

DC Axial Fans

ebmpapst

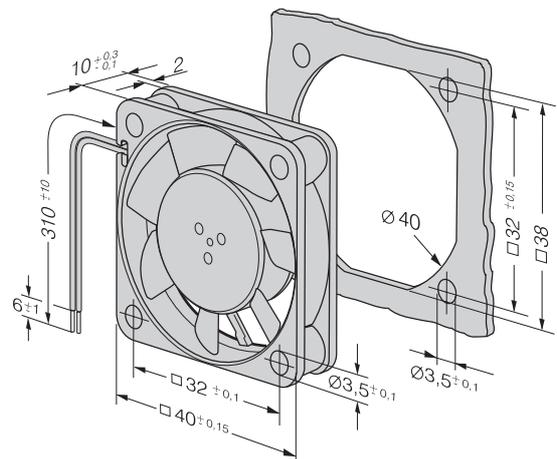
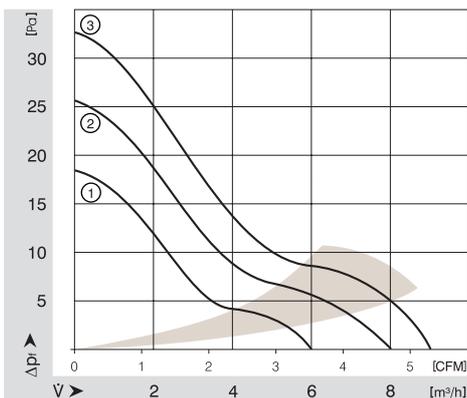
Series 400 F, Type 414 F 40 x 40 x 10 mm



- DC fans with electronically commutated external rotor motor. Fully integrated commutation electronics.
- With electronic protection against reverse polarity. The fan only operates when the polarity is correct. Impedance-protected* against blocking and overloading.
- Fan of fibreglass reinforced plastic. PBT housing, PA impeller.
- Air exhaust over struts. Rotational direction CCW looking at rotor.
- Electrical connection via 2 leads AWG 28, TR 64. Stripped and tinned ends.
- Mass 17 g.

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Nominal Data	Air Flow		Nominal Voltage	Voltage Range	Noise		Sinter-Sleeve Bearings Ball Bearings	Power Input	Nominal Speed	Temperature Range	Service Life L ₁₀		Curve
	m ³ /h	CFM			V DC	V DC					dB(A)	Bel	
405 F	8	4.7	5	4.5...5.5	22.1	4.4	■	0.7	5 400	-20...+70	45 000 / 15 000		2
405 FH	9	5.3	5	4.5...5.5	26.0	4.6	■	0.9	6 000	-20...+70	45 000 / 15 000		3
412 FM	6	3.5	12	10...14	16.5	3.8	■	0.6	4 300	-20...+70	45 000 / 15 000		1
412 F	8	4.7	12	10...14	22.1	4.4	■	0.7	5 400	-20...+70	45 000 / 15 000		2
412 FH	9	5.3	12	10...14	26.0	4.6	■	0.8	6 000	-20...+70	45 000 / 15 000		3
414 F	8	4.7	24	20...28	22.1	4.4	■	0.8	5 400	-20...+70	45 000 / 15 000		2
414 FH	9	5.3	24	21.6...26.4	26.0	4.4	■	0.9	6 000	-20...+70	45 000 / 15 000		3

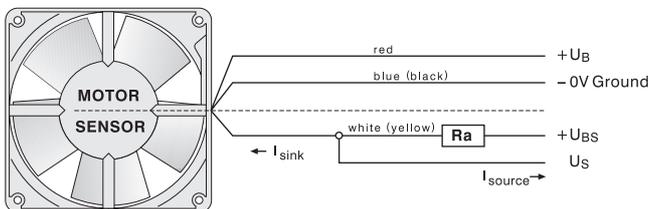




- Speed-proportional rectangular pulse for external speed monitoring of fan motor
- 2 pulses per revolution
- Open-Collector signal output
- Extremely wide operating voltage range (5 ... 60 V)
- Easy adaptation to user interface
- Connection via separate lead
- The sensor signal also serves as a major comparison variable for setting and maintaining the desired speed for interactive or controlled cooling with one or several interconnected fans.

