# E6C2-C

OSM F6C2-C DS F 5 1

## General-purpose Encoder with External Diameter of 50 mm

- Incremental model
- External diameter of 50 mm.
- Resolution of up to 2,000 ppr.
- IP64 (improved oil-proof construction with sealed bearings)
- Side or back connections are possible. Pre-wired Models with cable connected at an angle.





Be sure to read *Safety Precautions* on page 4.

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## **Ordering Information**

#### Encoders [Refer to Dimensions on page 4.]

Power supply voltage	Output configuration	Resolution (pulses/rotation)	Model	
5 to 24 VDC	Open-collector output (NPN)	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600	E6C2-CWZ6C (resolution) 2M Example: E6C2-CWZ6C 10P/R 2M	
		720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000		
12 to 24 VDC	Open-collector output (PNP)	100, 200, 360, 500, 600	E6C2-CWZ5B (resolution) 2M Example: E6C2-CWZ5B 100P/R 2M	
		1,000, 2,000		
5 to 12 VDC	Voltage output	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600	E6C2-CWZ3E (resolution) 2M	
		720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000	Example: E6C2-CWZ3E 10P/R 2M	
5 VDC	Line-driver output	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600	E6C2-CWZ1X (resolution) 2M Example: E6C2-CWZ1X 10P/R 2M	
		720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000		

## Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

Name	Model	Remarks	
	E69-C06B		
Caunlinas	E69-C68B	Different end diameter	
Couplings	E69-C610B	Different end diameter	
	E69-C06M	Metal construction	
Clanges	E69-FCA		
Flanges	E69-FCA02	E69-2 Servo Mounting Bracket provided.	
Servo Mounting Bracket	E69-2	Provided with E69-FCA02 Flange.	

Refer to Accessories for details.

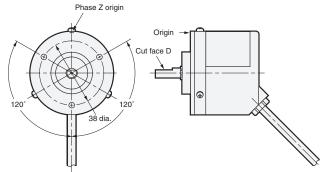
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## **Ratings and Specifications**

Item	Model	E6C2-CWZ6C	E6C2-CWZ5B	E6C2-CWZ3E	E6C2-CWZ1X			
Power supply voltage		5 VDC -5% to 24 VDC +15%, ripple (p-p): 5% max.	12 VDC -10% to 24 VDC +15%, ripple (p-p): 5% max.	5 VDC -5% to 12 VDC +10%, ripple (p-p): 5% max.	5 VDC ±5%, ripple (p-p): 5% max.			
Current consumption*1		80 mA max.	100 mA max.		160 mA max.			
Resolution (pulses/rotation)		10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600, 720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000	100, 200, 360, 500, 600, 1,000, 2,000		300, 360, 400, 500, 600, 720, 800, 0, 2,000			
Output phases		Phases A, B, and Z	Phases A, A, B, B, Z, and Z					
Output configuration		NPN open-collector output	PNP open-collector output Voltage output (NPN output)		Line driver output*2			
Output capacity		Applied voltage: 30 VDC max. Sink current: 35 mA max. Residual voltage: 0.4 V max. (at sink current of 35 mA)	Applied voltage: 30 VDC max. Source current: 35 mA max. Residual voltage: 0.4 V max. (at source current of 35 mA)	Output resistance: 2 kΩ Output current: 20 mA max. Residual voltage: 0.4 V max. (at sink current of 20 mA)	AM26LS31 equivalent Output voltage: High level: $lo = -20 \text{ mA}$ Low level: $ls = 20 \text{ mA}$ Output voltage: $log = 2.5 \text{ V min}$ . $log = 0.5 \text{ V max}$ .			
Maximum response frequency*3		100 kHz	50 kHz	100 kHz				
Phase di between	fference outputs	90°±45° between A and B (1/4 T ± 1/8 T)						
Rise and fall times of output		1 $\mu s$ max. (Control output voltage: 5 V, Load resistance: 1 $k\Omega$ , Cable length: 2 m)	1 μs max. (Cable length: 2 m, Sink current: 10 mA)		0.1 µs max. (Cable length: 2 m, lo = -20 mA, ls = 20 mA)			
Starting	torque	10 mN·m max.						
Moment	of inertia	$1 \times 10^{-6} \text{ kg} \cdot \text{m}^2 \text{ max}$ ; $3 \times 10^{-7} \text{ kg} \cdot \text{m}^2 \text{ max}$ . at 600 P/R max.						
Shaft Radial		50 N						
loading	Thrust	30 N						
Maximur permissi	n ble speed	6,000 r/min						
Protection circuits		Power supply reverse polarity pro-						
Ambient range	temperature	Operating: –10 to 70°C (with no icing), Storage: –25 to 85°C (with no icing)						
Ambient range	humidity	Operating/Storage: 35% to 85% (with no condensation)						
Insulatio	n resistance	20 M $\Omega$ min. (at 500 VDC) between current-carrying parts and case						
Dielectri	c strength	500 VAC, 50/60 Hz for 1 min betw	een current-carrying parts and cas	e				
Vibration	n resistance	Destruction: 10 to 500 Hz, 150 m/s² or 2-mm double amplitude for 11 min 3 times each in X, Y, and Z directions						
Shock re	sistance	Destruction: 1,000 m/s <sup>2</sup> 3 times each in X, Y, and Z directions						
Degree o	of protection	IEC 60529 IP64, in-house standards: oilproof						
Connect	ion method	Pre-wired Models (Standard cable length: 2 m)						
Material		Case: Zinc alloy, Main unit: Aluminum, Shaft: SUS420J2						
Weight (packed	state)	Approx. 400 g						
Accesso	ries	Instruction manual Note: Coupling, mounting bracket and hex-head spanner are sold separately.						
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Note: Origin Indication

The following illustration shows the relationship between phase Z and the origin. Set cut face D to the phase Z origin as shown in the illustration.

