

NCV7428

System Basis Chip with Integrated LIN and Voltage Regulator

Description

NCV7428 is a System Basis Chip (SBC) integrating functions typically found in automotive Electronic Control Units (ECUs). NCV7428 provides and monitors the low-voltage power supply for the application microcontroller and other loads and includes a LIN transceiver.

Features

- Control Logic
 - ◆ Ensures safe power-up sequence and the correct reaction to different supply conditions
 - ◆ Controls mode transitions including the power management and bus wakeup treatment
 - ◆ Generates reset
- 3.3 V or 5 V V_{OUT} Supply depending on the Version from a Low-drop Voltage Regulator
 - ◆ Can deliver up to 70 mA with accuracy of $\pm 2\%$
 - ◆ Supplies typically the ECU's microcontroller
 - ◆ Undervoltage detector with a reset output to the supplied microcontroller
- LIN Transceiver
 - ◆ LIN2.x and J2602 compliant
 - ◆ TxD dominant timeout protection
 - ◆ Transceiver mode controlled by dedicated input pin
- Protection and Monitoring Functions
 - ◆ Thermal shutdown protection
 - ◆ Load dump protection (45 V)
 - ◆ LIN Bus pin protected against transients in an automotive environment
 - ◆ ESD protection level for LIN and $V_S > \pm 8$ kV
- These are Pb-Free Devices

Quality

- NCV Prefix for Automotive and Other Applications Requiring Unique Site and Control Change Requirements; AEC-Q100 Qualified and PPAP Capable

Typical Applications

- Automotive
- Industrial Networks



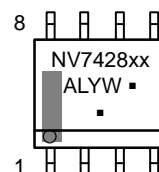
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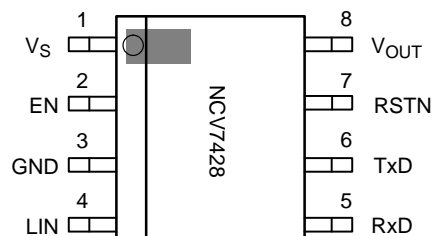
MARKING DIAGRAM



NV7428-5 = NCV7428D15
NV7428-3 = NCV7428D13
NV7428L5 = NCV7428D1L5
NV7428L3 = NCV7428D1L3
A = Assembly Location
L = Wafer Lot
Y = Year
W = Work Week
■ = Pb-Free Package

(Note: Microdot may be in either location)

PIN ASSIGNMENT



(Top View)

ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 17 of this data sheet.

NCV7428

Block Diagram

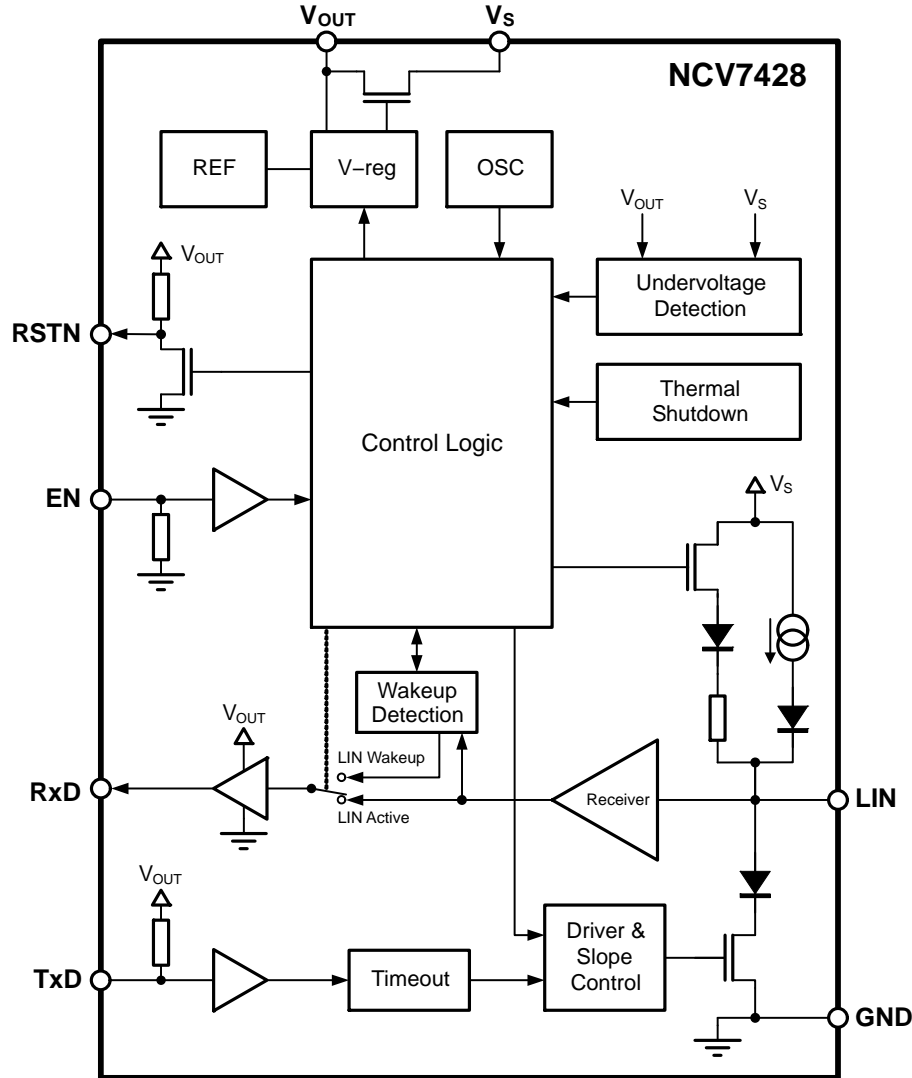


Figure 1. Block Diagram

Pin Description

Table 1. PIN DESCRIPTION

| Pin Number | Pin Name | Pin Type | Pin Function |
|------------|------------------|---|---|
| 1 | V _S | Battery supply input | Principle power supply of the device |
| 2 | EN | LV LIN enable input; internal pull-down | Input of the LIN block enable signal |
| 3 | GND | Ground connection | Ground connection |
| 4 | LIN | LIN bus interface | LIN bus line |
| 5 | RxD | LV digital output; push-pull | Output of data received on LIN bus |
| 6 | TxD | LV digital input; internal pull-up | Input of the data to be transmitted from LIN bus |
| 7 | RSTN | LV digital output; open drain; internal pull-up | System reset |
| 8 | V _{OUT} | LV supply output | Output of the 5 V or 3.3 V/70 mA low-drop regulator (for the MCU) |

NOTE: (LV = Low Voltage; HV = High Voltage)

Application Information

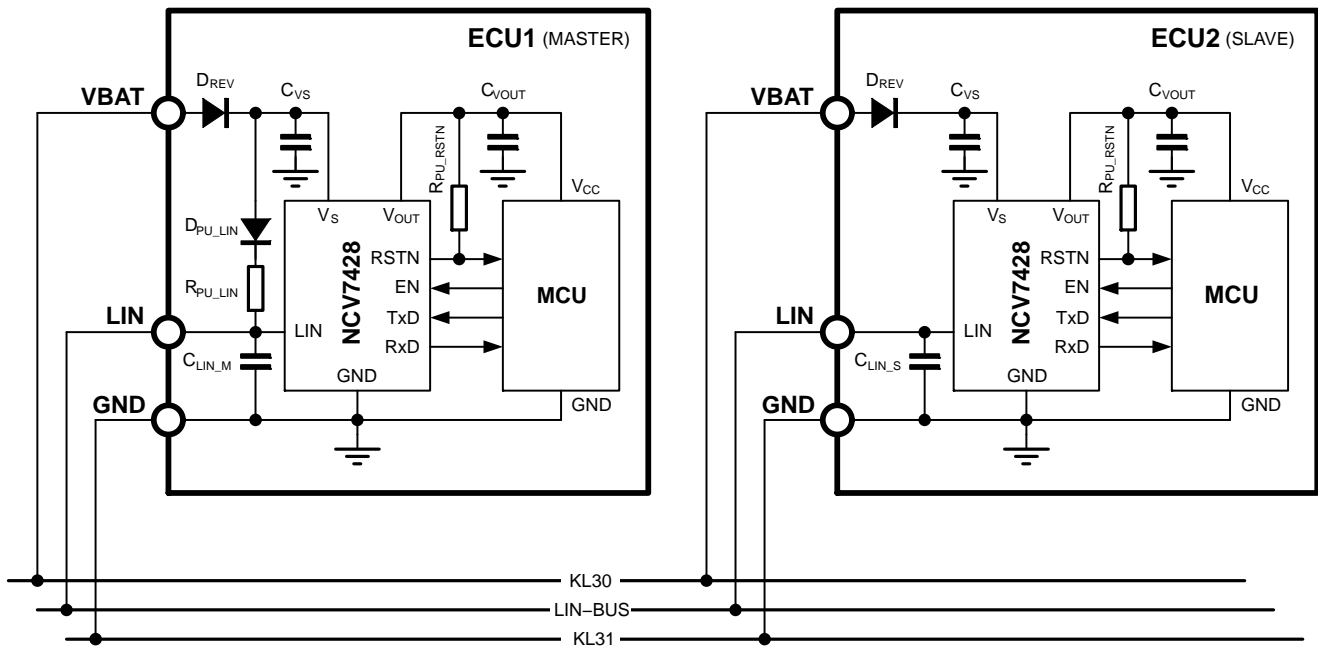


Figure 2. Example Application Diagram

External Components

Overview of external components from application schematic in Figure 2 is given in Table 2 together with their recommended or required values.