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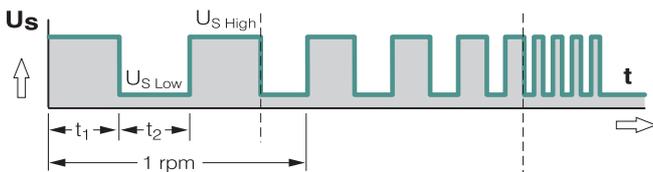
Electrical connection



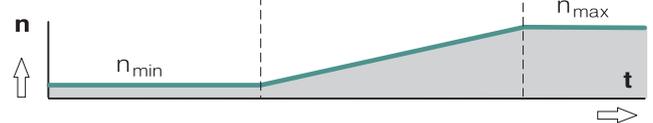
$$R_a = \frac{U_{BS} - U_{SLOW}}{I_{SINK}}$$

All voltages measured to ground.
External load resistance R_a from U_S to U_{BS} required.

Signal output voltage



Fan speed



Signal symmetry $[t_1, t_2] = 0.8 \dots 1.2$
Signal frequency $[F] = 2 \times n/60 \text{ Hz}$

Attention:

With these fan options, deviations in regard to temperature range, voltage range and power consumption are possible compared with standard fan data.

Signal data

Type	Sensor signal $U_{S \text{ Low}}$	Condition: I_{sink}	Sensor signal $U_{S \text{ High}}$	Condition: I_{source}	Sensor operating voltage U_{BS}	Perm. sink current $I_{\text{sink max.}}$
	V DC	mA	V DC	mA	V DC	mA
255 N/2	≤ 0.4	≤ 2	30	0	≤ 30	2
255 H/2	≤ 0.4	≤ 2	30	0	≤ 30	2
252 N/2	≤ 0.4	≤ 2	30	0	≤ 30	2
405 F/2	≤ 0.4	1	30	0	≤ 30	≤ 2
405 F/2 H	≤ 0.4	1	30	0	≤ 30	≤ 2
412 F/2 H	≤ 0.4	1	30	0	≤ 30	≤ 2
414 F/2	≤ 0.4	1	30	0	≤ 30	≤ 2
405 /2	≤ 0.4	1	30	0	≤ 30	≤ 2
412 /2	≤ 0.4	1	30	0	≤ 30	≤ 2
414 /2	≤ 0.4	1	30	0	≤ 30	≤ 2
414 /2 H	≤ 0.4	1	30	0	≤ 30	≤ 2
412 J/2 H	≤ 0.4	1	30	0	≤ 30	≤ 4
412 J/2 HH	≤ 0.4	1	30	0	≤ 30	≤ 4
414 J/2 H	≤ 0.4	2	30	0	≤ 30	≤ 4
414 J/2 HH	≤ 0.4	2	30	0	≤ 30	≤ 4
512 F/2	≤ 0.4	1	30	0	≤ 30	≤ 2
514 F/2	≤ 0.4	1	30	0	≤ 30	≤ 2
612 F/2	≤ 0.4	1	30	0	≤ 30	≤ 2
612 F/2 H	≤ 0.4	1	30	0	≤ 30	≤ 2
614 F/2	≤ 0.4	1	30	0	≤ 30	≤ 2
612 N/2 H	≤ 0.4	1	30	0	≤ 30	≤ 2
612 N/2 NHH-120	≤ 0.4	1	30	0	≤ 30	≤ 2
612 N/2 N	≤ 0.4	1	30	0	≤ 30	≤ 2
614 N/2 H	≤ 0.4	1	30	0	≤ 30	≤ 2
614 N/2 HH-121	≤ 0.4	1	30	0	≤ 30	≤ 2
614 N/2 M	≤ 0.4	2	28	0	≤ 30	≤ 4
712 F/2 L	≤ 0.4	1	30	0	≤ 30	≤ 2
712 F/2 M	≤ 0.4	1	30	0	≤ 30	≤ 2
8412 N/2 GL	≤ 0.4	2	28	0	≤ 28	≤ 4
8412 N/2 GM	≤ 0.4	2	28	0	≤ 28	≤ 4
8412 N/2 G	≤ 0.4	2	28	0	≤ 28	≤ 4
8414 N/2 GL	≤ 0.4	2	28	0	≤ 28	≤ 4
8414 N/2 GM	≤ 0.4	2	28	0	≤ 28	≤ 4
8414 N/2 G	≤ 0.4	2	28	0	≤ 28	≤ 4
8414 N/2	≤ 0.4	2	28	0	≤ 28	≤ 4
8412 N/2	≤ 0.4	2	28	0	≤ 28	≤ 4
8412 N/2 H	≤ 0.4	2	28	0	≤ 28	≤ 4
8414 N/2 H	≤ 0.4	2	28	0	≤ 28	≤ 4
8312 /2 HL	≤ 0.4	2	30	0	≤ 30	≤ 4
8314 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
8314 /2 H	≤ 0.4	2	30	0	≤ 30	≤ 4

