TOSHIBA CMOS DIGITAL INTEGRATED CIRCUIT   SILICON MONOLITHIC

TC4S66F, TC4S66FU

BILATERAL SWITCH

TC4S66F/FU contains one circuit of bidirectional switches. When control input, CONT is set to "H" level, the impedance between input and output of the switch becomes low and when it is set to "L" level, the switch becomes high. This can be applied for switching of analog signals and digital signals.

FEATURES

● ON-resistance (R_{ON})

$300\ \Omega$ (Typ.) .... $V_{DD} - V_{SS} = 5\ V$
$110\ \Omega$ (Typ.) .... $V_{DD} - V_{SS} = 10\ V$
$70\ \Omega$ (Typ.) ..... $V_{DD} - V_{SS} = 15\ V$

● OFF-resistance (R_{OFF})

R_{OFF} (Typ.) $> 10^9\ \Omega$

TC4S66F

TC4S66FU
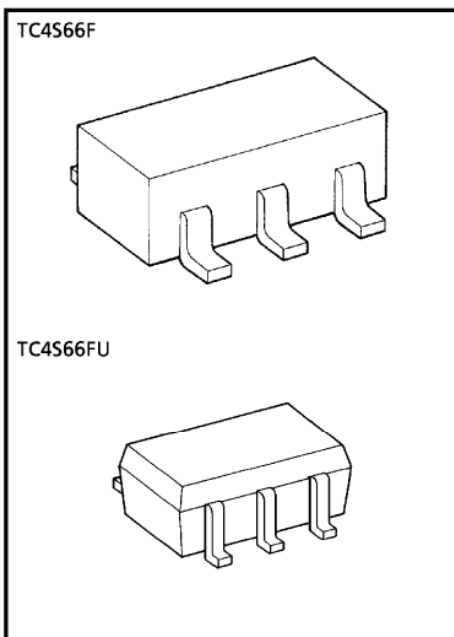
Weight
SSOP5-P-0.95   : 0.016 g (Typ.)
SSOP5-P-0.65A : 0.006 g (Typ.)

MAXIMUM RATINGS

CHARACTERISTIC	SYMBOL	RATING	UNIT
DC Supply Voltage	V_{DD}	$V_{SS} - 0.5 \sim V_{SS} + 20$	V
Control Input Voltage	$V_{C\ IN}$	$V_{SS} - 0.5 \sim V_{DD} + 0.5$	V
Switch I/O Voltage	$V_{I/O}$	$V_{SS} - 0.5 \sim V_{DD} + 0.5$	V
Power Dissipation	P_D	200	mW
Potential difference across I/O during ON	V_I-V_O	± 0.5	V
Control Input Current	$I_{C\ IN}$	± 10	mA
Operating Temperature Range	T_{opr}	$-40 \sim 85$	°C
Storage Temperature	T_{stg}	$-65 \sim 150$	°C
Lead Temperature (10 s)	T_L	260	°C

TRUTH TABLE

CONTROL	IMPEDANCE BETWEEN IN/OUT-OUT/IN *
H	$0.5 \sim 5 \times 10^2\ \Omega$
L	$> 10^9\ \Omega$

* : See static electrical characteristics.

CIRCUIT DIAGRAM
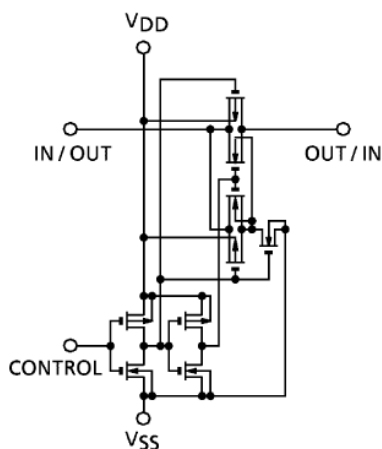
PIN ASSIGNMENT (TOP VIEW)
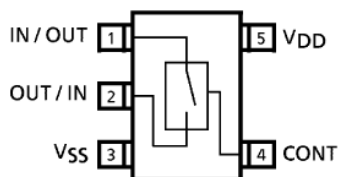
MARKING
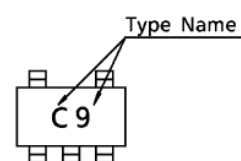
RECOMMENDED OPERATING CONDITIONS (V_{SS} = 0 V)