Table 2. EXTERNAL COMPONENTS OVERVIEW

| Component Name | Description | Value | Note |
|----------------------|--|---|---|
| D _{REV} | Reverse polarity protection diode | parameters application-specific; e.g. 0.5 A / 50 V | required values and types depend on the V _{OUT} load and the application needs |
| C _{VS} | Filtering capacitor for the battery input | recommended >100 nF ceramic | |
| C _{VOUT} | Voltage regulator output filtering and stabilization capacitor | > 1.8 μF, For the details of ESR range see Application note | |
| D _{PU_LIN} | Master node Pull-up diode on LIN line | | required only for master LIN node |
| R _{PU_LIN} | Master node Pull-up resistor on LIN line | 1 kΩ nominal, ≥500 mW | |
| C _{LIN_M} | Filtering capacitor on LIN line (Master node) | typically 1 nF | optional; is function of the entire LIN network |
| C _{LIN_S} | Filtering capacitor on LIN line (Slave node) | typically 100 pF – 220 pF | optional; is function of the entire LIN network |
| R _{PU_RSTN} | Pull-up resistor on RSTN pin | recommended 10 kΩ nominal | optional; depends on application needs |

Table 3. ABSOLUTE MAXIMUM RATINGS

| Symbol | Parameter | Min | Max | Units |
|------------------------|--|----------------|---------------|-------|
| V_S | Maximum DC voltage at V_S pin | -0.3 | 45 | V |
| V_{OUT} | Maximum voltage at V_{OUT} pin | -0.3 | 6 | V |
| V_{LIN} | Maximum voltage at LIN bus pin | -45 | 45 | V |
| $V_{Dig_IO_inputs}$ | Maximum voltage at digital input pins (TxD, EN) | -0.3 | 45 | V |
| $V_{Dig_IO_outputs}$ | Maximum voltage at digital output pins (RxD, RSTN) | -0.3 | $V_{OUT}+0.3$ | V |
| T_J | Junction temperature | -40 | +170 | °C |
| V_{ESD} | System ESD on pins V_S , LIN as per IEC 61000-4-2: 330 Ω / 150 pF (Verified by external test house) | $\geq \pm 14$ | | kV |
| | Human body model on pins V_S , LIN stressed towards GND with 1500 Ω / 100 pF | $\geq \pm 8$ | | kV |
| | Human body model on all pins as per JESD22-A114 / AEC-Q100-002 | $\geq \pm 4$ | | kV |
| | Charge device model on all pins as per JESD22-C101 / AEC-Q100-011 | $\geq \pm 500$ | | V |
| | Machine model; (200 pF; 0.75 μ H; 10 Ω) as per JESD22-A115 / AEC-Q100-003 | ± 200 | | V |

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

Table 4. OPERATING RANGES

| Symbol | Parameter | Min | Max | Units |
|------------------------|---|-------|-----------|-------|
| V_S | V_S operating voltage for parametric operation (Note 1) | 5.5 | 28 | V |
| | V_S operating voltage for limited operation (Note 1) | 4 | 28 | V |
| V_{OUT5} | Regulated voltage at V_{OUT} supply output for 5 V versions | 4.9 | 5.1 | V |
| V_{OUT33} | Regulated voltage at V_{OUT} supply output for 3.3 V versions | 3.234 | 3.366 | V |
| I_{VOUT} | Current delivered by the V_{OUT} regulator | 70 | | mA |
| V_{LIN} | Operating voltage at LIN bus pin | 0 | V_S | V |
| $V_{Dig_IO_inputs}$ | Operating voltage at digital input and output pins (TxD, EN) | 0 | 5.5 | V |
| $V_{Dig_IO_outputs}$ | Operating voltage at digital input and output pins (RxD, RSTN) | 0 | V_{OUT} | V |
| T_J | Junction temperature | -40 | +150 | °C |
| T_{AMB} | Ambient temperature | -40 | +125 | °C |

1. Below 5.5 V on V_S in normal mode, the bus will either stay recessive or comply with the voltage level specifications and transition time specifications as required by SAE J2602. It is ensured by the battery monitoring circuit. Above 28 V on V_S , LIN communication is operational (LIN pin toggling) but parameters cannot be guaranteed. For higher battery voltage operation above 28 V, LIN pull-up resistor must be selected large enough to avoid clamping of LIN pin by voltage drop over external pull-up resistor and LIN pin min current limitation. Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

Table 5. THERMAL CHARACTERISTICS

| Symbol | Parameter | Conditions | Value | Unit |
|--------------------|---|------------|-------|------|
| $R_{\theta JA_1}$ | Thermal Resistance Junction-to-Air, 1S0P PCB (Note 2) | Free air | 125 | K/W |
| $R_{\theta JA_2}$ | Thermal Resistance Junction-to-Air, 2S2P PCB (Note 3) | Free air | 75 | K/W |

2. Test board according to EIA/JEDEC Standard JESD51-3, signal layer with 10% trace coverage
 3. Test board according to EIA/JEDEC Standard JESD51-7, signal layers with 10% trace coverage

Definitions

The characteristics defined in this section are guaranteed within the operating ranges listed in Table 4, unless stated otherwise. All voltages are referenced to GND (Pin 3). Positive currents flow into the respective pin.

Table 6. DC CHARACTERISTICS ($V_S = 5.5\text{ V}$ to 28 V ; $T_J = -40^\circ\text{C}$ to $+150^\circ\text{C}$; Bus Load = $500\ \Omega$ (V_S to LIN); unless otherwise specified. Typical values are given at $V_S = 12\text{ V}$ and $T_J = 25^\circ\text{C}$, unless otherwise specified.)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------------------------------|--|---|-------------|------|-------|---------------|
| SUPPLY MONITORING | | | | | | |
| V_{S_PORH} | V_S threshold for the power-up of the circuit | V_S rising | 3.3 | | 4 | V |
| V_{S_PORL} | V_S threshold for the Shutdown of the circuit | V_S falling | 2.2 | | 3 | V |
| $V_{OUT_RES_5}$ | V_{OUT} monitoring threshold NV7428-5 | V_{OUT} falling | 4.55 | | 4.75 | V |
| $V_{OUT_RES_3}$ | V_{OUT} monitoring threshold NV7428-3 | V_{OUT} falling | 2.97 | | 3.135 | V |
| $V_{OUT_RES_hys5}$ | V_{OUT} monitoring threshold hysteresis for 5 V versions | | | 0.1 | | V |
| $V_{OUT_RES_hys33}$ | V_{OUT} monitoring threshold hysteresis for 3.3 V versions | | | 0.06 | | V |
| CURRENT CONSUMPTION | | | | | | |
| $I_{VS_LIN_Active_rec}$ | V_S supply current | LIN Active, LIN bus recessive | | | 1.8 | mA |
| $I_{VS_LIN_Wakeup}$ | V_S supply current (Note 6) | Standby mode; LIN Wakeup, LIN bus recessive; $I_{V_{OUT}} = 0\text{ mA}$ $V_S = 13.5\text{ V}$, $T_J < 105^\circ\text{C}$ | | 25 | 40 | μA |
| I_{VS_Sleep} | V_S supply current (Note 6) | Sleep mode; LIN Wakeup, LIN bus recessive; V_{OUT} off, $V_{OUT} < 0.5\text{ V}$ $V_S = 13.5\text{ V}$, $T_J < 105^\circ\text{C}$ | | 12 | 25 | μA |
| V_{OUT} REGULATOR | | | | | | |
| V_{OUT_5} | V_{OUT} regulator output voltage NCV7428-5 | V_{OUT} regulator active, $0 < I_{V_{OUT}} < 70\text{ mA}$, Static regulation, $V_S = 5.5\text{ V}$ to 28 V | 4.9 | 5 | 5.1 | V |
| V_{OUT_3} | V_{OUT} regulator output voltage NCV7428-3 | V_{OUT} regulator active, $0 < I_{V_{OUT}} < 70\text{ mA}$, Static regulation, $V_S = 4.5\text{ V}$ to 28 V | 3.234 | 3.3 | 3.366 | V |
| I_{LIM_VOUT} | V_{OUT} current limitation | V_{OUT} regulator active; current flowing to V_{OUT} load | 70 | 120 | 350 | mA |
| V_{DROP_VOUT} | Drop-out voltage between V_S and V_{OUT} | $5.5\text{ V} < V_S < 40\text{ V}$; $I_{V_{OUT}} = 70\text{ mA}$ | | | 0.55 | V |
| I_{SINK_VOUT} | V_{OUT} sink current | V_{OUT} regulator active, current flowing into the V_{OUT} pin | 100 | 240 | 400 | μA |
| C_{VOUT} | V_{OUT} regulator filtering capacitance (Note 5) | Equivalent series resistance $< 7\ \Omega$ | 1.8 | 10 | | μF |
| LIN TRANSMITTER | | | | | | |
| $V_{LIN_dom_LoSup}$ | LIN dominant output voltage | $TxD = \text{Low}$; $V_S = 7.3\text{ V}$ | | | 1.2 | V |
| $V_{LIN_dom_HiSup}$ | LIN dominant output voltage | $TxD = \text{Low}$; $V_S = 18\text{ V}$ | | | 2.0 | V |
| V_{LIN_REC} | LIN recessive output voltage | $TxD = \text{High}$; $I_{LIN} = 10\ \mu\text{A}$ (Note 4) | $V_S - 1.5$ | | V_S | V |
| I_{LIN_lim} | Short circuit current limitation | $V_{LIN} = V_S = 18\text{ V}$ | 40 | | 200 | mA |
| R_{slave} | Internal Pull-up Resistance | LIN Normal or Receive-only mode | 20 | 33 | 47 | k Ω |
| C_{LIN} | Capacitance on pin LIN (Note 6) | | | 20 | 30 | pF |

