SANYO *Semiconductors*

DATA SHEET

An ON Semiconductor Company

LV8735V — Bi-CMOS LSI
PWM Constant-Current Control Stepping Motor Driver

Overview

The LV8735V is a 2-channel H-bridge driver IC that can switch a stepping motor driver, which is capable of micro-step drive and supports 4W 1-2 phase excitation, and two channels of a brushed motor driver, which supports forward, reverse, brake, and standby of a motor. It is ideally suited for driving brushed DC motors and stepping motors used in office equipment and amusement applications.

Features

- Single-channel PWM current control stepping motor driver (selectable with DC motor driver channel 2) incorporated.
- BiCDMOS process IC
- Low on resistance (upper side : 0.75Ω ; lower side : 0.5Ω ; total of upper and lower : 1.25Ω ; Ta = 25°C, I_O = 1A)
- Excitation mode can be set to 2-phase, 1-2 phase, 2W1-2 phase , or 4W1-2 phase
- Excitation step proceeds only by step signal input
- Motor current selectable in four steps
- Output short-circuit protection circuit (selectable from latch-type or auto-reset-type) incorporated
- Unusual condition warning output pins
- Built-in thermal shutdown circuit
- No control power supply required

Specifications

Absolute Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	VM max		36	V
Output peak current	I_O peak	tw ≤ 10ms, duty 20%	1.5	A
Output current	I_O max		1	A
Logic input voltage	V_{IN} max		-0.3 to +6	V
MONI/EMO input voltage	Vmo/Vemo		-0.3 to +6	V

Continued on next page.

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Parameter	Symbol	Conditions	Ratings	Unit
Allowable power dissipation	Pd max	*	3.05	W
Operating temperature	Topr		-20 to +85	°C
Storage temperature	Tstg		-55 to +150	°C

* Specified circuit board : 90.0mm×90.0mm×1.6mm, glass epoxy 2-layer board, with backside mounting.

Allowable Operating Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	VM		9 to 32	V
Logic input voltage	V_{IN}		0 to 5.5	V
VREF input voltage range	VREF		0 to 3	V

Electrical Characteristics at Ta = 25°C, VM = 24V, VREF = 1.5V

Parameter		Symbol	Conditions	Ratings			Unit
				min	typ	max	
Standby mode current drain		IMst	ST = "L"		100	400	μA
Current drain		IM	ST = "H", OE = "L", with no load		3.2	5	mA
VREG5 output voltage		Vreg5	I_O = -1mA	4.5	5	5.5	V
Thermal shutdown temperature		TSD	Design guarantee	150	180	200	°C
Thermal hysteresis width		ΔTSD	Design guarantee		40		°C
Motor driver							
Output on resistance		Ronu	I_O = 1A, Upper-side on resistance		0.75	0.97	Ω
		Rond	I_O = 1A, Lower-side on resistance		0.5	0.65	Ω
Output leakage current		$I_O$leak				50	μA
Diode forward voltage		VD	ID = -1A		1.2	1.4	V
Logic high-level input voltage		$V_{IN}H$		2.0			V
Logic low-level input voltage		$V_{IN}L$				0.8	V
Logic pin input current		$I_{IN}L$	V_{IN} = 0.8V	4	8	12	μA
other MD2/DC12, OE/CMK pin		$I_{IN}H$	V_{IN} = 5V	30	50	70	μA
MD2/DC12 pin input current		$I_{MD}2L$	V_{IN} = 0.8V	8	16	24	μA
		$I_{MD}2H$	V_{IN} = 5V	60	100	140	μA
OE / CMK pin input current		$I_{CMK}L$	DM = "L", OE/CMK = 0.8V	4	8	12	μA
		$I_{CMK}H$	DM = "L", OE/CMK = 5V	30	50	70	μA
		I_{CMK}	DM = "H", OE/CMK = 0V	-32	-25	-18	μA
OE/CMK pin current LIMIT mask threshold voltage.		Vt_{CMK}	DM = "H"	1.2	1.5	1.8	V
Current setting comparator threshold voltage (current step switching)	4W1-2 phase drive	Vtdac0_4W	Step 0 (When initialized : channel 1 comparator level)	0.291	0.3	0.309	V
		Vtdac1_4W	Step 1 (Initial state+1)	0.291	0.3	0.309	V
		Vtdac2_4W	Step 2 (Initial state+2)	0.285	0.294	0.303	V
		Vtdac3_4W	Step 3 (Initial state+3)	0.279	0.288	0.297	V
		Vtdac4_4W	Step 4 (Initial state+4)	0.267	0.276	0.285	V
		Vtdac5_4W	Step 5 (Initial state+5)	0.255	0.264	0.273	V
		Vtdac6_4W	Step 6 (Initial state+6)	0.24	0.249	0.258	V
		Vtdac7_4W	Step 7 (Initial state+7)	0.222	0.231	0.24	V
		Vtdac8_4W	Step 8 (Initial state+8)	0.201	0.21	0.219	V
		Vtdac9_4W	Step 9 (Initial state+9)	0.18	0.189	0.198	V
		Vtdac10_4W	Step 10 (Initial state+10)	0.157	0.165	0.173	V
		Vtdac11_4W	Step 11 (Initial state+11)	0.134	0.141	0.148	V
		Vtdac12_4W	Step 12 (Initial state+12)	0.107	0.114	0.121	V
		Vtdac13_4W	Step 13 (Initial state+13)	0.08	0.087	0.094	V
		Vtdac14_4W	Step 14 (Initial state+14)	0.053	0.06	0.067	V
		Vtdac15_4W	Step 15 (Initial state+15)	0.023	0.03	0.037	V

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Parameter		Symbol	Conditions	Ratings			Unit
				min	typ	max	
2W1-2 phase drive		Vtdac0_2W	Step 0 (When initialized : channel 1 comparator level)	0.291	0.3	0.309	V
		Vtdac2_2W	Step 2 (Initial state+1)	0.285	0.294	0.303	V
		Vtdac4_2W	Step 4 (Initial state+2)	0.267	0.276	0.285	V
		Vtdac6_2W	Step 6 (Initial state+3)	0.24	0.249	0.258	V
		Vtdac8_2W	Step 8 (Initial state+4)	0.201	0.21	0.219	V
		Vtdac10_2W	Step 10 (Initial state+5)	0.157	0.165	0.173	V
		Vtdac12_2W	Step 12 (Initial state+6)	0.107	0.114	0.121	V
		Vtdac14_2W	Step 14 (Initial state+7)	0.053	0.06	0.067	V
1-2 phase drive		Vtdac0_H	Step 0 (When initialized : channel 1 comparator level)	0.291	0.3	0.309	V
		Vtdac8_H	Step 8 (Initial state+1)	0.201	0.21	0.219	V
2 phase drive		Vtdac8_F	Step 8' (When initialized : channel 1 comparator level)	0.291	0.3	0.309	V
Current setting comparator threshold voltage (current attenuation rate switching)		Vtatt00	ATT1 = L, ATT2 = L	0.291	0.3	0.309	V
		Vtatt01	ATT1 = H, ATT2 = L	0.232	0.24	0.248	V
		Vtatt10	ATT1 = L, ATT2 = H	0.143	0.15	0.157	V
		Vtatt11	ATT1 = H, ATT2 = H	0.053	0.06	0.067	V
Chopping frequency		Fchop	Cchop = 200pF	40	50	60	kHz
CHOP pin charge/discharge current		Ichop		7	10	13	μA
Chopping oscillation circuit threshold voltage		Vtup		0.8	1	1.2	V
VREF pin input current		Iref	VREF = 1.5V	-0.5			μA
MONI pin saturation voltage		Vsatmon	Imoni = 1mA			400	mV
Charge pump							
VG output voltage		VG		28	28.7	29.8	V
Rise time		tONG	VG = 0.1μF		200	500	μS
Oscillator frequency		Fosc		90	125	150	kHz
Output short-circuit protection							
EMO pin saturation voltage		Vsatemo	Iemo = 1mA			400	mV
CEM pin charge current		Icem	Vcem = 0V	7	10	13	μA
CEM pin threshold voltage		Vtcem		0.8	1	1.2	V

Package Dimensions

unit : mm (typ)

3333

SANYO : SSOP44K(275mil)

Pd max - Ta

*1 With components mounted on the exposed die-pad board
*2 With no components mounted on the exposed die-pad board

Two-layer circuit board 1 *1

Two-layer circuit board 2 *2

Allowable power dissipation, Pd max - W

Ambient temperature, Ta - °C

4.0
3.05
3.0
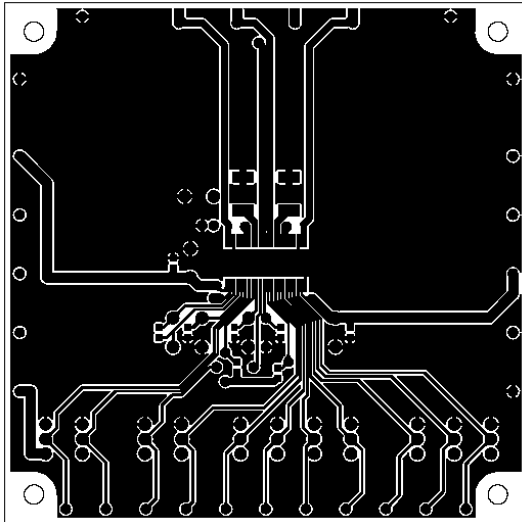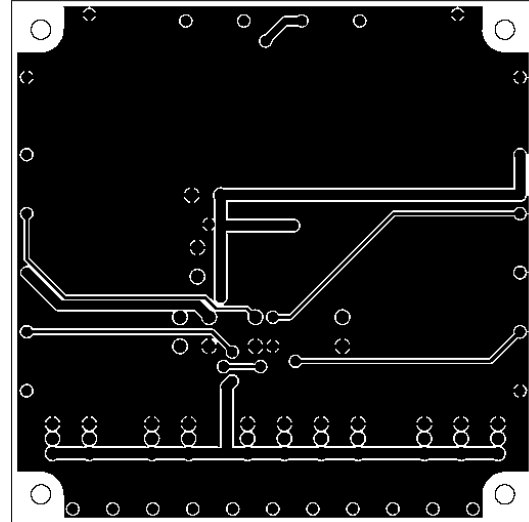2.30
2.0
1.59
1.20
1.0
0
-20   0   20   40   60   80   100
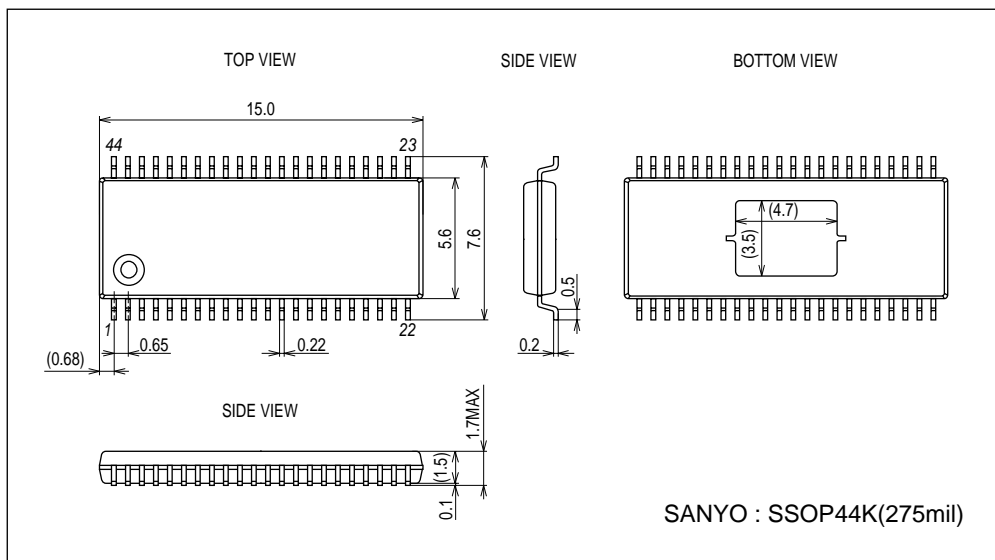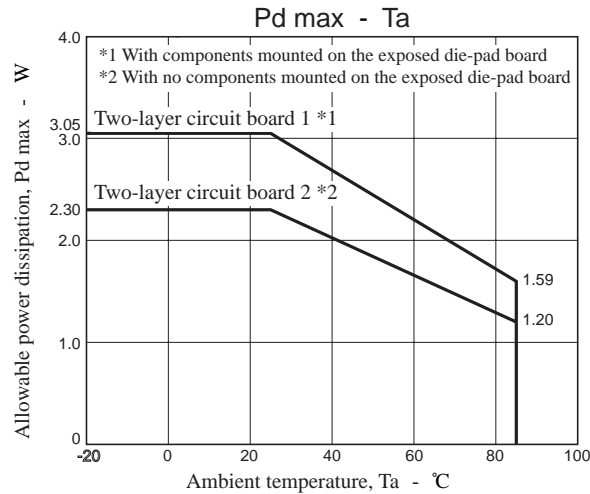
Substrate Specifications (Substrate recommended for operation of LV8735V)