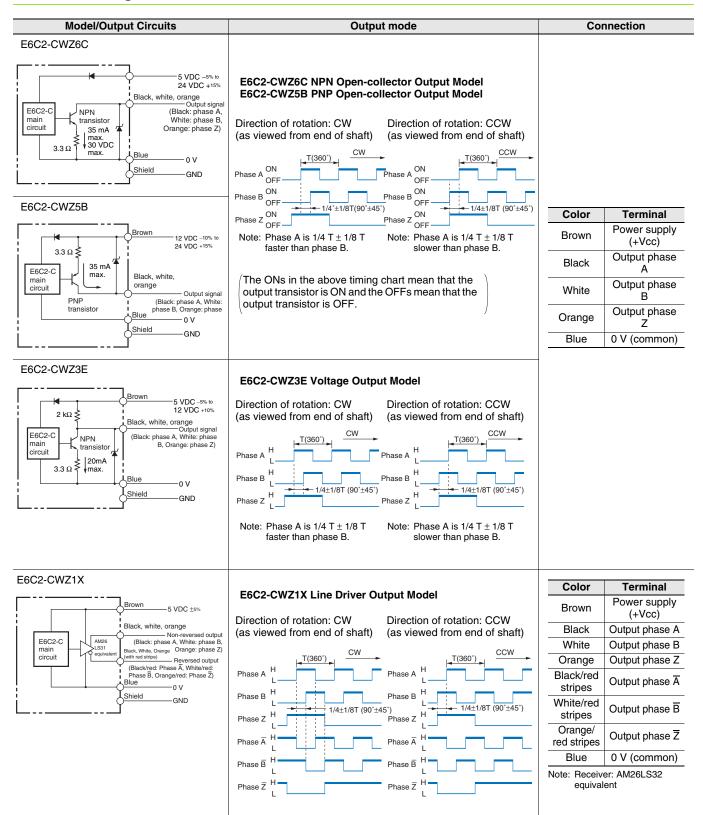


- \*1. An inrush current of approximately 9 A will flow for approximately 0.3 ms when the power is turned ON.
  \*2. The line driver output is a data transmission circuit compatible with RS-422A and long-distance transmission is possible with a twisted-pair cable.(AM26LS31 equivalent)
  \*3. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

Maximum electrical response speed (rpm) = Maximum response frequency × 60 Resolution

This means that the E6C2-C Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed.

## I/O Circuit Diagrams



Note: 1. The shielded cable outer core (shield) is not connected to the inner area or to the case.

- 2. The phase A, phase B, and phase Z circuits are all identical.
- 3. Normally, connect GND to 0 V or to an external ground.

## **Safety Precautions**

#### Refer to Warranty and Limitations of Liability.

#### **⚠ WARNING**

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



#### **Precautions for Correct Use**

Do not use the Encoder under ambient conditions that exceed the ratings.

#### Wiring

#### **Cable Extension Characteristics**

- When the cable length is extended, the output waveform startup time is lengthened and it affects the phase difference characteristics of phases A and B. Conditions will change according to frequency, noise, and other factors. As a guideline, use a cable length of 10 m\* or less. If the cable must be more than 2 m, use a Model with a Line-driver Output (max. length for line-driver output: 100 m).
- \* Recommended Cable Conductor cross section: 0.2 mm<sup>2</sup>

Spiral shield

Conductor resistance: 92  $\Omega$ /km max. (20°C) Insulation resistance: 5  $\Omega$ /km min. (20°C)

- The output waveform startup time changes not only according to the length of the cable, but also according to the load resistance and the cable type.
- Extending the cable length not only changes the startup time, but also increases the output residual voltage.

#### Connection

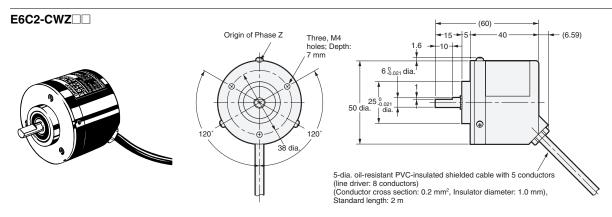
Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

(Unit: mm)

#### **Dimensions**

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

#### **Encoder**



#### Accessories (Order Separately)

Couplings Flanges

E69-C06B E69-FCA E69-C68B E69-FCA02 E69-C610B

E69-C610E

#### **Servo Mounting Bracket**

E69-2 (Three brackets in a set.)

Refer to Accessories for details.

#### Read and Understand This Catalog

Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments.

#### Warranty and Limitations of Liability

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