

DC Axial Fans

ebmpapst

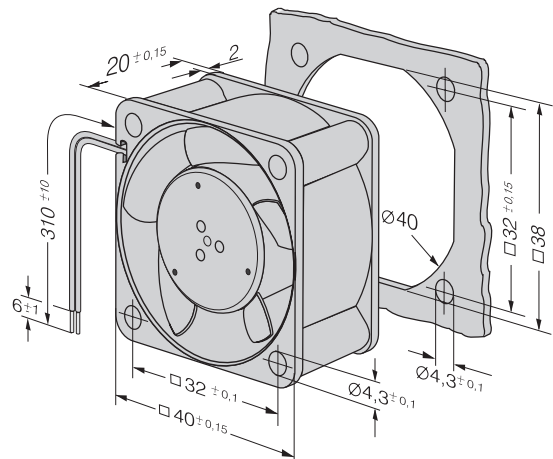
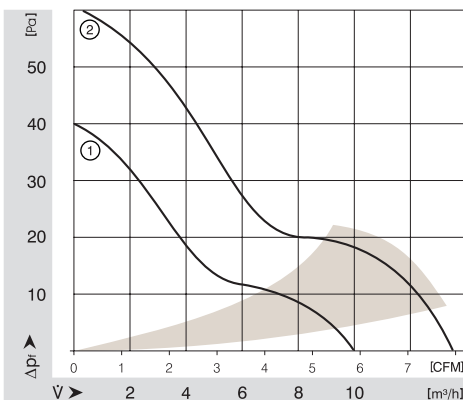
Series 400, Type 412 40 x 40 x 20 mm



- DC fans with electronically commutated external rotor motor. Fully integrated commutation electronics.
- With electronic protection against reverse polarity. The fan only operates when the polarity is correct. Impedance-protected against blocking and overloading. Type 412 H and 414 H with electronic protection against blocking
- Fan of fibreglass reinforced plastic. PBT housing, PA impeller.
- Air exhaust over struts. Rotational direction CCW looking at rotor.
- Electrical connection via 2 leads AWG 28, TR 64. Stripped and tinned ends.
- Mass 27 g.

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Nominal Data	Air Flow		Nominal Voltage	Voltage Range	Noise		Sinter-Sleeve Bearings Ball Bearings	Power Input	Nominal Speed	Temperature Range	Service Life L ₁₀		Curve
	m ³ /h	CFM									at 20 °C	at 60 °C	
Type			V DC	V DC	dB(A)	Bel	□/■	Watt	min ⁻¹	°C	Hours	Hours	
405	10	5.9	5	4.5...5.5	18	3.8	■	0.9	6 000	-20...+70	50 000 / 20 000		1
412	10	5.9	12	10...14	18	3.8	■	0.9	6 000	-20...+70	50 000 / 20 000		1
412 H	13.5	7.9	12	10...14	29	4.7	■	1.6	8 100	-20...+60	45 000 / 15 000		2
414	10	5.9	24	20...28	18	3.8	■	1.0	6 000	-20...+70	50 000 / 20 000		1
414 H	13.5	7.9	24	20...26.5	29	4.7	■	1.6	8 100	-20...+60	45 000 / 15 000		2

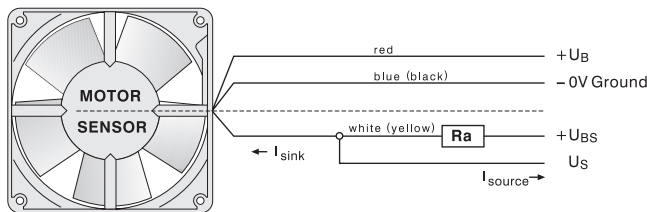




- Speed-proportional rectangular pulse for external speed monitoring of fan motor
- 2 pulses per revolution
- Open-Collector signal output
- Extremely wide operating voltage range (5 ... 60 V)
- Easy adaptation to user interface
- Connection via separate lead
- The sensor signal also serves as a major comparison variable for setting and maintaining the desired speed for interactive or controlled cooling with one or several interconnected fans.