Size : 90mm × 90mm × 1.6mm (two-layer substrate [2S0P])
Material : Glass epoxy
Copper wiring density : L1 = 85% / L2 = 90%
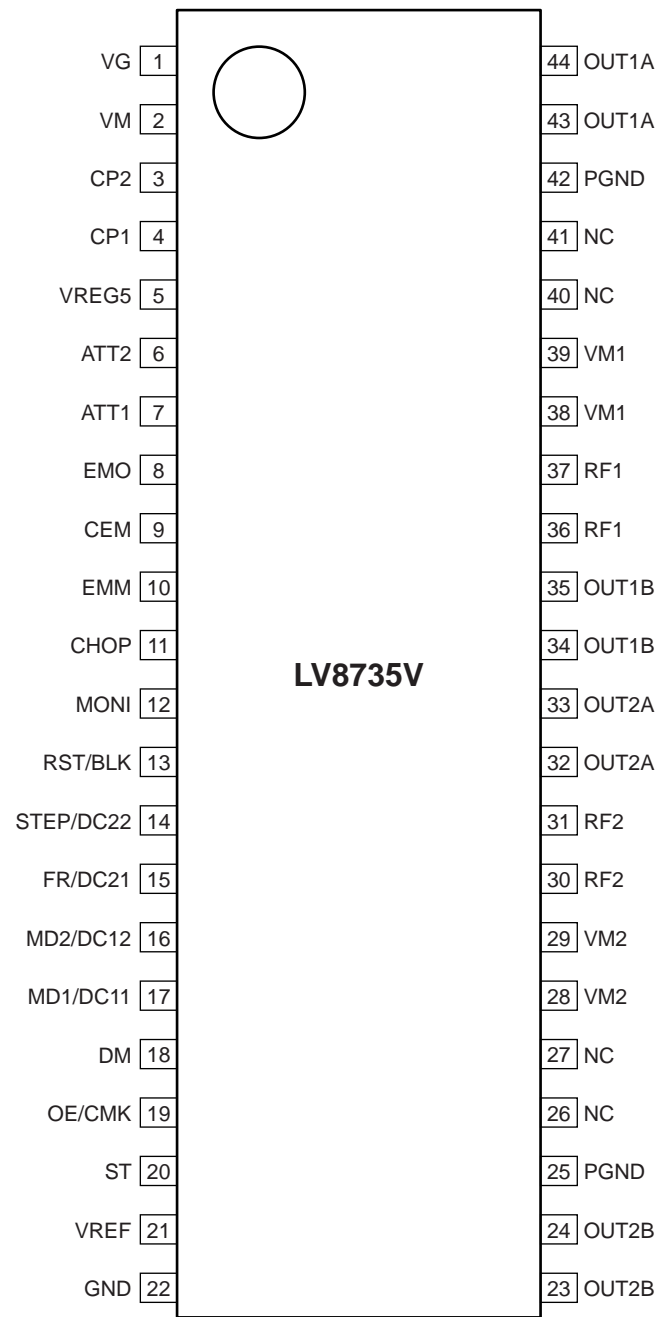
L1 : Copper wiring pattern diagram

L2 : Copper wiring pattern diagram

Cautions

1) The data for the case with the Exposed Die-Pad substrate mounted shows the values when 90% or more of the Exposed Die-Pad is wet.

2) For the set design, employ the derating design with sufficient margin.
Stresses to be derated include the voltage, current, junction temperature, power loss, and mechanical stresses such as vibration, impact, and tension.
Accordingly, the design must ensure these stresses to be as low or small as possible.
The guideline for ordinary derating is shown below :
(1)Maximum value 80% or less for the voltage rating
(2)Maximum value 80% or less for the current rating
(3)Maximum value 80% or less for the temperature rating

3) After the set design, be sure to verify the design with the actual product.
Confirm the solder joint state and verify also the reliability of solder joint for the Exposed Die-Pad, etc.
Any void or deterioration, if observed in the solder joint of these parts, causes deteriorated thermal conduction, possibly resulting in thermal destruction of IC.
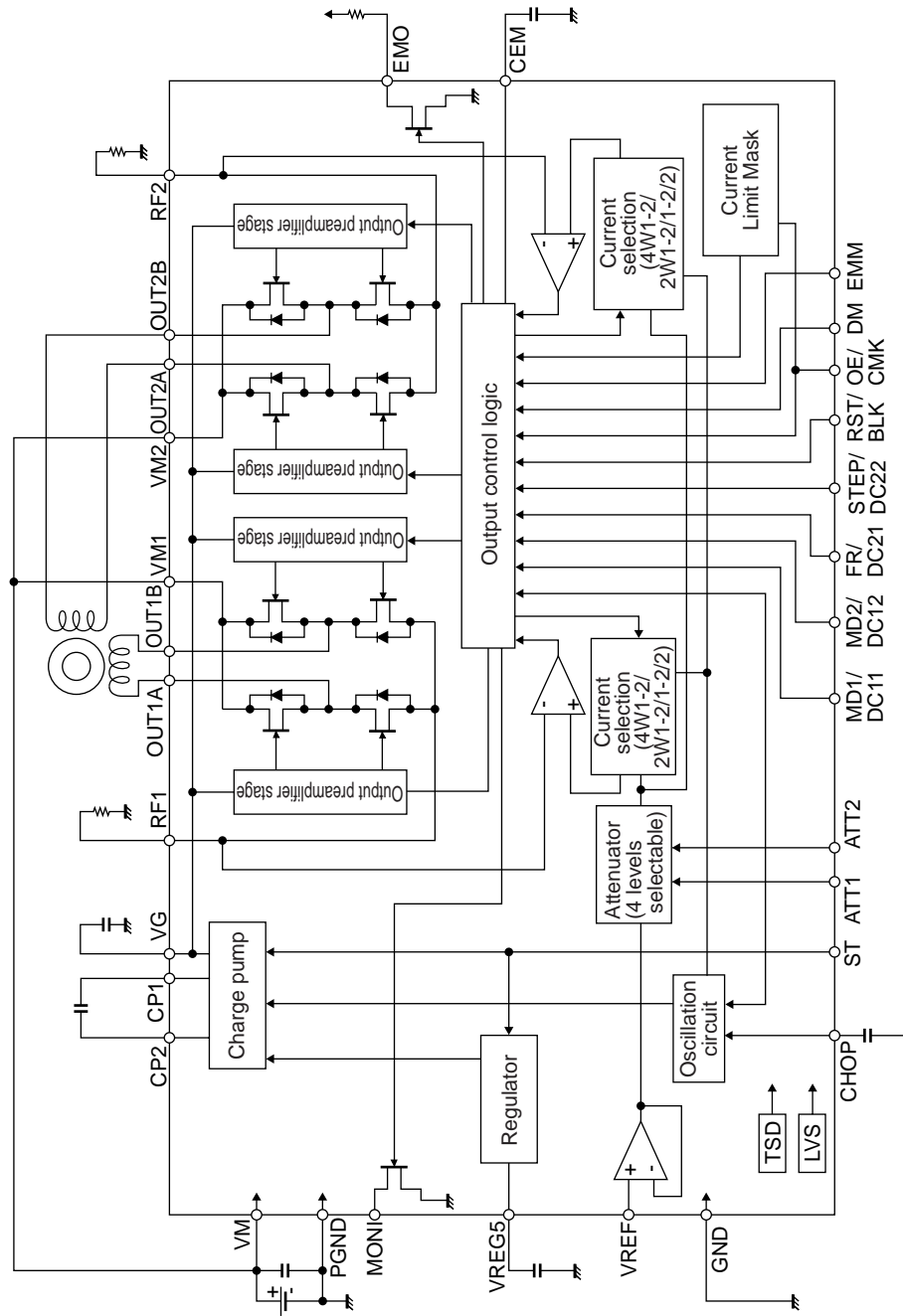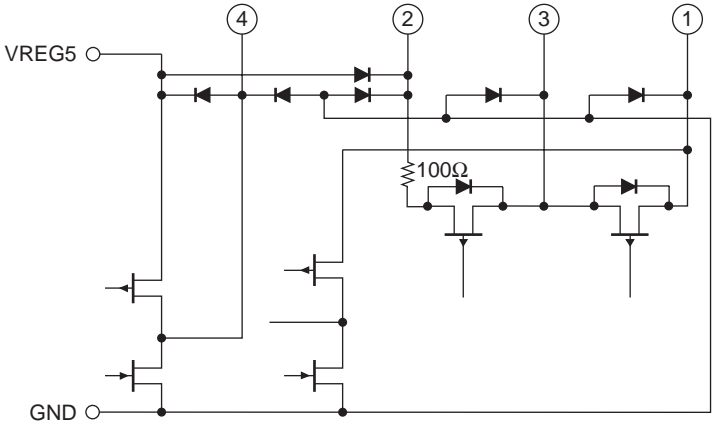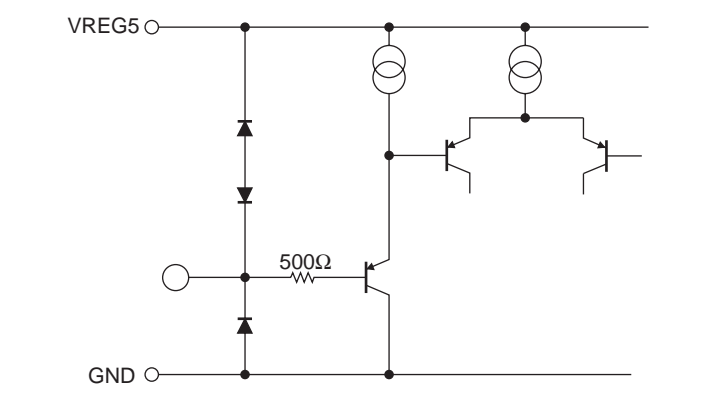
Pin Assignment