- The voltage drop in Normal mode between LIN and V_S pin is the sum of the diode drop and the drop at serial pull-up resistor. The drop at the switch is negligible. See Figure 1.
- In parallel with this capacitor any other capacitor can be placed with no limit to ESR and capacitance value
- Values based on design and characterization. Not tested in production.

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Table 6. DC CHARACTERISTICS ($V_S = 5.5\text{ V to }28\text{ V}$; $T_J = -40^\circ\text{C to }+150^\circ\text{C}$; Bus Load = $500\ \Omega$ (V_S to LIN); unless otherwise specified. Typical values are given at $V_S = 12\text{ V}$ and $T_J = 25^\circ\text{C}$, unless otherwise specified.)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--------|-----------|------------|-----|-----|-----|------|
|--------|-----------|------------|-----|-----|-----|------|

LIN Receiver

| | | | | | | |
|---------------------------|--|---|-------|-----|-------|---------------|
| V_{bus_dom} | Bus voltage for Dominant state | | | | 0.4 | V_S |
| V_{bus_rec} | Bus voltage for Recessive state | | 0.6 | | | V_S |
| V_{rec_dom} | Receiver threshold | LIN bus going from Recessive to Dominant | 0.4 | | 0.6 | V_S |
| V_{rec_rec} | Receiver threshold | LIN bus going from Dominant to Recessive | 0.4 | | 0.6 | V_S |
| V_{rec_cnt} | Receiver center voltage | $(V_{rec_dom} + V_{rec_rec})/2$ | 0.475 | | 0.525 | V_S |
| V_{rec_hys} | Receiver hysteresis | $V_{rec_rec} - V_{rec_dom}$ | 0.05 | | 0.175 | V_S |
| $I_{LIN_off_dom}$ | LIN output current, Bus in dominant state | LIN Active Mode, Driver Off; $V_S = 12\text{ V}$, $V_{LIN} = 0\text{ V}$ | -1 | | | mA |
| $I_{LIN_off_dom_wake}$ | LIN output current, Bus in dominant state | LIN Wakeup Mode; $V_S = 12\text{ V}$, $V_{LIN} = 0\text{ V}$ | -20 | -15 | -2 | μA |
| $I_{LIN_off_rec}$ | LIN output current, Bus in recessive state | Driver Off; $V_S < 18\text{ V}$; $V_S < V_{LIN} < 18\text{ V}$ | | | 1 | μA |
| $I_{LIN_no_GND}$ | LIN current with missing GND | $V_S = GND = 12\text{ V}$; $0 < V_{LIN} < 18\text{ V}$ | -1 | | 1 | mA |
| $I_{LIN_no_VBB}$ | LIN current with missing V_S | $V_S = GND = 0\text{ V}$; $0 < V_{LIN} < 18\text{ V}$ | | | 5 | μA |

PIN EN

| | | | | | | |
|--------------------|-----------------------------|--|------|-----|-----|------------|
| V_{IL_EN} | Low-level input voltage | | -0.3 | | 0.8 | V |
| V_{IH_EN} | High-level input voltage | | 2 | | 5.5 | V |
| $R_{pulldown_EN}$ | Pull-down resistance to GND | | 55 | 100 | 185 | k Ω |

PIN TxD

| | | | | | | |
|-------------------|---------------------------------|------------------------------------|------|-----|-----|---------------|
| V_{IL_TxD} | Low-level input voltage | | -0.3 | | 0.8 | V |
| V_{IH_TxD} | High-level input voltage | | 2 | | 5.5 | V |
| R_{pullup_TxD} | Pull-up resistance to V_{OUT} | | 55 | 100 | 185 | k Ω |
| I_{LEAK_TxD} | Leakage current | $V_{TxD} = V_{OUT} = 5.5\text{ V}$ | -1 | 0 | 1 | μA |

PIN RSTN

| | | | | | | |
|----------------------|--|---|----|-----|-----|------------|
| I_{OL_RSTN} | Low-level output driving current | $V_S = 4\text{ V to }28\text{ V}$; $V_{RSTN} = 0.4\text{ V}$ | 4 | | 30 | mA |
| V_{OL_RSTN} | Low-level output voltage | $V_S = 2\text{ V to }4\text{ V}$; $V_{OUT} = 0\text{ V to }5.5\text{ V}$; $I_{RSTN} = 100\ \mu\text{A}$ | | | 0.1 | V_{OUT} |
| | | $V_S < 2\text{ V}$; $V_{OUT} = 1\text{ V to }5.5\text{ V}$; $I_{RSTN} = 100\ \mu\text{A}$ | | | 0.1 | V_{OUT} |
| R_{pullup_RSTN} | Pull-up resistance to V_{OUT} | | 55 | 100 | 185 | k Ω |
| $V_{S_DigOut_Low}$ | V_S level guaranteeing Low level on RSTN pin | Shutdown mode; Low level guaranteed for $V_S > V_{S_DigOut_Low}$ | | | 2 | V |

PIN RxD

| | | | | | | |
|---------------|-----------------------------------|------------------------------------|-----|--|-------|----|
| I_{OL_RxD} | Low-level output driving current | $V_{RxD} = 0.4\text{ V}$ | 0.4 | | | mA |
| I_{OH_RxD} | High-level output driving current | $V_{RxD} = V_{OUT} - 0.4\text{ V}$ | | | -0.16 | mA |

THERMAL SHUTDOWN

| | | | | | | |
|------------------|---|--|-----|-----|-----|------------------|
| T_{J_SD} | Junction temperature for thermal Shutdown | | 160 | 180 | 200 | $^\circ\text{C}$ |
| $T_{J_SD_hys}$ | Thermal Shutdown hysteresis | | | 10 | | $^\circ\text{C}$ |

- The voltage drop in Normal mode between LIN and V_S pin is the sum of the diode drop and the drop at serial pull-up resistor. The drop at the switch is negligible. See Figure 1.
- In parallel with this capacitor any other capacitor can be placed with no limit to ESR and capacitance value
- Values based on design and characterization. Not tested in production.