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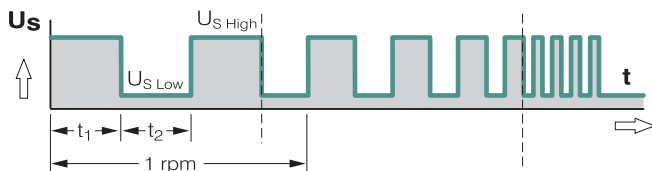
Electrical connection



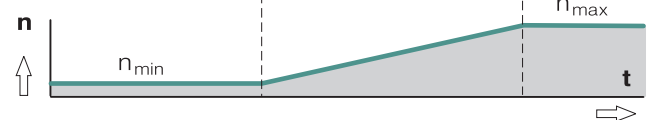
$$R_a = \frac{U_{BS} - U_{SLOW}}{I_{SINK}}$$

All voltages measured to ground.
External load resistance R_a from U_S to U_{BS} required.

Signal output voltage



Fan speed



Signal symmetry $[t_1, t_2] = 0.8 \dots 1.2$
Signal frequency $[F] = 2 \times n/60 \text{ Hz}$

Attention:

With these fan options, deviations in regard to temperature range, voltage range and power consumption are possible compared with standard fan data.

Signal data

	Sensor signal $U_{S \text{ Low}}$	Condition: I_{sink}	Sensor signal $U_{S \text{ High}}$	Condition: I_{source}	Sensor operating voltage U_{BS}	Perm. sink current $I_{\text{sink max.}}$
Type	V DC	mA	V DC	mA	V DC	mA
255 N/2	≤ 0.4	≤ 2	30	0	≤ 30	2
255 H/2	≤ 0.4	≤ 2	30	0	≤ 30	2
252 N/2	≤ 0.4	≤ 2	30	0	≤ 30	2
405 F/2	≤ 0.4	1	30	0	≤ 30	≤ 2
405 F/2 H	≤ 0.4	1	30	0	≤ 30	≤ 2
412 F/2 H	≤ 0.4	1	30	0	≤ 30	≤ 2
414 F/2	≤ 0.4	1	30	0	≤ 30	≤ 2
405 /2	≤ 0.4	1	30	0	≤ 30	≤ 2
412 /2	≤ 0.4	1	30	0	≤ 30	≤ 2
414 /2	≤ 0.4	1	30	0	≤ 30	≤ 2
414 /2 H	≤ 0.4	1	30	0	≤ 30	≤ 2
412 J/2 H	≤ 0.4	1	30	0	≤ 30	≤ 4
412 J/2 HH	≤ 0.4	1	30	0	≤ 30	≤ 4
414 J/2 H	≤ 0.4	2	30	0	≤ 30	≤ 4
414 J/2 HH	≤ 0.4	2	30	0	≤ 30	≤ 4
512 F/2	≤ 0.4	1	30	0	≤ 30	≤ 2
514 F/2	≤ 0.4	1	30	0	≤ 30	≤ 2
612 F/2	≤ 0.4	1	30	0	≤ 30	≤ 2
612 F/2 H	≤ 0.4	1	30	0	≤ 30	≤ 2
614 F/2	≤ 0.4	1	30	0	≤ 30	≤ 2
612 N/2 H	≤ 0.4	1	30	0	≤ 30	≤ 2
612 N/2 NHH-120	≤ 0.4	1	30	0	≤ 30	≤ 2
612 N/2 N	≤ 0.4	1	30	0	≤ 30	≤ 2
614 N/2 H	≤ 0.4	1	30	0	≤ 30	≤ 2
614 N/2 HH-121	≤ 0.4	1	30	0	≤ 30	≤ 2
614 N/2 M	≤ 0.4	2	28	0	≤ 30	≤ 4
712 F/2 L	≤ 0.4	1	30	0	≤ 30	≤ 2
712 F/2 M	≤ 0.4	1	30	0	≤ 30	≤ 2
8412 N/2 GL	≤ 0.4	2	28	0	≤ 28	≤ 4
8412 N/2 GM	≤ 0.4	2	28	0	≤ 28	≤ 4
8412 N/2 G	≤ 0.4	2	28	0	≤ 28	≤ 4
8414 N/2 GL	≤ 0.4	2	28	0	≤ 28	≤ 4
8414 N/2 GM	≤ 0.4	2	28	0	≤ 28	≤ 4
8414 N/2 G	≤ 0.4	2	28	0	≤ 28	≤ 4
8414 N/2	≤ 0.4	2	28	0	≤ 28	≤ 4
8412 N/2	≤ 0.4	2	28	0	≤ 28	≤ 4
8412 N/2 H	≤ 0.4	2	28	0	≤ 28	≤ 4
8414 N/2 H	≤ 0.4	2	28	0	≤ 28	≤ 4
8312 /2 HL	≤ 0.4	2	30	0	≤ 30	≤ 4
8314 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
8314 /2 H	≤ 0.4	2	30	0	≤ 30	≤ 4

