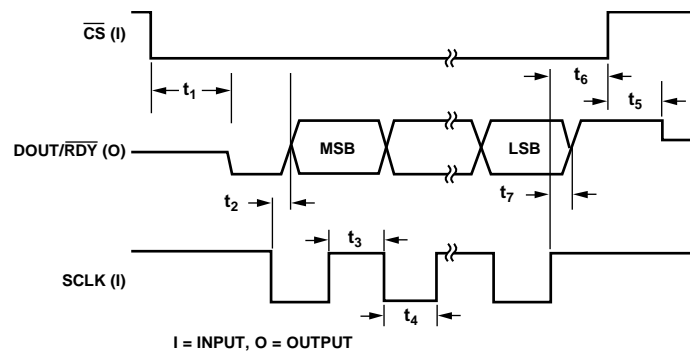


Figure 2. Read Cycle Timing Diagram

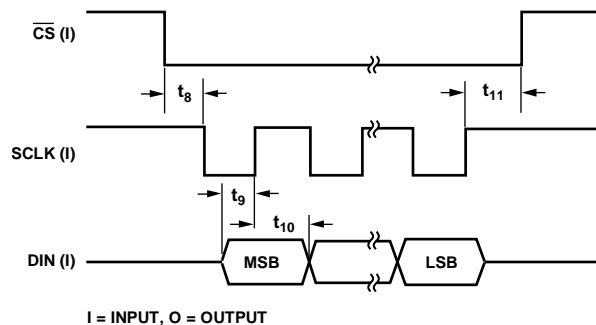


Figure 3. Write Cycle Timing Diagram

## ABSOLUTE MAXIMUM RATINGS

$T_A = 25^\circ\text{C}$ , unless otherwise noted.

Table 3.

Parameter	Rating
AVDD1, AVDD2 to AVSS	–0.3 V to +6.5 V
AVDD1 to DGND	–0.3 V to +6.5 V
IOVDD to DGND	–0.3 V to +6.5 V
IOVDD to AVSS	–0.3 V to +7.5 V
AVSS to DGND	–3.25 V to +0.3 V
Analog Input Voltage to AVSS	–0.3 V to AVDD1 + 0.3 V
Reference Input Voltage to AVSS	–0.3 V to AVDD1 + 0.3 V
Digital Input Voltage to DGND	–0.3 V to IOVDD + 0.3 V
Digital Output Voltage to DGND	–0.3 V to IOVDD + 0.3 V
AIN[4:0] or Digital Input Current	10 mA
Operating Temperature Range	–40°C to +105°C
Storage Temperature Range	–65°C to +150°C
Maximum Junction Temperature	150°C
Lead Soldering, Reflow Temperature	260°C

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## THERMAL RESISTANCE

$\theta_{JA}$  is specified for a device soldered on a JEDEC test board for surface-mount packages. The values listed in Table 4 are based on simulated data.

Table 4. Thermal Resistance

Package Type	$\theta_{JA}$	Unit
24-Lead TSSOP		
JEDEC Board Layer 1	156	°C/W
JEDEC Board Layer 2	87	°C/W

## ESD CAUTION



### ESD (electrostatic discharge) sensitive device.

Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.



## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

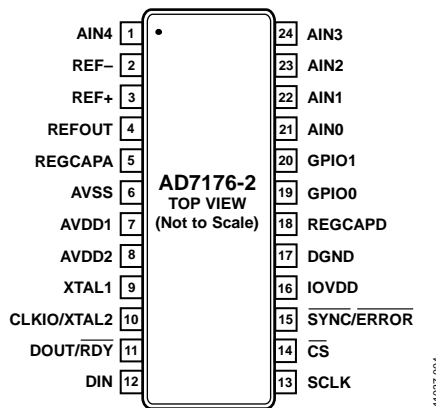


Figure 4. Pin Configuration

Table 5. Pin Function Descriptions

Pin No.	Mnemonic	Description
1	AIN4	Analog Input 4. Selectable through crosspoint multiplexer.
2	REF–	Reference Input Negative Terminal. REF– can span from AVSS to AVDD1 – 1 V.
3	REF+	Reference Input Positive Terminal. An external reference can be applied between REF+ and REF–. REF+ can span from AVDD1 to AVSS + 1 V. The part functions with a reference from 1 V to AVDD1.
4	REFOUT	Buffered Output of Internal Reference. The output is 2.5 V with respect to AVSS.
5	REGCAPA	Analog LDO Regulator Output. Decouple this pin to AVSS using a 1 $\mu$ F capacitor.
6	AVSS	Negative Analog Supply. This supply ranges from 0 V to –2.75 V and is nominally set to 0 V.
7	AVDD1	Analog Supply Voltage 1. This voltage is 5 V $\pm$ 10% with respect to AVSS.
8	AVDD2	Analog Supply Voltage 2. This voltage ranges from 2 V to AVDD1 with respect to AVSS.
9	XTAL1	Input 1 for Crystal.
10	CLKIO/XTAL2	Clock Input or Output (Based on the CLOCKSEL Bits in the ADCMODE Register)/Input 2 for Crystal. There are four options available: Internal oscillator—no output. Internal oscillator—output to CLKIO/XTAL2. Operates at IOVDD logic level. External clock—input to CLKIO/XTAL2. Input should be at IOVDD logic level. External crystal—connected between XTAL1 and CLKIO/XTAL2.
11	DOUT/RDY	Serial Data Output/Data Ready Output. DOUT/RDY serves a dual purpose. It functions as a serial data output pin to access the output shift register of the ADC. The output shift register can contain data from any of the on-chip data or control registers. The data-word/control word information is placed on the DOUT/RDY pin on the SCLK falling edge and is valid on the SCLK rising edge. When CS is high, the DOUT/RDY output is tristated. When CS is low, DOUT/RDY operates as a data ready pin, going low to indicate the completion of a conversion. If the data is not read after the conversion, the pin goes high before the next update occurs. The DOUT/RDY falling edge can be used as an interrupt to a processor, indicating that valid data is available.
12	DIN	Serial Data Input to the Input Shift Register on the ADC. Data in this shift register is transferred to the control registers in the ADC, with the register address (RA) bits of the communications register identifying the appropriate register. Data is clocked in on the rising edge of SCLK.
13	SCLK	Serial Clock Input. This serial clock input is for data transfers to and from the ADC. The SCLK has a Schmitt-triggered input, making the interface suitable for opto-isolated applications.
14	CS	Chip Select Input. This is an active low logic input used to select the ADC. CS can be used to select the ADC in systems with more than one device on the serial bus. CS can be hardwired low, allowing the ADC to operate in 3-wire mode with SCLK, DIN, and DOUT used to interface with the device. When CS is high, the DOUT/RDY output is tristated.

Pin No.	Mnemonic	Description
15	SYNC/ <u>ERROR</u>	<p>Can be switched between a logic input and a logic output in the GPIOCON register. When synchronization input is enabled, this pin allows for synchronization of the digital filters and analog modulators when using multiple <a href="#">AD7176-2</a> devices. When synchronization input is disabled, this pin can be used in one of three modes:</p> <p>Active low error input mode: this mode sets the ADC_ERROR bit in the STATUS register.</p> <p>Active low, open-drain error output mode: the STATUS register error bits are mapped to the <u>ERROR</u> pin. The <u>ERROR</u> pins of multiple devices can be wired together to a common pull-up resistor so that an error on any device can be observed.</p> <p>General-purpose output mode: the status of the pin is controlled by the ERR_DAT bit in the GPIOCON register. The pin is referenced between IOVDD and DGND, as opposed to the AVDD1 and AVSS levels used by the GPIO pins. The pin has an active pull-up in this case.</p>
16	IOVDD	Digital I/O Supply Voltage. IOVDD voltage ranges from 2 V to 5 V. IOVDD is independent of AVDD2. For example, IOVDD can be operated at 3 V when AVDD2 equals 5 V, or vice versa. If AVSS is set to -2.5 V, the voltage on IOVDD must not exceed 3.6 V.
17	DGND	Digital Ground.
18	REGCAPD	Digital LDO Regulator Output. This pin is for decoupling purposes only. Decouple this pin to DGND using a 1 $\mu$ F capacitor.
19	GPIO0	General-Purpose Input/Output. The pin is referenced between AVDD1 and AVSS levels.
20	GPIO1	General-Purpose Input/Output. The pin is referenced between AVDD1 and AVSS levels.
21	AIN0	Analog Input 0. Selectable through the crosspoint multiplexer.
22	AIN1	Analog Input 1. Selectable through the crosspoint multiplexer.
23	AIN2	Analog Input 2. Selectable through the crosspoint multiplexer.
24	AIN3	Analog Input 3. Selectable through the crosspoint multiplexer.

## TYPICAL PERFORMANCE CHARACTERISTICS

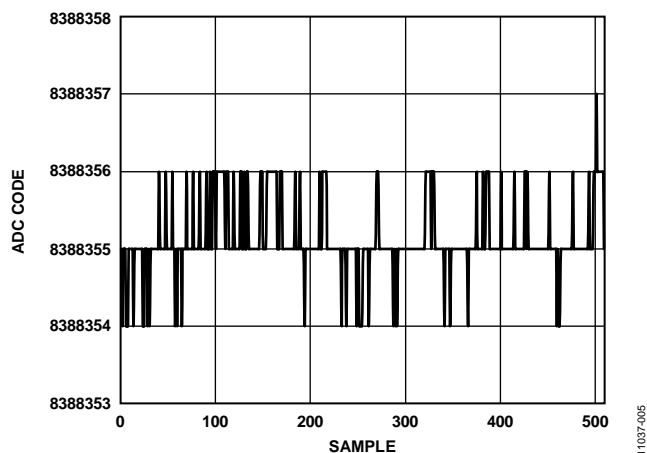


Figure 5. Noise ( $AVDD1 = 5\text{ V}$ ,  $AVDD2 = 5\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ ,  $V_{REF} = 5\text{ V}$ , Output Data Rate = 5 SPS)

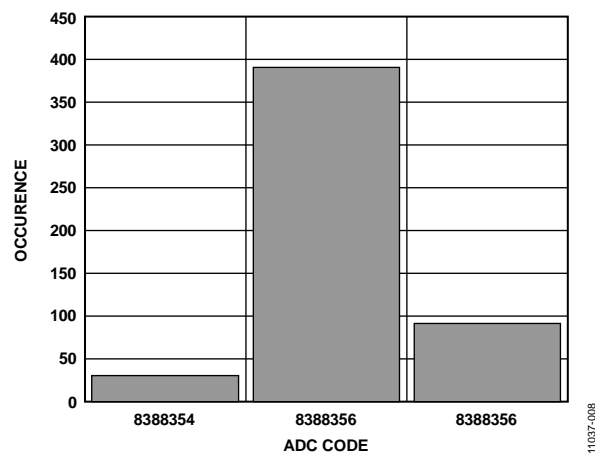


Figure 8. Noise Distribution Histogram ( $AVDD1 = 5\text{ V}$ ,  $AVDD2 = 5\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ ,  $V_{REF} = 5\text{ V}$ , Output Data Rate = 5 SPS)

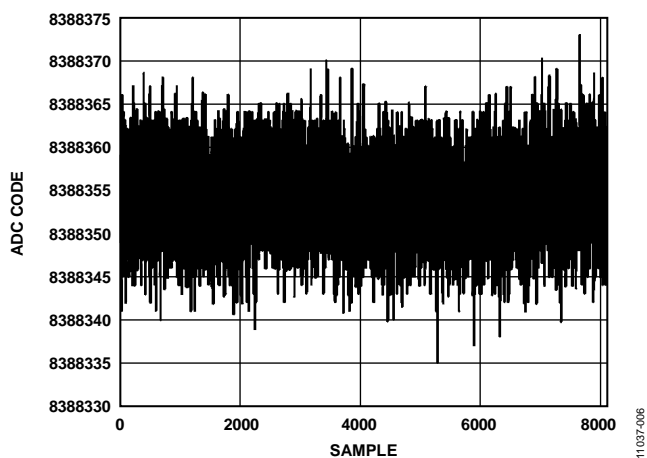


Figure 6. Noise ( $AVDD1 = 5\text{ V}$ ,  $AVDD2 = 5\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ ,  $V_{REF} = 5\text{ V}$ , Output Data Rate = 10 kSPS)

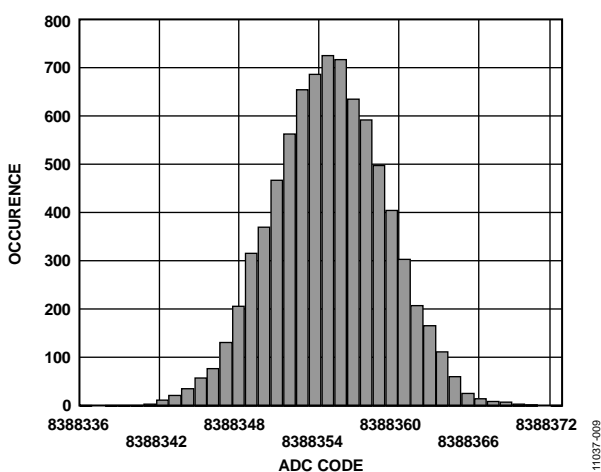


Figure 9. Noise Distribution Histogram ( $AVDD1 = 5\text{ V}$ ,  $AVDD2 = 5\text{ V}$ ,  $V_{REF} = 5\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ , Output Data Rate = 10 kSPS)

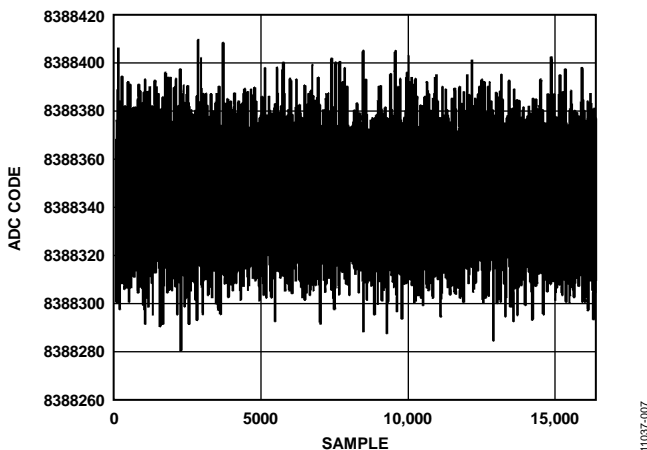


Figure 7. Noise ( $AVDD1 = 5\text{ V}$ ,  $AVDD2 = 5\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ ,  $V_{REF} = 5\text{ V}$ , Output Data Rate = 250 kSPS)

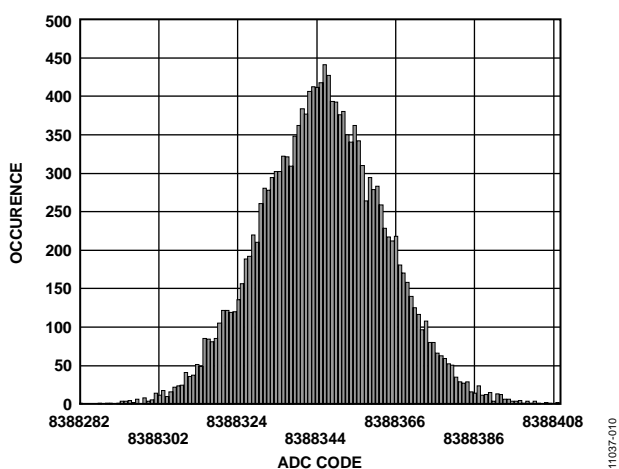


Figure 10. Noise Distribution Histogram ( $AVDD1 = 5\text{ V}$ ,  $AVDD2 = 5\text{ V}$ ,  $V_{REF} = 5\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ , Output Data Rate = 250 kSPS)

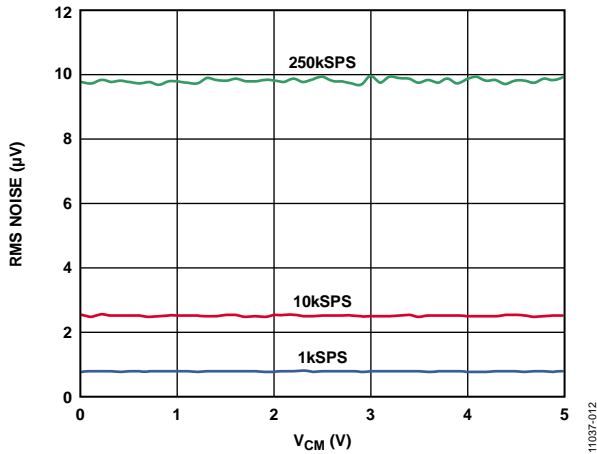


Figure 11. Noise vs. Common-Mode Input Voltage  
(AVDD1 = 5 V, AVDD2 = 5 V, IOVDD = 3.3 V, V<sub>REF</sub> = 2.5 V)

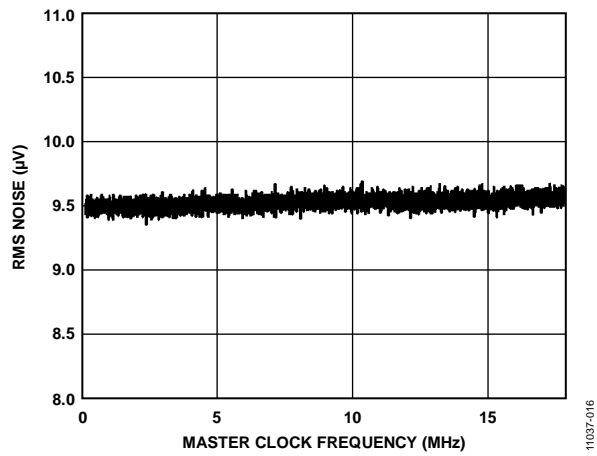


Figure 12. Noise vs. Master Clock  
(AVDD1 = 5 V, AVDD2 = 5 V, IOVDD = 3.3 V, V<sub>REF</sub> = 2.5 V)

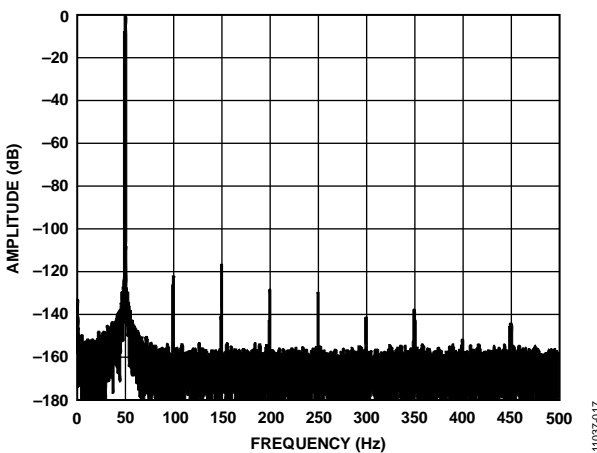


Figure 13. 50 Hz Input Tone, -0.5 dBFS Input FFT (AVDD1 = 5 V, AVDD2 = 5 V, IOVDD = 3.3 V, V<sub>REF</sub> = 2.5 V, Output Data Rate = 1 kSPS)

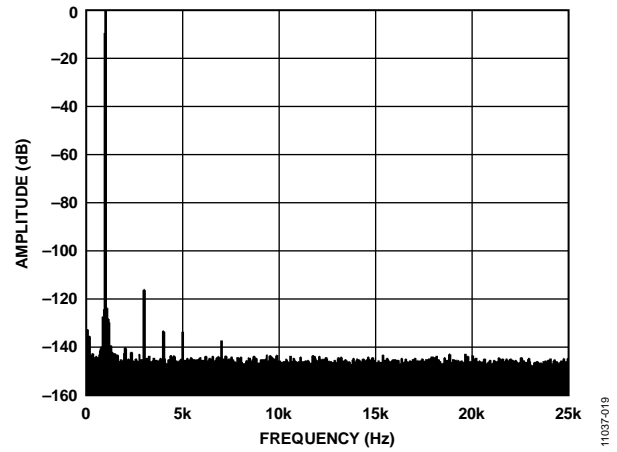


Figure 14. 1 kHz Input Tone, -0.5 dBFS Input FFT (AVDD1 = 5 V, AVDD2 = 5 V, IOVDD = 3.3 V, V<sub>REF</sub> = 2.5 V, Output Data Rate = 50 kSPS)