Pin	Name		Pin	Name
1	VG		44	OUT1A
2	VM		43	OUT1A
3	CP2		42	PGND
4	CP1		41	NC
5	VREG5		40	NC
6	ATT2		39	VM1
7	ATT1		38	VM1
8	EMO		37	RF1
9	CEM		36	RF1
10	EMM		35	OUT1B
11	CHOP		34	OUT1B
12	MONI		33	OUT2A
13	RST/BLK		32	OUT2A
14	STEP/DC22		31	RF2
15	FR/DC21		30	RF2
16	MD2/DC12		29	VM2
17	MD1/DC11		28	VM2
18	DM		27	NC
19	OE/CMK		26	NC
20	ST		25	PGND
21	VREF		24	OUT2B
22	GND		23	OUT2B

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Top view

Block Diagram

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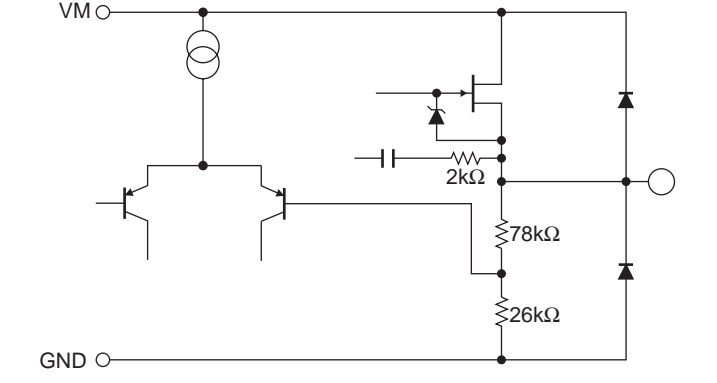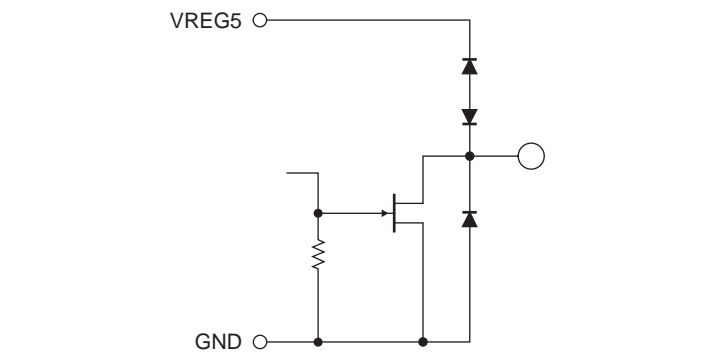
Pin Functions

Pin No.	Pin Name	Pin Functtion	Equivalent Circuit
6	ATT2	Motor holding current switching pin.	
7	ATT1	Motor holding current switching pin.	
10	EMM	Output short-circuit protection mode switching pin.	
13	RST/BLK	RESET input pin (STM) / Blanking time switching pin (DCM).	
14	STEP/DC22	STEP signal input pin (STM) / Channel 2 output control input pin 2 (DCM).	
15	FR/DC21	CW / CCW signal input pin (STM) / Channel 2 output control input pin 1 (DCM).	
17	MD1/DC11	Excitation mode switching pin 1 (STM) / Channel 1 output control input pin 1 (DCM).	
18	DM	Drive mode (STM/DCM) switching pin.	
20	ST	Chip enable pin.	
23, 24	OUT2B	Channel 2 OUTB output pin.	
25, 42	PGND	Power system ground.	
28, 29	VM2	Channel 2 motor power supply connection pin.	
30, 31	RF2	Channel 2 current-sense resistor connection pin.	
32, 33	OUT2A	Channel 2 OUTA output pin.	
34, 35	OUT1B	Channel 1 OUTB output pin.	
36, 37	RF1	Channel 1 current-sense resistor connection pin.	
38, 39	VM1	Channel 1 motor power supply pin.	
43, 44	OUT1A	Channel 1 OUTA output pin.	
22	GND	Ground.	
26,27 40,41	NC	No Connection (No internal connection to the IC)	

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Pin No.	Pin Name	Pin Functtion	Equivalent Circuit
1 2 3 4	VG VM CP2 CP1	Charge pump capacitor connection pin. Motor power supply connection pin. Charge pump capacitor connection pin. Charge pump capacitor connection pin.	
21	VREF	Constant current control reference voltage input pin.	
5	VREG5	Internal power supply capacitor connection pin.	
8 12	EMO MONI	Output short-circuit state warning output pin. Position detection monitor pin.	

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Pin No.	Pin Name	Pin Functtion	Equivalent Circuit
9	CEM	Pin to connect the output short-circuit state detection time setting capacitor.	
11	CHOP	Chopping frequency setting capacitor connection pin.	
19	OE	Output enable signal input pin.	
16	MD2/DC12	Excitation mode switching pin 2 (STM) / Channel 1 output control input pin 2 (DCM).	

Description of operation

Input Pin Function

The function to prevent including the turn from the input to the power supply is built into each input pin. Therefore, the current turns to the power supply even if power supply (VM) is turned off with the voltage impressed to the input pin and there is not crowding.

(1) Chip enable function

This IC is switched between standby and operating mode by setting the ST pin. In standby mode, the IC is set to power-save mode and all logic is reset. In addition, the internal regulator circuit and charge pump circuit do not operate in standby mode.

ST	Mode	Internal regulator	Charge pump
Low or Open	Standby mode	Standby	Standby
High	Operating mode	Operating	Operating

(2) Drive mode switching pin function

The IC drive mode is switched by setting the DM pin. In STM mode, stepping motor channel 1 can be controlled by the CLK-IN input. In DCM mode, DC motor channel 2 or stepping motor channel 1 can be controlled by parallel input. Stepping motor control using parallel input is 2-phase or 1-2 phase full torque.

DM	Drive mode	Application
Low or Open	STM mode	Stepping motor channel 1 (CLK-IN)
High	DCM mode	DC motor channel 2 or stepping motor channel 1 (parallel)

STM mode (DM = Low or Open)

(1) STEP pin function

Input		Operating mode
ST	STP	
Low	*	Standby mode
High	⌐_↑	Excitation step proceeds
High	⌐_↓	Excitation step is kept

(2) Excitation mode setting function

MD1	MD2	Excitation mode	Initial position	
			Channel 1	Channel 2
Low	Low	2 phase excitation	100%	-100%
High	Low	1-2 phase excitation	100%	0%
Low	High	2W1-2 phase excitation	100%	0%
High	High	4W1-2 phase excitation	100%	0%

This is the initial position of each excitation mode in the initial state after power-on and when the counter is reset.

(3) Position detection monitoring function

The MONI position detection monitoring pin is of an open drian type.
When the excitation position is in the initial position, the MONI output is placed in the ON state.
(Refer to "Examples of current waveforms in each of the excitation modes.")

(4) Setting constant-current control reference current

This IC is designed to automatically exercise PWM constant-current chopping control for the motor current by setting the output current. Based on the voltage input to the VREF pin and the resistance connected between RF and GND, the output current that is subject to the constant-current control is set using the calculation formula below :

$$I_{OUT} = (VREF/5)/RF \text{ resistance}$$

* The above setting is the output current at 100% of each excitation mode.

The voltage input to the VREF pin can be switched to four-step settings depending on the statuses of the two inputs, ATT1 and ATT2. This is effective for reducing power consumption when motor holding current is supplied.

Attenuation function for VREF input voltage

ATT1	ATT2	Current setting reference voltage attenuation ratio
Low	Low	100%
High	Low	80%
Low	High	50%
High	High	20%

The formula used to calculate the output current when using the function for attenuating the VREF input voltage is given below.

$$I_{OUT} = (VREF/5) \times (\text{attenuation ratio})/RF \text{ resistance}$$

Example : At VREF of 1.5V, a reference voltage setting of 100% [(ATT1, ATT2) = (L, L)] and an RF resistance of 0.5Ω, the output current is set as shown below.

$$I_{OUT} = 1.5V/5 \times 100\%/0.5\Omega = 0.6A$$

If, in this state, (ATT1, ATT2) is set to (H, H), IOUT will be as follows :

$$I_{OUT} = 0.6A \times 20\% = 120mA$$

In this way, the output current is attenuated when the motor holding current is supplied so that power can be conserved.

(5) Input timing
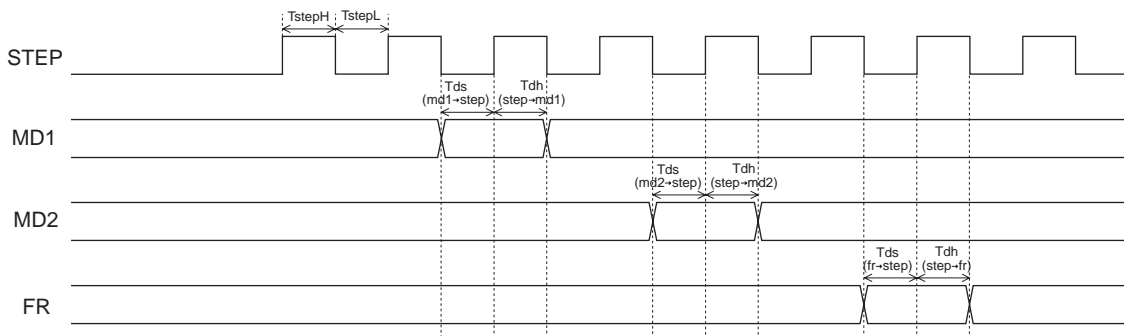
TstepH/TstepL : Clock H/L pulse width (min 500ns)
Tds : Data set-up time (min 500ns)
Tdh : Data hold time (min 500ns)

(6) Blanking period

If, when exercising PWM constant-current chopping control over the motor current, the mode is switched from decay to charge, the recovery current of the parasitic diode may flow to the current sensing resistance, causing noise to be carried on the current sensing resistance pin, and this may result in erroneous detection. To prevent this erroneous detection, a blanking period is provided to prevent the noise occurring during mode switching from being received. During this period, the mode is not switched from charge to decay even if noise is carried on the current sensing resistance pin.