CHARACTERISTIC	SYMBOL		MIN.	TYP.	MAX.	UNIT
DC Supply Voltage	V_{DD}	—	3	—	18	V
Input / Output Voltage	V_{IN}/V_{OUT}	—	0	—	V_{DD}	V

STATIC ELECTRICAL CHARACTERISTICS (In case not specifically appointed, V_{SS} = 0 V)

CHARACTERISTIC	SYM-BOL	TEST CONDITION	V_{DD} (V)	−40°C MIN.	−40°C MAX.	25°C MIN.	25°C TYP.	25°C MAX.	85°C MIN.	85°C MAX.	UNIT
Control Input High Voltage	V_{IH}	$|I_{IS}|$ = 10 μA	5	3.5	—	3.5	2.75	—	3.5	—	V
			10	7.0	—	7.0	5.50	—	7.0	—	
			15	11.0	—	11.0	8.25	—	11.0	—	
Control Input Low Voltage	V_{IL}	$|I_{IS}|$ = 10 μA	5	—	1.5	—	2.25	1.5	—	1.5	
			10	—	3.0	—	4.5	3.0	—	3.0	
			15	—	4.0	—	6.75	4.0	—	4.0	
On-State Resistance	R_{ON}	$0 \leq V_{IS} \leq V_{DD}$ R_L = 10 kΩ	5	—	800	—	290	950	—	1200	Ω
			10	—	210	—	120	250	—	300	
			15	—	140	—	85	160	—	200	
Input / Output Leakage Current	I_{OFF}	V_{IN} = 18 V V_{OUT} = 0 V	18	—	± 100	—	± 0.1	± 100	—	± 1000	nA
		V_{IN} = 0 V V_{OUT} = 18 V	18	—	± 100	—	± 0.1	± 100	—	± 1000	
Quiescent Device Current	I_{DD}	V_{IN} = V_{DD}, V_{SS}	5	—	0.25	—	0.001	0.25	—	7.5	μA
			10	—	0.5	—	0.001	0.5	—	15	
			15	—	1.0	—	0.002	1.0	—	30	
Input Current H Level	I_{IH}	V_{IH} = 18 V	18	—	0.1	—	10^{-5}	0.1	—	1.0	μA
Input Current L Level	I_{OL}	V_{IL} = 0 V	18	—	− 0.1	—	$- 10^{-5}$	− 0.1	—	− 1.0	

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DYNAMIC ELECTRICAL CHARACTERISTICS (Ta = 25°C)

| CHARACTERISTIC	SYMBOL	TEST CONDITION		V_{SS} (V)	V_{DD} (V)	MIN.	TYP.	MAX.	UNIT
Propagation Delay Time (IN-OUT)	t_{pLH} t_{pHL}	C_L = 50 pF		0	5	—	15	40	ns
				0	10	—	8	20	
				0	15	—	5	15	
Propagation Delay Time (CONTROL-OUT)	t_{pZL} t_{pZH}	R_L = 1 kΩ C_L = 50 pF		0	5	—	55	120	
				0	10	—	25	40	
				0	15	—	20	30	
Propagation Delay Time (CONTROL-OUT)	t_{pLZ} t_{pHZ}	R_L = 1 kΩ C_L = 50 pF		0	5	—	45	80	
				0	10	—	30	70	
				0	15	—	25	60	
Max. Control Input Repetition Rate	f_{MAX} (C)	R_L = 1 kΩ C_L = 50 pF		0	5	—	10	—	MHz
				0	10	—	12	—	
				0	15	—	12	—	
−3dB Cut Off Frequency	f_{MAX} (I-O)	R_L = 1 kΩ C_L = 50 pF (*1)		−5	5	—	30	—	
Total Harmonic Distortion	—	R_L = 10 kΩ f = 1 kHz (*2)		−5	5	—	0.03	—	%
−50dB Feedthrough Frequency	—	R_L = 1 kΩ (*3)		−5	5	—	600	—	kHz
Crosstalk (CONTROL-OUT)	—	R_{IN} = 1 kΩ R_{OUT} = 10 kΩ C_L = 15 pF		0	5	—	200	—	mV
				0	10	—	400	—	
				0	15	—	600	—	
Input Capacitance	C_{IN}	Control Input				—	5	7.5	pF
		Switch I/O				—	10	—	
Feedthrough Capacitance	C_{IN-OUT}	—				—	0.5	—	