Available on request:

- Galvanically separated sensor signal circuit
- Varying voltage potentials for power and logic circuit.

Signal data	Sensor signal $U_{S, Low}$	Condition: I_{Sink}	Sensor signal $U_{S, High}$	Condition: I_{Source}	Sensor operating voltage U_{ES}	Perm. sink current $I_{Sink, max.}$
Type	V DC	mA	V DC	mA	V DC	mA
8318 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
8318 /2 HL	≤ 0.4	2	30	0	≤ 30	≤ 4
8318 /2 H	≤ 0.4	2	30	0	≤ 30	≤ 4
3412 N/2 GL	≤ 0.4	2	28	0	≤ 28	≤ 4
3412 N/2 GM	≤ 0.4	2	28	0	≤ 28	≤ 4
3412 N/2	≤ 0.4	2	28	0	≤ 28	≤ 4
3412 N/2 G	≤ 0.4	2	28	0	≤ 28	≤ 4
3412 N/2 HH	≤ 0.4	2	28	0	≤ 28	≤ 4
3412 N/2 GHH	≤ 0.4	2	28	0	≤ 28	≤ 4
3412 N/2 H	≤ 0.4	2	28	0	≤ 28	≤ 4
3414 N/2 GH	≤ 0.4	2	28	0	≤ 28	≤ 4
3414 N/2	≤ 0.4	2	28	0	≤ 28	≤ 4
3312 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
3318 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
4412 F/2 GL	≤ 0.4	2	30	0	≤ 30	≤ 4
4412 F/2 GML	≤ 0.4	2	30	0	≤ 30	≤ 4
4412 F/2 M	≤ 0.4	2	30	0	≤ 30	≤ 4
4412 F/2	≤ 0.4	2	30	0	≤ 30	≤ 4
4414 F/2 L	≤ 0.4	2	30	0	≤ 30	≤ 4
4414 F/2 M	≤ 0.4	2	30	0	≤ 30	≤ 4
4414 F/2 G	≤ 0.4	2	30	0	≤ 30	≤ 4
4414 F/2	≤ 0.4	2	30	0	≤ 30	≤ 4
4418 F/2	≤ 0.4	2	30	0	≤ 30	≤ 4
4312 N/2 H	≤ 0.4	2	30	0	≤ 30	≤ 4
4312 N/2 HH	≤ 0.4	2	30	0	≤ 30	≤ 4
4312 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
4314 /2 G	≤ 0.4	2	30	0	≤ 30	≤ 4
4314 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
4318 /2 G	≤ 0.4	2	30	0	≤ 30	≤ 4
4318 /2 M	≤ 0.4	2	30	0	≤ 30	≤ 4
4318 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
4212 N/2 GN	≤ 0.4	2	30	0	≤ 30	≤ 4
4212 N/2 H	≤ 0.4	2	30	0	≤ 30	≤ 4
4214 N/2 GN	≤ 0.4	2	30	0	≤ 30	≤ 4
4214 N/2 H	≤ 0.4	2	30	0	≤ 30	≤ 4
4218 N/2 GN	≤ 0.4	2	30	0	≤ 30	≤ 4
4218 N/2 H	≤ 0.4	2	30	0	≤ 30	≤ 4
4212 /2 M	≤ 0.4	2	30	0	≤ 30	≤ 4
4212 /2	≤ 0.4	2	30	0	≤ 30	≤ 4
4212 /2 H	≤ 0.4	2	30	0	≤ 30	≤ 4
4214 /2	≤ 0.4	2	30	0	4–30	≤ 4