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

Table 7. AC CHARACTERISTICS ($V_S = 5.5\text{ V to }28\text{ V}$; $T_J = -40^\circ\text{C to }+150^\circ\text{C}$; unless otherwise specified. For the transmitter parameters, the following bus loads are considered: $L1 = 1\text{ k}\Omega / 1\text{ nF}$; $L2 = 660\text{ }\Omega / 6.8\text{ nF}$; $L3 = 500\text{ }\Omega / 10\text{ nF}$)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--------------------------------------|---|---|-------|-----|-------|---------------|
| LIN TRANSMITTER | | | | | | |
| D1 | Duty Cycle 1 = $t_{\text{BUS_REC(min)}} / (2 \times t_{\text{BIT}})$ | $\text{TH}_{\text{REC(max)}} = 0.744 \times V_S$ $\text{TH}_{\text{DOM(max)}} = 0.581 \times V_S$ $t_{\text{BIT}} = 50\text{ }\mu\text{s}$ $V_S = 7\text{ V to }18\text{ V}$ | 0.396 | | 0.5 | |
| D2 | Duty Cycle 2 = $t_{\text{BUS_REC(max)}} / (2 \times t_{\text{BIT}})$ | $\text{TH}_{\text{REC(min)}} = 0.422 \times V_S$ $\text{TH}_{\text{DOM(min)}} = 0.284 \times V_S$ $t_{\text{BIT}} = 50\text{ }\mu\text{s}$ $V_S = 7.6\text{ V to }18\text{ V}$ | 0.5 | | 0.581 | |
| D3 | Duty Cycle 3 = $t_{\text{BUS_REC(min)}} / (2 \times t_{\text{BIT}})$ | $\text{TH}_{\text{REC(max)}} = 0.778 \times V_S$ $\text{TH}_{\text{DOM(max)}} = 0.616 \times V_S$ $t_{\text{BIT}} = 96\text{ }\mu\text{s}$ $V_S = 7\text{ V to }18\text{ V}$ | 0.417 | | 0.5 | |
| D4 | Duty Cycle 4 = $t_{\text{BUS_REC(max)}} / (2 \times t_{\text{BIT}})$ | $\text{TH}_{\text{REC(min)}} = 0.389 \times V_S$ $\text{TH}_{\text{DOM(min)}} = 0.251 \times V_S$ $t_{\text{BIT}} = 96\text{ }\mu\text{s}$ $V_S = 7.6\text{ V to }18\text{ V}$ | 0.5 | | 0.590 | |
| t_{fallNS} | LIN falling edge normal slope | Normal Mode; $V_S = 12\text{ V}$ | | | 22.5 | μs |
| t_{riseNS} | LIN rising edge normal slope | Normal Mode; $V_S = 12\text{ V}$ | | | 22.5 | μs |
| t_{symNS} | LIN slope symmetry normal slope | Normal Mode; $V_S = 12\text{ V}$ | -4 | 0 | 4 | μs |
| t_{fallLS} | LIN falling edge low slope (Note 8) | Normal Mode; $V_S = 12\text{ V}$ | | | 45 | μs |
| t_{riseLS} | LIN rising edge low slope (Note 8) | Normal Mode; $V_S = 12\text{ V}$ | | | 45 | μs |
| $t_{\text{tx_prop_down}}$ | Propagation Delay of TxD to LIN. TxD high to low | (Note 7) | | | 10 | μs |
| $t_{\text{tx_prop_up}}$ | Propagation Delay of TxD to LIN. TxD low to high | (Note 7) | | | 10 | μs |
| $t_{\text{TxD_timeout}}$ | TxD dominant timeout | TxD = Low; LIN dominant timeout enabled | 7 | 13 | 24 | ms |
| LIN RECEIVER | | | | | | |
| $t_{\text{rec_prop_down}}$ | Propagation delay of receiver falling edge | | 0.1 | | 6 | μs |
| $t_{\text{rec_prop_up}}$ | Propagation delay of receiver rising edge | | 0.1 | | 6 | μs |
| $t_{\text{rec_sym}}$ | Propagation delay symmetry | $T_{\text{rec_prop_down}} -$ $T_{\text{rec_prop_up}}$ | -2 | | 2 | μs |
| $t_{\text{LIN_wake}}$ | Dominant duration for wakeup | LIN in wakeup mode | 30 | 80 | 150 | μs |
| MODE TRANSITIONS AND TIMEOUTS | | | | | | |
| t_{synch} | Input signal synchronization delay | | 5 | 15 | 40 | μs |
| $t_{\text{synch_action}}$ | Delay from the asynchronous input pin change to the system state change | | 11 | 25 | 55 | μs |
| $t_{\text{modsel_set}}$ | Low power mode selection delay | | 17 | 30 | 55 | μs |
| t_{reset} | RSTN pulse extension | | 2 | 5 | 10 | ms |
| $t_{\text{VOUT_RES_filt}}$ | Undervoltage detection filter time | | 11 | 25 | 55 | μs |

7. Values based on design and characterization. Not tested in production.

8. For low slope versions only (NV7428L5 and NV7428L3)

Functional Description

VS Supply Input

V_S pin of NCV7428 is typically connected to the car battery through a reverse-protection diode and can be exposed to all relevant automotive disturbances (ISO7637 pulses, system ESD ...). V_S supplies mainly the integrated LIN transceiver. Filtering capacitors should be connected between V_S and GND.

During power-up of the battery supply, V_S pin must reach V_{S_PORH} level in order for the circuit to become functional – the internal state machine is initiated and the V_{OUT} regulator is activated. The circuit remains functional until V_S falls back below V_{S_PORL} level, when the device enters the Shutdown mode.

VOUT Low-drop Voltage Regulator

The application low-voltage supply is provided by an integrated low-drop voltage regulator delivering a 5 V or 3.3 V output V_{OUT} . It is able to deliver up to 70 mA with given precision and is primarily intended to supply the application microcontroller unit (MCU) and related 5 V or 3.3 V loads (e.g. its own MCU-related digital inputs/outputs). An external capacitor needs to be connected on V_{OUT} pin in order to ensure the regulator's stability and to filter the disturbances caused by the connected loads.

All low-voltage digital pins are related to V_{OUT} .

LIN Transceiver

NCV7428 integrates on-chip LIN transceiver interface between physical LIN bus and the LIN protocol controller.

This LIN physical layer is compatible to LIN2.x and J2602 specifications.

NCV7428 LIN2.2 compliant physical layer can be combined on the network with all previous LIN physical layers.

NCV7428 LIN transceiver consists of a transmitter, receiver and wakeup detector. The LIN transceiver can be connected to the bus line via LIN pin, and to the digital control through pins TxD and RxD. The functional mode of the LIN transceiver depends on the operating mode and on EN pin state – see Figure 3. The LIN transceiver is supplied directly from the V_S pin.

LIN Operating Modes

In **LIN Active mode** the transceiver can transmit and receive data via LIN bus with speed up to 20 kBaud for normal slope mode and 10 kBaud/s for low slope version. The transmit data stream of the LIN protocol is present on the TxD pin and converted by the transmitter into a LIN bus signal with controlled slew rate to minimize EMC emission. The receiver consists of the comparator that has a threshold with hysteresis in respect to the supply voltage and an input filter to remove bus noise. The LIN output is pulled HIGH via an internal pull-up resistor (typ. 30 k Ω). For master applications, it is needed to put an external resistor (typ. 1 k Ω) with a serial diode between LIN and V_S . The mode selection is done by EN = High.

The transmission is only initiated with the TxD falling edge in LIN Active mode. Entering this mode with TxD already Low will not lead to transmitting bus Dominant signal.

When leaving Normal mode (EN pin falling edge), the transmitter is deactivated immediately.

The **LIN Wakeup mode** can be entered if the EN pin is Low. The LIN receiver stays active to be able to detect a remote wake-up via bus. The LIN transmitter is disabled and the slave internal termination resistor of 30 k Ω between LIN and V_S is disconnected in order to minimize current consumption. Only a pull-up current source between V_S and LIN is active. The valid LIN wakeup event causes driving RxD Low until EN pin is pulled High.

A Wakeup pattern that is initiated in LIN Active mode and ends in LIN Wakeup mode is also considered a valid Wakeup event.

The LIN Wakeup mode is also forced if the device enters to the Sleep operating mode.

The **LIN Off mode** provides extreme low current consumption, LIN transceiver is fully deactivated. Pin RxD stays High (as long as V_{OUT} is provided) and logical level on TxD is ignored.

The bus pin is internally pulled to V_S with a current source (thus limiting V_S consumption in case of a permanent LIN short to GND).

This mode is entered when NCV7428 is in Shutdown mode ($V_S < V_{S_PORL}$) or in Thermal Shutdown mode ($T_J > T_{J_SD}$).

