# 2096 (H) x 2096 (V) Interline

The KAE−04471 Image Sensor is a 4.4 Mp, 4/3″ format, Interline Transfer EMCCD image sensor that provides exceptional imaging performance in extreme low light applications. Each of the sensor's four outputs incorporates both a conventional horizontal CCD register and a high gain EMCCD register.

An intra-scene switchable gain feature samples each charge packet on a pixel-by-pixel basis. This enables the camera system to determine whether the charge will be routed through the normal gain output or the EMCCD output based on a user selectable threshold. This feature enables imaging in extreme low light, even when bright objects are within a dark scene, allowing a single camera to capture quality images from sunlight to starlight.



#### **Table 1. GENERAL SPECIFICATIONS**



# **ON Semiconductor®**

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#### **Figure 1. KAE−04471 Interline Transfer EMCCD Image Sensor**

#### **Features**

- Intra-Scene Switchable Gain
- Wide Dynamic Range
- Low Noise Architecture
- Exceptional Low Light Imaging
- Global Shutter
- Excellent Image Uniformity and MTF
- Bayer Color Pattern and Monochrome

#### **Applications**

- Scientific Imaging
- Medical Imaging
- Defense Imaging
- Surveillance
- Intelligent Transportation Systems

#### **ORDERING INFORMATION**

See detailed ordering and shipping information on page 2 of this data sheet.

#### **ORDERING INFORMATION**

US export controls apply to all shipments of this product designated for destinations outside of the US and Canada, requiring ON Semiconductor to obtain an export license from the US Department of Commerce before image sensors or evaluation kits can be exported.





See the ON Semiconductor *Device Nomenclature* document (TND310/D) for a full description of the naming convention used for image sensors. For reference documentation, including information on evaluation kits, please visit our web site at [www.onsemi.com.](http://onsemi.com)

#### **Warning**

The KAE−04471−ABA−SD and KAE−04471−FBA−SD packages have an integrated thermoelectric cooler (TEC) and have epoxy−sealed cover glass. The seal formed is non−hermetic, and may allow moisture ingress over time, depending on the storage environment.

As a result, care must be taken to avoid cooling the device below the dew point inside the package cavity, since this may result in moisture condensation.

For all KAE−04471 configurations, no warranty, expressed or implied, covers condensation.

#### **DEVICE DESCRIPTION**

#### **Architecture**



**Figure 2. Block Diagram**

#### **Dark Reference Pixels**

There are 12 dark reference rows at the top and bottom of the image sensor, as well as 24 dark reference columns on the left and right sides. However, the rows and columns at the perimeter edges should not be included in acquiring a dark reference signal, since they may be subject to some light leakage.

#### **Active Buffer Pixels**

12 unshielded pixels adjacent to any leading or trailing dark reference regions are classified as active buffer pixels. These pixels are light sensitive but are not tested for defects and non-uniformities.

#### **Image Acquisition**

An electronic representation of an image is formed when incident photons falling on the sensor plane create electron-hole pairs within the individual silicon photodiodes. These photoelectrons are collected locally by the formation of potential wells at each photo-site. Below photodiode saturation, the number of photoelectrons collected at each pixel is linearly dependent upon light level and exposure time and non-linearly dependent on wavelength. When the photodiodes charge capacity is reached, excess electrons are discharged into the substrate to prevent blooming.

#### <span id="page-3-0"></span>**Physical Description**

*Pin Grid Array Configuration*





#### **Table 3. PIN DESCRIPTION**







#### **Table [3](#page-3-0). PIN DESCRIPTION** (continued)







#### <span id="page-7-0"></span>**Table [3](#page-3-0). PIN DESCRIPTION** (continued)



#### **Table 4. PIN DESCRIPTION FOR PACKAGE WITH INTEGRATED TEC**



#### **Table [4](#page-7-0). PIN DESCRIPTION FOR PACKAGE WITH INTEGRATED TEC** (continued)









#### **Table [4](#page-7-0). PIN DESCRIPTION FOR PACKAGE WITH INTEGRATED TEC** (continued)

#### <span id="page-11-0"></span>**Imaging Performance**

#### **Table 5. TYPICAL OPERATION CONDITIONS**

(Unless otherwise noted, the Imaging Performance Specifications are measured using the following conditions.)



1. For monochrome sensor, only green LED light source is used.

#### **Table 6. SPECIFICATIONS**



#### <span id="page-12-0"></span>**Table [6](#page-11-0). SPECIFICATIONS** (continued)



2. Per color

3. Value is over the range of 10% to 90% of photodiode saturation.

4. The operating value of the substrate reference voltage, V<sub>AB</sub>, can be read from V<sub>SUBREF</sub>.<br>5. At 20 MHz.

6. Uses 20 LOG (P<sub>Ne</sub>/n<sub>e−T</sub>)

7. Calculated from f<sub>−3db</sub> = 1 / 2π \* R<sub>OUT</sub> \* C<sub>LOAD</sub> where C<sub>LOAD</sub> = 5 pF.<br>8. The output-to-output gain differences may be adjusted by independently adjusting the EMCCD amplitude for each output.

# **TYPICAL PERFORMANCE CURVES**

#### **Quantum Efficiency**

*Monochrome and Color with Microlens, No Cover Glass*



**Figure 4. Monochrome and Color Quantum Efficiency**

#### **Angular Response**

The incident light angle is varied in a plane parallel to the HCCD.

