## E6H-C

CSM E6H-C DS E 3

## Hollow Shafts Eliminate the Need for a Coupling. Compact, High-resolution, General-purpose Rotary Encoder.

- Power supply voltage from 5 to 24 VDC (for Models with Open-collector Output).
- Resolution of up to 3,600 ppr in Encoders with an external diameter of only 40 mm.
- Only 26 mm thick.
- Line driver output also available (maximum cable length extension of 100 m).



Be sure to read *Safety Precautions* on page 4.



## **Ordering Information**

### Encoders [Refer to Dimensions on page 4.]

Power supply voltage	Output configuration	Resolution (pulses/rotation)	Model
5 to 24 VDC	Open-collector output	300, 360, 500, 600, 720, 800, 1,000, 1,024	E6H-CWZ6C (resolution) 0.5M Example: E6H-CWZ6C 300P/R 0.5M
		1,200, 1,500, 1,800, 2,000, 2,048	
		2,500, 3,600	
5 to 12 VDC	Voltage output	300, 360, 500, 600, 720, 800, 1,000, 1,024	E6H-CWZ3E (resolution) 0.5M Example: E6H-CWZ3E 300P/R 0.5M
		1,200, 1,500, 1,800, 2,000, 2,048	
		2,500, 3,600	
5 to 12 VDC	Line-driver output	300, 360, 500, 600, 720, 800, 1,000, 1,024	E6H-CWZ3X (resolution) 0.5M Example: E6H-CWZ3X 300P/R 0.5M
		1,200, 1,500, 1,800, 2,000, 2,048	
		2,500, 3,600	

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## **Ratings and Specifications**

Power supply voltage5 VDC –5% to 24 VDC +15%, ripple (p-p): 5% max.5 VDC –5% to 12 VDC +10%, ripple (p-p): 5% max.Current consumption*1100 mA max.150 mA max.Resolution pulses/rotation)300, 360, 500, 600, 720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000, 2,048, 2,500, 3,600Output phasesPhases A, B, and ZPhases A, A, B, B, Z, and ZOutput configurationVoltage outputLine-driver output*4Output capacityApplied voltage: 35 VDC max. Sink current: 35 mA max. Residual voltage: 0.7 V max. (at sink output of 25 mA)Output resistance: 1 kΩ Sink current: 30 mA max. Residual voltage: 0.7 V max. (at sink output voltage: Vo = 2.5 V m	)=
100 mA max.   150 mA max.	) =
Pulses/rotation)       300, 360, 500, 600, 720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000, 2,048, 2,500, 3,600         Pulses A, B, and Z       Phases A, B, B, Z, and Z         Dutput configuration       Open-collector output       Voltage output       Line-driver output*4         Applied voltage: 35 VDC max. Sink current: 35 mA max. Posidual voltage: 0.7 V max (et sink)       Sink current: 30 mA max. Posidual voltage: 0.7 V max (et sink)       Output resistance: 1 kΩ Sink current: 30 mA max. Posidual voltage: 0.7 V max (et sink)	) =
Output configuration         Open-collector output         Voltage output         Line-driver output*4           Applied voltage: 35 VDC max. Sink current: 35 mA max.         Output resistance: 1 kΩ         Output current: High level: Is sink current: 30 mA max.           Posidual voltage: 0.7 V max (et sink)         Posidual voltage: 0.7 V max (et sink)         Output resistance: 1 kΩ	) =
Applied voltage: 35 VDC max. Sink current: 35 mA max.  Sink current: 35 mA max.  Posidual voltage: 0.7 V max. (et sink.)  Sink current: 30 mA max.  Desidual voltage: 0.7 V max. (et sink.)	) =
Applied voltage: 35 VDC max.  Output resistance: 1 k2/2  Sink current: 35 mA max.  Sink current: 30 mA max.  Sink current: 30 mA max.  Posidual voltage: 0.7 V max (et sink)  Low level: Is	o =
current of 35 mA) current of 30 mA) Output voltage: vo = 2.5 v m	
Maximum response requency*2	
Phase difference petween outputs 90°±45° between A and B (1/4 T ± 1/8 T)	
Rise and fall times of output $1 \mu s$ max. (Control output voltage: 5 V, Load resistance: $1 k\Omega$ , Output cable: $1 \mu s$ max. (	10 mA,
Starting torque 1.5 mN·m max.	
Moment of inertia 2×10 <sup>-6</sup> kg·m² max.	
Shaft Radial 29.4 N	
oading Thrust 4.9 N	
Maximum permissible speed  10,000 r/min	
Ambient temperature Operating: -10 to 70°C (at 90% humidity max.), Storage: -30 to 85°C (with no icing)	
Ambient humidity operating/Storage: 90% max. (with no condensation)	
nsulation resistance Excluded because of capacitor ground.	
Dielectric strength Excluded because of capacitor ground.	
<b>/ibration resistance</b> Destruction: 10 to 500 Hz, 100 m/s² or 1.5-mm double amplitude for 2 hours each in X, Y, and Z directions	
Shock resistance 300 m/s² for 11 ms 3 times each in X, Y, and Z directions (excluding shock to the shaft)	
Degree of orotection*3 IEC 60529 IP50	
Connection method Pre-wired Models (Standard cable length: 0.5 m)	
Material Case: Iron, Main unit: Aluminum, Pressboard panel: SUS304	
Weight (packed state) Approx. 120 g	
Accessories Instruction manual	

<sup>\*1.</sup> An inrush current of approximately 6 A will flow for approximately 0.3 ms when the power is turned ON.