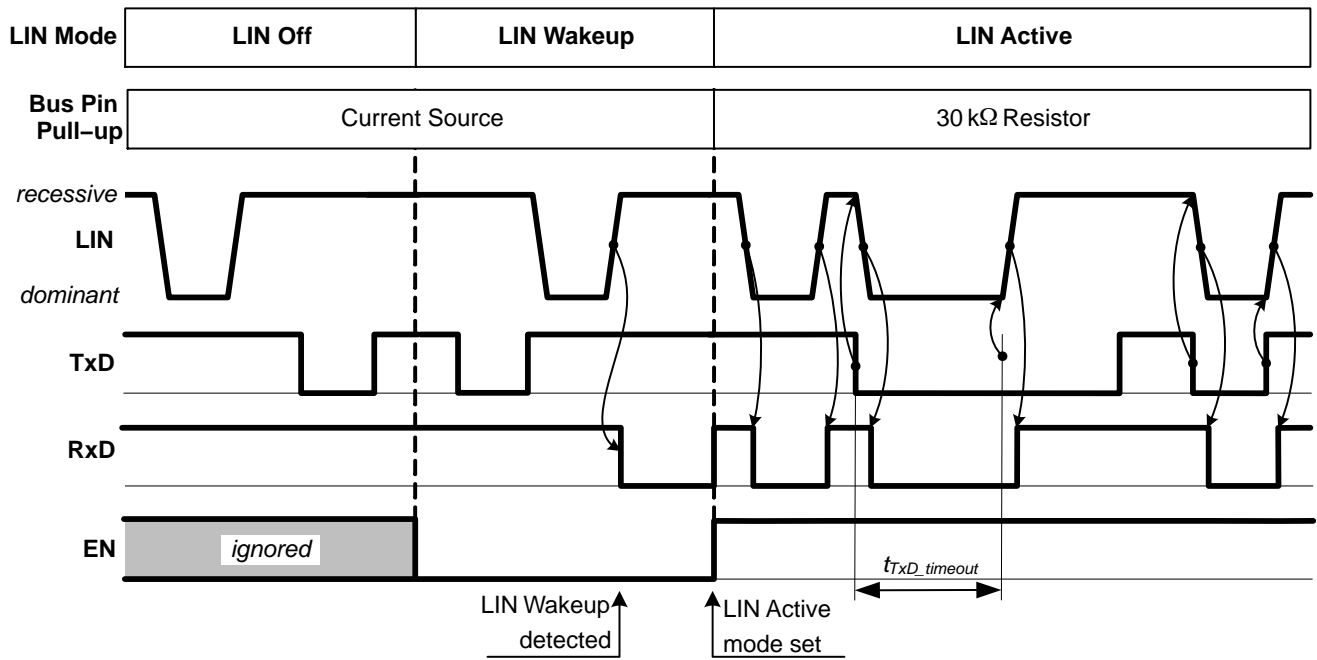


Figure 3. LIN Modes

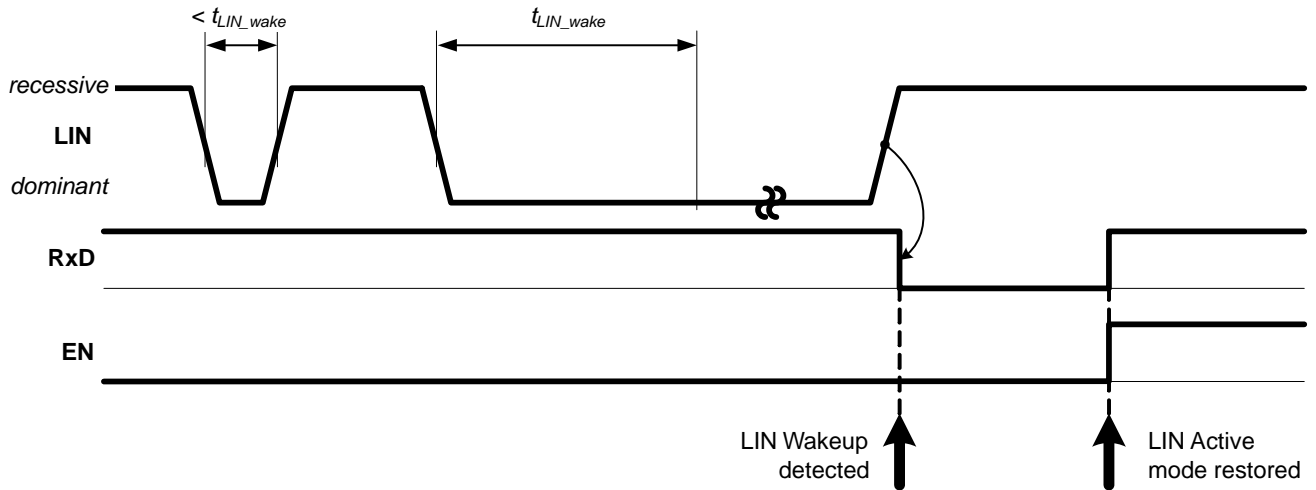


Figure 4. LIN Wakeup Detection

Operating Modes

The principal operating modes of NCV7428 are shown in Figure 5 and described in the following paragraphs.

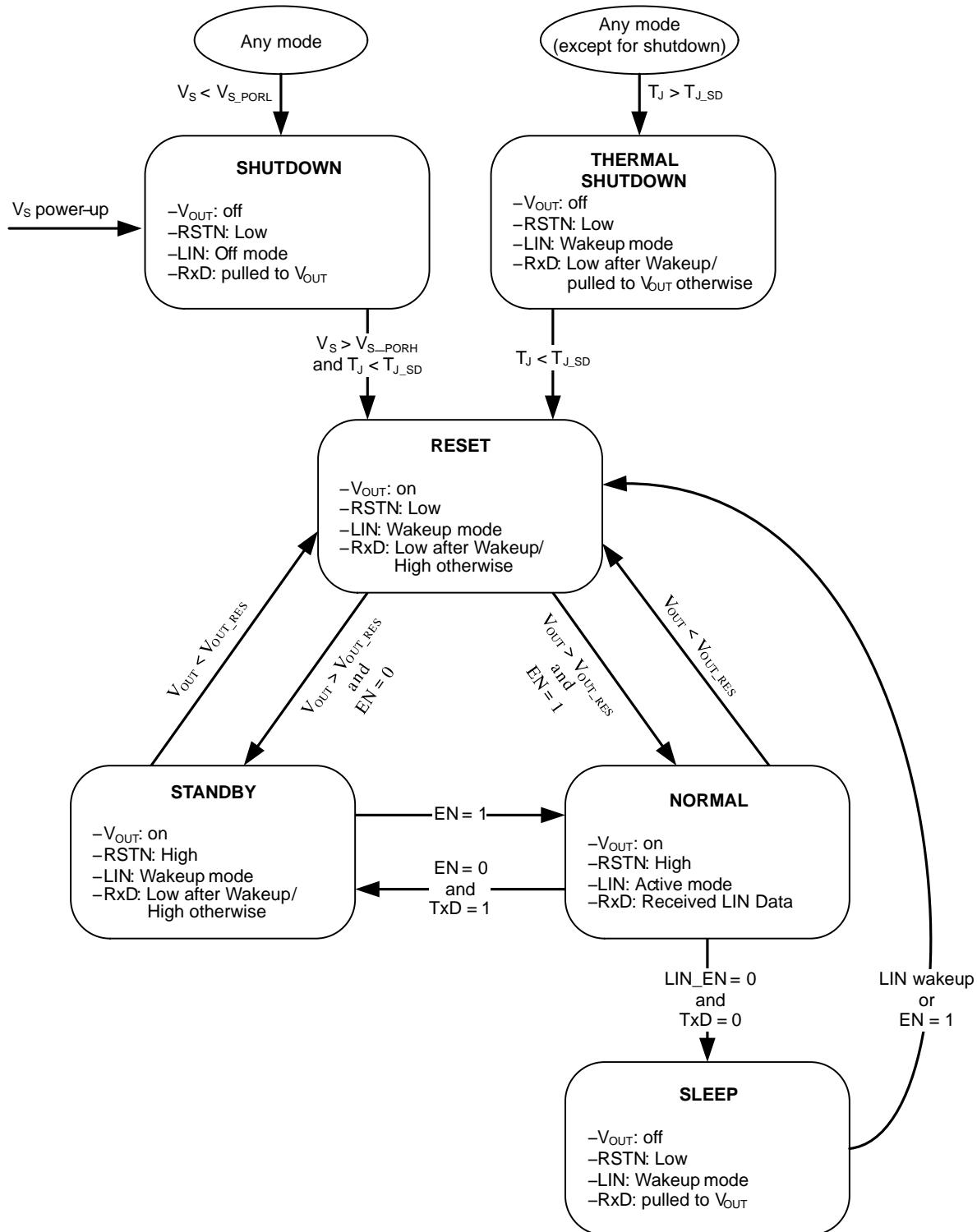


Figure 5. Operating Modes

Shutdown Mode

The Shutdown mode is a passive state, in which all NCV7428 resources are inactive. The Shutdown mode provides a defined starting point for the circuit in case of supply undervoltage, thermal Shutdown or the first supply connection.

On-chip power-supply V_{OUT} is switched off and the LIN pin remains passive so that it does not disturb the communication of other nodes connected to the LIN bus. RxD pin stays pulled to V_{OUT} . No wakeups can be detected.

RSTN pin is forced Low – RSTN Low level is guaranteed for V_S supply above $V_{S_DigOut_Low}$.

The Shutdown mode is entered asynchronously whenever the V_S level falls below the power-on-reset level V_{S_PORL} .

The Shutdown mode is left only when the V_S supply exceeds the high power-on-reset level V_{S_PORH} while junction temperature is below T_{J_SD} . When exiting the Shutdown mode, NCV7428 always enters the Reset mode.

RESET Mode

The Reset mode is a transient mode providing a defined RSTN pulse for the application microcontroller.

V_{OUT} supply is kept active. The LIN pin is passive so that it does not disturb the communication of other nodes connected to the bus. RxD pin is High if no wakeup was detected, RxD Low level indicates pending LIN wakeup. Pin RSTN is forced Low.

Reset mode will be entered as a consequence of one of the following events:

- Shutdown mode is exited
- Thermal Shutdown mode is exited
- V_{OUT} voltage falls below V_{OUT_RES} level
- LIN wakeup or EN = High was detected in Sleep mode

Normally, the Reset mode is left when V_{OUT} voltage is above V_{OUT_RES} threshold and defined time t_{reset} elapses. The RSTN pin is internally released to High and the chip then goes to the Normal or Standby mode, depending on EN state.

Normal Mode

Normal mode is entered from Standby mode after a host request – driving EN pin High (Figure 9), or if EN pin is High when leaving Reset mode – t_{reset} time elapsed (Figure 8).