*1 : The frequency at $20\log_{10} \dfrac{V_{OS}}{V_{IS}} = -3$ dB shall be $f_{MAX(I/O)}$ using sine wave of $\pm 2.5\,V_{p\text{-}p}$ for V_{IS}.

*2 : V_{IS} shall be sine wave of $\pm 2.5\,V$.

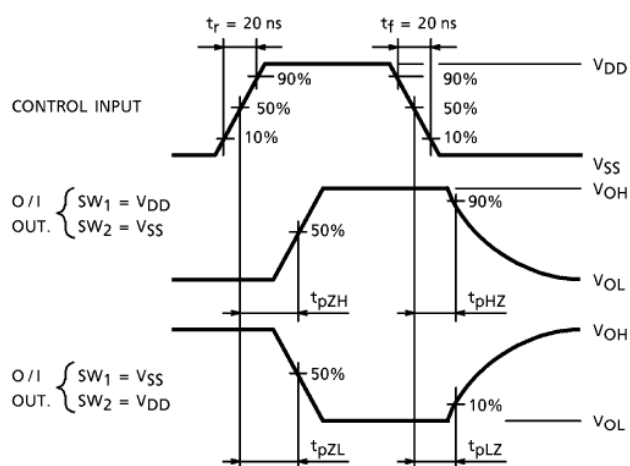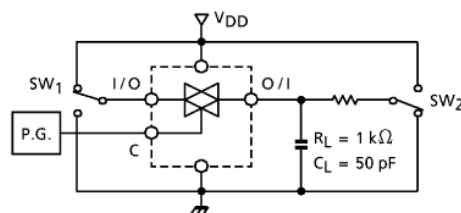*3 : The frequency at $20\log_{10} \dfrac{V_{OS}}{V_{IS}} = 50$ dB shall be the feed through using of $\pm 2.5\,V_{p\text{-}p}$.
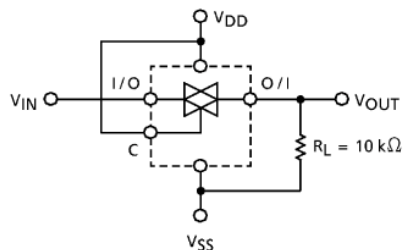
1. t_{pLH}, t_{pHL}