Available on request:

- Galvanically separated sensor signal circuit
- Varying voltage potentials for power and logic circuit.

Signal data	Sensor signal U _{S, Low}	Condition: I _{sink}	Sensor signal U _{S, High}	Condition: I _{source}	Sensor operating voltage U _{BS}	Perm. sink current I _{sink max.}
Type	V DC	mA	V DC	mA	V DC	mA
8318 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
8318 /2 HL	≤ 0.4	2	30	0	≤ 30	≤ 4
8318 /2 H	≤ 0.4	2	30	0	≤ 30	≤ 4
3412 N/2 GL	≤ 0.4	2	28	0	≤ 28	≤ 4
3412 N/2 GM	≤ 0.4	2	28	0	≤ 28	≤ 4
3412 N/2	≤ 0.4	2	28	0	≤ 28	≤ 4
3412 N/2 G	≤ 0.4	2	28	0	≤ 28	≤ 4
3412 N/2 HH	≤ 0.4	2	28	0	≤ 28	≤ 4
3412 N/2 GHH	≤ 0.4	2	28	0	≤ 28	≤ 4
3412 N/2 H	≤ 0.4	2	28	0	≤ 28	≤ 4
3414 N/2 GH	≤ 0.4	2	28	0	≤ 28	≤ 4
3414 N/2	≤ 0.4	2	28	0	≤ 28	≤ 4
3312 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
3318 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
4412 F/2 GL	≤ 0.4	2	30	0	≤ 30	≤ 4
4412 F/2 GML	≤ 0.4	2	30	0	≤ 30	≤ 4
4412 F/2 M	≤ 0.4	2	30	0	≤ 30	≤ 4
4412 F/2	≤ 0.4	2	30	0	≤ 30	≤ 4
4414 F/2 L	≤ 0.4	2	30	0	≤ 30	≤ 4
4414 F/2 M	≤ 0.4	2	30	0	≤ 30	≤ 4
4414 F/2 G	≤ 0.4	2	30	0	≤ 30	≤ 4
4414 F/2	≤ 0.4	2	30	0	≤ 30	≤ 4
4418 F/2	≤ 0.4	2	30	0	≤ 30	≤ 4
4312 N/2 H	≤ 0.4	2	30	0	≤ 30	≤ 4
4312 N/2 HH	≤ 0.4	2	30	0	≤ 30	≤ 4
4312 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
4314 /2 G	≤ 0.4	2	30	0	≤ 30	≤ 4
4314 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
4318 /2 G	≤ 0.4	2	30	0	≤ 30	≤ 4
4318 /2 M	≤ 0.4	2	30	0	≤ 30	≤ 4
4318 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
4212 N/2 GN	≤ 0.4	2	30	0	≤ 30	≤ 4
4212 N/2 H	≤ 0.4	2	30	0	≤ 30	≤ 4
4214 N/2 GN	≤ 0.4	2	30	0	≤ 30	≤ 4
4214 N/2 H	≤ 0.4	2	30	0	≤ 30	≤ 4
4218 N/2 GN	≤ 0.4	2	30	0	≤ 30	≤ 4
4218 N/2 H	≤ 0.4	2	30	0	≤ 30	≤ 4
4212 /2 M	≤ 0.4	2	30	0	≤ 30	≤ 4
4212 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
4212 /2 H	≤ 0.4	2	30	0	≤ 30	≤ 4
4214 /2	≤ 0.4	2	30	0	4-30	≤ 4