In the stepping motor driver mode (DM = Low or Open) of this IC, the blanking time is fixed at approximately 1μs. In the DC motor driver mode (DM = High), the blanking time can be switched to one of two levels using the RST/BLK pin. (Refer to "Blanking time switching function.")

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(7) Reset function

Only STM mode is pin at the DCM mode BLK: It operates as a switch function of the time of the bran king.

| RST	Operating mode
Low	Normal operation
High	Reset state
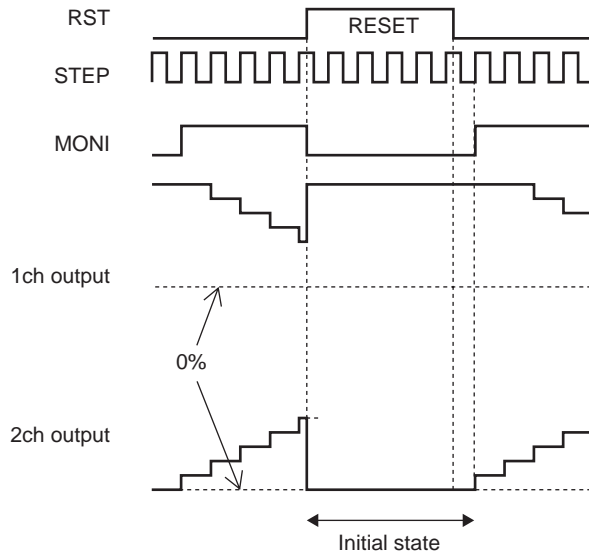
Initial state

When the RST pin is set to High, the excitation position of the output is forcibly set to the initial state, and the MONI output is placed in the ON state. When RST is then set to Low, the excitation position is advanced by the next STEP input.

(8) Output enable function

Only STM mode is pin at the DCM mode CMK: It operates as current LIMIT mask function.

OE	Operating mode
Low	Output ON
High	Output OFF

Output is high-impedance
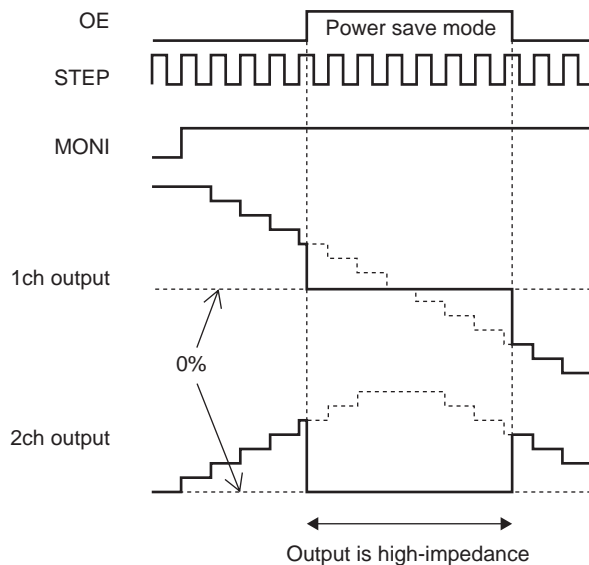
When the OE pin is set High, the output is forced OFF and goes to high impedance.
However, the internal logic circuits are operating, so the excitation position proceeds when the STEP signal is input. Therefore, when OE is returned to Low, the output level conforms to the excitation position proceeded by the STEP input.

(9) Forward/reverse switching function

FR	Operating mode
Low	Clockwise (CW)
High	Counter-clockwise (CCW)
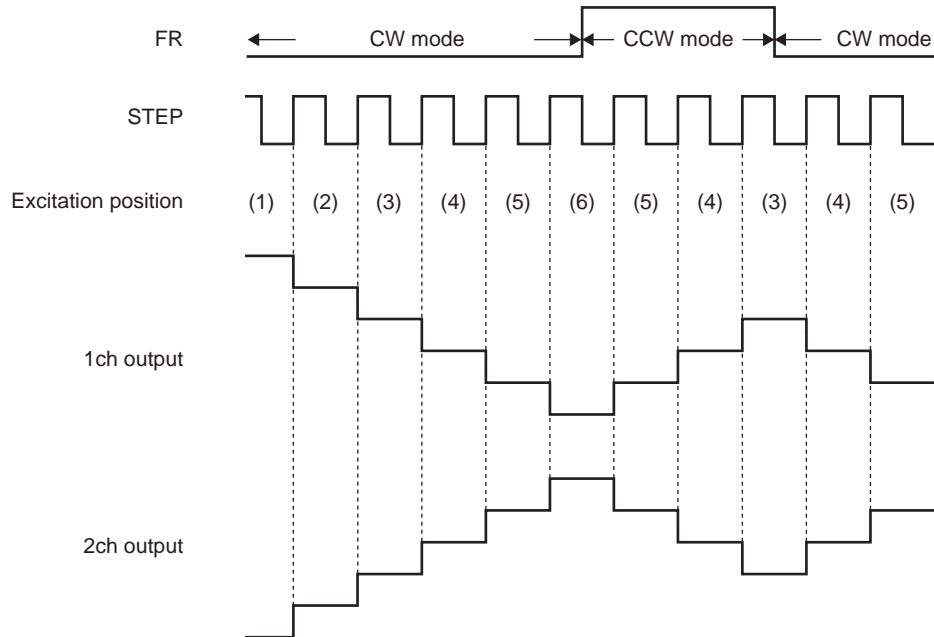
The internal D/A converter proceeds by one bit at the rising edge of the input STEP pulse.

In addition, CW and CCW mode are switched by setting the FR pin.

In CW mode, the channel 2 current phase is delayed by 90° relative to the channel 1 current.

In CCW mode, the channel 2 current phase is advanced by 90° relative to the channel 1 current.

(10) Chopping frequency setting

For constant-current control, this IC performs chopping operations at the frequency determined by the capacitor (Cchop) connected between the CHOP pin and GND.

The chopping frequency is set as shown below by the capacitor (Cchop) connected between the CHOP pin and GND.

$$Fchop = Ichop/ (Cchop \times Vtchop \times 2) \text{ (Hz)}$$

Ichop : Capacitor charge/discharge current, typ 10μA

Vtchop : Charge/discharge hysteresis voltage (Vtup-Vtdown), typ 0.5V

For instance, when Cchop is 200pF, the chopping frequency will be as follows :

$$Fchop = 10μA/ (200pF \times 0.5V \times 2) = 50kHz$$

(11) Output current vector locus (one step is normalized to 90 degrees)
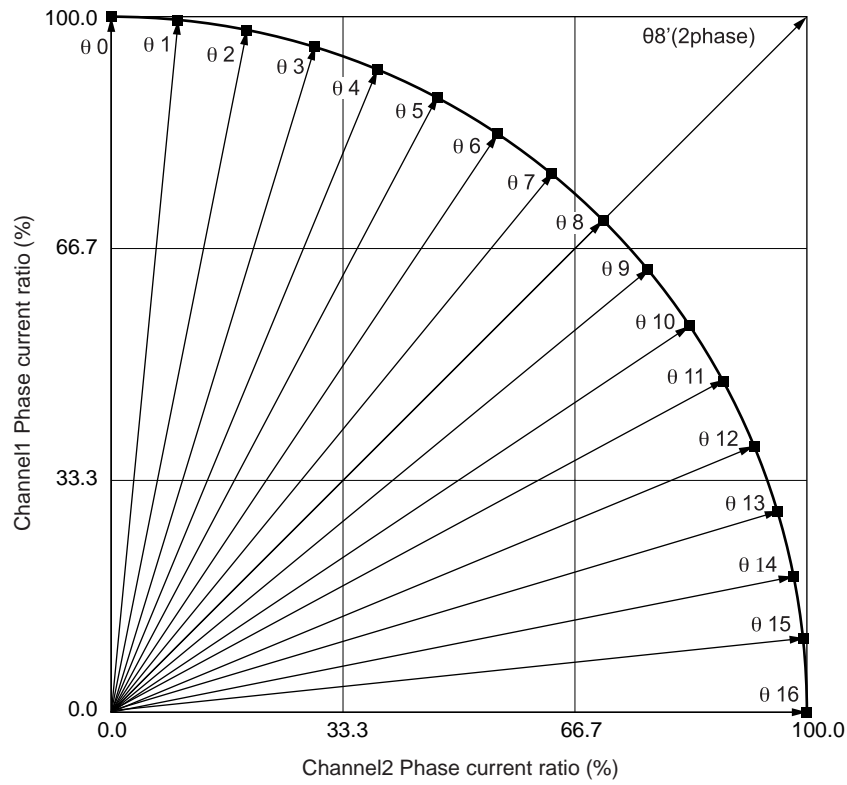
Setting current ration in each excitation mode

STEP	4W1-2 phase (%)		2W1-2 phase (%)		1-2 phase (%)		2-phase (%)	
	Channel 1	Channel 2	Channel 1	Channel 2	Channel 1	Channel 2	Channel 1	Channel 2
θ0	100	0	100	0	100	0		
θ1	100	10						
θ2	98	20	98	20				
θ3	96	29						
θ4	92	38	92	38				
θ5	88	47						
θ6	83	55	83	55				
θ7	77	63						
θ8	70	70	70	70	70	70	100	100
θ9	63	77						
θ10	55	83	55	83				
θ11	47	88						
θ12	38	92	38	92				
θ13	29	96						
θ14	20	98	20	98				
θ15	10	100						
θ16	0	100	0	100	0	100		

(12) Typical current waveform in each excitation mode

2-phase excitation (CW mode)

1-2 phase excitation (CW mode)