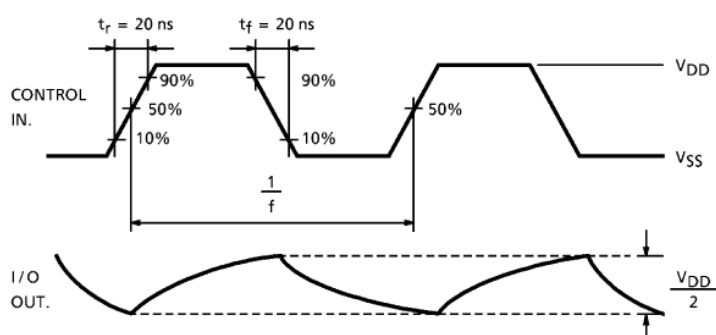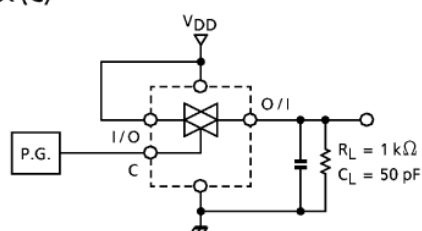I/O-O/I
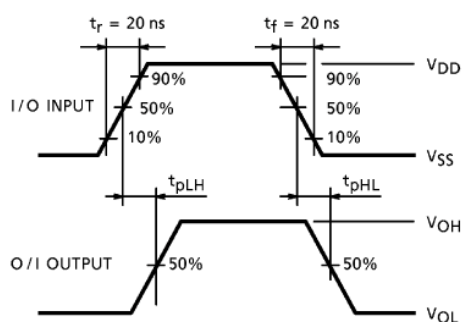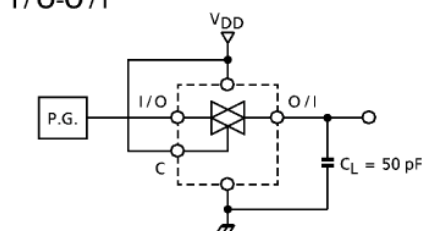
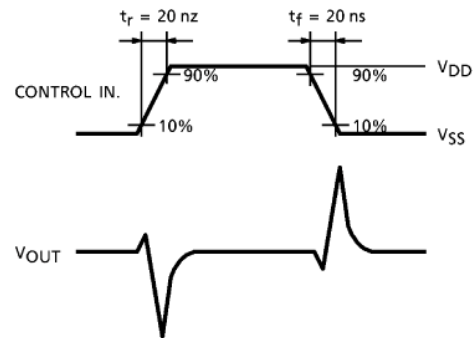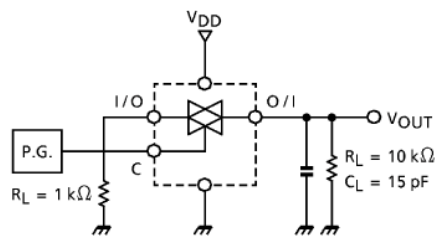2. t_{pZL}, t_{pZH}, t_{pLZ}, t_{pHZ}

CONTROL-O/I

3. R_{ON}

$$R_{ON} = 10 \times \frac{(V_{IN} - V_{OUT})}{V_{OUT}} (k\Omega)$$

4. f_{MAX} (C)

5. CROSSTALK (CONTROL INPUT)

V_{DD}

I/O ... O/I

C

P.G.

R_L = 1 kΩ

V_{OUT}

R_L = 10 kΩ
C_L = 15 pF

t_r = 20 nz t_f = 20 ns

CONTROL IN.

90%   90% V_{DD}

10%   10% V_{SS}

V_{OUT}

6. TOTAL HARMONIC DISTORTION, f_{MAX} (I/O-O/I), FEEDTHROUGH (SWITCH OFF)

V_{DD}

P.G.

I/O ... O/I

C

V_{SS}

R_L
C_L } SEE TEST CONDITIONS

I/O IN.