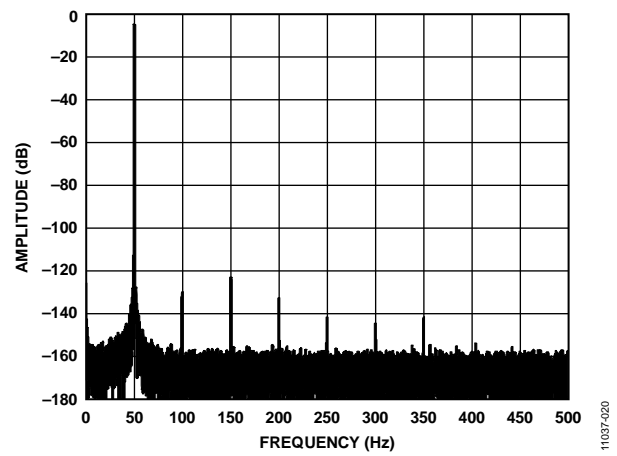


Figure 15. 50 Hz Input Tone, -6 dBFS Input FFT (AVDD1 = 5 V, AVDD2 = 5 V, IOVDD = 3.3 V, V<sub>REF</sub> = 2.5 V, Output Data Rate = 1 kSPS)

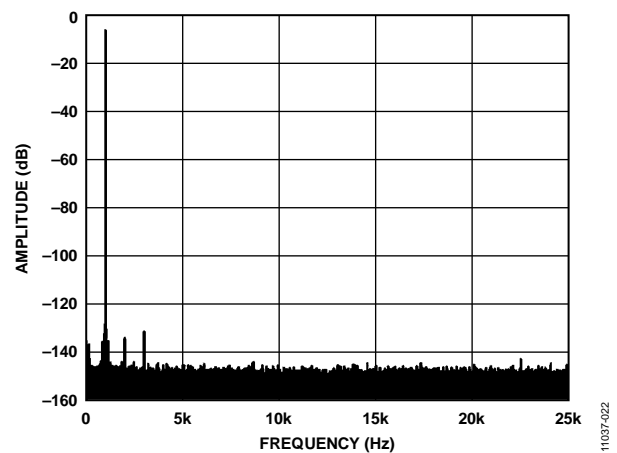


Figure 16. 1 kHz Input Tone, -6 dBFS Input FFT (AVDD1 = 5 V, AVDD2 = 5 V, IOVDD = 3.3 V, V<sub>REF</sub> = 2.5 V, Output Data Rate = 50 kSPS)

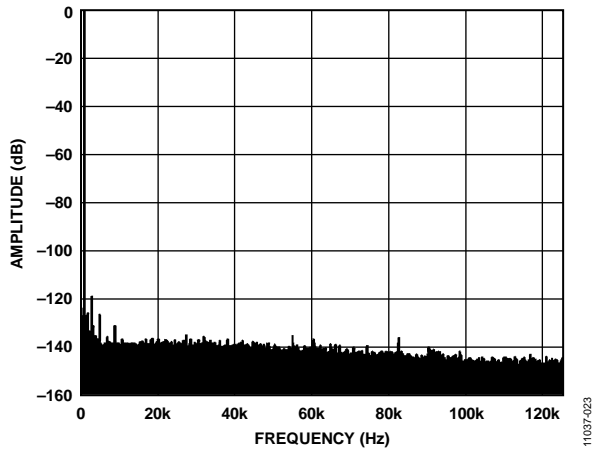


Figure 17. 1 kHz Input Tone, -0.5 dBFS Input FFT (AVDD1 = 5 V, AVDD2 = 5 V, IOVDD = 3.3 V,  $V_{REF}$  = 2.5 V, Output Data Rate = 250 kSPS)

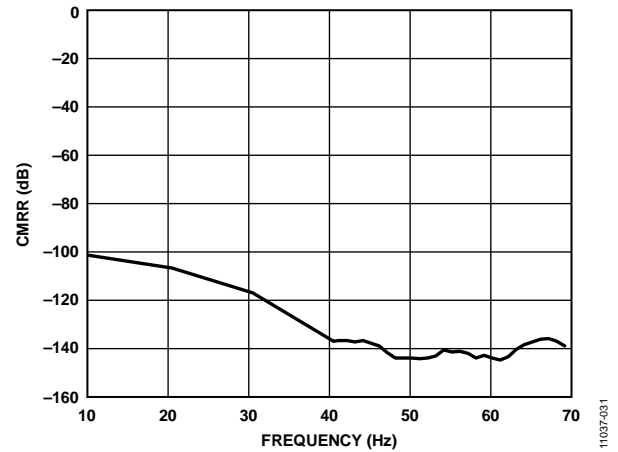


Figure 20. Common-Mode Rejection Ratio (10 Hz to 70 Hz) (AVDD1 = 5 V, AVDD2 = 5 V, IOVDD = 3.3 V, 20 SPS Enhanced Filter)

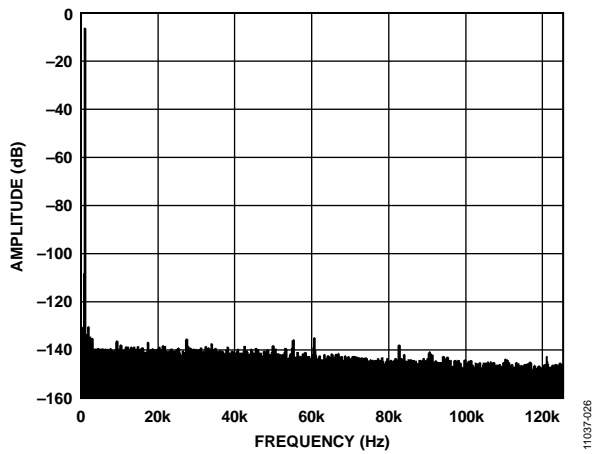


Figure 18. 1 kHz Input Tone, -6 dBFS Input FFT (AVDD1 = 5 V, AVDD2 = 5 V, IOVDD = 3.3 V,  $V_{REF}$  = 2.5 V, Output Data Rate = 250 kSPS)

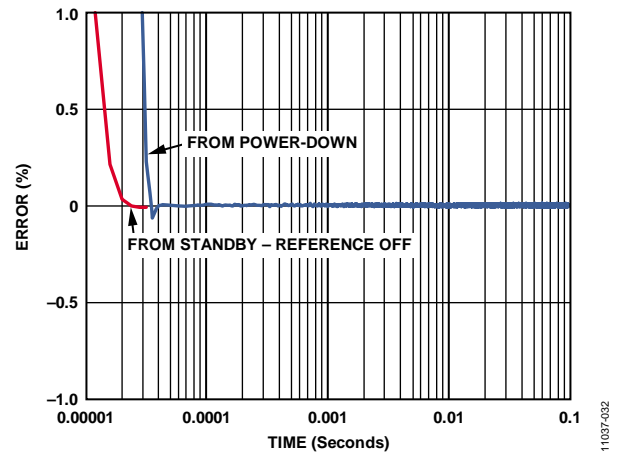


Figure 21. Internal Reference Settling Time (AVDD1 = 5 V, AVDD2 = 5 V, IOVDD = 3.3 V)

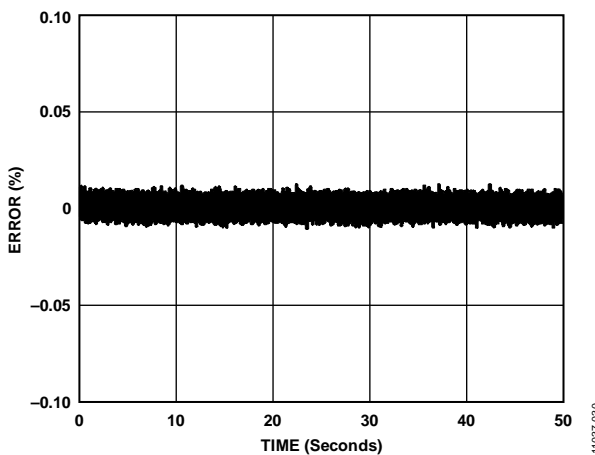


Figure 19. Internal Reference Settling Time (Extended) (AVDD1 = 5 V, AVDD2 = 5 V, IOVDD = 3.3 V)

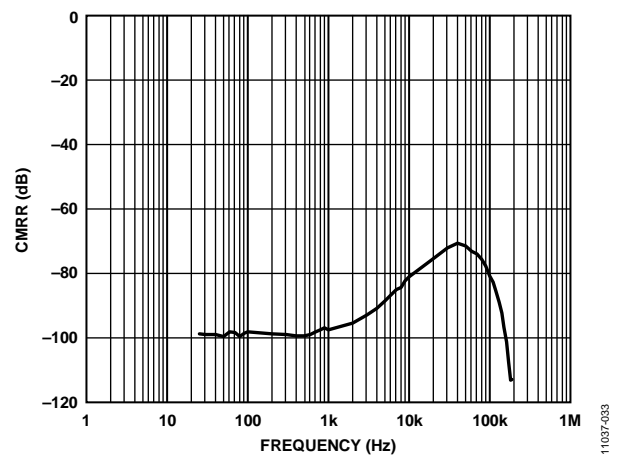


Figure 22. Common-Mode Rejection Ratio vs. Frequency (AVDD1 = 5 V, AVDD2 = 5 V, IOVDD = 3.3 V, Output Data Rate = 250 kSPS)

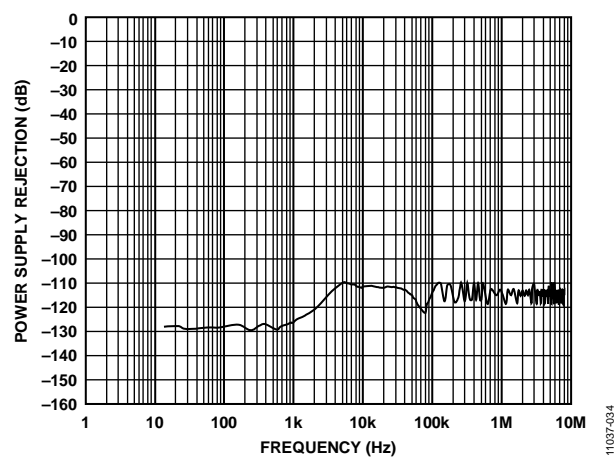


Figure 23. Power Supply Rejection Ratio vs. Frequency  
(AVDD1 = 5 V, AVDD2 = 5 V, IOVDD = 3.3 V)

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## NOISE PERFORMANCE AND RESOLUTION

Table 6 shows the rms noise and the noise free (peak-to-peak) resolution of the AD7176-2 for various output data rates and filters. The numbers given are for the bipolar input range with an external 5 V reference.

These numbers are typical and are generated with a differential input voltage of 0 V when the ADC is continuously converting

on a single channel. It is important to note that the peak-to-peak resolution is calculated based on the peak-to-peak noise. The peak-to-peak resolution represents the resolution for which there is no code flicker.

**Table 6. RMS Noise and Peak-to-Peak Resolution vs. Output Data Rate<sup>1</sup>**

Output Data Rate (SPS)	Sinc5 + Sinc1 Filter (Default)		Sinc3 Filter	
	Noise (μV rms)	Peak-to-Peak Resolution (Bits)	Noise (μV rms)	Peak-to-Peak Resolution (Bits)
250,000	9.7	17.2	220	12.8
62,500	5.4	18.2	5.1	18.3
10,000	2.5	19	1.8	19.8
1000	0.82	20.8	0.62	21
60	0.46	21.4	0.32	22
50	0.42	21.7	0.31	22
16.7	0.42	21.7	0.29	22.4
5	0.32	22.2	0.29	22.4

<sup>1</sup> Selected rates only, 1000 samples.

## GETTING STARTED

The **AD7176-2** offers the user a fast settling, high resolution, multiplexed ADC with high levels of configurability.

- Two fully differential or four single-ended analog inputs.
- Crosspoint multiplexer selects any analog input combination as the input signals to be converted, routing them to the modulator positive or negative input.
- Fully differential input, single-ended relative to any analog input and pseudo differential configuration available.
- Per channel configurability—up to four different setups can be defined. A separate setup can be mapped to each of the channels. Each setup allows the user to configure:
  - Gain and offset correction
  - Filter type
  - Output data rate
  - Reference source selection (internal/external)

The **AD7176-2** includes a precision 2.5 V low drift (2 ppm/°C) band gap internal reference. This reference can be selected to be used for the ADC conversions, reducing the external component count. Alternatively, the reference can be output to the REFOUT pin to be used as a low noise biasing voltage for the external circuitry. An example of this is using the REFOUT signal to set the input common mode for an external driving amplifier.

The **AD7176-2** includes two separate linear regulator blocks for both the analog and digital circuitry. The analog LDO regulates the AVDD2 supply to 2 V supplying the ADC core. The user can tie the AVDD1 and AVDD2 supplies together for easiest connection. If there is already a clean analog supply rail in the range of 2 V to 5 V, the user can also choose to connect this to the AVDD2 input, allowing for lower power dissipation.

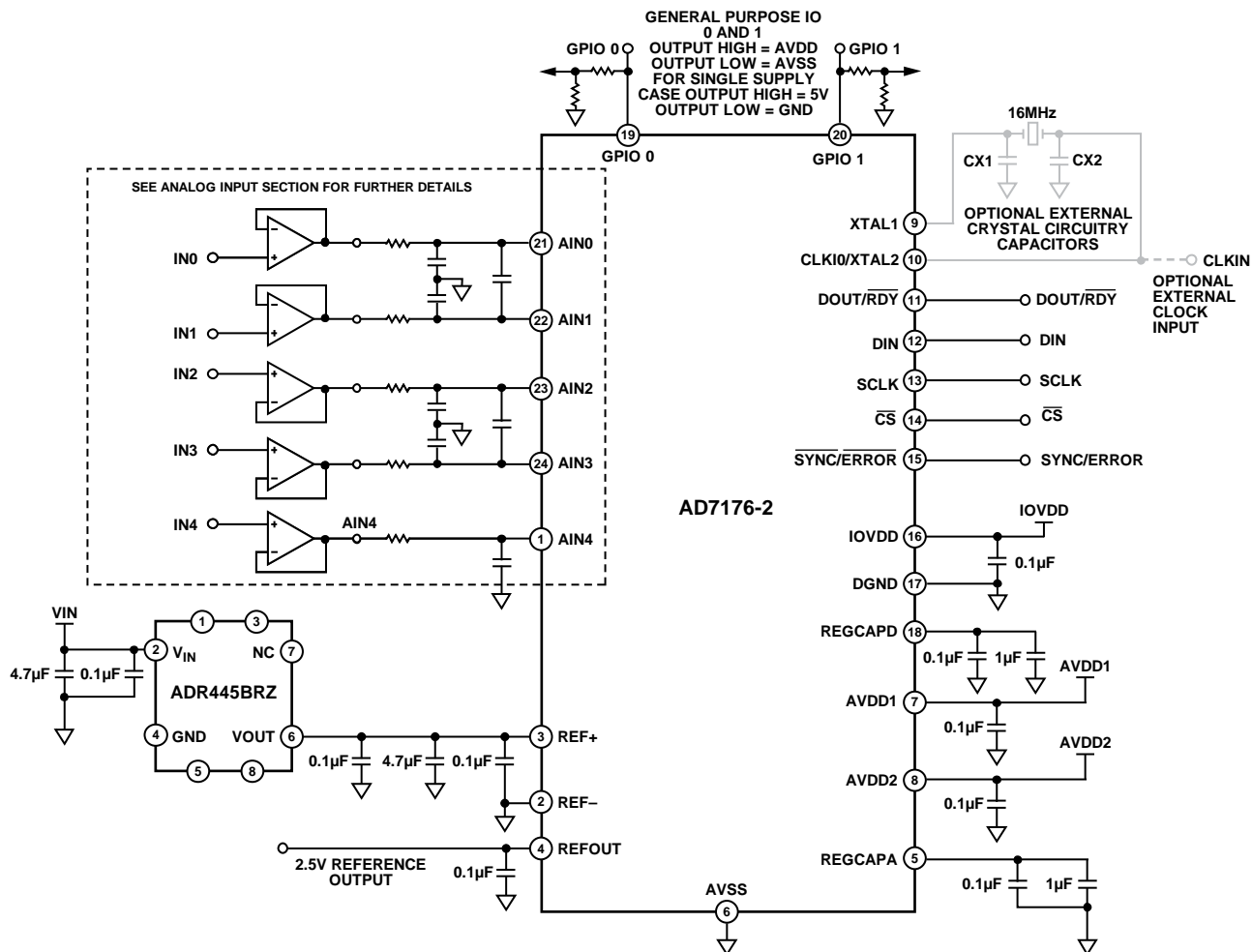


Figure 24. Typical Connection Diagram

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The linear regulator for the digital IOVDD supply performs a similar function, regulating the input voltage applied at the IOVDD pin to 2 V for the internal digital filtering. The serial interface signals always operate from the IOVDD supply seen at the pin. This means that if 3.3 V is applied to the IOVDD pin, the interface logic inputs and outputs operate at this level.

The AD7176-2 can be used across a wide variety of applications, providing high resolution and accuracy. A sample of these scenarios is as follows:

- Fast scanning of analog input channels using the internal multiplexer.
- Fast scanning of analog input channels using an external multiplexer.
- High resolution at lower speeds in either channel scanning or ADC per channel applications.
- Single ADC per channel: the fast low latency output allows further application specific filtering in an external micro-controller, DSP, or FPGA.

## POWER SUPPLIES

The AD7176-2 has three independent power supply pins: AVDD1, AVDD2, and IOVDD.

AVDD1 powers the front-end circuitry, including the crosspoint multiplexer. AVDD1 is referenced to AVSS and  $AVDD1 - AVSS = 5\text{ V}$  only. This can be a single 5 V supply or a  $\pm 2.5\text{ V}$  split supply. The split supply operation allows for true bipolar inputs. When using split supplies, the absolute maximum ratings (see the Absolute Maximum Ratings section) must be kept in mind.

AVDD2 powers the internal 1.8 V analog LDO regulator. This regulator powers the ADC core. AVDD2 is referenced to AVSS, and  $AVDD2 - AVSS$  can range from 5 V to 2 V.

IOVDD powers the internal 1.8 V digital LDO regulator. This regulator powers the digital logic of the ADC. IOVDD sets the voltage levels for the SPI interface of the ADC. IOVDD is referenced to DGND, and  $IOVDD - DGND$  can vary from 5 V to 2 V.

## DIGITAL COMMUNICATION

The AD7176-2 has a 3- or 4-wire SPI interface that is compatible with QSPI™, MICROWIRE®, and DSPs. The interface operates in SPI Mode 3 and can be operated with  $\overline{CS}$  tied low. In SPI Mode 3, the SCLK idles high, the falling edge of SCLK is the drive edge, and the rising edge of SCLK is the sample edge. This means that data is clocked out on the falling/drive edge and data is clocked in on the rising/sample edge.



Figure 25. SPI Mode 3 SCLK Edges

## Accessing the ADC Register Map

The communications register controls access to the full register map of the ADC. This register is an 8-bit write only register. On power-up or after a reset, the digital interface defaults to a state where it is expected a write to the communications register; therefore, all communication begins by writing to the communications register.

The data written to the communications register determines which register is being accessed and if the next operation is a read or write. The register address bits ( $RA[5:0]$ ) determine the specific register to which the read or write operation applies.

When the read or write operation to the selected register is complete, the interface returns to its defaults state, where it expects a write operation to the communications register.

In situations where interface synchronization is lost, a write operation of at least 64 serial clock cycles with DIN high returns the ADC to its default state by resetting the entire part, including the register contents. Alternatively, if  $\overline{CS}$  is being used with the digital interface, returning  $\overline{CS}$  high sets the digital interface to its default state and aborts any current operation.

Figure 26 and Figure 27 illustrate writing to and reading from a register by first writing the 8-bit command to the communications register followed by the data for that register.