LV8735V
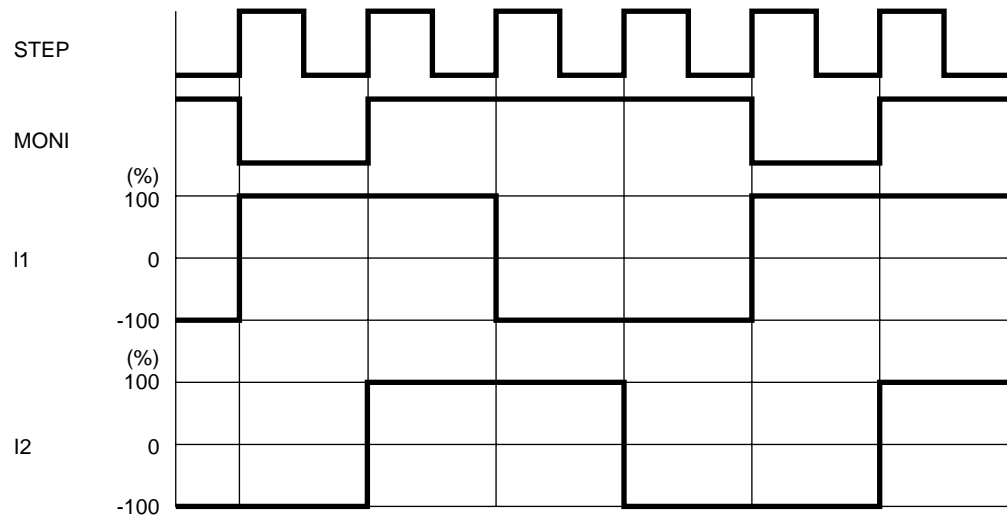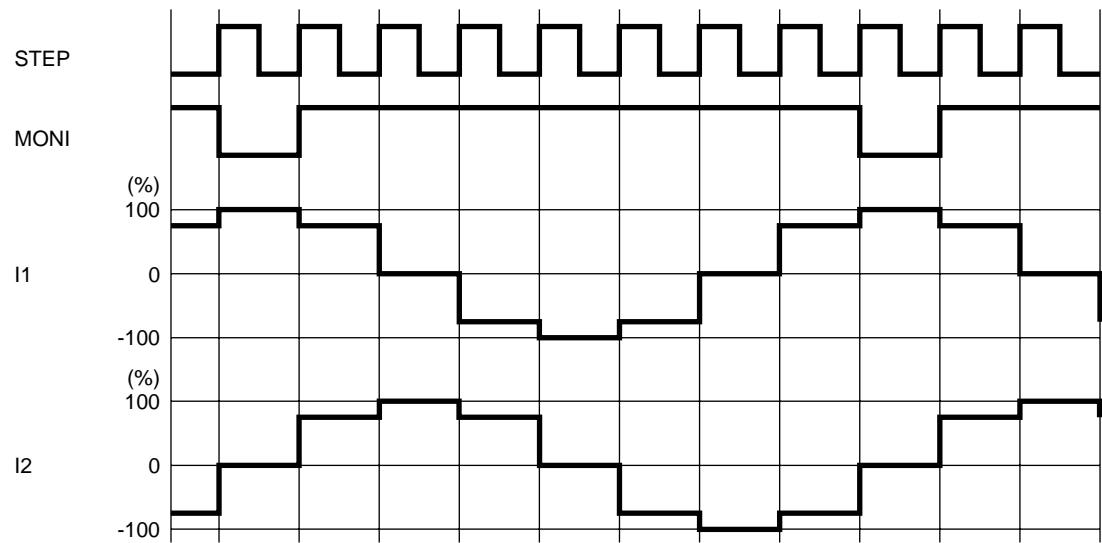
2W1-2 phase excitation (CW mode)
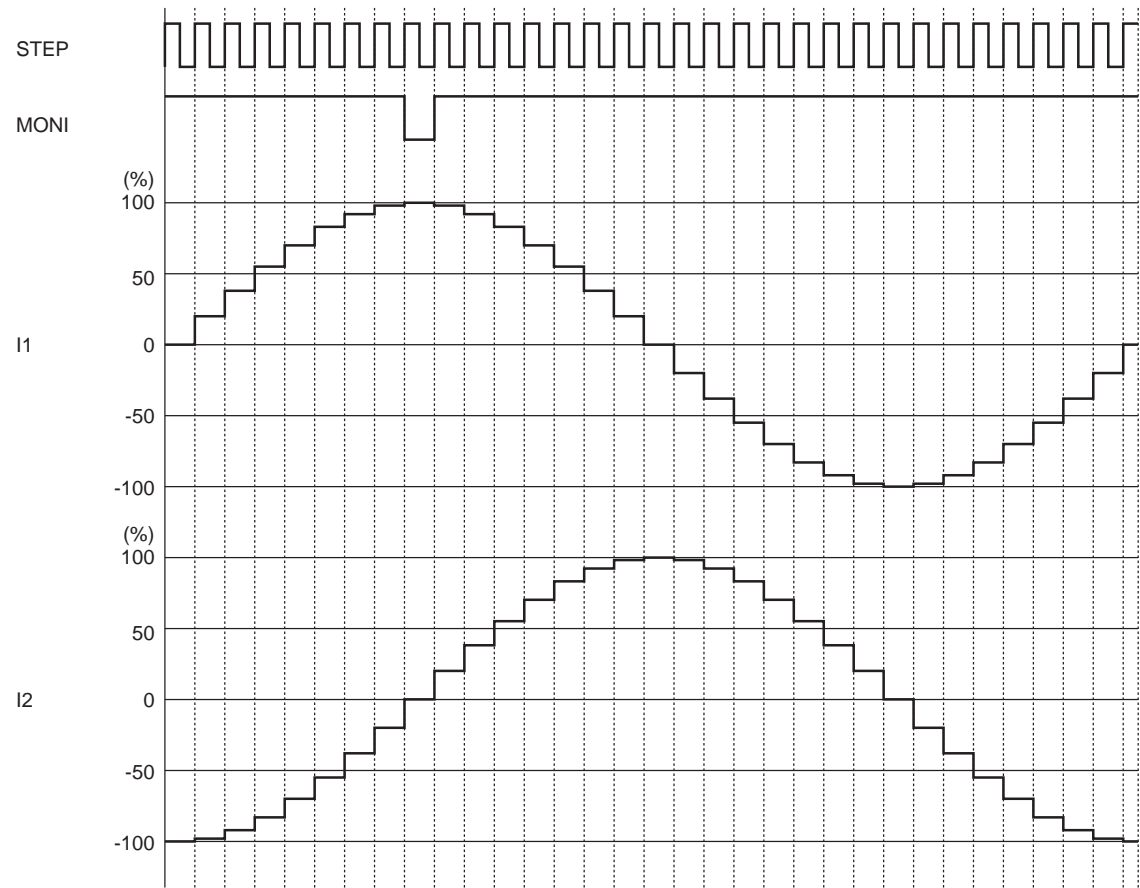
4W1-2 phase excitation (CW mode)
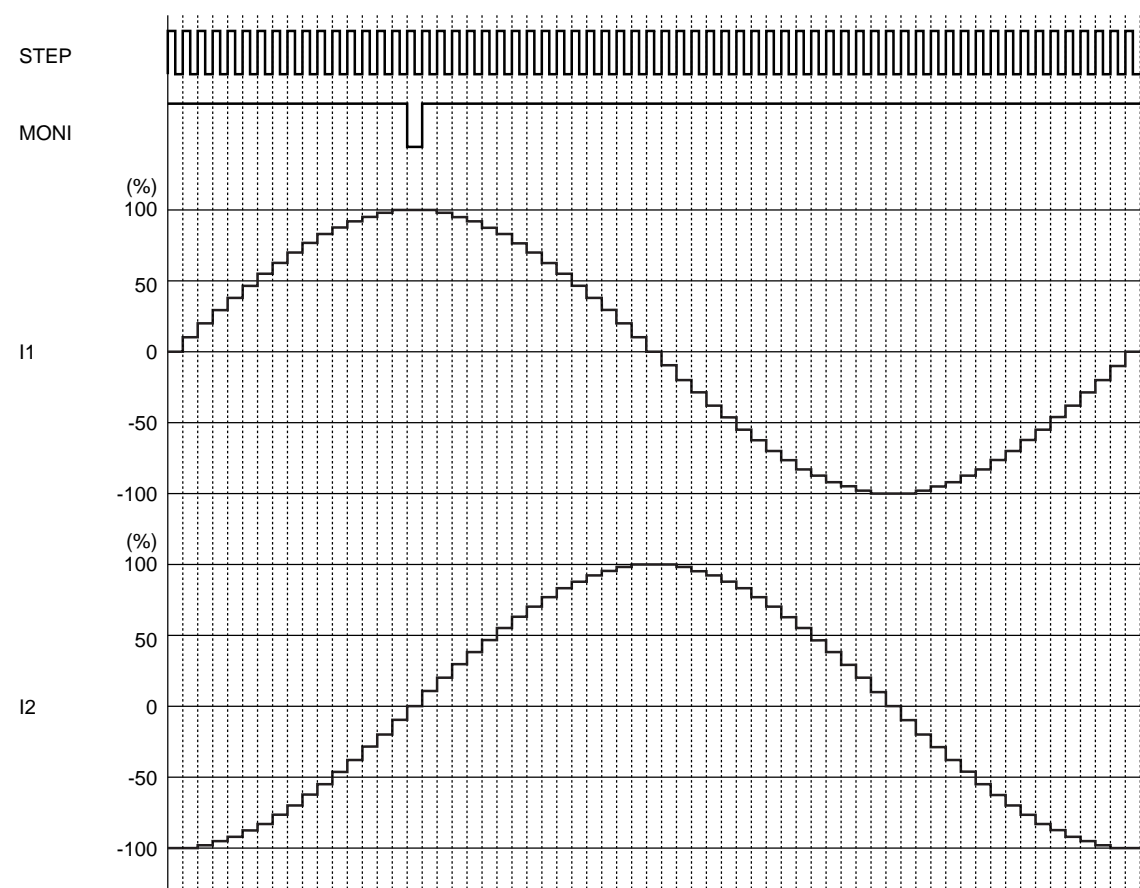
(13) Current control operation specification

(Sine wave increasing direction)

STEP

Set current

Coil current

Set current

Forced CHARGE
section

Current mode   CHARGE   SLOW   FAST   CHARGE   SLOW   FAST
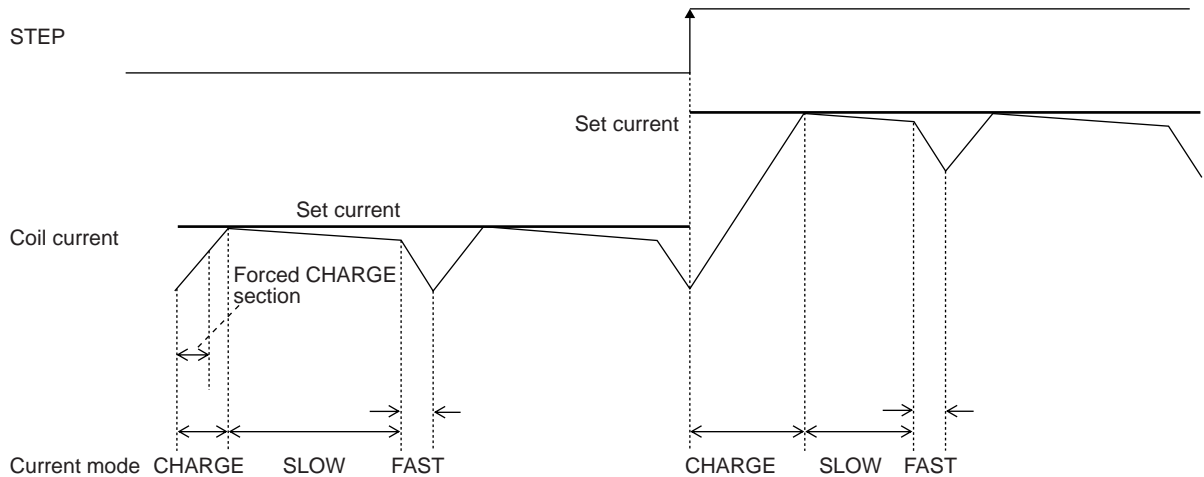
(Sine wave decreasing direction)