LIN transceiver is in Active mode. V_{OUT} is kept on. Pin RSTN remains High.

Standby Mode

Standby mode is entered from Normal mode after host request – EN pin falling edge followed by TxD pin High. TxD is sampled $t_{synch} + t_{modesel}$ after EN edge (Figure 9). Standby mode is also entered if EN pin is Low when leaving Reset mode – t_{reset} time elapsed (Figure 7).

LIN transceiver is in Wakeup mode – RxD pin is latched Low after valid Wakeup recognition until Normal mode is requested. V_{OUT} is kept active. Pin RSTN remains High.

Sleep Mode

Sleep mode can be only entered from Normal mode after a host request – EN pin falling edge followed by TxD pin Low. TxD is sampled $t_{synch} + t_{modesel}$ after EN pin edge (Figure 10).

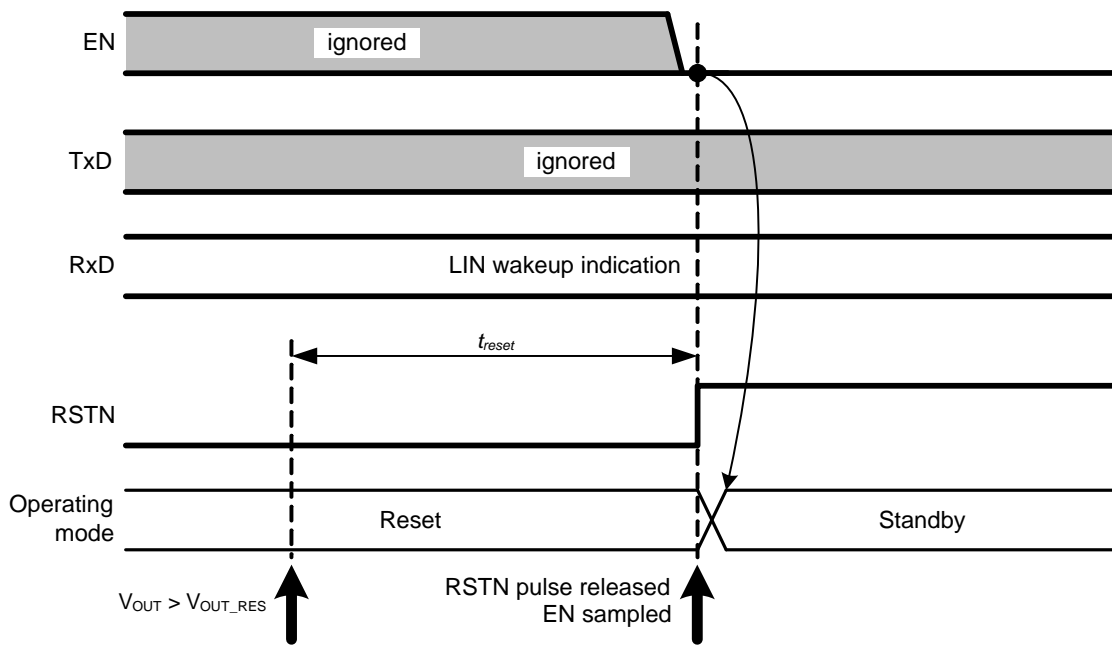
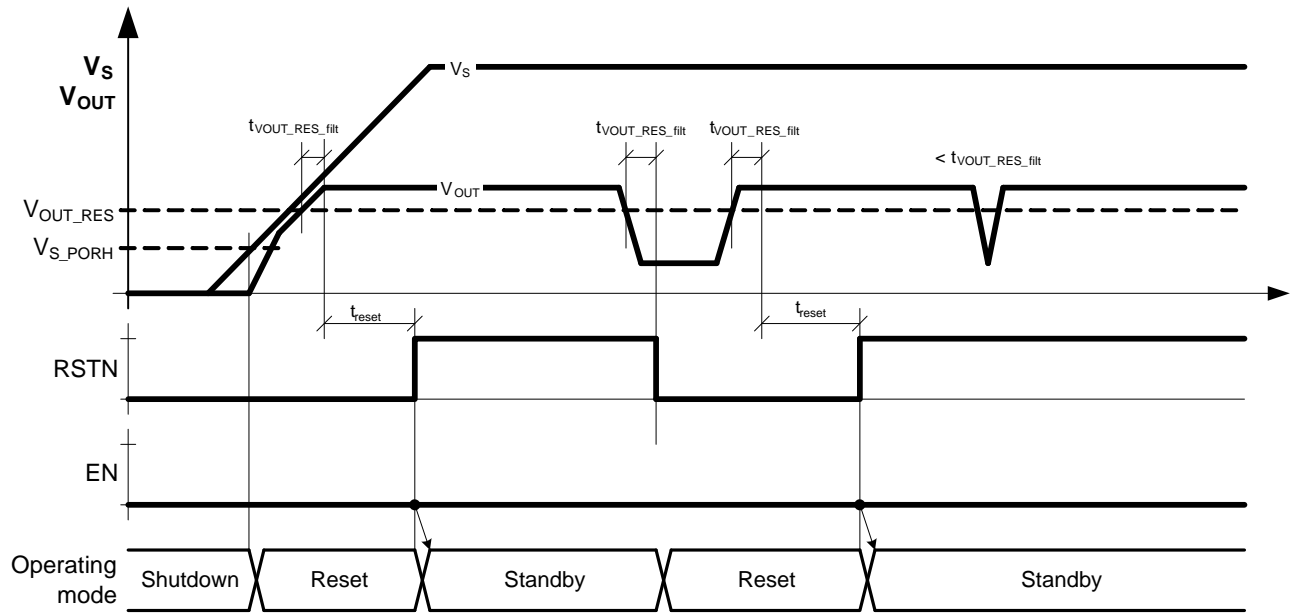
V_{OUT} regulator is switched off, LIN transceiver is in the Wakeup mode.

If LIN wakeup is detected or EN goes High, Reset mode is entered. LIN wakeup is signaled by RxD, which remains Low until Normal mode is restored (EN is High).

Thermal Shutdown

The device junction temperature is monitored in order to avoid permanent degradation or damage of the chip. Junction temperature exceeding the Shutdown level T_{J_SD} puts the chip into Thermal Shutdown mode.

In Thermal Shutdown mode, V_{OUT} regulator is switched off. LIN transceiver is in Wakeup mode and can detect bus Wakeup. RxD pin stays pulled to V_{OUT} or is driven Low after valid Wakeup recognition. RSTN pin is pulled low. The mode is automatically left only when the junction cools down below the T_{J_SD} threshold.