Signal data	Sensor signal $U_{S, Low}$	Condition: I_{Sink}	Sensor signal $U_{S, High}$	Condition: I_{Source}	Sensor operating voltage U_{ES}	Perm. sink current $I_{Sink, max.}$
Type	V DC	mA	V DC	mA	V DC	mA
4214 /2 H	≤ 0.4	2	30	0	4–30	≤ 4
4218 /2	≤ 0.4	2	30	0	4–30	≤ 4
4218 /2 H	≤ 0.4	2	30	0	4–30	≤ 4
4182 N/2 X	≤ 0.4	2	30	0	4–30	≤ 4
4184 N/2 GX	≤ 0.4	2	30	0	4–30	≤ 4
4184 N/2 X	≤ 0.4	2	30	0	4–30	≤ 4
4184 N/2 XH	≤ 0.4	2	30	0	4–30	≤ 4
5112 N/2	≤ 0.4	2	15	0	≤ 5	≤ 20
5114 N/2	≤ 0.4	2	60	0	≤ 60	≤ 20
5118 N/2	≤ 0.4	2	60	0	≤ 60	≤ 20
5212 N/2 H	≤ 0.4	2	30	0	4–30	≤ 2
5212 N/2 N	≤ 0.4	2	30	0	4–30	≤ 2
5214 N/2 N	≤ 0.4	2	30	0	4–30	≤ 2
5218 N/2 H	≤ 0.4	2	30	0	4–30	≤ 2
7112 N/2	≤ 0.4	2	60	0	≤ 60	≤ 20
7114 N/2	≤ 0.4	2	30	0	≤ 30	≤ 20
7118 N/2	≤ 0.4	2	60	0	≤ 60	≤ 20
6224 N/2	≤ 0.4	8	30	0	≤ 30	≤ 20
6248 N/2	≤ 0.4	8	60	0	≤ 30	≤ 20
DV 6224 /2	≤ 0.4	2	30	0	≤ 60	≤ 20
6424 /2	≤ 0.4	2	60	0	≤ 60	≤ 20
6448 /2	≤ 0.4	2	60	0	≤ 60	≤ 20
6448 /2 T	≤ 0.4	2	60	0	≤ 60	≤ 20
RL 48-19/12/2	≤ 0.4	2	28	0	4–30	≤ 4
RL 48-19/14/2	≤ 0.4	2	28	0	4–30	≤ 4
RL 90-18/12N/2	≤ 0.4	2	30	0	≤ 30	≤ 4
RL 90-18/14N/2	≤ 0.4	2	30	0	≤ 30	≤ 4
RG 90-18/12N/2	≤ 0.4	2	30	0	≤ 30	≤ 4
RG 90-18/14N/2	≤ 0.4	2	30	0	≤ 30	≤ 4
RG 125-19/14N/2	≤ 0.4	2	30	0	≤ 30	≤ 4
RG 125-19/18N/2	≤ 0.4	2	60	0	≤ 30	≤ 4
RER 125-19/14N/2	≤ 0.4	2	30	0	≤ 30	≤ 4
RG 160-28/14N/2	≤ 0.4	2	30	0	≤ 30	≤ 20

Attention:

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Данный компонент на территории Российской Федерации

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<http://moschip.ru/get-element>

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Нашей специализацией является поставка электронной компонентной базы двойного назначения, продукции таких производителей как XILINX, Intel (ex.ALTERA), Vicor, Microchip, Texas Instruments, Analog Devices, Mini-Circuits, Amphenol, Glenair.

Сотрудничество с глобальными дистрибьюторами электронных компонентов, предоставляет возможность заказывать и получать с международных складов практически любой перечень компонентов в оптимальные для Вас сроки.

На всех этапах разработки и производства наши партнеры могут получить квалифицированную поддержку опытных инженеров.

Система менеджмента качества компании отвечает требованиям в соответствии с ГОСТ Р ИСО 9001, ГОСТ РВ 0015-002 и ЭС РД 009

Офис по работе с юридическими лицами:

105318, г.Москва, ул.Щербаковская д.3, офис 1107, 1118, ДЦ «Щербаковский»

Телефон: +7 495 668-12-70 (многоканальный)

Факс: +7 495 668-12-70 (доб.304)

E-mail: info@moschip.ru

Skype отдела продаж:

moschip.ru

moschip.ru_4

moschip.ru_6

moschip.ru_9