STEP

Set current

Coil current

Forced CHARGE
section

Set current

Current mode   CHARGE   SLOW   FAST   Forced CHARGE   FAST   CHARGE   SLOW
                                                section
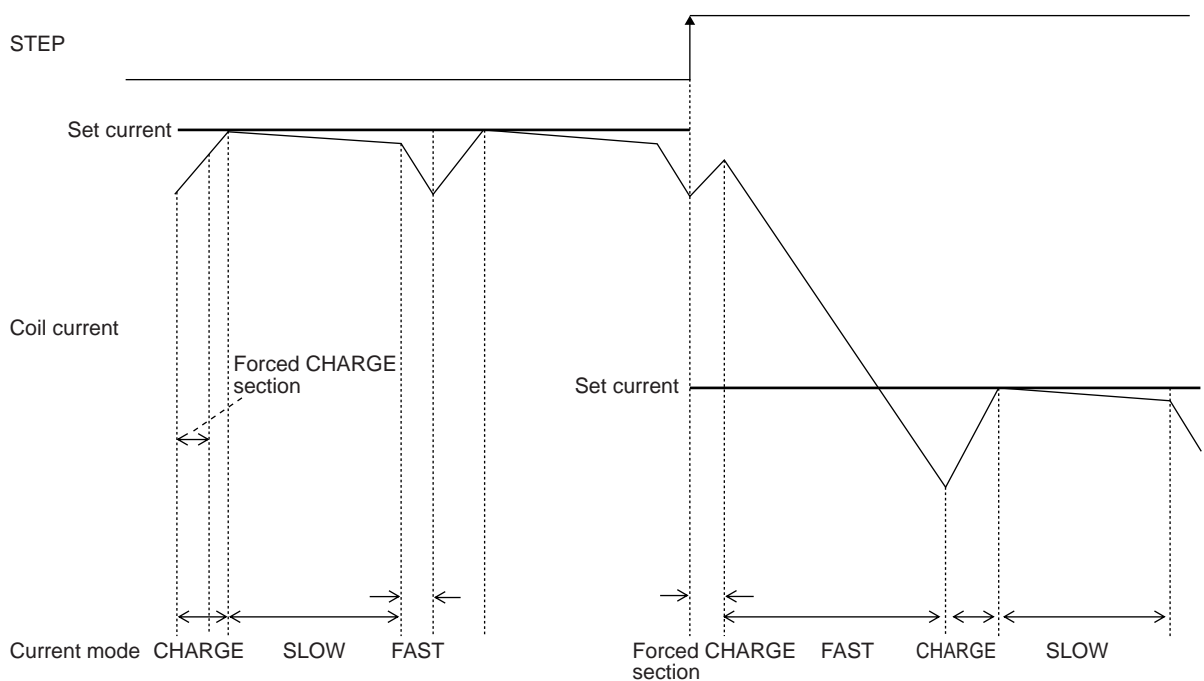
In each current mode, the operation sequence is as described below :
- At rise of chopping frequency, the CHARGE mode begins. (In the time defined as the "blanking time," the CHARGE mode is forced regardless of the magnitude of the coil current (ICOIL) and set current (IREF).)
- The coil current (ICOIL) and set current (IREF) are compared in this blanking time.

    When (ICOIL < IREF) state exists ;

        The CHARGE mode up to ICOIL ≥ IREF, then followed by changeover to the SLOW DECAY mode, and finally by the FAST DECAY mode for approximately 1μs.

    When (ICOIL < IREF) state does not exist ;

        The FAST DECAY mode begins. The coil current is attenuated in the FAST DECAY mode till one cycle of chopping is over.

Above operations are repeated. Normally, the SLOW (+FAST) DECAY mode continues in the sine wave increasing direction, then entering the FAST DECAY mode till the current is attenuated to the set level and followed by the SLOW DECAY mode.

DCM Mode (DM-High)

(1) DCM mode output control logic

Parallel input		Output		Mode
DC11 (21)	DC12 (22)	OUT1 (2) A	OUT1 (2) B	
Low	Low	OFF	OFF	Standby
High	Low	High	Low	CW (Forward)
Low	High	Low	High	CCW (Reverse)
High	High	Low	Low	Brake

(2) Blanking time switching function

Only the DCM mode. At STM mode RST pin : It operates as RESET function.

BLK	Blanking time
Low	$2\mu s$
High	$3\mu s$

(3) Current limit reference voltage setting function

By setting a current limit, this IC automatically exercises short braking control to ensure that when the motor current has reached this limit, the current will not exceed it.

(Current limit control time chart)
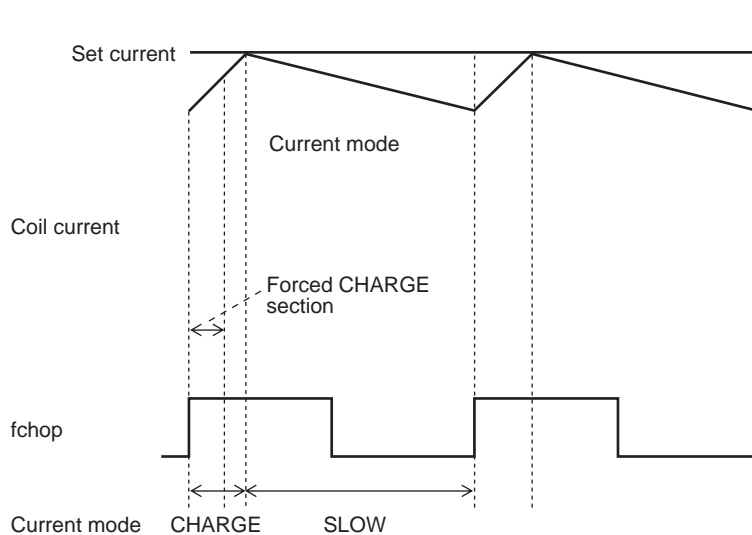
The limit current is set as calculated on the basis of the voltage input to the VREF pin and the resistance between the RF pin and GND using the formula given below.

$$Ilimit = (VREF/5) / RF\ resistance$$

The voltage applied to the VREF pin can be switched to any of the four setting levels depending on the statuses of the two inputs, ATT1 and ATT2.

Function for attenuating VREF input voltage

ATT1	ATT2	Current setting reference voltage attenuation ratio
Low	Low	100%
High	Low	80%
Low	High	50%
High	High	20%

The formula used to calculate the output current when using the function for attenuating the VREF input voltage is given below.

$$Ilimit = (VREF/5) \times (attenuation\ ratio) / RF\ resistance$$

Example : At VREF of 1.5V, a reference voltage setting of 100% [(ATT1, ATT2) = (L, L)] and an RF resistance of 0.5Ω, the output current is set as shown below.

$Ilimit = 1.5V/5 \times 100\%/0.5\Omega = 0.6A$

If, in this state, (ATT1, ATT2) has been set to (H, H), Ilimit will be as follows :

$Ilimit = 0.6A \times 20\% = 120mA$

(4) Current LIMIT mask function

Only the DCM mode. At STM mode OE pin : It operates as output enable function.

The mask can do current LIMIT function during the fixed time set with the CMK pin at the DCM mode. It is effective to make it not hang to the limiter by the start current of the motor to set current LIMIT low.

The charge is begun, current LIMIT function is done to the CMK capacitor meanwhile when switching to forward/ reverse mode, and the mask is done. Afterwards, the mask is released when the voltage of the CMK pin reaches set voltage (typ 1.5V), and the current limit function works.

When 2ch side begins forward (reverse) operation while the mask on 1ch side is operating, the CMK pin is discharged one degree up to a constant voltage, and begins charging again because the CMK pin becomes 2ch using combinedly. Meanwhile, 1ch side and 2ch side enter the state of the mask.
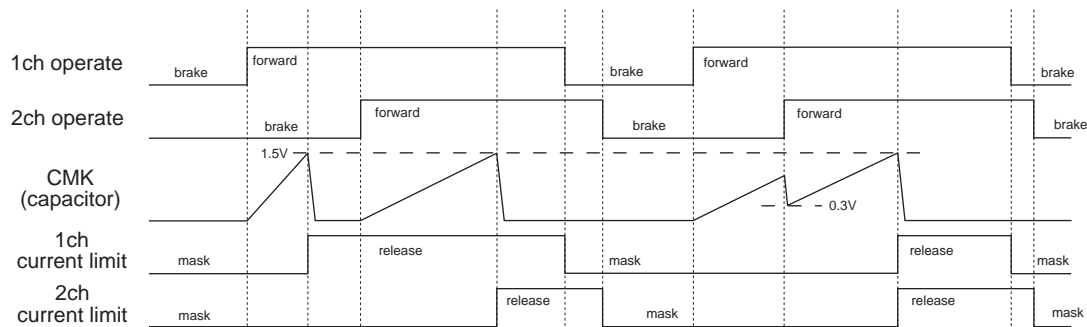
When the capacitor is not connected, the function of LIMIT in the current can be switched to operation/nonoperating state by the state of the input of the CMK pin.

CMK	Current LIMIT function
"L"	nonoperating
"H" or OPEN	operation

(5) Current LIMIT mask time (Tcmk)

The time of the mask of current LIMIT function can be set by connecting capacitor C_{CMK} between CMK pin - GND. Decide the value of capacitor C_{CMK} according to the following expressions.