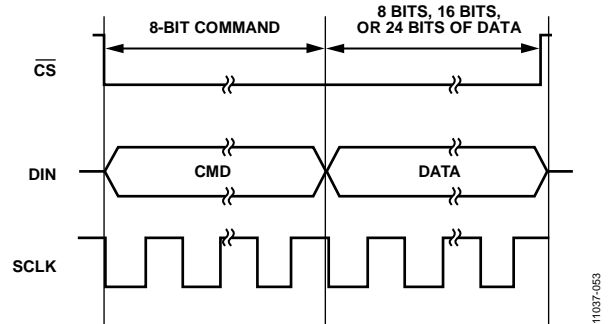


Figure 26. Writing to a Register  
(8-Bit Command with Register Address Followed by Data of 8, 16, or 24 Bits;  
Data Length Is Dependent on the Register Selected)

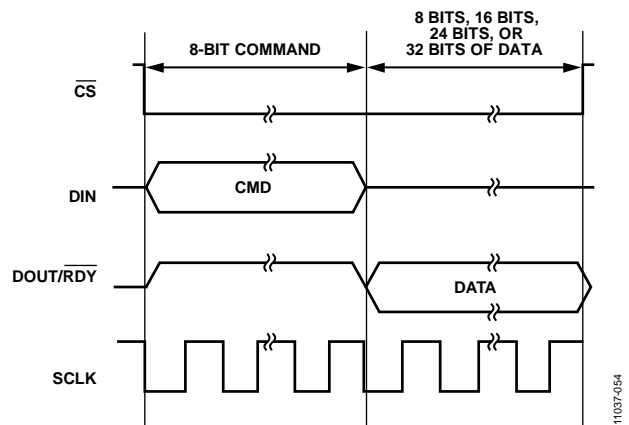


Figure 27. Reading from a Register  
(8-Bit Command with Register Address Followed by Data of 8, 16, or 24 Bits;  
Data Length on DOUT Is Dependent on the Register Selected)

Reading the ID register is the recommended method for verifying correct communication with the part. The ID registers is a read only register and contains the value 0x0C9X for the [AD7176-2](#). The communication register and ID register details are described in Table 7 and Table 8.

Table 7. Communications Register

Reg	Name	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset	RW
0x00	COMMS	[7:0]	$\overline{\text{WEN}}$	R/ $\overline{\text{W}}$	RA						0x00	W

Table 8. ID Register

Reg	Name	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset	RW
0x07	ID	[15:8]	ID[15:8]								0x0C9X	R
		[7:0]	ID[7:0]									

**CONFIGURATION OVERVIEW**

Figure 28 provides an overview of the configuration flow, divided into the following three blocks:

- ADC and interface mode configuration (labeled A in Figure 28)
- ADC setups (labeled B in Figure 28)
- Channel map configuration (labeled C in Figure 28)

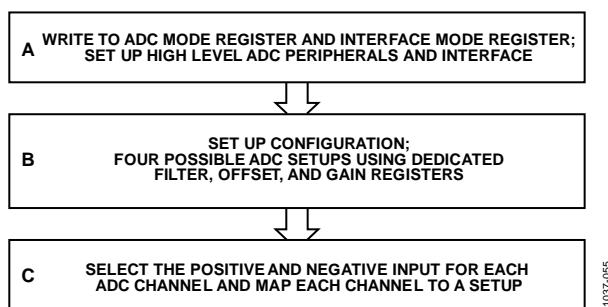


Figure 28. Configuration Flow

**ADC and Interface Mode Configuration**

The ADC mode register and the interface mode register (see Block A in Figure 28) configure the core peripherals to be used by the [AD7176-2](#) and the mode for the digital interface.

**ADC Mode Register**

The ADC mode register is used primarily to set the conversion mode of the ADC to either continuous or single conversion. The user can also select the standby and power-down modes as well as any of the calibration modes. In addition, this register contains the clock source select bits and the internal reference

enable bits. The reference select bits are contained in the setup configuration registers (see the ADC Setups section for more information).

**Interface Mode Register**

The interface mode register is used to configure the digital interface operation. This register allows the user to control data-word length, CRC enable, data + status read and continuous read mode.

Both register details are shown in Table 9 and Table 10. For more information, see the Digital Interface section.

**Table 9. ADC Mode Register**

Reg	Name	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset	RW
0x01	ADCMODE	[15:8]	REF_EN	RESERVED	SING_CYC	RESERVED		DELAY			0x8000	RW
		[7:0]	RESERVED	MODE			CLOCKSEL		RESERVED			

**Table 10. Interface Mode Register**

Reg	Name	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset	RW
0x02	IFMODE	[15:8]	RESERVED			ALT_SYNC	IOSTRENGTH	RESERVED		DOUT_RESET	0x0000	RW
		[7:0]	CONTREAD	DATA_STAT	REG_CHECK	RESERVED	CRC_EN		RESERVED	WL16		

### ADC Setups

The AD7176-2 has four independent setups (see Block B in Figure 28). Each setup consists of the following four registers:

- Setup configuration register
- Filter configuration register
- Offset register
- Gain register

For example, Setup 0 consists of Setup Configuration 0, Filter Configuration 0, Offset 0, and Gain 0. The setup is selectable from the channel map registers detailed in the Channel Map Configuration section. This allows each channel to be assigned to a separate setup; therefore, each channel is fully configurable because each setup has its own filter, offset, and gain register. Table 11 through Table 14 show the four registers that are associated with Setup 0.

#### Setup Configuration Register

The setup configuration registers allow the user to select the output coding of the ADC by selecting between bipolar and unipolar. In bipolar mode, the ADC accepts negative differential input voltages, and the output coding is offset binary. In unipolar mode, the ADC accepts only positive differential voltages, and the coding is straight binary. In either case, the input voltage must be within the supply voltages. The user can also select the reference source using this register. There are three options available—an internal 2.5 V

reference, an external reference connected between REF+ and REF– pins, or AVDD1 – AVSS.

#### Filter Configuration Register

The filter configuration register is used to select which digital filter is used at the output of the ADC modulator. The order of the filter and the output data rate is selected by setting the bits in this register. For more information, see the Digital Filters section.

#### Offset Register

The offset register holds the offset calibration coefficient for the ADC. The power-on reset value of the offset register is 0x800000. The offset register is a 24-bit read/write register. The power-on reset value is automatically overwritten if an internal or system zero-scale calibration is initiated by the user or if the offset register is written to by the user.

#### Gain Register

The gain register is a 24-bit register that holds the gain calibration coefficient for the ADC. The gain registers are read/write registers. These registers are configured at power-on with factory calibrated coefficients. Therefore, every device has different default coefficients. The default value is automatically overwritten if a system full-scale calibration is initiated by the user or if the gain register is written to by the user. For more information on calibration, see the Operating Modes section.

**Table 11. Setup Configuration 0 Register**

Reg	Name	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset	RW
0x20	SETUPCON0	[15:8]	RESERVED			BI_UNIPOLAR0	RESERVED				0x1020	RW
		[7:0]	RESERVED		REF_SEL0		RESERVED					

**Table 12. Filter Configuration 0 Register**

Reg	Name	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset	RW
0x28	FILTCON0	[15:8]	SINC3_MAP0	RESERVED			ENHFILTEN0	ENHFILTO			0x0000	RW
		[7:0]	RESERVED	ORDER0		ODR0						

**Table 13. Offset 0 Register**

Reg	Name	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset	RW
0x30	OFFSET0	[23:16]	OFFSET0[23:16]								0x800000	RW
		[15:8]	OFFSET0[15:8]									
		[7:0]	OFFSET0[7:0]									

**Table 14. Gain 0 Register**

Reg	Name	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset	RW
0x38	GAIN0	[23:16]	GAIN0[23:16]								0x5XXXX0	RW
		[15:8]	GAIN0[15:8]									
		[7:0]	GAIN0[7:0]									

Channel Map Configuration

The AD7176-2 has four independent channels (see Block C in Figure 28). The user can select which of the four setups is used for each channel. This allows for per channel configuration.

Channel Map Register

The channel map register is used to select which of the five analog input pins are used as either the positive analog input or the negative analog input for that channel. This register also

contains a channel enable/disable bit and the setup selection bits, which are used to pick which of the four available setups are used for this channel.

When the AD7176-2 is operating in continuous conversion mode with more than one channel enabled, the channel sequencer cycles through the enabled channels in sequential order, from Channel Map 0 to Channel Map 3. If a channel is disabled, it is skipped by the sequencer. Details of the channel map register for Channel 0 are shown in Table 15.

Table 15. Channel Map Register

Reg	Name	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset	RW
0x10	CHMAP0	[15:8]	CH_EN0	RESERVED	SETUP_SELO		RESERVED		AINPOS0[4:3]		0x8001	RW
		[7:0]	AINPOS0[2:0]			AINNEG0						

## CIRCUIT DESCRIPTION

### ANALOG INPUT

The AD7176-2 has five analog input pins: AIN0, AIN1, AIN2, AIN3, and AIN4. Each of these pins connects to the internal crosspoint multiplexer. The crosspoint multiplexer enables any of these inputs to be configured as an input pair, either pseudo differential or fully differential. The AD7176-2 can have up to four active channels. When more than one channel is enabled, the channels are automatically sequenced in order. The output of the multiplexer is connected directly to the switched-capacitor input of the ADC. The simplified analog input circuit is shown in Figure 29.

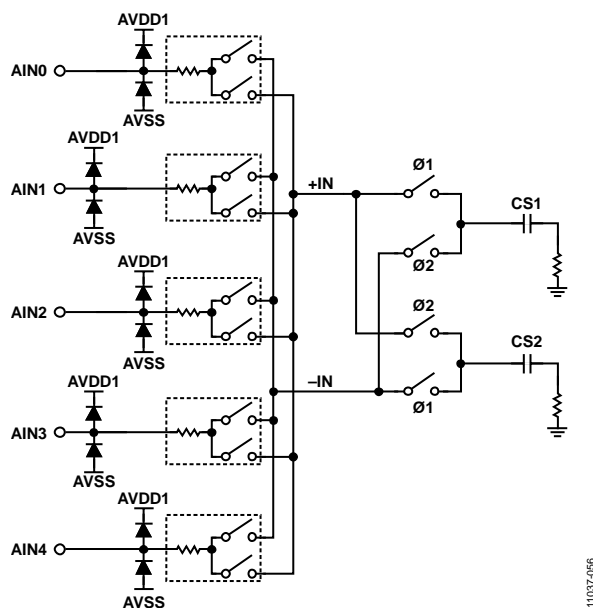


Figure 29. Simplified Analog Input Circuit

The CS1 and CS2 capacitors have a magnitude in the order of a number of picofarads each. This capacitance is the combination of both the sampling capacitance and the parasitic capacitance. The average input current to the AD7176-2 changes linearly with the differential input voltage at a rate of  $48 \mu\text{A}/\text{V}$ . Each of the analog inputs must be buffered externally not only to provide the varying input current with differential input amplitude but also to settle the switched-capacitor input to allow for accurate sampling.

Recommended amplifiers for this purpose are discussed in the Driver Amplifiers section.

### Fully Differential Inputs

Because the AIN0 to AIN4 analog inputs are connected to a crosspoint multiplexer, any combination of signals can be used to create an analog input pair. This allows the user to select two fully differential inputs or four pseudo differential inputs.

If two fully differential input paths are connected to the AD7176-2, using AIN0/AIN1 as one differential input pair and AIN2/AIN3 as the second differential input pair is recommended. This is due to the relative locations of these pins to each other. All analog inputs should be decoupled to AVSS.

### Pseudo Differential Inputs

The user can also choose to measure four different single-ended analog inputs. In this case, each of the analog inputs is converted as being the difference between the single-ended input to be measured and a set analog input common pin. Because there is a crosspoint multiplexer, the user can set any of the analog inputs as the common pin. An example of such a scenario is to connect the AIN4 pin to AVSS or to the REFOUT voltage (that is,  $\text{AVSS} + 2.5 \text{ V}$ ) and select this input when configuring the crosspoint multiplexer. When using the AD7176-2 with pseudo differential inputs, the INL specification is degraded.

### DRIVER AMPLIFIERS

To drive the analog input switch capacitor, an external amplifier is required. Details of three recommended amplifiers for the AD7176-2 are shown in the Driver Amplifiers section. Each of the amplifiers can run from a single 5 V voltage rail.

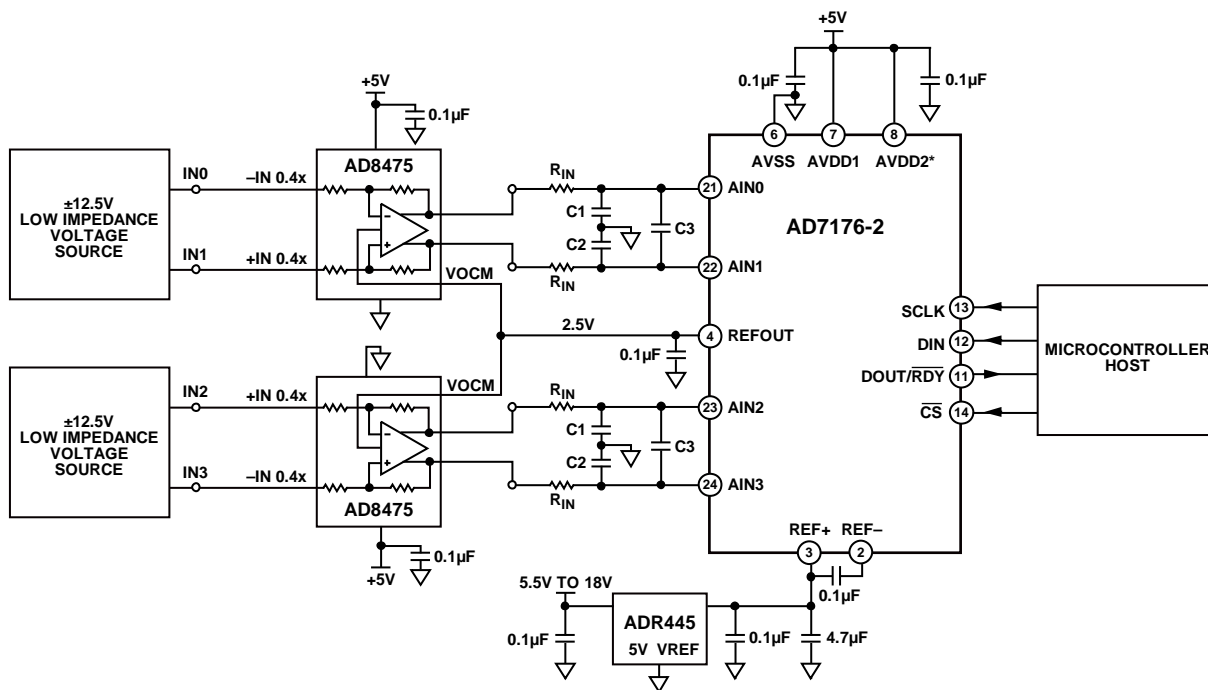
**AD8475**

The **AD8475** features an attenuating input stage of  $0.8\times$  or  $0.4\times$  (using integrated precision resistors), allowing inputs in the  $\pm 10$  V range with a single 5 V supply and a 3 mA current consumption to be used. The **AD8475** performs single-ended to differential conversions, allows easy setting of the common-mode output, and drives the **AD7176-2** with a differential input.

Figure 30 shows a typical connection to the **AD7176-2**, where two **AD8475** amplifiers attenuate two differential inputs and then drive the **AD7176-2** inputs. The common-mode output of the **AD8475** is set by connecting the internal, buffered 2.5 V reference of the **AD7176-2** to the **VOCM** pin of the **AD8475**. The output of the **AD8475** to the **AD7176-2** is fully differential

with a fixed common mode of 2.5 V. The output of the **AD8475** amplifier is connected to an RC network. The RC network, as shown in Figure 30, includes  $R_{IN} = 10\ \Omega$ ;  $C1, C2 = 270\ \text{pF}$ ; and  $C3 = 680\ \text{pF}$ . The RC circuit acts to provide the dynamic charge required by the **AD7176-2** switched sampling capacitors while isolating the amplifier output from any kickback from the dynamic switched capacitor input. The configuration of the **AD8475** in Figure 30 shows a fully differential signal source with a gain of  $0.4\times$ .

The **AD8475** can also be set up to convert single-ended signals to fully differential inputs. Ground the  $-IN\ 0.4\times$  input and apply the single-ended input to the  $+IN\ 0.4\times$  input.



\*AVDD2 CAN BE SUPPLIED BY VOLTAGES RANGING FROM 2V TO 5.5V.

Figure 30. **AD8475** Driving Two Differential Inputs of the **AD7176-2**

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**AD8656**

The **AD8656** is a low noise, dual precision CMOS amplifier. The **AD8656** allows the user to connect a signal of interest directly to a high impedance, low noise, low offset amplifier input that can drive the **AD7176-2** switched capacitor input. The **AD8656** can operate from a single 5 V supply. When using an external 5 V reference such as the **ADR445** in conjunction with the **AD7176-2**, the **AD8656** output can swing to within  $-1$  dBFS (which equates to a differential input of  $\pm 4.45$  V) of the ADC input range.

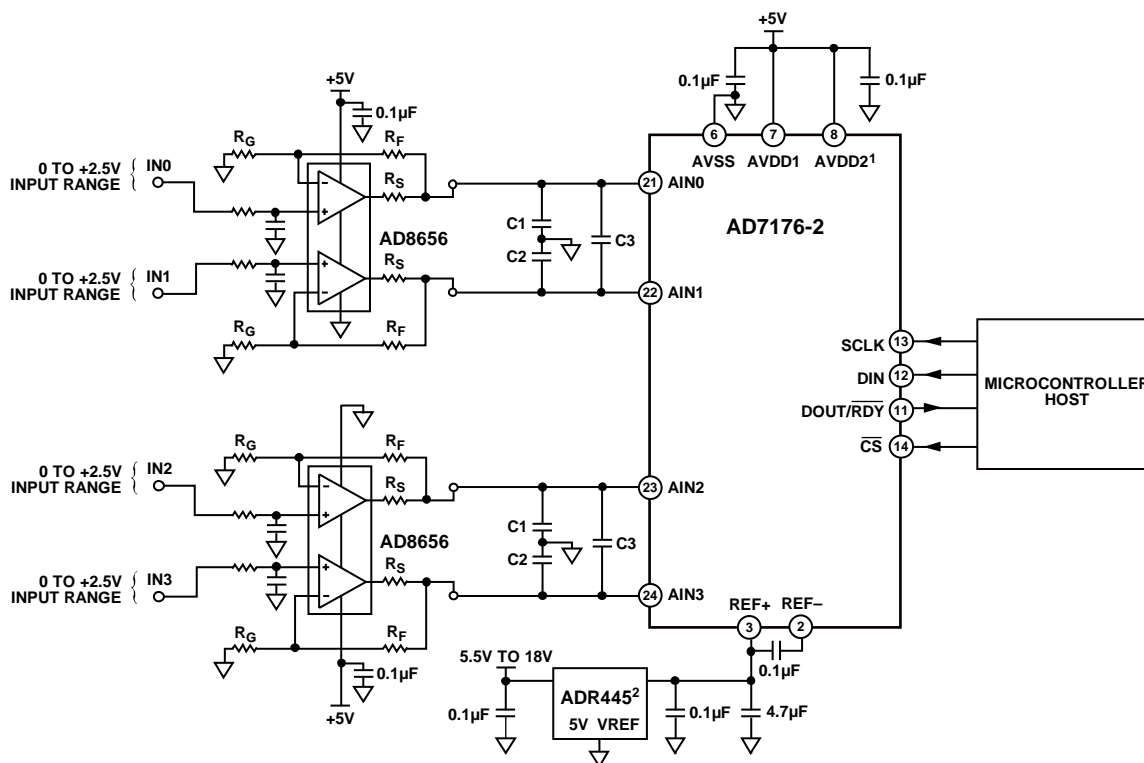
A simple configuration for use of the **AD8656** is to connect the amplifiers in a configuration for a gain of more than 1. Each of the **AD7176-2** analog inputs has its own amplifier. This allows the user to connect either fully differential inputs or single-ended inputs to the **AD7176-2**. The example shown in Figure 31 is configured with two fully differential inputs connecting to the AIN0/AIN1 pair and the AIN2/AIN3 pair.

The high impedance input to the amplifier allows the user to band-limit the input with a suitable passive filter RC combination. The gain of the configuration used is set by the  $R_G$  and  $R_F$  resistors.

To improve accuracy, use precision resistors for  $R_G$  and  $R_F$ . Setting  $R_G = R_F = 1$  k $\Omega$  results in a gain of 2 for the circuit. The matching of the  $R_G$  and  $R_F$  resistors directly affects the gain error of the circuit. The drift and matching of these resistors affect the gain error drift of the circuit. A  $10$   $\Omega$  source resistor ( $R_S$ ) is placed between the feedback resistor ( $R_F$ ) and the amplifier output. This resistor acts to isolate the amplifier from any kickback from the ADC input and does not directly affect the gain error of the circuit.

The output of each of the amplifier pairs is connected directly to a network of decoupling and differential capacitors prior to being connected to the **AD7176-2** analog inputs. The capacitor network shown in Figure 31 includes  $C_1$ ,  $C_2 = 270$  pF and  $C_3 = 680$  pF. The capacitor network acts to provide the dynamic charge required by the **AD7176-2** switched sampling capacitors.

The circuit example in Figure 31 requires inclusion of two precision gain resistors per amplifier ( $R_G$  and  $R_F$ ). Choose the value, precision, and matching of such resistors according to the requirements of the application.