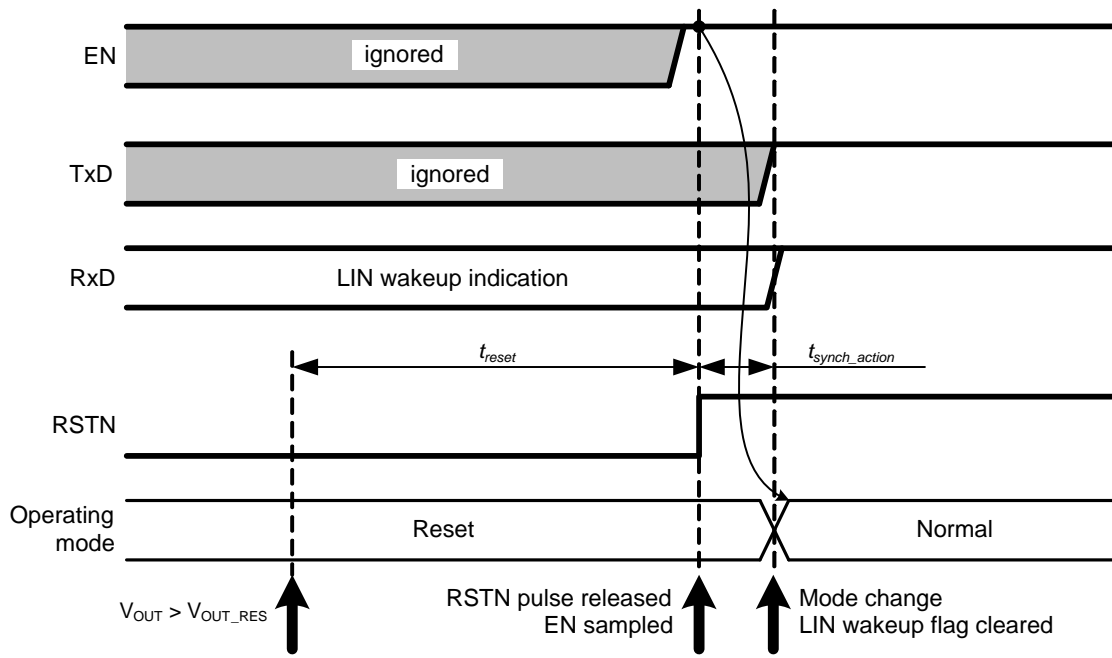


Figure 8. Operating Modes, Transition from Reset to Normal Mode

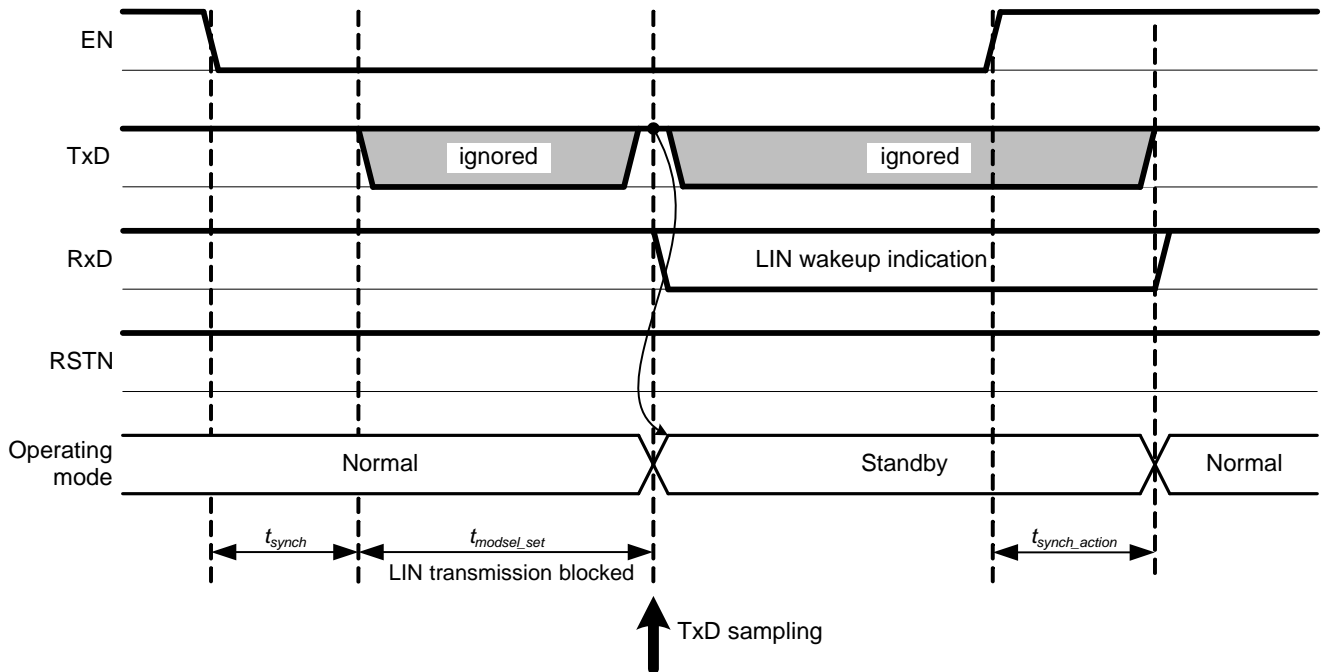


Figure 9. Operating Modes, Transition from Normal to Standby Mode

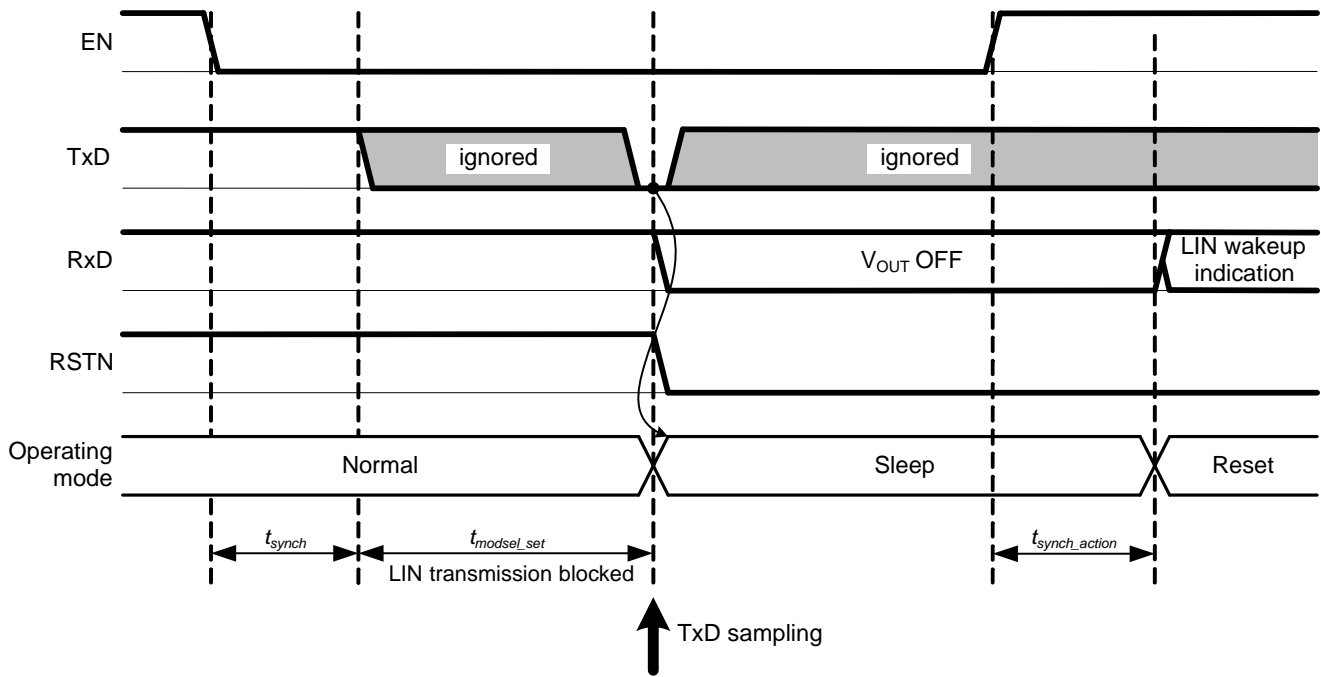


Figure 10. Operating Modes, Transition from Normal to Sleep Mode

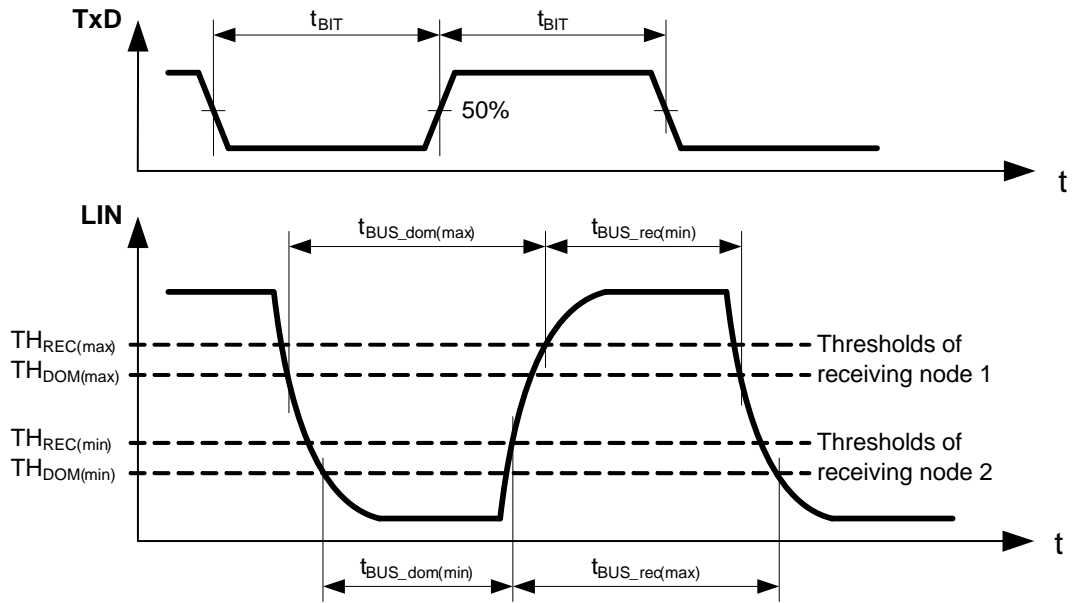


Figure 11. Definition of LIN Duty Cycle Parameters

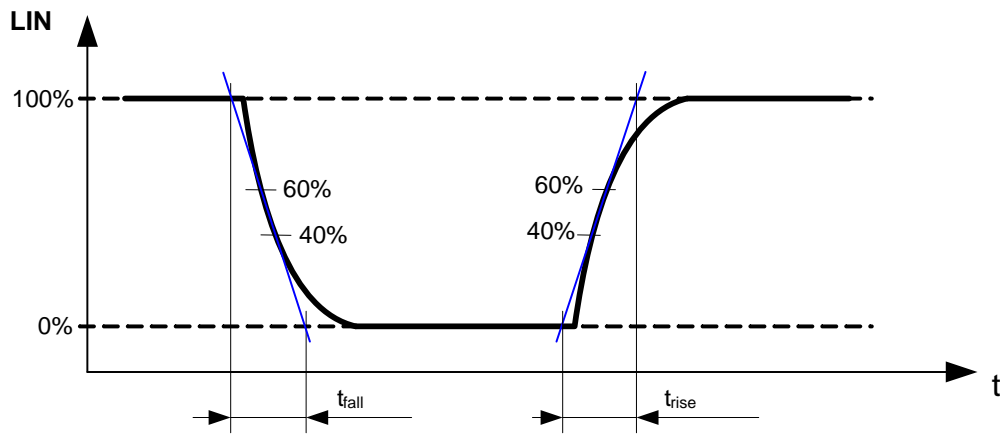


Figure 12. Definition of LIN Edge Parameters

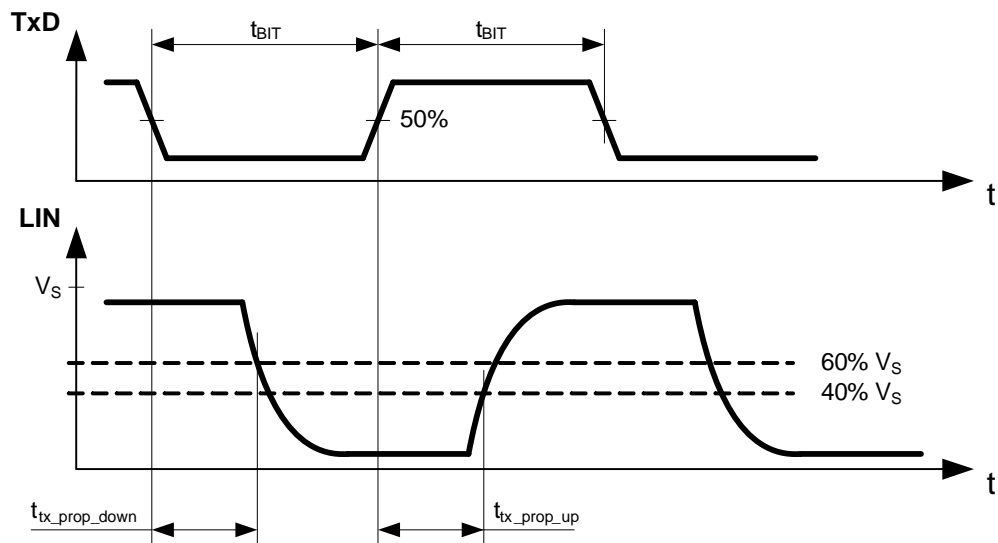


Figure 13. Definition of LIN Transmitter Timing Parameters

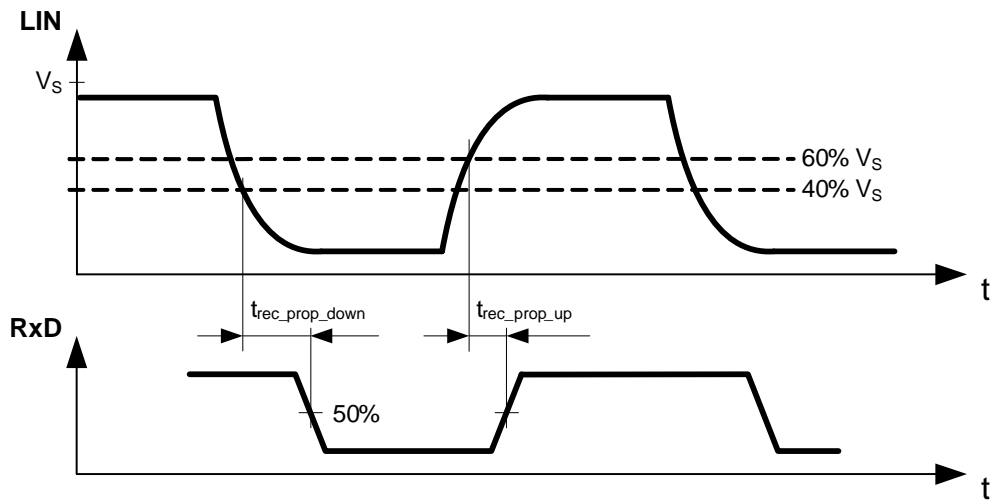
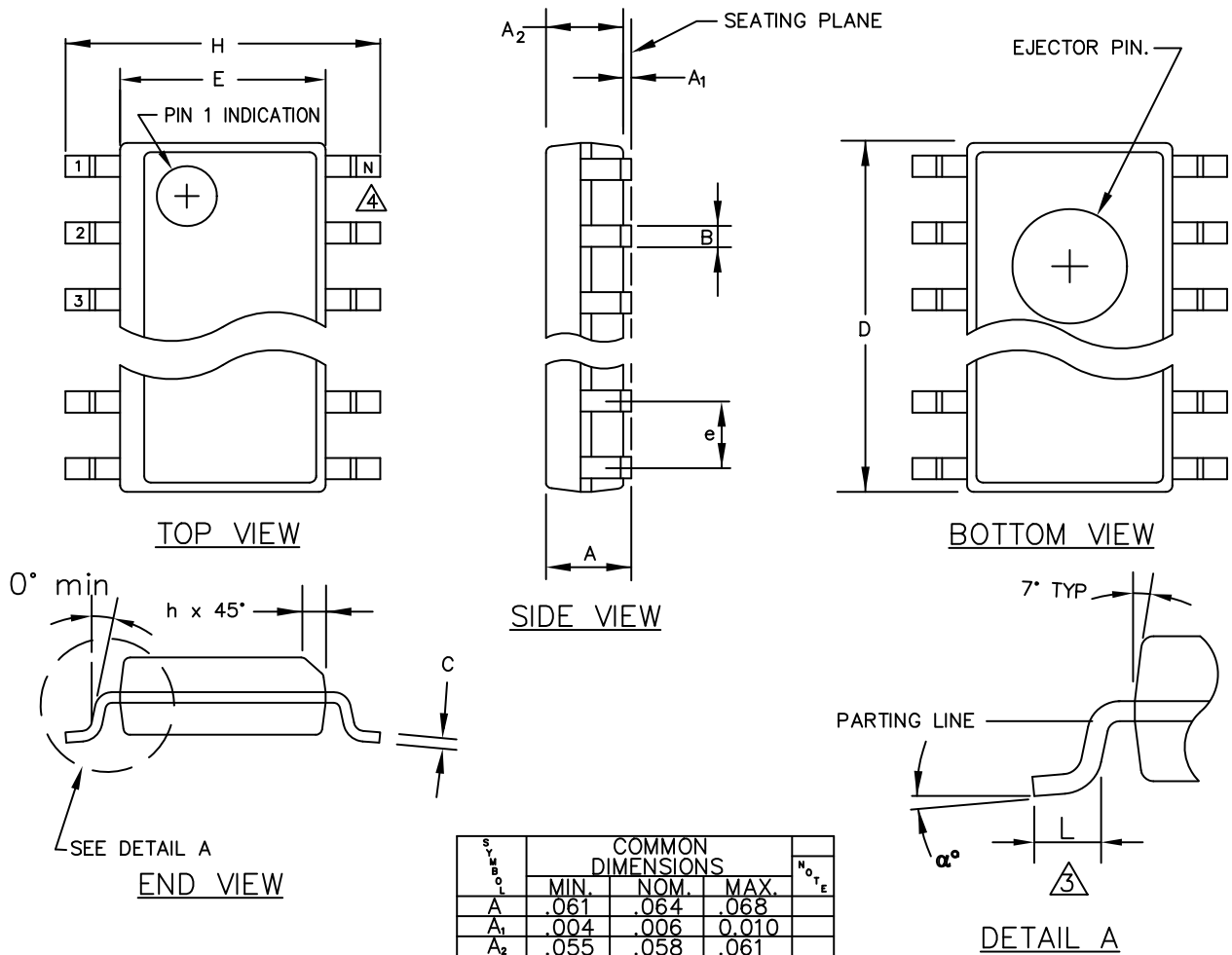


Figure 14. Definition of LIN Receiver Timing Parameters

PACKAGE DIMENSIONS

SOIC 8
CASE 751AZ
ISSUE O




1. ALL DIMENSIONS ARE IN MILLIMETERS.

NCV7428

ORDERING INFORMATION

| Part Number | Description | Temperature Range | Package | Container † | |
|----------------|--|-------------------|--|-------------|----------|
| | | | | Type | Quantity |
| NCV7428D15R2G | LIN transceiver with 5 V regulator | -40°C to +125°C | SOIC150 8 LEADS GREEN (Matte Sn, JEDEC MS-012) | Tape & Reel | 3000 |
| NCV7428D13R2G | LIN transceiver with 3.3 V regulator | | | | |
| NCV7428D1L5R2G | LIN transceiver with 5 V regulator, low slope LIN | | | | |
| NCV7428D1L3R2G | LIN transceiver with 3.3 V regulator, low slope LIN | | | | |

†For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

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