Mask time : T_{CMK} $T_{CMK} \approx -C_{CMK} \times R \times 1n \left(1 - Vt_{CMK} / (I_{CMK} \times R) \right)$ (sec)
Vt_{CMK} : LIMIT mask threshold voltage   typ. 1.5V
I_{CMK} : CMK pin charge current   typ. 25μA
R : Internal resistance   typ. 100kΩ

(6) Typical current waveform in each excitation mode when stepping motor parallel input control
2-phase excitation (CW mode)
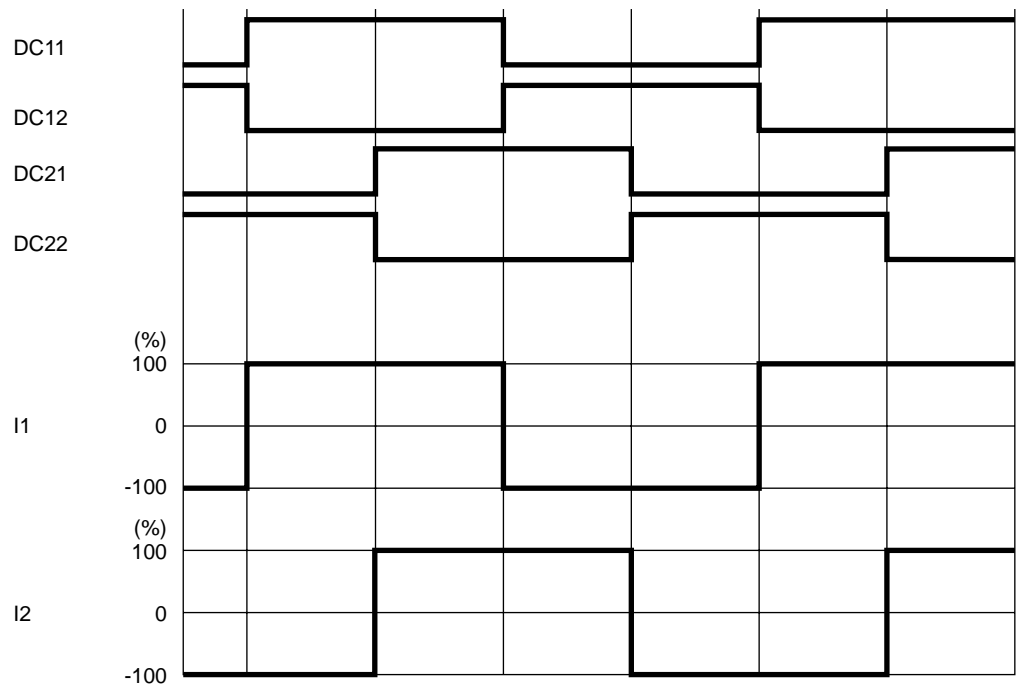
1-2 phase excitation full torque (CW mode)
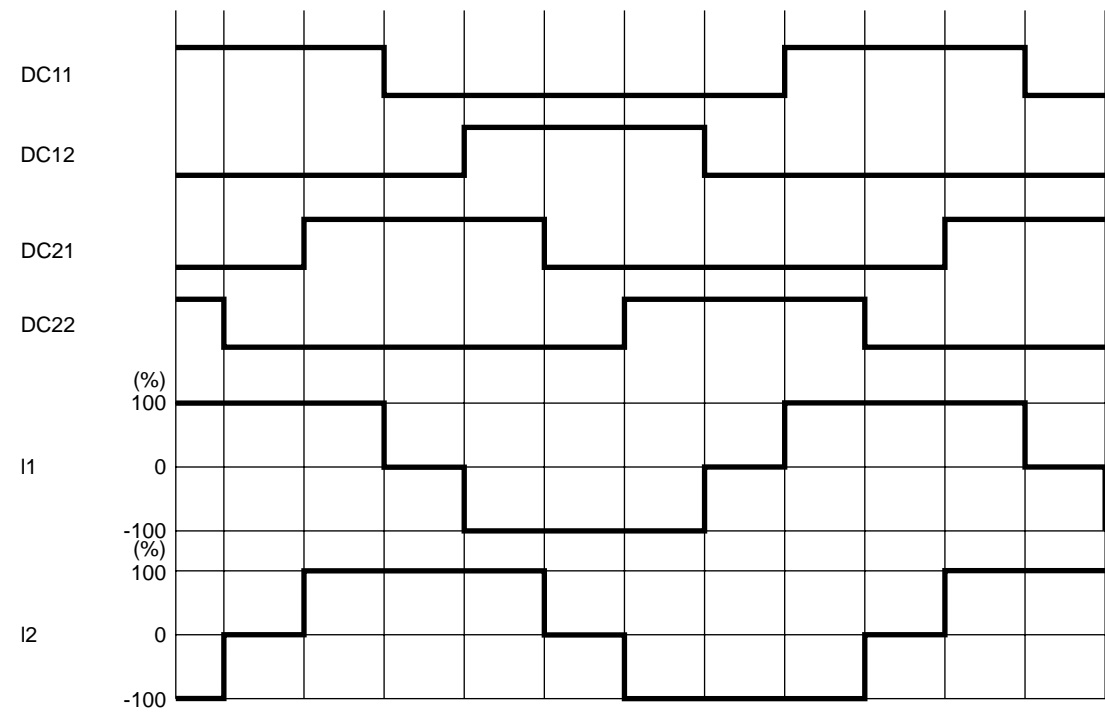
Output short-circuit protection function

This IC incorporates an output short-circuit protection circuit that, when the output has been shorted by an event such as shorting to power or shorting to ground, sets the output to the standby mode and turns on the warning output in order to prevent the IC from being damaged. In the stepping motor driver (STM) mode (DM = Low), this function sets the output to the standby mode for both channels by detecting the short-circuiting in one of the channels. In the DC motor driver mode (DM = High), channels 1 and 2 operate independently. (Even if the output of channel 1 has been short-circuited, channel 2 will operate normally.)

(1) Output short-circuit protection operation changeover function

Changeover to the output short-circuit protection of IC is made by the setting of EMM pin.

EMM	State
Low or Open	Latch method
High	Auto reset method

(2) Latch type

In the latch mode, when the output current exceeds the detection current level, the output is turned OFF, and this state is held.

The detection of the output short-circuited state by the IC causes the output short-circuit protection circuit to be activated.

When the short-circuited state continues for the period of time set using the internal timer (approximately 2μs), the output in which the short-circuiting has been detected is first set to OFF. After this, the output is set to ON again as soon as the timer latch time (Tcem) described later has been exceeded, and if the short-circuited state is still detected, all the outputs of the channel concerned are switched to the standby mode, and this state is held.

This state is released by setting ST to low.

LV8735V
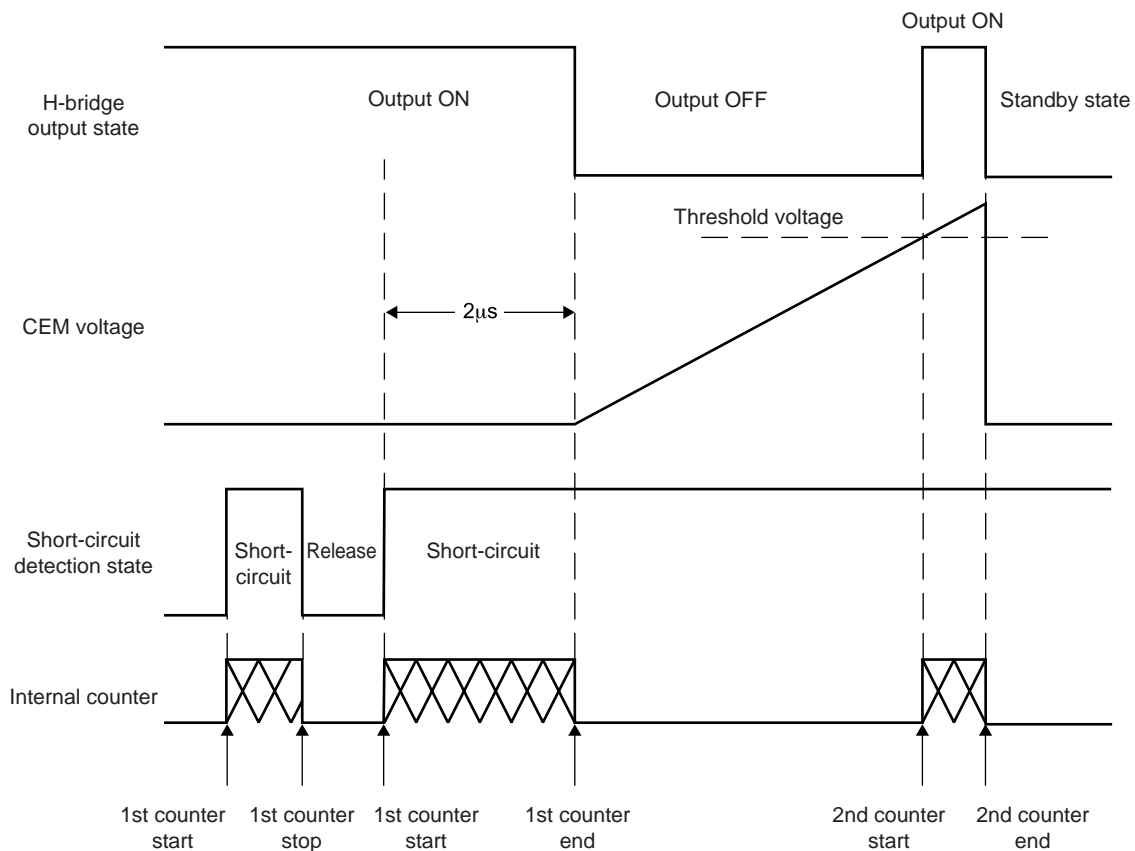
(3) Auto reset type

In the automatic reset mode, when the output current exceeds the detection current level, the output waveform changes to the switching waveform.

As with the latch system, when the output short-circuited state is detected, the short-circuit protection circuit is activated. When the operation of the short-circuit detection circuit exceeds the timer latch time (Tcem) described later, the output is changed over to the standby mode and is reset to the ON mode again in 2ms (typ). In this event, if the overcurrent mode still continues, the switching mode described above is repeated until the overcurrent mode is canceled.

(4) Unusual condition warning output pins (EMO, MONI)

The LV8731V is provided with the EMO pin which notifies the CPU of an unusual condition if the protection circuit operates by detecting an unusual condition of the IC. This pin is of the open-drain output type and when an unusual condition is detected, the EMO output is placed in the ON (EMO = Low) state.
In the DC motor driver mode (DM = High), the MONI pin also functions as a warning output pin.
The functions of the EMO pin and MONI pin change as shown below depending on the state of the DM pin.

When the DM is low (STM mode) :
EMO : Unusual condition warning output pin
MONI : Excitation initial position detection monitoring

When the DM is high (DCM) mode) :
EMO : Channel 1 warning output pin
MONI : Channel 2 warning output pin

Furthermore, the EMO (MONI) pin is placed in the ON state when one of the following conditions occurs.
1. Shorting-to-power, shorting-to-ground, or shorting-to-load occurs at the output pin and the output short-circuit protection circuit is activated.
2. The IC junction temperature rises and the thermal protection circuit is activated.

Unusual condition	DM = L (STM mode)		DM = H (DCM mode)	
	EMO	MONI	EMO	MONI
Channel 1 short-circuit detected	ON	-	ON	-
Channel 2 short-circuit detected	ON	-	-	ON
Overheating condition detected	ON	-	ON	ON

(5) Timer latch time (Tcem)

The time taken for the output to be set to OFF when the output has been short-circuited can be set using capacitor Ccem, connected between the CEM pin and GND. The value of capacitor Ccem is determined by the formula given below.

Timer latch : Tcem $\qquad$ $Tcem \approx Ccem \times Vtcem/Icem$ [sec]
Vtcem : Comparator threshold voltage, typ 1V
Icem : CEM pin charge current, typ 10μA

Overheating protection function

The overheating protection circuit is built into, and the output is turned off when junction temperature Tj exceeds 180°C, and the abnormal state warning output is turned on at the same time. The value of hysteresis and when it falls, the temperature drives the output again (automatic restoration).
The overheating protection circuit doesn't secure protection and the destruction prevention of the set because it becomes operation by the area where ratings Tjmax=150°C of the junction temperature was exceeded.