<sup>1</sup>AVDD2 CAN BE SUPPLIED BY VOLTAGES RANGING FROM 2V TO 5.5V.

<sup>2</sup>USING ADR444 (4.096V REFERENCE) IN PLACE OF THE ADR445 AS SHOWN IN THIS EXAMPLE WOULD ALLOW THE ENTIRE CCT TO BE OPERATED FROM A SINGLE 5V SUPPLY RAIL.

Figure 31. Dual **AD8656** Amplifiers Driving the **AD7176-2**

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### ADA4940

The ADA4940-1/ADA4940-2 is an alternate option to drive the AD7176-2. It is a low noise, low distortion fully differential amplifier with very low power consumption (1.25 mA of quiescent current). The AD7176-2 REFOUT pin can be used to connect to the ADA4940-1/ADA4940-2 to set the common-mode output to 2.5 V. This option requires the use of external resistors to set the gain of the amplifier.

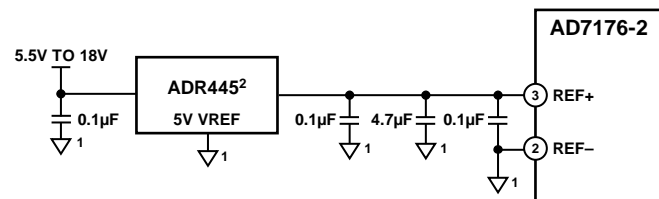
### AD7176-2 REFERENCE

The AD7176-2 offers the user the option of either supplying an external reference to the REF+ and REF– pins of the device or allowing the use of the internal 2.5 V, low noise, low drift reference. Select the reference source to be used by the analog input by setting the REF\_SELx bits (Bits[5:4]) in the setup configuration registers appropriately. The structure of the Setup Configuration 0 register is shown in Table 16. The AD7176-2 defaults on power-up to use the internal 2.5 V reference.

#### External Reference

The AD7176-2 has a fully differential reference input applied through the REF+ and REF– pins. Standard low noise, low drift voltage references, such as the ADR445, ADR444, and ADR441,

are recommended for use. The external reference should be applied to the AD7176-2 reference pins as shown in Figure 32. The output of any external reference should be decoupled to AVSS. As shown in Figure 32, the ADR445 output is decoupled with a 0.1  $\mu$ F capacitor at its output for stability purposes. The output is then connected to a 4.7  $\mu$ F capacitor, which acts as a reservoir for any dynamic charge required by the ADC, and followed by a 0.1  $\mu$ F decoupling capacitor at the REF+ input. This capacitor is placed as close as possible to the REF+ and REF– pins. The REF– pin is connected directly to the AVSS potential. On power-up of the AD7176-2, the internal reference is enabled by default and is output on the REFOUT pin. When an external reference is used instead of the internal reference to supply the AD7176-2, attention must be paid to the output of the REFOUT pin. If the internal reference is not being used elsewhere in the application, ensure that the REFOUT pin is not hardwired to AVSS because this will draw a large current on power-up. On power-up if the internal reference is not being used, write to the ADC mode register, disabling the internal reference. This is controlled by the REF\_EN bit (Bit 15) in the ADC mode register and is shown in Table 17.



<sup>1</sup>ALL DECOUPLING IS TO AVSS.

<sup>2</sup>ANY OF THE ADR44x FAMILY REFERENCES MAY BE USED.

ADR444 OR ADR441 BOTH ENABLE REUSE OF THE 5V ANALOG SUPPLY NEEDED FOR AVDD1 TO POWER THE REFERENCE VIN.

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Figure 32. External Reference ADR445 Connected to AD7176-2 Reference Pins

Table 16. Setup Configuration 0 Register

Reg	Name	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset	RW
0x20	SETUPCON0	[15:8]	RESERVED			BI_UNIPOLAR0	RESERVED				0x1020	RW
		[7:0]	RESERVED		REF_SEL0		RESERVED					

Table 17. ADC Mode Register

Reg	Name	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset	RW
0x01	ADCMODE	[15:8]	REF_EN	RESERVED	SING_CYC	RESERVED		DELAY			0x8000	RW
		[7:0]	RESERVED	MODE			CLOCKSEL		RESERVED			

### Internal Reference

The AD7176-2 includes its own low noise, low drift voltage reference. The internal reference has a 2.5 V output. The internal reference is output on the REFOUT pin after the REF\_EN bit in the ADC mode register is set and is decoupled to AVSS with a 0.1  $\mu$ F capacitor. The AD7176-2 internal reference is enabled by default on power-up and is selected as the reference source for the ADC.

The REFOUT signal is buffered prior to being output to the pin. The signal can be used externally in the circuit as a common-mode source for external amplifier configurations. This is shown in Figure 30 in the Driver Amplifiers section, where the REFOUT pin supplies the VOCM input of the AD8475 amplifier.

### AD7176-2 CLOCK SOURCE

The AD7176-2 requires a master clock of 16 MHz. The AD7176-2 can source its sampling clock from one of three scenarios:

- Internal oscillator
- External crystal
- External clock source

All output data rates listed in the data sheet relate to a master clock rate of 16 MHz. Using a lower clock frequency from, for instance, an external source will scale any listed data rate proportionally. To achieve the specified data rates, particularly rates for rejection of 50 Hz and 60 Hz, a 16 MHz clock should be used. The source of the master clock is selected by setting the CLOCKSEL bits (Bits[3:2]) in the ADC mode register as shown in Table 17. The default operation on power-up and reset of the AD7176-2 is to operate with the internal oscillator.

### Internal Oscillator

The internal oscillator runs at 16 MHz and can be used as the ADC master clock. It is the default clock source for the AD7176-2 and is specified with an accuracy of  $\pm 2.5\%$ .

There is an option to allow the internal clock oscillator to be output on the AD7176-2 CLKIO/XTAL2 pin. The clock output is driven to the IOVDD logic level. Use of this option can affect the dc performance of the AD7176-2 due to the disturbance

introduced by the output driver. The extent to which the performance is affected depends on the IOVDD voltage supply. Higher IOVDD voltages create a wider logic output swing from the driver and affect performance to a greater extent. This is further exaggerated if the IOSTRENGTH bit is set at higher IOVDD levels (see Table 25 for more information).

### External Crystal

If higher precision, lower jitter clock sources are required, the AD7176-2 has the ability to use an external crystal to generate the master clock. The crystal is connected to the XTAL1 and XTAL2 pins. A recommended crystal for use is the FA-20H—a 16 MHz, 10 ppm, 9 pF crystal from Epson-Toyocom—which is available in a surface-mounted package. As shown in Figure 33, allow for two capacitors to be inserted from the traces connecting the crystal to the XTAL1 and XTAL2 pins. These capacitors allow for circuit tuning. Connect these capacitors to the DGND pin. The value for these capacitors depends on the length and capacitance of the trace connections between the crystal and the XTAL1 and XTAL2 pins. Therefore, the values of these capacitors differ depending on the PCB layout and the crystal employed. As a result, empirical testing of the circuit is required.

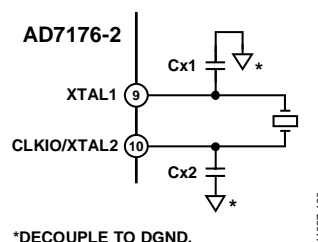


Figure 33. External Crystal Connections

### External Clock

The AD7176-2 can also use an externally supplied clock. In systems where this is desirable, the external clock is routed to the CLKIO pin. In this configuration, the CLKIO pin accepts the externally sourced clock and routes it to the modulator. The logic level of this clock input is defined by the voltage applied to the IOVDD pin.

## DIGITAL FILTERS

The AD7176-2 has three flexible filter options to allow for optimization of noise, settling time, and rejection:

- Sinc5 + Sinc1 filter
- Sinc3 filter
- Enhanced 50 Hz and 60 Hz rejection filters

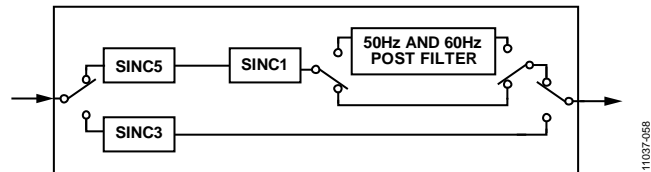


Figure 34. Digital Filter Block Diagram

The filter and output data rate is configured by setting the appropriate bits in the filter configuration register for the selected setup. See the Register Details section for more information.

### SINC5 + SINC1 FILTER

The Sinc5 + Sinc1 filter is targeted at fast switching multiplexed applications and achieves single cycle settling at output data rates of 10 kSPS and lower. The Sinc5 block output is fixed at the maximum rate of 250 kSPS, and the Sinc1 block output data rate can be varied

to control the final ADC output data rate. Figure 35 shows the frequency domain response of the Sinc5 + Sinc1 filter at a 50 SPS output data rate. The Sinc5 + Sinc1 filter has a slow roll-off over frequency and narrow notches.

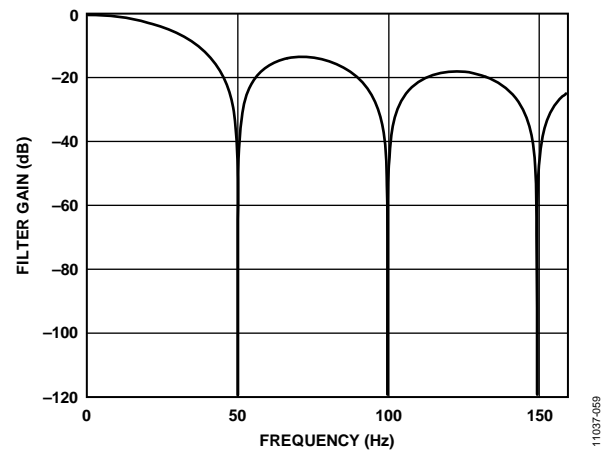


Figure 35. Sinc5 + Sinc1 Filter Response at 50 SPS ODR

The output data rates with the accompanying settling time and rms noise for the Sinc5 + Sinc1 filter are shown in Table 18.

Table 18. AD7176-2 Output Data Rate (ODR), Noise, Settling Time ( $t_{SETTLE}$ ), and Rejection Using the Sinc5 + Sinc1 Filter

Output Data Rate (SPS) <sup>1</sup>	Settling Time <sup>1</sup>	Switching Rate (Hz) <sup>1</sup>	Notch Frequency (Hz)	Rejection $\pm 1$ Hz (dB) <sup>2</sup>	Noise ( $\mu$ V rms)	Peak-to-Peak Resolution with 5 V Reference (Bits)
250,000	20 $\mu$ s	50,000	250,000		9.7	17.25
125,000	24 $\mu$ s	41,667	125,000		7.4	17.6
62,500	32 $\mu$ s	31,250	62,500		5.4	18.1
50,000	36 $\mu$ s	27,778	50,000		5	18.2
31,250	48 $\mu$ s	20,833	31,250		4	18.5
25,000	56 $\mu$ s	17,857	25,000		3.6	18.7
15,625	80 $\mu$ s	12,500	15,625		2.7	19.1
10,000	100 $\mu$ s	10,000	11,905		2.5	19.2
5000	200 $\mu$ s	5000	5435		1.8	19.7
2500	400 $\mu$ s	2500	2604		1.3	20.2
1000	1.0 ms	1000	1016		0.82	20.8
500	2.0 ms	500.0	504		0.63	21.2
400	2.516 ms	400	400.00		0.62	21.2
200	5.0 ms	200.0	200.64		0.47	21.6
100	10.0 ms	100.0	100.16		0.46	21.7
60	16.68 ms	460	60.00	34 dB (60 Hz)	0.43	21.7
50	20.016 ms	50	50.00	34 dB (50 Hz)	0.42	21.8
20	50.0 ms	20.00	20.01		0.42	21.8
16.667	60.02 ms	16.66	16.67		0.42	21.8
10	100.02 ms	10.00	10.00	34 dB (50 Hz and 60 Hz)	0.38	22
5	200.02 ms	5.00	5.00		0.32	22.1

<sup>1</sup> The settling time has been rounded to the nearest microsecond. This is reflected in the output data rate and switching rate. Switching rate =  $1 \div t_{SETTLE}$ .

<sup>2</sup> Master clock = 160 MHz.

## SINC3 FILTER

The Sinc3 filter achieves the best single-channel noise performance at lower rates and is, therefore, most suitable for single-channel applications. The Sinc3 filter always has a settling time equal to

$$t_{\text{SETTLE}} = 3/\text{Output Data Rate}$$

Figure 36 shows the frequency domain filter response for the Sinc3 filter. The Sinc3 filter has good roll-off over frequency and has wide notches for good notch frequency rejection.

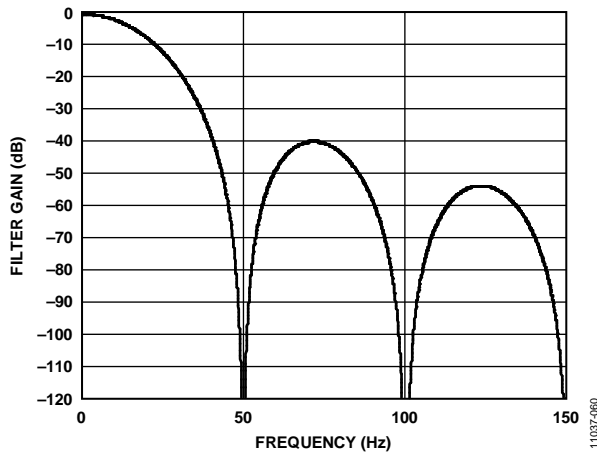


Figure 36. Sinc3 Filter Response

The output data rates with the accompanying settling time and rms noise for the Sinc3 filter are shown in Table 19.

It is possible to finely tune the output data rate for the Sinc3 filter by setting the SINC3\_MAP bit in the filter configuration register. If this bit is set, the mapping of the filter register changes to directly program the decimation rate of the Sinc3 filter. All other options are eliminated. The data rate when on a single channel can be calculated using the following equation:

$$\text{Output Data Rate} = \frac{f_{\text{MOD}}}{32 \times \text{FILTCONx}[14:0]}$$

where:

$f_{\text{MOD}}$  is the modulator rate and is 8 MHz.

$\text{FILTCONx}[14:0]$  are the contents on the filter configuration register excluding the MSB.

For example, an output data rate of 50 SPS can be achieved with SINC3\_MAP enabled by setting the FILTCONx[14:0] bits to a value of 5000.

## SINGLE CYCLE SETTling

The AD7176-2 can be configured by setting the SING\_CYC bit in the ADC mode register so that only fully settled data is output, thus effectively putting the ADC into a single cycle settling mode. This mode achieves single cycle settling by reducing the output data rate to be equal to the settling time of the ADC for the selected output data rate. This bit has no effect with the Sinc5 + Sinc1 at output data rates of 10 kSPS and lower.

Figure 37 shows a step on the analog input with this mode disabled and the Sinc3 filter selected. It takes at least three cycles after the step change for the output to reach the final settled value.

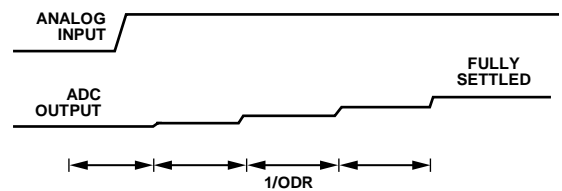


Figure 37. Step Input Without Single Cycle Settling

Figure 38 shows the same step on the analog input but with single cycle settling enabled. It takes at least a single cycle for the output to be fully settled. The output data rate is now reduced to equal the settling time of the filter at the selected output data rate.

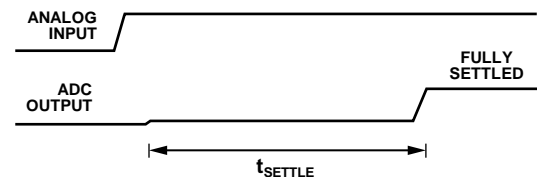


Figure 38. Step Input with Single Cycle Settling

Table 19. AD7176-2 Output Data Rate (ODR), Noise, Settling Time ( $t_{\text{SETTLE}}$ ), and Rejection Using the Sinc3 Filter

Output Data Rate (SPS) <sup>1</sup>	Settling Time (ms) <sup>1</sup>	Switching Rate <sup>1</sup> (Hz)	Notch Frequency (Hz)	Rejection $\pm 1$ Hz (dB) <sup>2</sup>	Noise ( $\mu\text{V rms}$ )	Peak-to-Peak Resolution with 5 V Reference (Bits)
250,000	0.012	83,333	250,000		220	12.8
125,000	0.024	41,667	125,000		27	15.9
62,500	0.048	20,833	62,500		5.1	18.3
50,000	0.060	16,667	50,000		4.3	18.5
31,250	0.096	10,417	31,250		3.2	18.8
25,000	0.120	8333	25,000		2.7	19
15,625	0.192	5208	15,625		2.3	19.4
10,000	0.300	3333	10,000		1.8	19.8
5000	0.600	1667	5000		1.3	20.2
2500	1.200	833	2500		0.91	20.5
1000	3.000	333.3	1000		0.62	21
500	6.000	166.7	500		0.49	21.4
400	7.500	133.3	400		0.45	21.7
200	15.000	66.7	200		0.37	22
100	30.000	33.3	100		0.33	22
59.94	50.004	20.00	59.94	100 (60 Hz)	0.32	22
49.96	60.000	16.67	49.96	100 (50 Hz)	0.31	22
20	150.000	6.67	20		0.31	22
16.667	180.000	5.56	16.667		0.29	22.4
10	300.000	3.33	10	100 (50 Hz and 60 Hz)	0.29	22.4
5	600.000	1.67	5		0.29	22.4

<sup>1</sup> The settling time has been rounded to the nearest microsecond. This is reflected in the output data rate and switching rate. Switching rate =  $1 \div t_{\text{SETTLE}}$ .<sup>2</sup> Master clock = 160 MHz.

**ENHANCED 50 HZ AND 60 HZ REJECTION FILTERS**

The enhanced filters are designed to provide rejection of 50 Hz and 60 Hz simultaneously and to allow the user to trade off settling time and rejection. These filters can operate up to 27.27 SPS or can reject up to 90 dB of 50 Hz  $\pm$  1 Hz and 60 Hz  $\pm$  1 Hz interference. These filters are realized by post filtering the output of the Sinc5 + Sinc1 filter. For this reason, the Sinc5

+ Sinc1 filter must be selected when using the enhanced filters. Table 20 shows the output data rates with the accompanying settling time, rejection, and rms noise. Figure 39 to Figure 46 show the frequency domain plots of the responses from the enhanced filters.

**Table 20. AD7176-2 Enhanced Filters Output Data Rate, Noise, Settling Time ( $t_{\text{SETTLE}}$ ), and Rejection Using the Enhanced Filters**

Output Data Rate (SPS)	Settling Time (ms)	Simultaneous Rejection of 50 Hz $\pm$ 1 Hz and 60 Hz $\pm$ 1 Hz (dB) <sup>1</sup>	Noise ( $\mu$ V rms)	Peak-to-Peak Resolution (Bits)	Comments
27.27	36.67	47	0.15	23.26	See Figure 39 and Figure 40
25	40.0	62	0.14	23.36	See Figure 41 and Figure 42
20	50.0	85	0.125	23.53	See Figure 43 and Figure 44
16.667	60.0	90	0.125	23.53	See Figure 45 and Figure 46

<sup>1</sup> Master clock = 160 MHz.