Signal data	Sensor signal U _{S, Low}	Condition: I _{sink}	Sensor signal U _{S, High}	Condition: I _{source}	Sensor operating voltage U _{BS}	Perm. sink current I _{sink max.}
Type	V DC	mA	V DC	mA	V DC	mA
4214 /2 H	≤ 0.4	2	30	0	4-30	≤ 4
4218 /2	≤ 0.4	2	30	0	4-30	≤ 4
4218 /2 H	≤ 0.4	2	30	0	4-30	≤ 4
4182 N/2 X	≤ 0.4	2	30	0	4-30	≤ 4
4184 N/2 GX	≤ 0.4	2	30	0	4-30	≤ 4
4184 N/2 X	≤ 0.4	2	30	0	4-30	≤ 4
4184 N/2 XH	≤ 0.4	2	30	0	4-30	≤ 4
5112 N/2	≤ 0.4	2	15	0	≤ 5	≤ 20
5114 N/2	≤ 0.4	2	60	0	≤ 60	≤ 20
5118 N/2	≤ 0.4	2	60	0	≤ 60	≤ 20
5212 N/2 H	≤ 0.4	2	30	0	4-30	≤ 2
5212 N/2 N	≤ 0.4	2	30	0	4-30	≤ 2
5214 N/2 N	≤ 0.4	2	30	0	4-30	≤ 2
5218 N/2 H	≤ 0.4	2	30	0	4-30	≤ 2
7112 N/2	≤ 0.4	2	60	0	≤ 60	≤ 20
7114 N/2	≤ 0.4	2	30	0	≤ 30	≤ 20
7118 N/2	≤ 0.4	2	60	0	≤ 60	≤ 20
6224 N/2	≤ 0.4	8	30	0	≤ 30	≤ 20
6248 N/2	≤ 0.4	8	60	0	≤ 30	≤ 20
DV 6224 /2	≤ 0.4	2	30	0	≤ 60	≤ 20
6424 /2	≤ 0.4	2	60	0	≤ 60	≤ 20
6448 /2	≤ 0.4	2	60	0	≤ 60	≤ 20
6448 /2 T	≤ 0.4	2	60	0	≤ 60	≤ 20
RL 48-19/12/2	≤ 0.4	2	28	0	4-30	≤ 4
RL 48-19/14/2	≤ 0.4	2	28	0	4-30	≤ 4
RL 90-18/12N/2	≤ 0.4	2	30	0	≤ 30	≤ 4
RL 90-18/14N/2	≤ 0.4	2	30	0	≤ 30	≤ 4
RG 90-18/12N/2	≤ 0.4	2	30	0	≤ 30	≤ 4
RG 90-18/14N/2	≤ 0.4	2	30	0	≤ 30	≤ 4
RG 125-19/14N/2	≤ 0.4	2	30	0	≤ 30	≤ 4
RG 125-19/18N/2	≤ 0.4	2	60	0	≤ 30	≤ 4
RER 125-19/14N/2	≤ 0.4	2	30	0	≤ 30	≤ 4
RG 160-28/14N/2	≤ 0.4	2	30	0	≤ 30	≤ 20

Attention:

With these fan options, deviations in regard to temperature range, voltage range and power consumption are possible compared with standard fan data.

Данный компонент на территории Российской Федерации

Вы можете приобрести в компании MosChip.

Для оперативного оформления запроса Вам необходимо перейти по данной ссылке:

<http://moschip.ru/get-element>

Вы можете разместить у нас заказ для любого Вашего проекта, будь то серийное производство или разработка единичного прибора.

В нашем ассортименте представлены ведущие мировые производители активных и пассивных электронных компонентов.

Нашей специализацией является поставка электронной компонентной базы двойного назначения, продукции таких производителей как XILINX, Intel (ex.ALTERA), Vicor, Microchip, Texas Instruments, Analog Devices, Mini-Circuits, Amphenol, Glenair.

Сотрудничество с глобальными дистрибьюторами электронных компонентов, предоставляет возможность заказывать и получать с международных складов практически любой перечень компонентов в оптимальные для Вас сроки.

На всех этапах разработки и производства наши партнеры могут получить квалифицированную поддержку опытных инженеров.

Система менеджмента качества компании отвечает требованиям в соответствии с ГОСТ Р ИСО 9001, ГОСТ РВ 0015-002 и ЭС РД 009

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