TSD = 180°C (typ)
ΔTSD = 40°C (typ)

Charge Pump Circuit

When the ST pin is set High, the charge pump circuit operates and the VG pin voltage is boosted from the VM voltage to the VM + VREG5 voltage. Because the output is not turned on if VM+4V or more is not pressured, the voltage of the VG pin recommends the drive of the motor to put the time of t_{ONG} or more, and to begin.
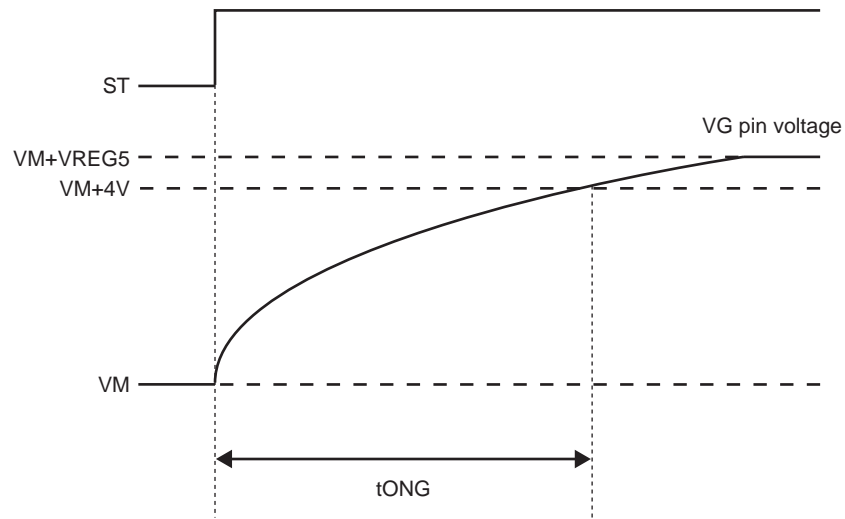
VG Pin Voltage Schematic View

Application Circuit Example

• Stepping motor driver circuit (DM = Low)
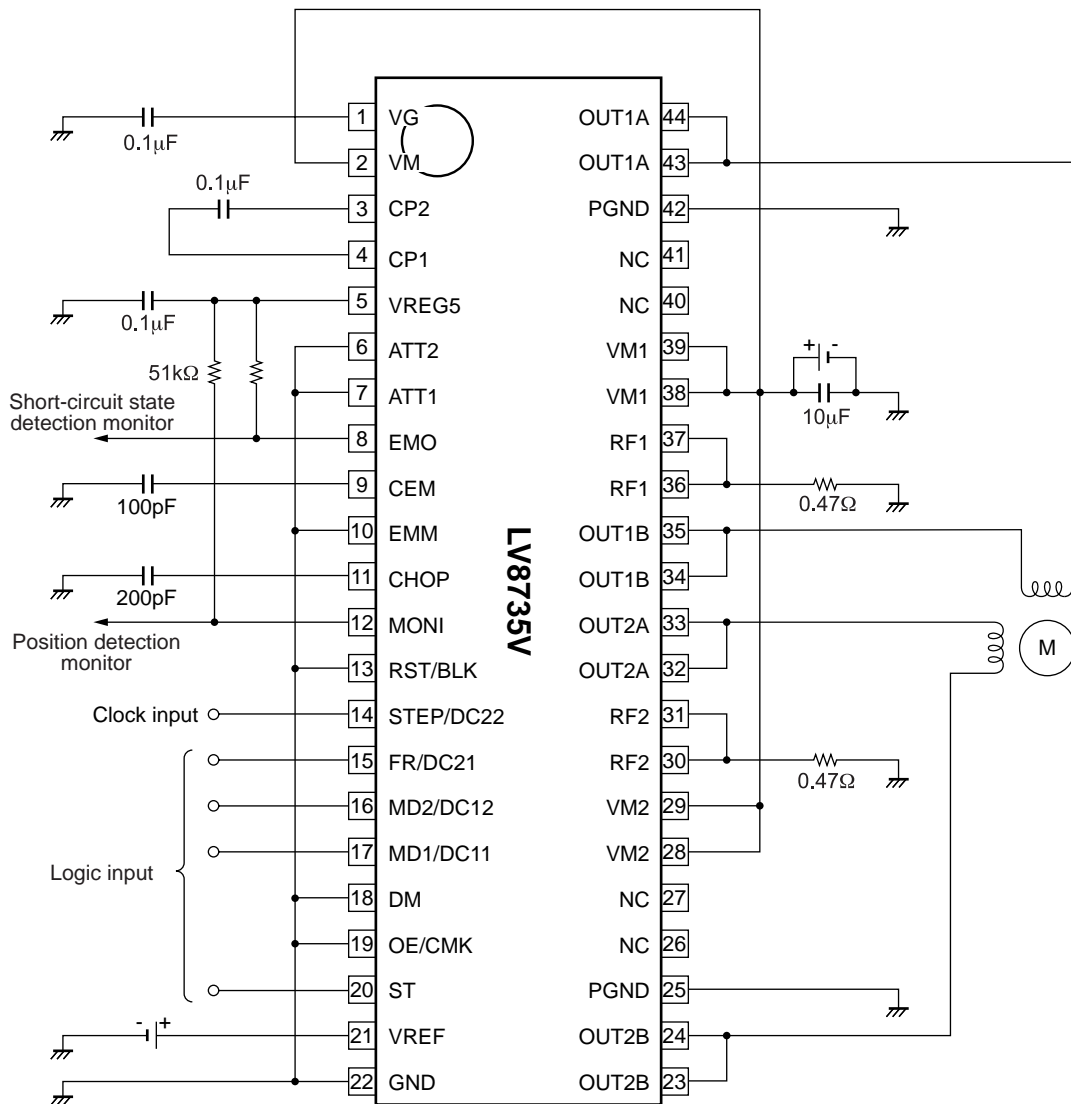
The formulae for setting the constants in the examples of the application circuits above are as follows :

Constant current (100%) setting

When VREF = 1.5V

$$I_{OUT} = VREF/5/RF \text{ resistance}$$
$$= 1.5V/5/0.47\Omega = 10.64A$$

Chopping frequency setting

$$Fchop = Ichop/ (Cchop \times Vtchop \times 2)$$
$$= 10\mu A/ (200pF \times 0.5V \times 2) = 50kHz$$

Timer latch time when the output is short-circuited

$$Tcem = Ccem \times Vtcem/Icem$$
$$= 100pF \times 1V/10\mu A = 10\mu s$$

• DC motor driver circuit (DM = High, and the current limit function is in use.)
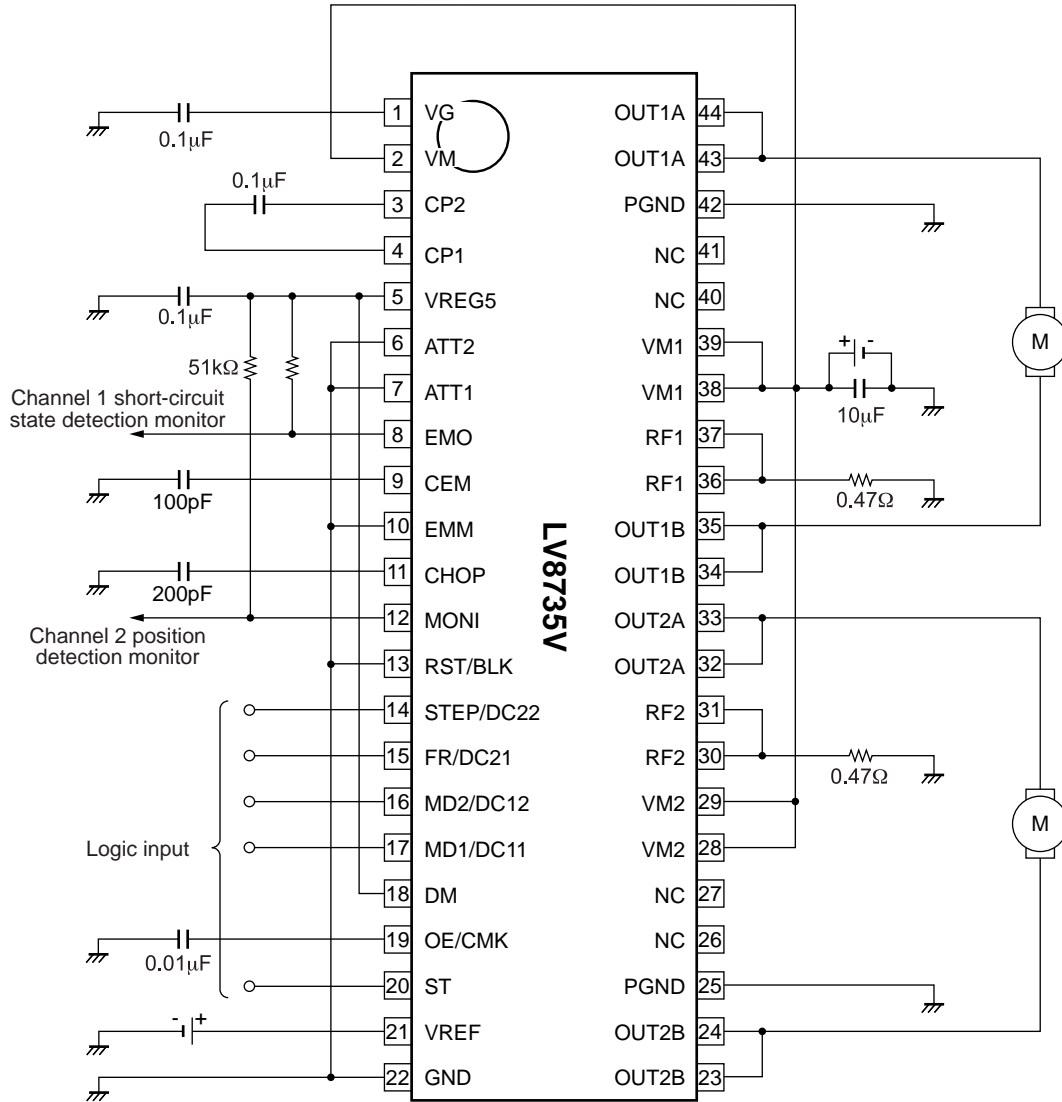
The formulae for setting the constants in the examples of the application circuits above are as follows :

Constant current limit (100%) setting

When VREF = 1.5V

Ilimit = VREF/5/RF resistance

= 1.5V/5/0.47Ω = 0.6A

Chopping frequency setting

Fchop = Ichop/ (Cchop × Vtchop × 2)

= 10μA/ (200pF × 0.5V × 2) = 50kHz

Timer latch time when the output is short-circuited

Tcem = Ccem × Vtcem/Icem

= 100pF × 1V/10μA = 10μs

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