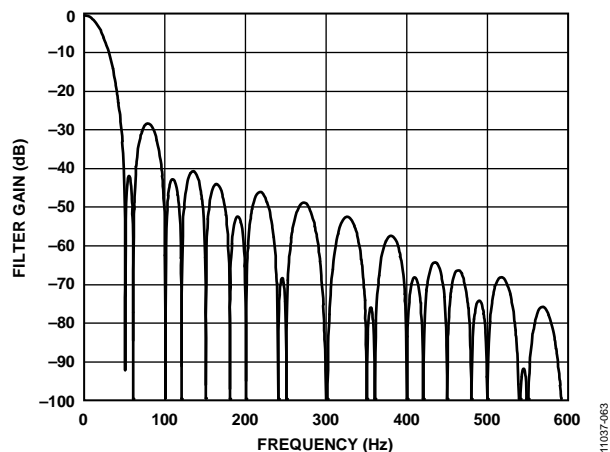


Figure 39. DC to 600 Hz, 27.27 SPS ODR, 36.67 ms Settling Time

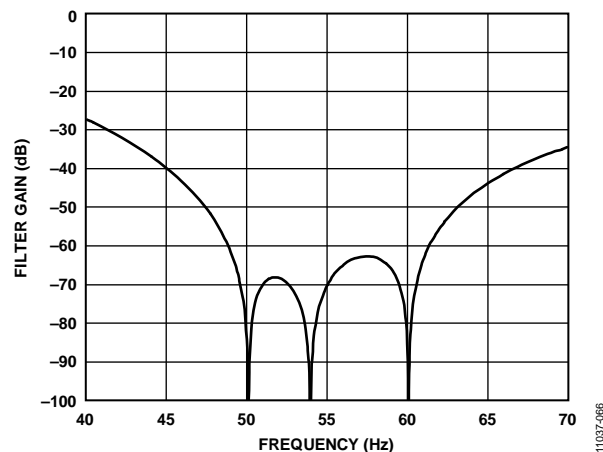


Figure 42. Zoom in 40 Hz to 70 Hz, 25 SPS ODR, 40 ms Settling Time

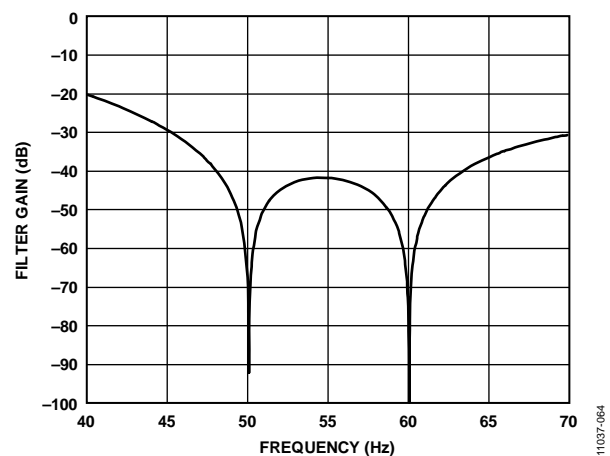


Figure 40. Zoom in 40 Hz to 70 Hz, 27.27 SPS ODR, 36.67 ms Settling Time

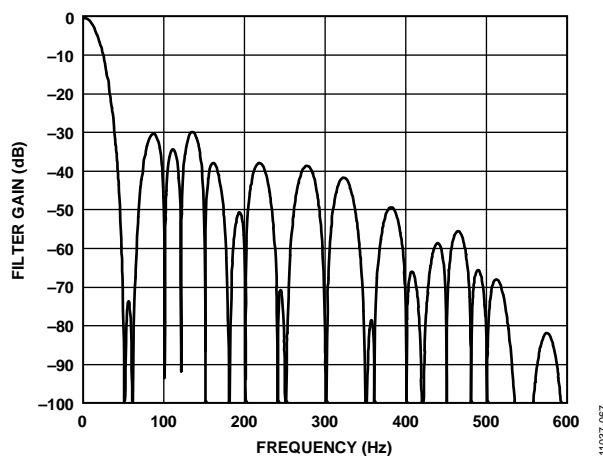


Figure 43. DC to 600 Hz, 20 SPS ODR, 50 ms Settling Time

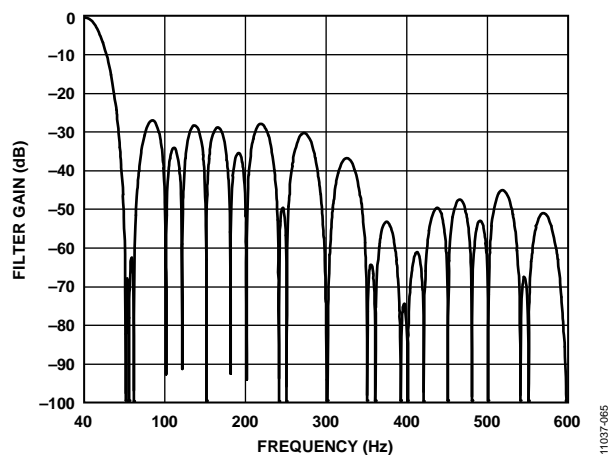


Figure 41. DC to 600 Hz, 25 SPS ODR, 40 ms Settling Time

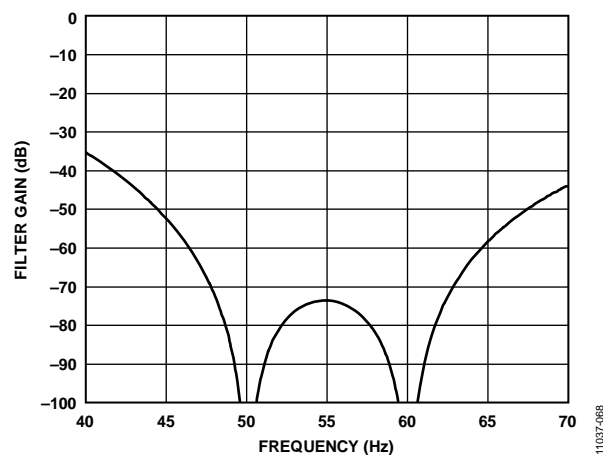


Figure 44. Zoom in 40 Hz to 70 Hz, 20 SPS ODR, 50 ms Settling Time



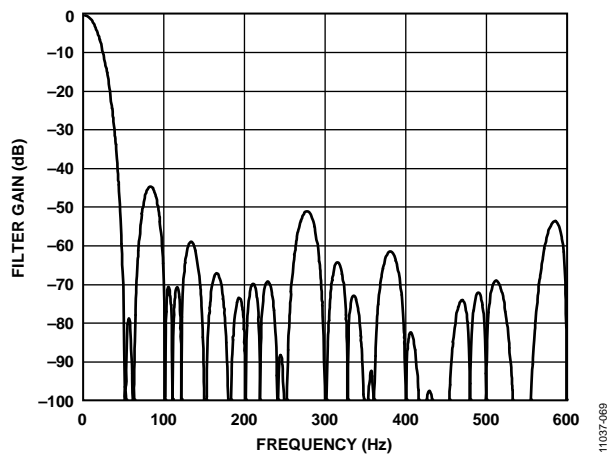


Figure 45. DC to 600 Hz, 16.667 SPS ODR, 60 ms Settling Time

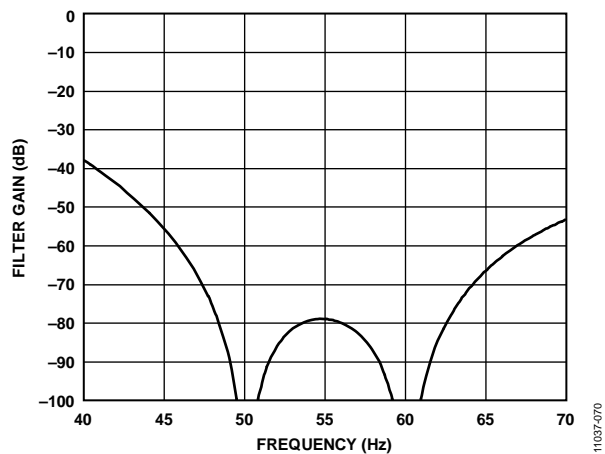


Figure 46. Zoom in 40 Hz to 70 Hz, 16.667 SPS ODR, 60 ms Settling Time

OPERATING MODES

CONTINUOUS CONVERSION MODE

Continuous conversion is the default power-up mode. The AD7176-2 converts continuously, and the RDY bit in the status register goes low each time a conversion is complete. If CS is low, the DOUT/RDY line also goes low when a conversion is complete. To read a conversion, the user writes to the communications register, indicating that the next operation is a read of the data register. When the data-word has been read from the data register, DOUT/RDY goes high. The user can read this register additional times, if required. However, the user must ensure that the data register is not being accessed at the completion of the next conversion; otherwise the new conversion word will be lost.

When several channels are enabled, the ADC automatically sequences through the enabled channels, performing one conversion on each channel. When all channels have been converted, the sequence starts again with the first channel. The channels are converted in order from lowest enabled channel to highest enabled channel. The data register is updated as soon as each conversion is available. The DOUT/RDY pin pulses low each time a conversion is available. The user can then read the conversion while the ADC converts the next enabled channel.

If the DATA\_STAT bit in the interface mode register is set to 1, the contents of the status register, along with the conversion data, are output each time the data register is read. The status register indicates the channel to which the conversion corresponds.

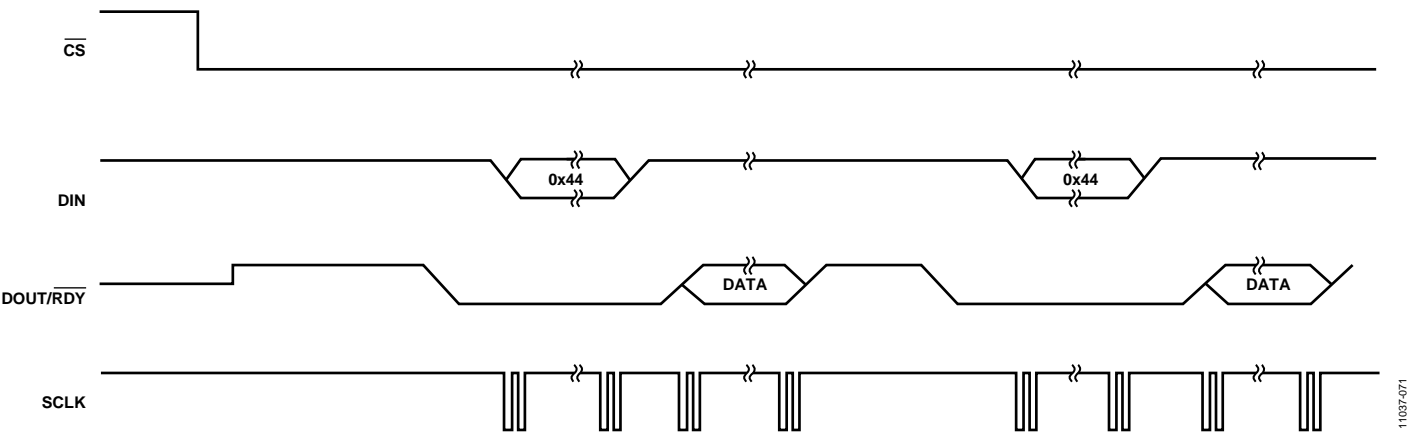


Figure 47. Continuous Conversion Mode

**CONTINUOUS READ MODE**

In continuous read mode, it is not required to write to the communications register before reading ADC data; just apply the required number of SCLKs after DOUT/RDY goes low to indicate the end of a conversion. When the conversion is read, DOUT/RDY returns high until the next conversion is available. In this mode, the data can be read only once. The user must also ensure that the data-word is read before the next conversion is complete. If the user has not read the conversion before the completion of the next conversion or if insufficient serial clocks are applied to the AD7176-2 to read the word, the serial output register is reset when the next conversion is complete, and the new conversion is placed in the output serial register. The ADC must be configured for continuous conversion mode to use continuous read mode.

To enable continuous read mode, set the CONTREAD bit in the interface mode register. When this bit is set, the only serial interface operations possible are reads from the data register. To exit continuous read mode, issue a dummy read of the ADC data register command (0x44) while RDY is low. Alternatively, apply a software reset, that is, 64 SCLKs with CS = 0 and DIN = 1. This resets the ADC and all register contents. These are the only commands that the interface recognizes after it is placed in continuous read mode. DIN should be held low in continuous read mode until an instruction is to be written to the device.

If multiple ADC channels are enabled, each channel is output in turn, with the status bits being appended to the data if DATA\_STAT is set in the interface mode register. The status register indicates the channel to which the conversion corresponds.

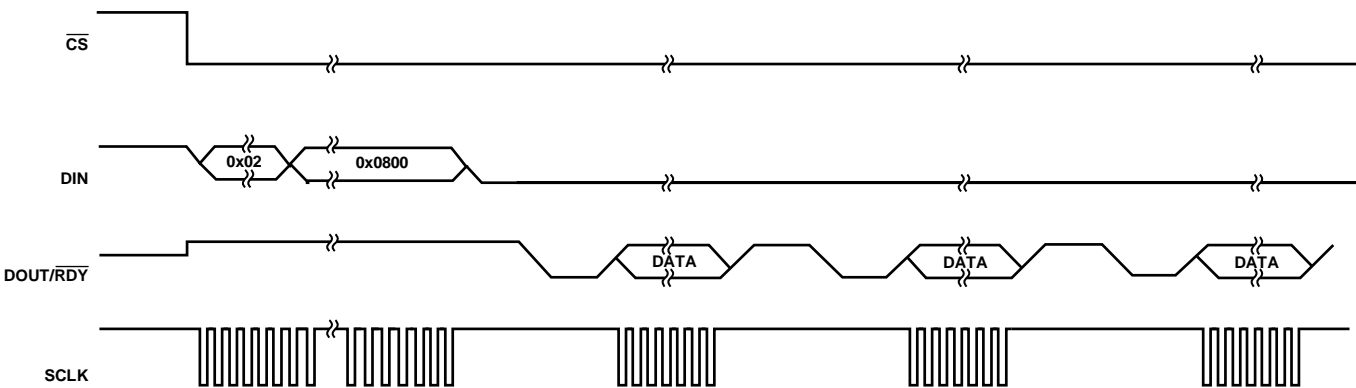


Figure 48. Continuous Read Mode

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SINGLE CONVERSION MODE

In single conversion mode, the AD7176-2 performs a single conversion and is placed in standby mode after the conversion is complete. DOUT/RDY goes low to indicate the completion of a conversion. When the data-word has been read from the data register, DOUT/RDY goes high. The data register can be read several times, if required, even when DOUT/RDY has gone high.

If several channels are enabled, the ADC automatically sequences through the enabled channels and performs a conversion on each channel. When a conversion is started, DOUT/RDY goes high and remains high until a valid conversion is available and CS is low. As soon as the conversion is available,

DOUT/RDY goes low. The ADC then selects the next channel and begins a conversion. The user can read the present conversion while the next conversion is being performed. As soon as the next conversion is complete, the data register is updated; therefore, the user has a limited period in which to read the conversion. When the ADC has performed a single conversion on each of the selected channels, it returns to standby mode.

If the DATA\_STAT bit in the interface mode register is set to 1, the contents of the status register, along with the conversion, are output each time the data register is read. The two LSBs of the status register indicate the channel to which the conversion corresponds.

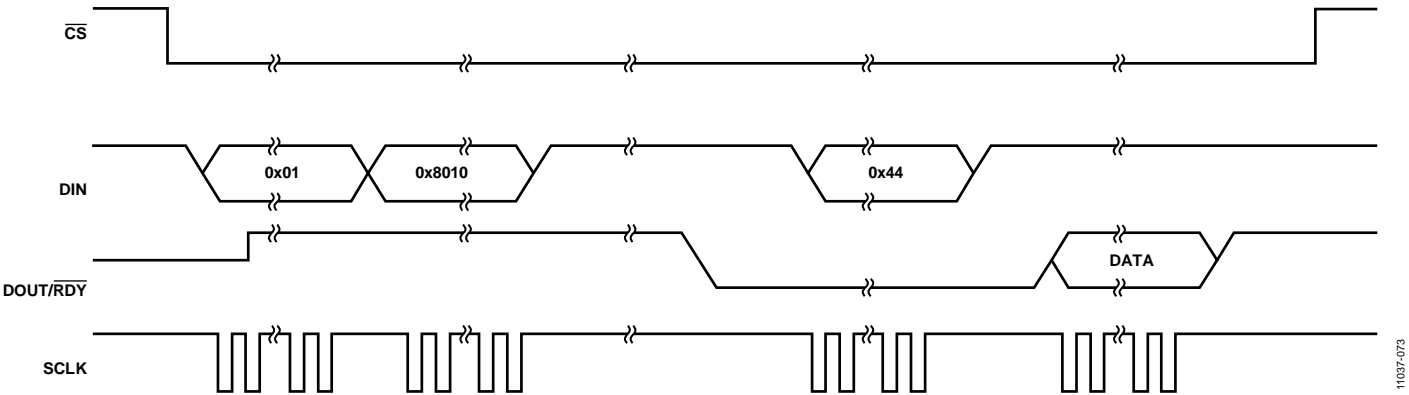


Figure 49. Single Conversion Mode

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## STANDBY AND POWER-DOWN MODES

In standby mode, most blocks are powered down. The LDOs remain active so that registers maintain their contents. The internal reference remains active if enabled, and the crystal oscillator remains active if selected. To power down the reference in standby mode, set the REF\_EN bit in the ADC mode register to 0. To power down the clock in standby mode, set the CLOCKSEL bits in the ADC mode register to 00 (internal oscillator).

In power-down mode, all blocks are powered down, including the LDOs. All registers lose their contents, and the GPIO outputs are placed in tristate. To prevent accidental entry to power-down mode, the ADC must first be placed into standby mode. Exiting power-down mode requires 64 SCLKs with  $\overline{CS} = 0$  and  $DIN = 1$ , that is, a serial interface reset. A delay of 500  $\mu$ s is recommended before issuing a subsequent serial interface command to allow the LDO to power up.

## CALIBRATION MODES

The AD7176-2 provides three calibration modes that can be used to eliminate the offset and gain errors on a per setup basis:

- Internal zero-scale calibration mode
- System zero-scale calibration mode
- System full-scale calibration mode

Only one channel can be active during calibration. After each conversion, the ADC conversion result is scaled using the ADC calibration registers before being written to the data register.

The default value of the offset register is 0x800000, and the nominal value of the gain register is 0x555555. The calibration range of the ADC gain is from  $0.4 \times V_{REF}$  to  $1.05 \times V_{REF}$ . The following equations show the calculations that are used. In unipolar mode, the ideal relationship—that is, not taking into account the ADC gain error and offset error—is as follows:

$$Data = \left[ \frac{0.75 \times V_{IN}}{V_{REF}} \times 2^{23} - (Offset - 0x800000) \right] \times \frac{Gain}{0x400000} \times 2$$

In bipolar mode, the ideal relationship—that is, not taking into account the ADC gain error and offset error—is as follows:

$$Data = \left[ \frac{0.75 \times V_{IN}}{V_{REF}} \times 2^{23} - (Offset - 0x800000) \right] \times \frac{Gain}{0x400000} + 0x800000$$

To start a calibration, write the relevant value to the MODE bits in the ADC mode register. The DOUT/RDY pin and the RDY bit in the status register go high when the calibration initiates. When the calibration is complete, the contents of the corresponding offset or gain register are updated, the RDY bit in the status register is reset, the DOUT/RDY pin returns low (if  $\overline{CS}$  is low), and the AD7176-2 reverts to standby mode.

During an internal offset calibration, the selected positive analog input pin is disconnected, and both modulator inputs are connected internally to the selected negative analog input pin. For this reason, it is necessary to ensure that the voltage on the selected negative analog input pin does not exceed the allowed limits and is free from excessive noise and interference.

System calibrations, however, expect the system zero-scale (offset) and system full-scale (gain) voltages to be applied to the ADC pins before initiating the calibration modes. As a result, errors external to the ADC are removed.

From an operational point of view, treat a calibration like another ADC conversion. An offset calibration, if required, must always be performed before a full-scale calibration. Set the system software to monitor the RDY bit in the status register or the DOUT/RDY pin to determine the end of a calibration via a polling sequence or an interrupt-driven routine. All calibrations require a time equal to the settling time of the selected filter and output data rate to be completed.

An internal offset calibration, system zero-scale calibration, and system full-scale calibration can be performed at any output data rate. Using lower output data rates results in better calibration accuracy and is accurate for all output data rates. A new calibration is required for a given channel if the reference source for that channel is changed.

The offset error is typically  $\pm 40 \mu$ V and an offset calibration reduces the offset error to the order of the noise. The gain error is factory calibrated at ambient temperature. Following this calibration, the gain error is typically  $\pm 0.001\%$ .

The AD7176-2 provides the user with access to the on-chip calibration registers, allowing the microprocessor to read the calibration coefficients of the device and to write its own calibration coefficients. A read or write of the offset and gain registers can be performed at any time except during an internal or self-calibration.

## DIGITAL INTERFACE

The programmable functions of the AD7176-2 are via the SPI serial interface. The serial interface of the AD7176-2 consists of four signals:  $\overline{\text{CS}}$ , DIN, SCLK, and DOUT/RDY. The DIN line is used to transfer data into the on-chip registers, and DOUT/RDY is used to access data from the on-chip registers. SCLK is the serial clock input for the device, and all data transfers (either on DIN or on DOUT/RDY) occur with respect to the SCLK signal.

The DOUT/RDY pin also functions as a data-ready signal, with the line going low if  $\overline{\text{CS}}$  is low when a new data-word is available in the data register. The pin is reset high when a read operation from the data register is complete. The DOUT/RDY pin also goes high before updating the data register to indicate when not to read from the device to ensure that a data read is not attempted while the register is being updated.  $\overline{\text{CS}}$  is used to select a device. It can be used to decode the AD7176-2 in systems where several components are connected to the serial bus.