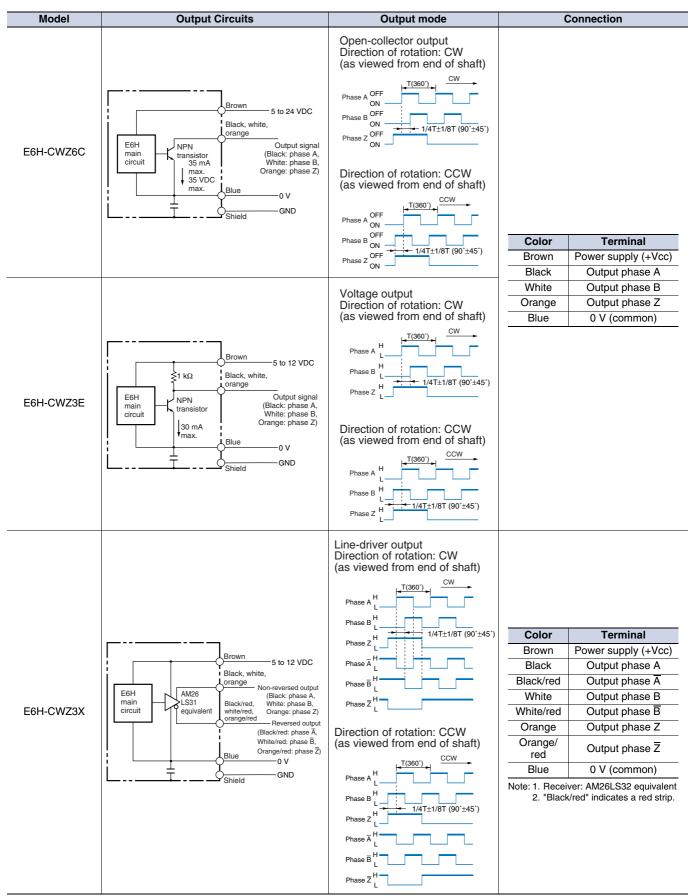
Maximum response frequency ×60 Maximum electrical response speed (rpm) = Resolution

<sup>\*2.</sup> The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

This means that the Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed. \*3. No protection is provided against water or oil.

<sup>\*4.</sup> The line driver output is a data transmission circuit compatible with RS-422A and long-distance transmission is possible with a twisted-pair cable. The quality is equivalent to AM26LS31.

## I/O Circuit Diagrams



Note: Normally connect GND to 0 V or to an external ground.

## **Safety Precautions**

#### Refer to Warranty and Limitations of Liability.

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#### WARNING

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



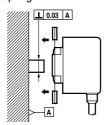
#### **Precautions for Correct Use**

Do not use the Encoder under ambient conditions that exceed the ratings.

#### Mounting

- The diameter of the mating shaft must be 8  $^{-0.012}_{-0.004}$  mm and 8 to 11 mm long from the mounting surface.
- The allowable displacement in the mating shaft must 0.05 mm in the radial direction and 0.3 mm in the thrust direction.
- The mounting surface and shaft must be perpendicular to within 0.03 mm.
- When securing the Encoder, do not allow force to be applied to the leaf spring.

length: 500 mm



Eccentricity will develop in the Encoder if the above values are not satisfied, and the mounting leaf spring may be destroyed.

- When securing the Encoder, use two M3 screws to secure the leaf spring to the mounting surface.
- Use the Allen set screw provided with the hollow shaft to secure the shaft. Use a tightening torque of 0.4 N·m and apply screw lock glue to the screw to prevent it from becoming loose.
- If wiring after securing the Encoder, do not pull on the cable. Also, do not apply shock to the Encoder or hollow shaft.
- If the Encoder phase Z must be aligned with the origin of the installation device, mount the Encoder while checking the phase Z output.

#### Wiring

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

Rotary Encoder Recommended Power Supplies: Consult your OMRON representative for details.

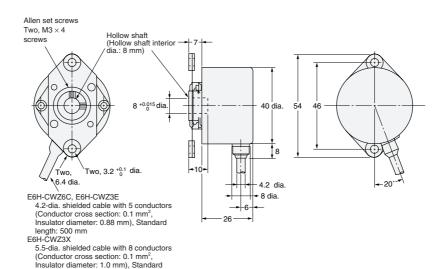
(Unit: mm)

#### **Dimensions**

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

#### E6H-C





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#### **Read and Understand This Catalog**

Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments.

#### Warranty and Limitations of Liability

#### WARRANTY

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#### **DIMENSIONS AND WEIGHTS**

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#### **ERRORS AND OMISSIONS**

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In the interest of product improvement, specifications are subject to change without notice.



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