2.5 V

0 V

−2.5 V

$\dfrac{1}{f}$
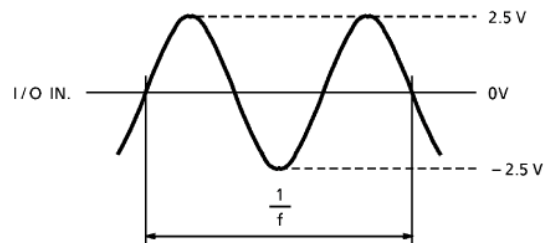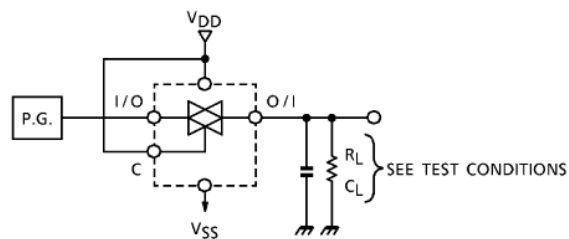
PACKAGE DIMENSIONS
SSOP5-P-0.95   Unit : mm
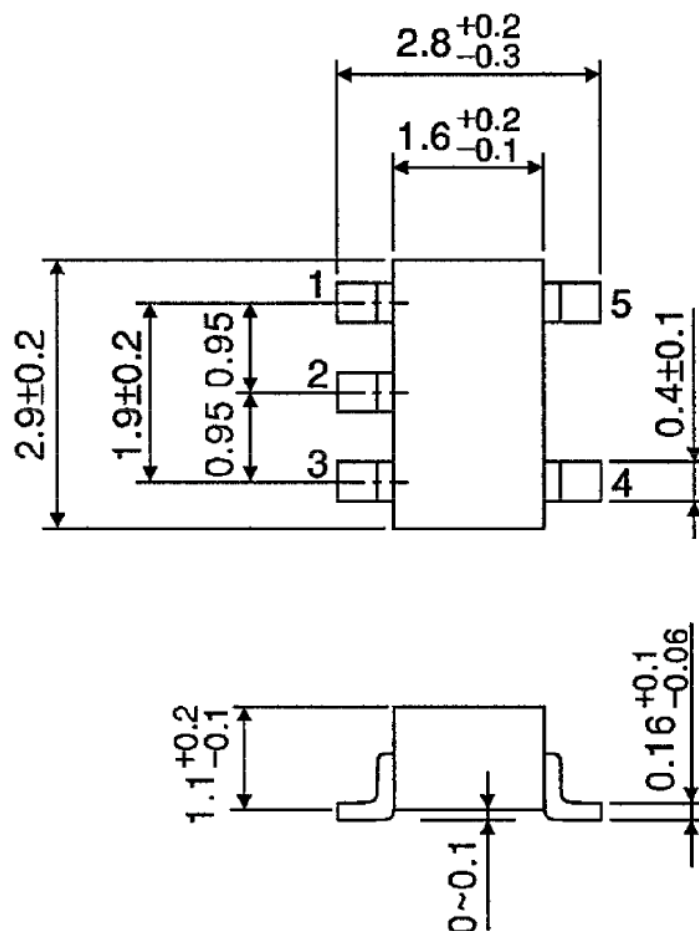
Weight : 0.016 g (Typ.)

PACKAGE DIMENSIONS
SSOP5-P-0.65A

Unit : mm

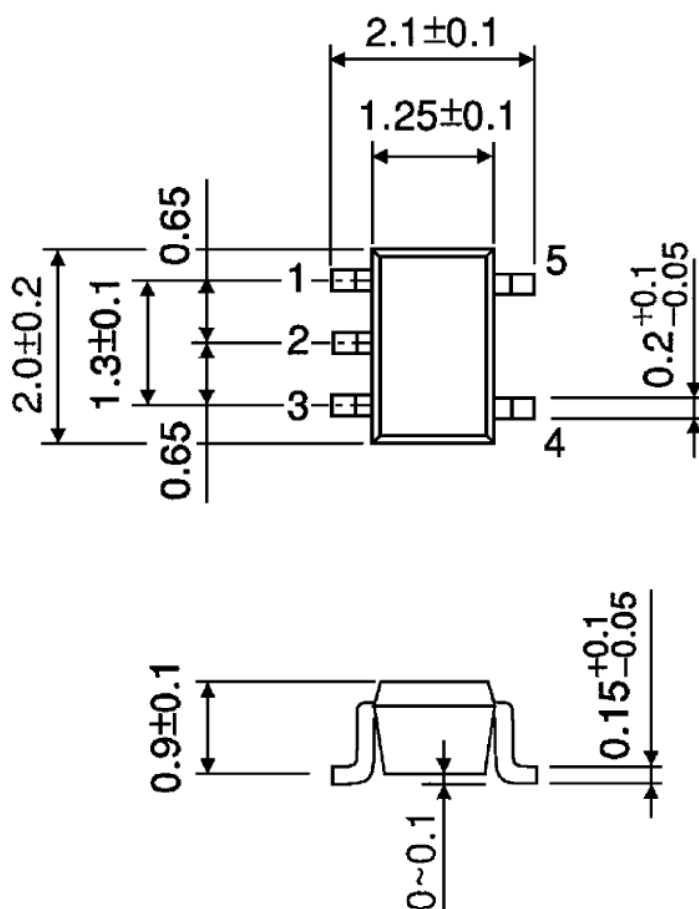
Weight : 0.006 g (Typ.)

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