Figure 2 and Figure 3 show timing diagrams for interfacing to the AD7176-2 using  $\overline{\text{CS}}$  to decode the part. Figure 2 shows the timing for a read operation from the AD7176-2, and Figure 3 shows the timing for a write operation to the AD7176-2. It is possible to read from the data register several times even though the DOUT/RDY line returns high after the first read operation. However, care must be taken to ensure that the read operations are completed before the next output update occurs. In continuous read mode, the data register can be read only once.

The serial interface can operate in 3-wire mode by tying  $\overline{\text{CS}}$  low. In this case, the SCLK, DIN, and DOUT/RDY lines are used to communicate with the AD7176-2. The end of the conversion can also be monitored using the RDY bit in the status register.

The serial interface can be reset by writing 64 SCLKs with  $\overline{\text{CS}} = 0$  and DIN = 1. A reset returns the interface to the state in which it expects a write to the communications register. This operation resets the contents of all registers to their power-on values. Following a reset, allow a period of 500  $\mu\text{s}$  before addressing the serial interface.

## CHECKSUM PROTECTION

The AD7176-2 has a checksum mode, which can be used to improve interface robustness. Using the checksum ensures that only valid data is written to a register and allows data read from a register to be validated. If an error occurs during a register write, the CRC\_ERROR bit is set in the status register. However, to ensure that the register write was successful, the register should be read back and checksum verified.

For CRC checksum calculations during a write operation, the following polynomial is always used:

$$x^8 + x^2 + x + 1$$

During read operations, the user can select between this polynomial and a similar XOR function. The XOR function requires less time to process on the host microcontroller than the polynomial-based checksum. The CRC\_EN bits in the interface mode register enable and disable the checksum and allow the user to select between the polynomial check and the simple XOR check.

The checksum is appended to the end of each read and write transaction. The checksum calculation for the write transaction is calculated using the 8-bit command word and the 8- to 24-bit data. For a read transaction, the checksum is calculated using the command word and the 8- to 32-bit data output. Figure 50 and Figure 51 show SPI write and read transactions, respectively.

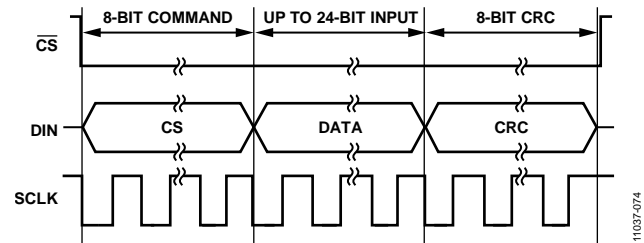


Figure 50. SPI Write Transaction with CRC

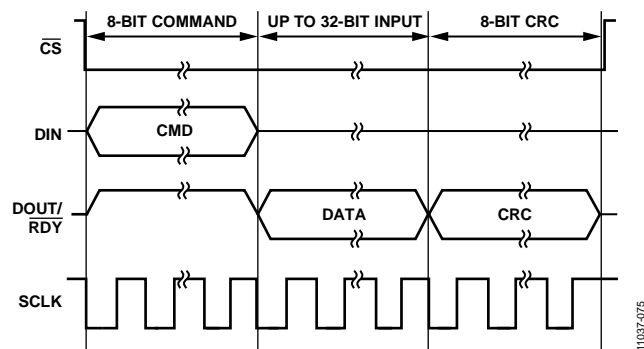


Figure 51. SPI Read Transaction with CRC

If checksum protection is enabled when continuous read mode is active, there is an implied read data command of 0x44 before every data transmission that needs to be accounted for when calculating the checksum value. This ensures a nonzero checksum value even if the ADC data equals 0x000000.

**CRC CALCULATION*****Polynomial***

The checksum, which is 8-bits wide, is generated using the polynomial

$$x^8 + x^2 + x + 1$$

To generate the checksum, the data is left shifted by eight bits to create a number ending in eight Logic 0s. The polynomial is aligned so that its MSB is adjacent to the leftmost Logic 1 of the data. An XOR (exclusive OR) function is applied to the data to produce a new, shorter number. The polynomial is again aligned so that its MSB is adjacent to the leftmost Logic 1 of the new result, and the procedure is repeated. This process is repeated until the original data is reduced to a value less than the polynomial. This is the 8-bit checksum.

**Example of a Polynomial CRC Calculation—24-Bit Word: 0x654321 (Eight Command Bits and 16-Bit Data)**

An example of generating the 8-bit checksum using the polynomial based checksum is as follows:

Initial value	011001010100001100100001	
	01100101010000110010000100000000	left shifted eight bits
$x^8 + x^2 + x + 1$	=	100000111 polynomial
100100100000110010000100000000		XOR result
100000111		polynomial
1000110001100100001000000000		XOR result
100000111		polynomial
111111001000010000000000		XOR result
100000111		polynomial value
111110111000010000000000		XOR result
100000111		polynomial value
1111000000001000000000		XOR result
100000111		polynomial value
1110011100010000000000		XOR result
100000111		polynomial value
11001001001000000000		XOR result
100000111		polynomial value
10010101010000000000		XOR result
100000111		polynomial value
1011011000000000		XOR result
100000111		polynomial value
11010110000000		XOR result
100000111		polynomial value
101010110000		XOR result
100000111		polynomial value
1010001000		XOR result
100000111		polynomial value
10000110		checksum = 0x86.

***XOR Calculation***

The checksum, which is 8-bits wide, is generated by splitting the data into bytes and then performing an XOR of the bytes.

**Example of an XOR Calculation—24-Bit Word: 0x654321 (Eight Command Bits and 16-Bit Data)**

Using the previous example,

Divide into three bytes: 0x65, 0x43, and 0x21

01100101	0x65
01000011	0x43
00100110	XOR result
00100001	0x21
00000111	CRC



## GENERAL-PURPOSE I/O

The AD7176-2 has two general-purpose digital input/output pins: GPIO0 and GPIO1. These are enabled using the IP\_EN0/IP\_EN1 or OP\_EN0/OP\_EN1 bits in the GPIOCON register. When the GPIO0 or GPIO1 pin is enabled as an input, the logic level at the pin is contained in the DATA0 or DATA1 bit, respectively. When the GPIO0 or GPIO1 pin is enabled as an output, the GP\_DATA0 or GP\_DATA1 bits, respectively, determine the logic level output at the pin. The logic levels for these pins are referenced to AVDD1 and AVSS; therefore, outputs have an amplitude of 5 V.

If an external multiplexer is used to increase the channel count, the multiplexer logic pins can be controlled via the AD7176-2 GPIO pins. With the MUX\_IO bit, the GPIOs timing is controlled by the ADC; therefore, the channel change is synchronized with the ADC, eliminating any need for external synchronization.

The SYNC/ERROR pin can also be used as a general-purpose output. When ERR\_EN bits in the GPIOCON register are set to 11, the SYNC/ERROR pin operates as a general-purpose output. In this configuration, the ERR\_DAT bit in the GPIOCON register determines the logic level output at the pin. The logic level for the pin is referenced to IOVDD and DGND, and the SYNC/ERROR pin has an active pull-up.

## 16-BIT/24-BIT CONVERSIONS

By default, the AD7176-2 generates 24-bit conversions. However, the width of the conversions can be reduced to 16 bits. Setting Bit WL16 in the interface mode register to 1 rounds all data conversions to 16 bits. Clearing this bit sets the width of the data conversions to 24 bits.

## SERIAL INTERFACE RESET (DOUT\_RESET)

The serial interface is reset when each read operation is complete. The instant at which the serial interface is reset is programmable. By default, the serial interface is reset after a period of time following the last SCLK rising edge, the SCLK edge on which the LSB is read by the processor. By setting Bit DOUT\_RESET in the interface mode register to 1, the instant at which the interface is reset is controlled by the CS rising edge. In this case, the DOUT/RDY pin continues to output the LSB of the register being read until CS is taken high. Only on the CS rising edge is the interface reset. This configuration is useful if the CS signal is used to frame all read operations. If CS is not used to frame all read operations, DOUT\_RESET should be set to 0 so that the interface is reset following the last SCLK edge in the read operation.

## SYNCHRONIZATION (SYNC/ERROR)

### Normal Synchronization

When the SYNC\_EN bit in the GPIOCON register is set to 0, the SYNC/ERROR pin functions as a synchronization pin. The

SYNC input allows the user to reset the modulator and the digital filter without affecting any of the setup conditions on the part. This allows the user to start gathering samples of the analog input from a known point in time, that is, the rising edge of SYNC. This pin must be low for at least one master clock cycle to ensure that synchronization occurs.

If multiple AD7176-2 devices are operated from a common master clock, they can be synchronized so that their data registers are updated simultaneously. This is normally done after each AD7176-2 has performed its own calibration or has calibration coefficients loaded into its calibration registers. A falling edge on the SYNC pin resets the digital filter and the analog modulator and places the AD7176-2 into a consistent known state. While the SYNC pin is low, the AD7176-2 is maintained in this state. On the SYNC rising edge, the modulator and filter are taken out of this reset state, and on the next master clock edge, the part starts to gather input samples again.

The part is taken out of reset on the master clock falling edge following the SYNC low-to-high transition. Therefore, when multiple devices are being synchronized, the SYNC pin should be taken high on the master clock rising edge to ensure that all devices begin sampling on the master clock falling edge. If the SYNC pin is not taken high in sufficient time, it is possible to have a difference of one master clock cycle between the devices; that is, the instant at which conversions are available differs from part to part by a maximum of one master clock cycle.

The SYNC pin can also be used as a start conversion command. In this mode, the rising edge of SYNC starts a conversion, and the falling edge of RDY indicates when the conversion is complete. The settling time of the filter has to be allowed for each data register update.

### Alternate Synchronization

Setting Bit ALT\_SYNC in the interface mode register to 1 enables an alternate synchronization scheme. The SYNC\_EN bit in the GPIOCON register must be set to 1 to enable this alternate scheme. In this mode, the SYNC pin operates as a start conversion command when several channels of the AD7176-2 are enabled. When SYNC is taken low, the ADC completes the conversion on the current channel, selects the next channel in the sequence, and then waits until SYNC is taken high to commence the conversion. The RDY pin goes low when the conversion is complete on the current channel, and the data register is updated with the corresponding conversion. Therefore, the SYNC command does not interfere with the sampling on the currently selected channel but allows the user to control the instant at which the conversion begins on the next channel in the sequence.

The mode can be used only when several channels are enabled. It is not recommended to use this mode when a single channel is enabled.

## ERROR FLAGS

The status register contains three error bits—ADC\_ERROR, CRC\_ERROR, and REG\_ERROR—that flag errors with the ADC conversion, errors with the CRC check, and errors due to changes in the registers, respectively. In addition, the ERROR pin can indicate that an error has occurred.

### ADC\_ERROR

The ADC\_ERROR bit in the status register flags any errors that occur during the conversion process. The flag is set when an over-voltage or undervoltage occurs on the analog inputs. The ADC also outputs all 0s or all 1s when an undervoltage or overvoltage occurs. This flag is reset only when the overvoltage/undervoltage is removed. It is not reset by a read of the data register.

### CRC\_ERROR

If the CRC value that accompanies a write operation does not correspond with the information sent, the CRC\_ERROR flag is set. The flag is reset as soon as the status register is explicitly read.

### REG\_ERROR

This flag is used in conjunction with the REG\_CHECK bit in the interface mode register. When the REG\_CHECK bit is set, the AD7176-2 monitors the values in the on-chip registers. If a bit changes, the REG\_ERROR bit is set. Therefore, for writes to the on-chip registers, REG\_CHECK should be set to 0. When the registers have been updated, the REF\_CHK bit can be set to 1. The AD7176-2 calculates a checksum of the on-chip registers. If one of the register values has changed, the REG\_ERROR bit is set. If an error is flagged, the REG\_CHECK bit must be set to 0 to clear the REG\_ERROR bit in the status register. The register check function does not monitor the data register, status register, or interface mode register.

### ERROR Pin

When the SYNC\_EN bit in the GPIOCON register is set to 1 and Bit ALT\_SYNC in the interface mode register is set to 0, the SYNC/ERROR pin functions as an error input/output pin or a general-purpose output pin. The ERR\_EN bits in the GPIOCON register determine the function of the pin.

With ERR\_EN bits are set to 10, the pin functions as an open-drain error output pin. The three error bits in the status register (ADC\_ERROR, CRC\_ERROR, and REG\_ERROR) are OR'ed, inverted, and mapped to the ERROR pin. Therefore, the ERROR pin indicates that an error has occurred. The status register must be read to identify the error source.

When ERR\_EN bits are set to 01, the ERROR pin functions as an error input pin. The error pin of another component can be connected to the AD7176-2 ERROR pin so that the AD7176-2 indicates when an error occurs on either itself or the external component. The value on the ERROR pin is inverted and OR'ed with the errors from the ADC conversion, and the result is indicated via the ADC\_ERROR bit in the status register. The value of the ERROR pin is reflected in the ERR\_DAT bit in the status register.

The ERROR pin is disabled when the ERR\_EN bits are set to 00. When the ERR\_EN1 bits are set to 11, the ERROR pin operates as a general-purpose output.

## DATA\_STAT

The contents of the status register can be appended to each conversion on the AD7176-2. This is a useful function if several channels are enabled. Each time a conversion is output, the contents of the status register are appended. The two LSBs of the status register indicate to which channel the conversion corresponds. In addition, the user can determine if any errors are being flagged by the error bits.

## IOSTRENGTH

The serial interface can operate with a power supply as low as 2 V. However, at this low voltage, the DOUT/RDY pin may not have sufficient drive strength if there is moderate parasitic capacitance on the board or the SCLK frequency is high. The IOSTRENGTH bit in the interface mode register increases the drive strength of the DOUT/RDY pin.

## GROUNDING AND LAYOUT

The analog inputs and reference inputs are differential and, therefore, most of the voltages in the analog modulator are common-mode voltages. The high common-mode rejection of the part removes common-mode noise on these inputs. The analog and digital supplies to the [AD7176-2](#) are independent and separately pinned out to minimize coupling between the analog and digital sections of the device. The digital filter provides rejection of broadband noise on the power supplies, except at integer multiples of the master clock frequency.

The digital filter also removes noise from the analog and reference inputs, provided that these noise sources do not saturate the analog modulator. As a result, the [AD7176-2](#) is more immune to noise interference than a conventional high resolution converter. However, because the resolution of the [AD7176-2](#) is high and the noise levels from the converter are so low, care must be taken with regard to grounding and layout.

The printed circuit board (PCB) that houses the ADC must be designed so that the analog and digital sections are separated and confined to certain areas of the board. A minimum etch technique is generally best for ground planes because it results in the best shielding.

In any layout, the user must keep in mind the flow of currents in the system, ensuring that the paths for all return currents are as close as possible to the paths the currents took to reach their destinations.

Avoid running digital lines under the device because this couples noise onto the die and allows the analog ground plane to run under the [AD7176-2](#) to prevent noise coupling. The power supply lines to the [AD7176-2](#) must use as wide a trace as possible to provide low impedance paths and reduce glitches on

the power supply line. Shield fast switching signals like clocks with digital ground to prevent radiating noise to other sections of the board and never run clock signals near the analog inputs. Avoid crossover of digital and analog signals. Run traces on opposite sides of the board at right angles to each other. This reduces the effects of feedthrough on the board. A microstrip technique is by far the best but is not always possible with a double-sided board. In this technique, the component side of the board is dedicated to ground planes, whereas signals are placed on the solder side.

Good decoupling is important when using high resolution ADCs. The [AD7176-2](#) has three power supply pins—AVDD1, AVDD2, and IOVDD. The AVDD1 and AVDD2 pins are referenced to AVSS, and the IOVDD pin is referenced to DGND. AVDD1 and AVDD2 should be decoupled with a 10  $\mu\text{F}$  tantalum capacitor in parallel with a 0.1  $\mu\text{F}$  capacitor to AVSS on each pin. The 0.1  $\mu\text{F}$  capacitor should be placed as close as possible to the device on each supply, ideally right up against the device. IOVDD should be decoupled with a 10  $\mu\text{F}$  tantalum capacitor in parallel with a 0.1  $\mu\text{F}$  capacitor to DGND. All analog inputs should be decoupled to AVSS. If an external reference is used, the REF+ and REF– pins should be decoupled to AVSS.

The [AD7176-2](#) also has two on-board LDO regulators—one that regulates the AVDD2 supply and one that regulates the IOVDD supply. For the REGCAPA pin, it is recommended that 1  $\mu\text{F}$  and 0.1  $\mu\text{F}$  capacitors to AVSS be used. Similarly, for the REGCAPD pin, it is recommended that 1  $\mu\text{F}$  and 0.1  $\mu\text{F}$  capacitors to DGND be used.

If using the [AD7176-2](#) for split supply operation, a separate plane must be used for AVSS.

## REGISTER SUMMARY

Table 21. AD7176-2 Register Summary

Reg	Name	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset	RW	
0x00	COMMS	[7:0]	WEN	R/W	RA							0x00	W
0x00	STATUS	[7:0]	RDY	ADC_ERROR	CRC_ERROR	REG_ERROR	RESERVED		CHANNEL		0x80	R	
0x01	ADCMODE	[15:8]	REF_EN	RESERVED	SING_CYC	RESERVED		DELAY			0x8000	RW	
		[7:0]	RESERVED	MODE			CLOCKSEL		RESERVED				
0x02	IFMODE	[15:8]	RESERVED			ALT_SYNC	IOSTRENGTH	RESERVED		DOUT_RESET	0x0000	RW	
		[7:0]	CONTREAD	DATA_STAT	REG_CHECK	RESERVED	CRC_EN		RESERVED	WL16			
0x03	REGCHECK	[23:16]	REGISTER_CHECK[23:16]									0x000000	R
		[15:8]	REGISTER_CHECK[15:8]										
		[7:0]	REGISTER_CHECK[7:0]										
0x04	DATA	[23:16]	DATA[23:16]									0x000000	R
		[15:8]	DATA[15:8]										
		[7:0]	DATA[7:0]										
0x06	GPIOCON	[15:8]	RESERVED			MUX_IO	SYNC_EN	ERR_EN		ERR_DAT	0x0800	RW	
		[7:0]	RESERVED		IP_EN1	IP_EN0	OP_EN1	OP_EN0	GP_DATA1	GP_DATA0			
0x07	ID	[15:8]	ID[15:8]									0x0C9X	R
		[7:0]	ID[7:0]										
0x10	CHMAP0	[15:8]	CH_EN0	RESERVED	SETUP_SEL0		RESERVED		AINPOS0[4:3]		0x8001	RW	
		[7:0]	AINPOS0[2:0]			AINNEG0							
0x11	CHMAP1	[15:8]	CH_EN1	RESERVED	SETUP_SEL1		RESERVED		AINPOS1[4:3]		0x0001	RW	
		[7:0]	AINPOS1[2:0]			AINNEG1							
0x12	CHMAP2	[15:8]	CH_EN2	RESERVED	SETUP_SEL2		RESERVED		AINPOS2[4:3]		0x0001	RW	
		[7:0]	AINPOS2[2:0]			AINNEG2							
0x13	CHMAP3	[15:8]	CH_EN3	RESERVED	SETUP_SEL3		RESERVED		AINPOS3[4:3]		0x0001	RW	
		[7:0]	AINPOS3[2:0]			AINNEG3							
0x20	SETUPCON0	[15:8]	RESERVED			BI_UNIPOLAR0	RESERVED					0x1020	RW
		[7:0]	RESERVED		REF_SEL0		RESERVED						
0x21	SETUPCON1	[15:8]	RESERVED			BI_UNIPOLAR1	RESERVED					0x1020	RW
		[7:0]	RESERVED		REF_SEL1		RESERVED						
0x22	SETUPCON2	[15:8]	RESERVED			BI_UNIPOLAR2	RESERVED					0x1020	RW
		[7:0]	RESERVED		REF_SEL2		RESERVED						
0x23	SETUPCON3	[15:8]	RESERVED			BI_UNIPOLAR3	RESERVED					0x1020	RW
		[7:0]	RESERVED		REF_SEL3		RESERVED						
0x28	FILTCON0	[15:8]	SINC3_MAP0	RESERVED			ENHFILTEN0	ENHFILT0			0x0000	RW	
		[7:0]	RESERVED	ORDER0		ODR0							
0x29	FILTCON1	[15:8]	SINC3_MAP1	RESERVED			ENHFILTEN1	ENHFILT1			0x0000	RW	
		[7:0]	RESERVED	ORDER1		ODR1							
0x2A	FILTCON2	[15:8]	SINC3_MAP2	RESERVED			ENHFILTEN2	ENHFILT2			0x0000	RW	
		[7:0]	RESERVED	ORDER2		ODR2							
0x2B	FILTCON3	[15:8]	SINC3_MAP3	RESERVED			ENHFILTEN3	ENHFILT3			0x0000	RW	
		[7:0]	RESERVED	ORDER3		ODR3							
0x30	OFFSET0	[23:16]	OFFSET0[23:16]									0x800000	RW
		[15:8]	OFFSET0[15:8]										
		[7:0]	OFFSET0[7:0]										
0x31	OFFSET1	[23:16]	OFFSET1[23:16]									0x800000	RW
		[15:8]	OFFSET1[15:8]										
		[7:0]	OFFSET1[7:0]										
0x32	OFFSET2	[23:16]	OFFSET2[23:16]									0x800000	RW
		[15:8]	OFFSET2[15:8]										
		[7:0]	OFFSET2[7:0]										
0x33	OFFSET3	[23:16]	OFFSET3[23:16]									0x800000	RW
		[15:8]	OFFSET3[15:8]										
		[7:0]	OFFSET3[7:0]										

Reg	Name	Bits	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset	RW
0x38	GAIN0	[23:16]	GAIN0[23:16]								0x5XXXX0	RW
		[15:8]	GAIN0[15:8]									
		[7:0]	GAIN0[7:0]									
0x39	GAIN1	[23:16]	GAIN1[23:16]								0x5XXXX0	RW
		[15:8]	GAIN1[15:8]									
		[7:0]	GAIN1[7:0]									
0x3A	GAIN2	[23:16]	GAIN2[23:16]								0x5XXXX0	RW
		[15:8]	GAIN2[15:8]									
		[7:0]	GAIN2[7:0]									
0x3B	GAIN3	[23:16]	GAIN3[23:16]								0x5XXXX0	RW
		[15:8]	GAIN3[15:8]									
		[7:0]	GAIN3[7:0]									

## REGISTER DETAILS

### COMMUNICATIONS REGISTER

Address: 0x00, Reset: 0x00, Name: COMMS

Table 22. Bit Descriptions for COMMS

Bits	Bit Name	Settings	Description	Reset	Access
7	WEN		This bit must be low to begin communications with the ADC.	0x0	W
6	R/W	0 1	This bit determines if the command is a read or write operation. Write command Read command	0x0	W
[5:0]	RA	000000 000001 000010 000011 000100 000110 000111 010000 010001 010010 010011 100000 100001 100010 100011 101000 101001 101010 101011 110000 110001 110010 110011 111000 111001 111010	The register address bits determine which register is to be read from or written to as part of the current communication. Status Register ADC Mode Register Interface Mode Register Register Checksum Register Data Register GPIO Configuration Register ID Register Channel Map 1 Register Channel Map 2 Register Channel Map 3 Register Channel Map 4 Register Setup Configuration 1 Register Setup Configuration 2 Register Setup Configuration 3 Register Setup Configuration 4 Register Filter Configuration 1 Register Filter Configuration 2 Register Filter Configuration 3 Register Filter Configuration 4 Register Offset 1 Register Offset 2 Register Offset 3 Register Offset 4 Register Gain 1 Register Gain 2 Register Gain 3 Register	0x00	W

**STATUS REGISTER****Address: 0x00, Reset: 0x80, Name: STATUS**

The Status Register is an 8-bit register that contains ADC and serial interface status information. It can optionally be appended to the Data Register by setting the DATA\_STAT bit in the Interface Mode Register.

**Table 23. Bit Descriptions for STATUS**

Bits	Bit Name	Settings	Description	Reset	Access
7	RDY	0 New data result available 1 Awaiting new data result	The status of RDY is output to the DOUT/RDY pin whenever CS is low and a register is not being read. This bit goes low when the ADC has written a new result to the Data Register. In ADC calibration modes, this bit goes low when the ADC has written the calibration result. RDY is brought high automatically by a read of the Data Register.	0x1	R
6	ADC_ERROR	0 No Error 1 Error	This bit by default indicates if an ADC overrange or underrange has occurred. The ADC result will be clamped to $\pm$ full scale if this happens. This bit is updated when the ADC result is written and is cleared by removing the overrange or underrange condition on the analog inputs.	0x0	R
5	CRC_ERROR	0 No Error 1 CRC Error	This bit indicates if a CRC error has taken place during a register write. For register reads, the host microcontroller determines if a CRC error has occurred. This bit is cleared by a read of this register.	0x0	R
4	REG_ERROR	0 No Error 1 Error	This bit indicates if the content of one of the internal registers has changed from the value calculated when the register integrity check was activated. The check is activated by setting the REG_CHECK bit in the Interface Mode Register. This bit is cleared by clearing the REG_CHECK bit.	0x0	R
[3:2]	RESERVED		These bits are reserved.	0x0	R
[1:0]	CHANNEL	00 Channel 0 01 Channel 1 10 Channel 2 11 Channel 3	These bits indicate which channel was active for the ADC conversion whose result is currently in the Data Register. This may be different from the channel currently being converted. The mapping is a direct map from the Channel Map Register; therefore, Channel 0 results in 0x0 and Channel 3 results in 0x3.	0x0	R

**ADC MODE REGISTER****Address: 0x01, Reset: 0x8000, Name: ADCMODE**

The ADC Mode Register controls the operating mode of the ADC and the master clock selection. A write to the ADC Mode Register resets the filter and the  $\overline{\text{RDY}}$  bits and starts a new conversion or calibration.

**Table 24. Bit Descriptions for ADCMODE**

Bits	Bit Name	Settings	Description	Reset	Access
15	REF_EN	0 1	Enables internal reference and outputs a buffered 2.5 V to the REFOUT pin. Disabled Enabled	0x1	RW
14	RESERVED		This bit is reserved and should be set to 0.	0x0	R
13	SING_CYC	0 1	This bit can be used when only a single channel is active to set the ADC to only output at the settled filter data rate. Disabled Enabled	0x0	RW
[12:11]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
[10:8]	DELAY	000 001 010 011 100 101 110 111	These bits allow a programmable delay to be added after a channel switch to allow for settling of external circuitry before the ADC starts processing its input. 0 4 $\mu\text{s}$ 16 $\mu\text{s}$ 40 $\mu\text{s}$ 100 $\mu\text{s}$ 200 $\mu\text{s}$ 500 $\mu\text{s}$ 1 ms	0x0	RW
7	RESERVED		This bit is reserved and should be set to 0.	0x0	R
[6:4]	MODE	000 001 010 011 100 110 111	These bits control the operating mode of the ADC. Details can be found in the Operating Modes section. Continuous Conversion Mode Single Conversion Mode Standby Mode Power-Down Mode Internal Offset Calibration System Offset Calibration System Gain Calibration	0x0	RW
[3:2]	CLOCKSEL	00 01 10 11	This bit is used to select the ADC clock source. Selecting internal oscillator also enables the internal oscillator. Internal oscillator Internal oscillator output on XTAL2 pin External clock input on XTAL2 pin External crystal on XTAL1 and XTAL2 pins	0x0	RW
[1:0]	RESERVED		These bits are reserved and should be set to 0.	0x0	R



**INTERFACE MODE REGISTER**

Address: 0x02, Reset: 0x0000, Name: IFMODE

The Interface Mode Register configures various serial interface options.

**Table 25. Bit Descriptions for IFMODE**

Bits	Bit Name	Settings	Description	Reset	Access
[15:13]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
12	ALT_SYNC	0 Disabled 1 Enabled	This bit enables a different behavior of the $\overline{\text{ERROR\_SYNC}}$ pin to allow the use of $\overline{\text{ERROR\_SYNC}}$ as a control for conversions when cycling channels (see the description of the SYNC_EN bit in the GPIO Configuration Register for details).	0x0	RW
11	IOSTRENGTH	0 Disabled (default) 1 Enabled	This bit controls the drive strength of the DOUT pin. This bit should be set when reading from the serial interface at high speed with low IOVDD supply and moderate capacitance.	0x0	RW
[10:9]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
8	DOUT_RESET	0 Disabled 1 Enabled	This bit prevents the DOUT/ $\overline{\text{RDY}}$ pin from switching from outputting DOUT to outputting $\overline{\text{RDY}}$ soon after the last rising edge of SCLK during a read operation. Instead, the DOUT/ $\overline{\text{RDY}}$ pin will continue to output the LSB of the data until $\overline{\text{CS}}$ goes high. This allows for longer hold times for the SPI master to sample the LSB of the data. When this bit is set, $\overline{\text{CS}}$ must not be tied low.	0x0	RW
7	CONTREAD	0 Disabled 1 Enabled	This enables continuous read of the ADC data register. The ADC should be configured in continuous conversion mode to use continuous read. For more details, see the Operating Modes section.	0x0	RW
6	DATA_STAT	0 Disabled 1 Enabled	This enables the Status Register to be appended to the Data Register when read so that channel and status information are transmitted with the data. This is the only way to be sure that the channel bits read from the Status Register correspond to the data in the Data Register.	0x0	RW
5	REG_CHECK	0 Disabled 1 Enabled	This bit enables a register integrity checker, which can be used to monitor any change in the value of the user registers. To use this feature, all other registers should be configured as desired, with this bit cleared. Then write to this register to set the REG_CHECK bit to 1. If the contents of any of the registers change, the REG_ERROR bit is set in the Status Register. To clear the error, the REG_CHECK bit should be set to 0. Neither the Interface Mode Register nor the ADC Data or Status Register is included in the registers that are checked. If a register needs to have a new value written, this bit should first be cleared; otherwise, an error will be flagged falsely when the new register contents are written.	0x0	RW
4	RESERVED		This bit is reserved and should be set to 0.	0x0	R

Bits	Bit Name	Settings	Description	Reset	Access
[3:2]	CRC_EN	00 Disabled. 01 XOR checksum enabled for register read transactions. Register writes will still use CRC with these bits set. 10 CRC checksum enabled for read and write transactions.	Enables CRC protection of register reads/writes. CRC increases the number of bytes in a serial interface transfer by one. See the CRC Calculation section for more details.	0x00	RW
1	RESERVED		This bit is reserved and should be set to 0.	0x0	R
0	WL16	0 24-bit data 1 16-bit data	Changes the ADC Data Register to 16 bits. The ADC is not reset by a write to the Interface Mode Register; therefore, the ADC result will not be rounded to the correct word length immediately after writing to these bits. The first new ADC result will be correct.	0x0	RW

## REGISTER CHECK

Address: 0x03, Reset: 0x000000, Name: REGCHECK

This Register Check Register is a 24-bit checksum calculated by exclusively OR'ing the contents of the user registers. The REG\_CHECK bit in the Interface Mode Register must be set for this to operate; otherwise, the register reads 0.

Table 26. Bit Descriptions for REGCHECK

Bits	Bit Name	Settings	Description	Reset	Access
[23:0]	REGISTER_CHECK		This register contains the 24-bit checksum of user registers when the REG_CHECK bit is set in the Interface Mode Register.	0x000000	R

## DATA REGISTER

Address: 0x04, Reset: 0x000000, Name: DATA

The Data Register contains the ADC conversion result. The encoding is offset binary, or it can be changed to unipolar by the BI\_UNIPOLAR bit in the Setup Configuration Register. Reading the Data Register brings the  $\overline{\text{RDY}}$  bit and pin high if they had been low. The ADC result can be read multiple times; however, because  $\overline{\text{RDY}}$  has been brought high, it is not possible to know if another ADC result is imminent. The ADC will not write a new result into the data register if the register is currently being read.

Table 27. Bit Descriptions for DATA

Bits	Bit Name	Settings	Description	Reset	Access
[23:0]	DATA		This register contains the ADC conversion result. If DATA_STAT is set in the Interface Mode Register, then the Status Register is appended to this register when read, making this a 32-bit register. If WL16 is set in the Interface Mode Register, then this register is rounded to 16 bits.	0x000000	R

**GPIO CONFIGURATION REGISTER**

Address: 0x06, Reset: 0x0800, Name: GPIOCON

The GPIO Configuration Register controls the general-purpose I/O pins of the ADC.

**Table 28. Bit Descriptions for GPIOCON**

Bits	Bit Name	Settings	Description	Reset	Access
[15:13]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
12	MUX_IO		This bit allows the ADC to control an external multiplexer, using GPIO0/GPIO1 in sync with the internal channel sequencing. The analog input pins used for a channel can still be selected on a per channel basis. Therefore, it is possible to have a 4-channel multiplexer in front of AIN0/AIN1 and another in front of AIN2/AIN3, giving a total of eight differential channels with the AD7175-2. However, only four channels at a time can be automatically sequenced. A delay can be inserted after switching an external multiplexer (see the DELAY bits in the ADC Mode Register).	0x0	RW
11	SYNC_EN	0 Disabled 1 Enabled	This bit enables the SYNC/ERROR pin as a sync input. When set low, the SYNC/ERROR pin holds the ADC and filter in reset until SYNC/ERROR goes high. An alternative operation of the SYNC/ERROR pin is available when the ALT_SYNC bit in the Interface Mode Register is set. This mode only works when multiple channels are enabled. In this case, a low on the SYNC/ERROR pin does not immediately reset the filter/modulator. Instead, if the SYNC/ERROR pin is low when the channel is due to be switched, the modulator and filter are prevented from starting a new conversion. Bringing SYNC/ERROR high begins the next conversion. This alternative sync mode allows SYNC/ERROR to be used while cycling through channels.	0x1	RW
[10:9]	ERR_EN	00 Disabled 01 SYNC/ERROR is an error input. The (inverted) readback state is OR'ed with other error sources and is available in the ADC_ERROR bit in the Status Register. The SYNC/ERROR pin state can also be read from the ERR_DAT bit in this register. 10 SYNC/ERROR is an open-drain error output. The Status Register error bits are OR'ed, inverted, and mapped to the SYNC/ERROR pin. SYNC/ERROR pins of multiple devices can be wired together to a common pull-up resistor so that an error on any device can be observed. 11 SYNC/ERROR is a general-purpose output. The status of the pin is controlled by the ERR_DAT bit in this register. This is referenced between IOVDD and DGND, as opposed to the AVDD1 and AVSS levels used by the general-purpose I/O pins. It has an active pull-up in this case.	These bits enable the SYNC/ERROR pin as an error input/output.	0x0	RW
8	ERR_DAT		This bit determines the logic level at the ERROR pin if the pin is enabled as a general-purpose output. It reflects the readback status of the pin if the pin is enabled as an input.	0x0	RW
[7:6]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
5	IP_EN1	0 Disabled 1 Enabled	This bit turns GPIO1 into an input. Input should equal AVDD5 or AVSS.	0x0	RW
4	IP_EN0	0 Disabled 1 Enabled	This bit turns GPIO0 into an input. Input should equal AVDD5 or AVSS.	0x0	RW
3	OP_EN1	0 Disabled 1 Enabled	This bit turns GPIO1 into an output. Outputs are referenced between AVDD1 and AVSS.	0x0	RW
2	OP_EN0		This bit turns GPIO0 into an output. Outputs are referenced between AVDD1 and AVSS.	0x0	RW

Bits	Bit Name	Settings	Description	Reset	Access
		0	Disabled		
		1	Enabled		
1	GP_DATA1		This bit is the readback or write data for GPIO1.	0x0	RW
0	GP_DATA0		This bit is the readback or write data for GPIO0.	0x0	RW

## ID REGISTER

Address: 0x07, Reset: 0x0C9X, Name: ID

The ID register returns a 16-bit ID. For the [AD7176-2](#), this should be 0x0C94.

**Table 29. Bit Descriptions for ID**

Bits	Bit Name	Settings	Description	Reset	Access
[15:0]	ID	0x0C9X	The ID register returns a 16-bit ID code that is specific to the ADC. <a href="#">AD7176-2</a>	0x0C9X	R

**CHANNEL MAP REGISTER 0****Address: 0x10, Reset: 0x8001, Name: CHMAP0**

The Channel Map Registers are 16-bit registers that are used to select which channels are currently active, which inputs are selected for each channel, and which setup should be used to configure the ADC for that channel.

**Table 30. Bit Descriptions for CHMAP0**

Bits	Bit Name	Settings	Description	Reset	Access
15	CH_EN0	0 1	This bit enables Channel 0. If more than one channel is enabled, the ADC will automatically sequence between them. Disabled Enabled (default)	0x1	RW
14	RESERVED		This bit is reserved and should be set to 0.	0x0	R
[13:12]	SETUP_SEL0	000 001 010 011	These bits identify which of the four setups are used to configure the ADC for this channel. A setup comprises a set of four registers: Setup Configuration Register, Filter Configuration Register, Offset Register, Gain Register. All channels can use the same setup, in which case the same 3-bit value should be written to these bits on all active channels, or up to four channels can be configured differently. Setup 0 Setup 1 Setup 2 Setup 3	0x0	RW
[11:10]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
[9:5]	AINPOS0	00000 00001 00010 00011 00100 10101 10110	These bits select which of the analog inputs is connected to the positive input of the ADC for this channel. AIN0 (default) AIN1 AIN2 AIN3 AIN4 REF+ REF–	0x0	RW
[4:0]	AINNEG0	00000 00001 00010 00011 00100 10101 10110	These bits select which of the analog inputs is connected to the negative input of the ADC for this channel. AIN0 AIN1 (default) AIN2 AIN3 AIN4 REF+ REF–	0x1	RW

**CHANNEL MAP REGISTER 1****Address: 0x11, Reset: 0x0001, Name: CHMAP1**

The Channel Map Registers are 16-bit registers that are used to select which channels are currently active, which inputs are selected for each channel, and which setup should be used to configure the ADC for that channel.

**Table 31. Bit Descriptions for CHMAP1**

Bits	Bit Name	Settings	Description	Reset	Access
15	CH_EN1	0 1	This bit enables Channel 1. If more than one channel is enabled, the ADC will automatically sequence between them. Disabled (default) Enabled	0x0	RW
14	RESERVED		This bit is reserved and should be set to 0.	0x0	R
[13:12]	SETUP_SEL1	000 001 010 011	These bits identify which of the four setups are used to configure the ADC for this channel. A setup comprises a set of four registers: Setup Configuration Register, Filter Configuration Register, Offset Register, Gain Register. All channels can use the same setup, in which case the same 3-bit value should be written to these bits on all active channels, or up to four channels can be configured differently. Setup 0 Setup 1 Setup 2 Setup 3	0x0	RW
[11:10]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
[9:5]	AINPOS1	00000 00001 00010 00011 00100 10101 10110	These bits select which of the analog inputs is connected to the positive input of the ADC for this channel. AIN0 (default) AIN1 AIN2 AIN3 AIN4 REF+ REF–	0x0	RW
[4:0]	AINNEG1	00000 00001 00010 00011 00100 10101 10110	These bits select which of the analog inputs is connected to the negative input of the ADC for this channel. AIN0 AIN1 (default) AIN2 AIN3 AIN4 REF+ REF–	0x1	RW

**CHANNEL MAP REGISTER 2****Address: 0x12, Reset: 0x0001, Name: CHMAP2**

The Channel Map Registers are 16-bit registers that are used to select which channels are currently active, which inputs are selected for each channel, and which setup should be used to configure the ADC for that channel.

**Table 32. Bit Descriptions for CHMAP2**

Bits	Bit Name	Settings	Description	Reset	Access
15	CH_EN2	0 1	This bit enables Channel 2. If more than one channel is enabled, the ADC will automatically sequence between them. Disabled (default) Enabled	0x0	RW
14	RESERVED		This bit is reserved and should be set to 0.	0x0	R
[13:12]	SETUP_SEL2	000 001 010 011	These bits identify which of the four setups are used to configure the ADC for this channel. A setup comprises a set of four registers: Setup Configuration Register, Filter Configuration Register, Offset Register, Gain Register. All channels can use the same setup, in which case the same 3-bit value should be written to these bits on all active channels, or up to four channels can be configured differently. Setup 0 Setup 1 Setup 2 Setup 3	0x0	RW
[11:10]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
[9:5]	AINPOS2	00000 00001 00010 00011 00100 10101 10110	These bits select which of the analog inputs is connected to the positive input of the ADC for this channel. AIN0 (default) AIN1 AIN2 AIN3 AIN4 REF+ REF–	0x0	RW
[4:0]	AINNEG2	00000 00001 00010 00011 00100 10101 10110	These bits select which of the analog inputs is connected to the negative input of the ADC for this channel. AIN0 AIN1 (default) AIN2 AIN3 AIN4 REF+ REF–	0x1	RW

**CHANNEL MAP REGISTER 3****Address: 0x13, Reset: 0x0001, Name: CHMAP3**

The Channel Map Registers are 16-bit registers that are used to select which channels are currently active, which inputs are selected for each channel, and which setup should be used to configure the ADC for that channel.

**Table 33. Bit Descriptions for CHMAP3**

Bits	Bit Name	Settings	Description	Reset	Access
15	CH_EN3	0 1	This bit enables Channel 3. If more than one channel is enabled, the ADC will automatically sequence between them. Disabled (default) Enabled	0x0	RW
14	RESERVED		This bit is reserved and should be set to 0.	0x0	R
[13:12]	SETUP_SEL3	000 001 010 011	These bits identify which of the four setups are used to configure the ADC for this channel. A setup comprises a set of four registers: Setup Configuration Register, Filter Configuration Register, Offset Register, Gain Register. All channels can use the same setup, in which case the same 3-bit value should be written to these bits on all active channels, or up to four channels can be configured differently. Setup 0 Setup 1 Setup 2 Setup 3	0x0	RW
[11:10]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
[9:5]	AINPOS3	00000 00001 00010 00011 00100 10101 10110	These bits select which of the analog inputs is connected to the positive input of the ADC for this channel. AIN0 (default) AIN1 AIN2 AIN3 AIN4 REF+ REF–	0x0	RW
[4:0]	AINNEG3	00000 00001 00010 00011 00100 10101 10110	These bits select which of the analog inputs is connected to the negative input of the ADC for this channel. AIN0 AIN1 (default) AIN2 AIN3 AIN4 REF+ REF–	0x1	RW



**SETUP CONFIGURATION REGISTER 0****Address: 0x20, Reset: 0x1020, Name: SETUPCON0**

The Setup Configuration Registers are 16-bit registers that configure the reference selection and output coding of the ADC.

**Table 34. Bit Descriptions for SETUPCON0**

Bits	Bit Name	Settings	Description	Reset	Access
[15:13]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
12	BI_UNIPOLAR0	0 1	This bit sets the output coding of the ADC for Setup 0. Unipolar coded output Offset binary coded output	0x1	RW
[11:6]	RESERVED		These bits are reserved and should be set to 0.	0x00	R
[5:4]	REF_SEL0	00 10 11	These bits allow you to select the reference source for ADC conversion on Setup 0. External Reference. Internal 2.5 V Reference. This must also be enabled in the ADC Mode Register. AVDD1 – AVSS. This can be used to as a diagnostic to validate other reference values.	0x2	RW
[3:0]	RESERVED		These bits are reserved and should be set to 0.	0x0	R

**SETUP CONFIGURATION REGISTER 1****Address: 0x21, Reset: 0x1020, Name: SETUPCON1**

The Setup Configuration Registers are 16-bit registers that configure the reference selection and output coding of the ADC.

**Table 35. Bit Descriptions for SETUPCON1**

Bits	Bit Name	Settings	Description	Reset	Access
[15:13]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
12	BI_UNIPOLAR1	0 1	This bit sets the output coding of the ADC for Setup 1. Unipolar coded output Offset binary coded output	0x1	RW
[11:6]	RESERVED		These bits are reserved and should be set to 0.	0x00	R
[5:4]	REF_SEL1	00 10 11	These bits allow you to select the reference source for ADC conversion on Setup 1. External Reference Internal 2.5 V Reference. This must also be enabled in the ADC Mode Register. AVDD1 – AVSS. This can be used to as a diagnostic to validate other reference values.	0x2	RW
[3:0]	RESERVED		These bits are reserved and should be set to 0.	0x0	R

**SETUP CONFIGURATION REGISTER 2****Address: 0x22, Reset: 0x1020, Name: SETUPCON2**

The Setup Configuration Registers are 16-bit registers that configure the reference selection and output coding of the ADC.

**Table 36. Bit Descriptions for SETUPCON2**

Bits	Bit Name	Settings	Description	Reset	Access
[15:13]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
12	BI_UNIPOLAR2	0 1	This bit sets the output coding of the ADC for Setup 2. Unipolar coded output Offset binary coded output	0x1	RW
[11:6]	RESERVED		These bits are reserved and should be set to 0.	0x00	R
[5:4]	REF_SEL2	00 10 11	These bits allow you to select the reference source for ADC conversion on Setup 2. External Reference Internal 2.5 V Reference. This must also be enabled in the ADC Mode Register. AVDD1 – AVSS. This can be used to as a diagnostic to validate other reference values.	0x2	RW
[3:0]	RESERVED		These bits are reserved and should be set to 0.	0x0	R

**SETUP CONFIGURATION REGISTER 3****Address: 0x23, Reset: 0x1020, Name: SETUPCON3**

The Setup Configuration Registers are 16-bit registers that configure the reference selection and output coding of the ADC.

**Table 37. Bit Descriptions for SETUPCON3**

Bits	Bit Name	Settings	Description	Reset	Access
[15:13]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
12	BI_UNIPOLAR3	0 1	This bit sets the output coding of the ADC for Setup 3. Unipolar coded output Offset binary coded output	0x1	RW
[11:6]	RESERVED		These bits are reserved and should be set to 0.	0x00	R
[5:4]	REF_SEL3	00 10 11	These bits allow you to select the reference source for ADC conversion on Setup 3. External Reference Internal 2.5 V Reference. This must also be enabled in the ADC Mode Register. AVDD1 – AVSS. This can be used to as a diagnostic to validate other reference values.	0x2	RW
[3:0]	RESERVED		These bits are reserved and should be set to 0.	0x0	R

**FILTER CONFIGURATION REGISTER 0****Address: 0x28, Reset: 0x0000, Name: FILTCON0**

The Filter Configuration Registers are 16-bit registers that configure the ADC data rate and filter options. Writing to any of these registers resets any active ADC conversion and restarts converting at the first channel in the sequence.

**Table 38. Bit Descriptions for FILTCON0**

Bits	Bit Name	Settings	Description	Reset	Access
15	SINC3_MAP0		If this bit is set, the mapping of the Filter Register changes to directly program the decimation rate of the Sinc3 filter for Setup 0. All other options are eliminated. This allows for fine tuning of the output data rate and filter notch for rejection of specific frequencies. The data rate when on a single channel equals $F_{MOD}/(32 \times FILTCON0[14:0])$ .	0x0	RW
[14:12]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
11	ENHFILTEN0	0 1	This bit enables various post filters for enhanced 50 Hz/60 Hz rejection for Setup 0. The ORDER bits must be set to 00 to select the Sinc5 + Sinc1 filter for this to work. 0 Disabled 1 Enabled	0x0	RW
[10:8]	ENHFILTO	010 011 101 110	These bits select between various post filters for enhanced 50 Hz/60 Hz rejection for Setup 0. 010 27 SPS, 47 dB rejection, 36.7 ms settling 011 25 SPS, 62 dB rejection, 40 ms settling 101 20 SPS, 86 dB rejection, 50 ms settling 110 16.67 SPS, 92 dB rejection, 60 ms settling	0x0	RW
7	RESERVED		This bit is reserved and should be set to 0.	0x0	R
[6:5]	ORDER0	00 11	These bits control the order of the digital filter that processes the modulator data for Setup 0. 00 Sinc5 + Sinc1 (default) 11 Sinc3	0x0	RW
[4:0]	ODR0	00000 00001 00010 00011 00100 00101 00110 00111 01000 01001 01010 01011 01100 01101 01110 01111 10000 10001 10010 10011 10100	These bits control the output data rate of the ADC and, therefore, the settling time and noise for Setup 0. 250,000 125,000 62,500 50,000 31,250 25,000 15,625 10,000 5000 2500 1000 500 397.5 200 100 59.94 49.96 20 16.667 10 5	0x0	RW

**FILTER CONFIGURATION REGISTER 1**

Address: 0x29, Reset: 0x0000, Name: FILTCON1

The Filter Configuration Registers are 16-bit registers that configure the ADC data rate and filter options. Writing to any of these registers resets any active ADC conversion and restarts converting at the first channel in the sequence.

**Table 39. Bit Descriptions for FILTCON1**

Bits	Bit Name	Settings	Description	Reset	Access
15	SINC3_MAP1		If this bit is set, the mapping of the Filter Register changes to directly program the decimation rate of the Sinc3 filter for Setup 1. All other options are eliminated. This allows for fine tuning of the output data rate and filter notch for rejection of specific frequencies. The data rate when on a single channel equals $F_{MOD}/(32 \times FILTCON1[14:0])$ .	0x0	RW
[14:12]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
11	ENHFILTEN1	0 Disabled 1 Enabled	This bit enables various post filters for enhanced 50 Hz/60 Hz rejection for Setup 1. The ORDER bits must be set to 00 to select the Sinc5 + Sinc1 filter for this to work.	0x0	RW
[10:8]	ENHFILT1	010 27 SPS, 47 dB rejection, 36.7 ms settling 011 25 SPS, 62 dB rejection, 40 ms settling 101 20 SPS, 86 dB rejection, 50 ms settling 110 16.67 SPS, 92 dB rejection, 60 ms settling	These bits select between various post filters for enhanced 50 Hz/60 Hz rejection for Setup 1.	0x0	RW
7	RESERVED		This bit is reserved and should be set to 0.	0x0	R
[6:5]	ORDER1	00 Sinc5 + Sinc1 (default) 11 Sinc3	These bits control the order of the digital filter that processes the modulator data for Setup 1.	0x0	RW
[4:0]	ODR1	00000 250,000 00001 125,000 00010 62,500 00011 50,000 00100 31,250 00101 25,000 00110 15,625 00111 10,000 01000 5000 01001 2500 01010 1000 01011 500 01100 397.5 01101 200 01110 100 01111 59.94 10000 49.96 10001 20 10010 16.667 10011 10 10100 5	These bits control the output data rate of the ADC and, therefore, the settling time and noise for Setup 1.	0x0	RW

**FILTER CONFIGURATION REGISTER 2**

Address: 0x2A, Reset: 0x0000, Name: FILTCON2

The Filter Configuration Registers are 16-bit registers that configure the ADC data rate and filter options. Writing to any of these registers resets any active ADC conversion and restarts converting at the first channel in the sequence.

**Table 40. Bit Descriptions for FILTCON2**

Bits	Bit Name	Settings	Description	Reset	Access
15	SINC3_MAP2		If this bit is set, the mapping of the Filter Register changes to directly program the decimation rate of the Sinc3 filter for Setup 2. All other options are eliminated. This allows for fine tuning of the output data rate and filter notch for rejection of specific frequencies. The data rate when on a single channel equals $F_{MOD}/(32 \times FILTCON2[14:0])$ .	0x0	RW
[14:12]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
11	ENHFILTEN2	0 Disabled 1 Enabled	This bit enables various post filters for enhanced 50 Hz/60 Hz rejection for Setup 2. The ORDER bits must be set to 00 to select the Sinc5 + Sinc1 filter for this to work.	0x0	RW
[10:8]	ENHFILT2	010 27 SPS, 47dB rejection, 36.7 ms settling 011 25 SPS, 62 dB rejection, 40 ms settling 101 20 SPS, 86 dB rejection, 50 ms settling 110 16.67 SPS, 92 dB rejection, 60 ms settling	These bits select between various post filters for enhanced 50 Hz/60 Hz rejection for Setup 2.	0x0	RW
7	RESERVED		This bit is reserved and should be set to 0.	0x0	R
[6:5]	ORDER2	00 Sinc5 + Sinc1 (default) 11 Sinc3	These bits control the order of the digital filter that processes the modulator data for Setup 2.	0x0	RW
[4:0]	ODR2	00000 250,000 00001 125,000 00010 62,500 00011 50,000 00100 31,250 00101 25,000 00110 15,625 00111 10,000 01000 5000 01001 2500 01010 1000 01011 500 01100 397.5 01101 200 01110 100 01111 59.94 10000 49.96 10001 20 10010 16.667 10011 10 10100 5	These bits control the output data rate of the ADC and, therefore, the settling time and noise for Setup 2.	0x0	RW

**FILTER CONFIGURATION REGISTER 3**

Address: 0x2B, Reset: 0x0000, Name: FILTCON3

The Filter Configuration Registers are 16-bit registers that configure the ADC data rate and filter options. Writing to any of these registers resets any active ADC conversion and restarts converting at the first channel in the sequence.

**Table 41. Bit Descriptions for FILTCON3**

Bits	Bit Name	Settings	Description	Reset	Access
15	SINC3_MAP3		If this bit is set, the mapping of the Filter Register changes to directly program the decimation rate of the Sinc3 filter for Setup 3. All other options are eliminated. This allows for fine tuning of the output data rate and filter notch for rejection of specific frequencies. The data rate when on a single channel equals $F_{MOD}/(32 \times FILTCON3[14:0])$ .	0x0	RW
[14:12]	RESERVED		These bits are reserved and should be set to 0.	0x0	R
11	ENHFILTEN3	0 Disabled 1 Enabled	This bit enables various post filters for enhanced 50 Hz/60 Hz rejection for Setup 3. The ORDER bits must be set to 00 to select the Sinc5 + Sinc1 filter for this to work.	0x0	RW
[10:8]	ENHFILT3	010 27 SPS, 47 dB rejection, 36.7 ms settling 011 25 SPS, 62 dB rejection, 40 ms settling 101 20 SPS, 86 dB rejection, 50 ms settling 110 16.67 SPS, 92 dB rejection, 60 ms settling	These bits select between various post filters for enhanced 50 Hz/60 Hz rejection for Setup 3.	0x0	RW
7	RESERVED		This bit is reserved and should be set to 0.	0x0	R
[6:5]	ORDER3	00 Sinc5 + Sinc1 (default) 11 Sinc3	These bits control the order of the digital filter that processes the modulator data for Setup 3.	0x0	RW
[4:0]	ODR3	00000 250,000 00001 125,000 00010 62,500 00011 50,000 00100 31,250 00101 25,000 00110 15,625 00111 10,000 01000 5000 01001 2500 01010 1000 01011 500 01100 397.5 01101 200 01110 100 01111 59.94 10000 49.96 10001 20 10010 16.667 10011 10 10100 5	These bits control the output data rate of the ADC and, therefore, the settling time and noise for Setup 3.	0x0	RW

**OFFSET REGISTER 0**

Address: 0x30, Reset: 0x800000, Name: OFFSET0

The Offset (Zero-Scale) Registers are 24-bit registers that can be used to compensate for any offset error in the ADC or in the system.

Table 42. Bit Descriptions for OFFSET0

Bits	Bit Name	Settings	Description	Reset	Access
[23:0]	OFFSET0		Offset calibration coefficient for Setup 0.	0x800000	RW

**OFFSET REGISTER 1**

Address: 0x31, Reset: 0x800000, Name: OFFSET1

The Offset (Zero-Scale) Registers are 24-bit registers that can be used to compensate for any offset error in the ADC or in the system.

Table 43. Bit Descriptions for OFFSET1

Bits	Bit Name	Settings	Description	Reset	Access
[23:0]	OFFSET1		Offset calibration coefficient for Setup 1.	0x800000	RW

**OFFSET REGISTER 2**

Address: 0x32, Reset: 0x800000, Name: OFFSET2

The Offset (Zero-Scale) Registers are 24-bit registers that can be used to compensate for any offset error in the ADC or in the system.

Table 44. Bit Descriptions for OFFSET2

Bits	Bit Name	Settings	Description	Reset	Access
[23:0]	OFFSET2		Offset calibration coefficient for Setup 2.	0x800000	RW

**OFFSET REGISTER 3**

Address: 0x33, Reset: 0x800000, Name: OFFSET3

The Offset (Zero-Scale) Registers are 24-bit registers that can be used to compensate for any offset error in the ADC or in the system.

Table 45. Bit Descriptions for OFFSET3

Bits	Bit Name	Settings	Description	Reset	Access
[23:0]	OFFSET3		Offset calibration coefficient for Setup 3.	0x800000	RW

**GAIN REGISTER 0**

Address: 0x38, Reset: 0x5xxxx0, Name: GAIN0

The Gain (Full-Scale) Registers are 24-bit registers that can be used to compensate for any gain error in the ADC or in the system.

Table 46. Bit Descriptions for GAIN0

Bits	Bit Name	Settings	Description	Reset	Access
[23:0]	GAIN0		Gain calibration coefficient for Setup 0.	0x5XXXX0	RW

**GAIN REGISTER 1**

Address: 0x39, Reset: 0x5xxxx0, Name: GAIN1

The Gain (Full-Scale) Registers are 24-bit registers that can be used to compensate for any gain error in the ADC or in the system.

Table 47. Bit Descriptions for GAIN1

Bits	Bit Name	Settings	Description	Reset	Access
[23:0]	GAIN1		Gain calibration coefficient for Setup 1.	0x5XXXX0	RW

**GAIN REGISTER 2**

Address: 0x3A, Reset: 0x5xxxx0, Name: GAIN2

The Gain (Full-Scale) Registers are 24-bit registers that can be used to compensate for any gain error in the ADC or in the system.

Table 48. Bit Descriptions for GAIN2

Bits	Bit Name	Settings	Description	Reset	Access
[23:0]	GAIN2		Gain calibration coefficient for Setup 2.	0x5XXXX0	RW

**GAIN REGISTER 3**

Address: 0x3B, Reset: 0x5xxxx0, Name: GAIN3

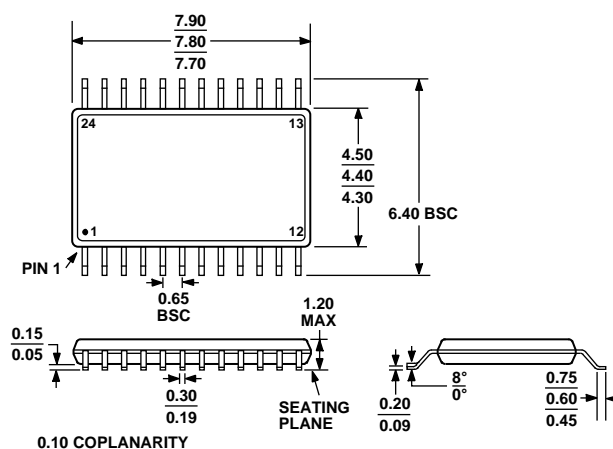
The Gain (Full-Scale) Registers are 24-bit registers that can be used to compensate for any gain error in the ADC or in the system.

Table 49. Bit Descriptions for GAIN3

Bits	Bit Name	Settings	Description	Reset	Access
[23:0]	GAIN3		Gain calibration coefficient for Setup 3.	0x5XXXX0	RW



## OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MO-153-AD

Figure 52. 24-Lead Thin Shrink Small Outline Package [TSSOP]  
(RU-24)

Dimensions shown in millimeters

## ORDERING GUIDE

Models <sup>1</sup>	Temperature Range	Package Description	Package Option
AD7176-2BRUZ	−40°C to +105°C	24-Lead TSSOP	RU-24
AD7176-2BRUZ-RL	−40°C to +105°C	24-Lead TSSOP	RU-24
EVAL-AD7176-2SDZ		Evaluation Board	
EVAL-SDP-CB1Z		Evaluation Controller Board	

<sup>1</sup> Z = RoHS Compliant Part.

**NOTES**

## NOTES

## NOTES

## Данный компонент на территории Российской Федерации

**Вы можете приобрести в компании MosChip.**

Для оперативного оформления запроса Вам необходимо перейти по данной ссылке:

<http://moschip.ru/get-element>

Вы можете разместить у нас заказ для любого Вашего проекта, будь то серийное производство или разработка единичного прибора.

В нашем ассортименте представлены ведущие мировые производители активных и пассивных электронных компонентов.

Нашей специализацией является поставка электронной компонентной базы двойного назначения, продукции таких производителей как XILINX, Intel (ex.ALTERA), Vicor, Microchip, Texas Instruments, Analog Devices, Mini-Circuits, Amphenol, Glenair.

Сотрудничество с глобальными дистрибьюторами электронных компонентов, предоставляет возможность заказывать и получать с международных складов практически любой перечень компонентов в оптимальные для Вас сроки.

На всех этапах разработки и производства наши партнеры могут получить квалифицированную поддержку опытных инженеров.

Система менеджмента качества компании отвечает требованиям в соответствии с ГОСТ Р ИСО 9001, ГОСТ РВ 0015-002 и ЭС РД 009

### Офис по работе с юридическими лицами:

105318, г.Москва, ул.Щербаковская д.3, офис 1107, 1118, ДЦ «Щербаковский»

Телефон: +7 495 668-12-70 (многоканальный)

Факс: +7 495 668-12-70 (доб.304)

E-mail: [info@moschip.ru](mailto:info@moschip.ru)

Skype отдела продаж:

moschip.ru

moschip.ru\_4

moschip.ru\_6

moschip.ru\_9