*Monochrome with Microlens, No Cover Glass*



**Figure 5. Angled Response for Monochrome Device**





**Figure 6. Vertical Angled Response for Color Device**



**Figure 7. Horizontal Angled Response for Color Device**



**Figure 8. Frame Rates vs. Clock Frequency**

#### **DEFECT DEFINITIONS**

#### **Table 7. DEFECT DEFINITIONS**



9. Low exposure dark column defects are not counted at temperatures above -10°C

10.For the color device, a bright field defective pixel deviates by 12% with respect to pixels of the same color.

11. Column and cluster defects are separated by no less than 2 good pixels in any direction (excluding single pixel defects).

### **OPERATION**

#### **Absolute Maximum Ratings**

Absolute maximum rating is defined as a level or condition that should not be exceeded at any time per the description. If the level or the condition is exceeded, the device will be degraded and may be damaged. Operation at these values will reduce MTTF.

#### **Table 8. ABSOLUTE MAXIMUM RATINGS**



Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

12.Noise performance will degrade at higher temperatures.

 $13.\text{T} = 25^{\circ}\text{C}$ . Excessive humidity will degrade MTTF.

14.Total for all outputs. Maximum current is −15 mA for each output. Avoid shorting output pins to ground or any low impedance source during operation. Amplifier bandwidth increases at higher current and lower load capacitance at the expense of reduced gain (sensitivity).

#### **Table 9. ABSOLUTE MAXIMUM VOLTAGE RATINGS BETWEEN PINS AND GROUND**



15.Refer to Application Note *Using Interline CCD Image Sensors in High Intensity Visible Lighting Conditions.*

16.The measured value for VSUBREF is a diode drop higher than the recommended minimum VSUB bias.

#### **Power Up and Power Down Sequence**

SUB and ESD power up first, then power up all other biases in any order. No pin may have a voltage less than ESD at any time. All HCCD pins must be greater than or equal to GND at all times. The SUBREF pin will not become valid until VDD15ac and VDD15bd have been powered. The SUB pin should be at least 4 V before powering up  $VDD2(a,b,c,d)$  and  $VDD3(a,b,c,d)$ .



#### **Table 10. DC BIAS OPERATING CONDITIONS**

17.VDD15ac and VDDD15bd bias pins must be maintained at 15 V during operation.

18.For each image sensor, the voltage output on the VSUBREF pin is programmed to be one diode drop, 0.5 V, above the nominal VSUB voltage. So, the applied VSUB should be one diode drop (0.5 V) lower than the VSUBREF value measured on the device, when VDD2(a,b,c,d) and VDD3(a,b,c,d) are at the specified voltage. This value corresponds to the VAB printed on the label for each sensor and applies to operation<br>at 0°C. (For other temperatures, there is a temperature dependence of approximatel at 0°C. (For other temperatures, there is a temperature dependence of approximately 0.01 V/degree.) It is noted that VSUBREF is unique to each image sensor and may vary from 6.5 to 10.0 V. In addition, the output impedance of VSUBREF is approximately 100 k. 19.Caution: The EMCCD register must NOT be clocked while the electronic shutter pulse is high.

#### **AC Operating Conditions**

*Clock Levels*

#### **Table 11. CLOCK LEVELS**



20.HCCD Operating Voltages. There can be no overshoot on any horizontal clock below −0.4 V: the specified absolute minimum. The H1SEM and H2SEM clock amplitudes need to be software programmable independently for each quadrant to adjust the charge multiplier gain.

21. Reset Clock Operation: The RG1, RG23 signals must be capacitive coupled into the image sensor with a 0.01  $\mu$ F to 0.1  $\mu$ F capacitor. The reset clock overshoot can be no greater than 0.3 V, as shown in Figure [9](#page-19-0), below.

<span id="page-19-0"></span>

**Pin pF** H1SEMc 45 H<sub>2</sub>SEM<sub>c</sub> 45 H1BEMc 45 H<sub>2</sub>B<sub>EMc</sub> 45 H<sub>1c</sub> 65 H<sub>2c</sub> 65 H<sub>1</sub>Sc 75 H<sub>2</sub>Sc 75 H<sub>1</sub>Bc 75 H<sub>2</sub>Bc 75



┑

#### *Clock Capacitances*







NOTE: The capacitances of all other HCCD pins is 15 pF or less.



**Figure 10. EMCCD Clock Adjustable Levels**

For the EMCCD clocks, each quadrant must have independently adjustable high levels. All quadrants have a common low level of GND. The high level adjustments

must be software controlled to balance the gain of the four outputs.



**Figure 11. Reset Clock Drivers**

The reset clock drivers must be coupled by capacitors to the image sensor. The capacitors can be anywhere in the range  $0.01$  to  $0.1 \mu$ F. The damping resistor values would

vary between 0 and 75  $\Omega$  depending on the layout of the circuit board.

#### **Table 12. VCCD**



22. The Vertical CCD operating voltages. The VCCD low level will be −8.0 V for operating temperatures of −10°C and above. Below −10°C the VCCD low level should be increased for optimum noise performance.

#### **Table 13. ELECTRONIC SHUTTER PULSE**



#### **Device Identification**

The device identification pin (DevID) may be used to determine which ON Semiconductor 5.5 micron pixel interline CCD sensor is being used.

#### **Table 14. DEVICE IDENTIFICATION VALUES**



23.Nominal value subject to verification and/or change during release of preliminary specifications.

24.If the Device Identification is not used, it may be left disconnected.

25.After Device Identification resistance has been read during camera initialization, it is recommended that the circuit be disabled to prevent localized heating of the sensor due to current flow through the R\_DeviceID resistor.

*Recommended Circuit*



**Figure 12. Device Identification Recommended Circuit**

#### **THEORY OF OPERATION**

**Image Acquisition**



**Figure 13. An Illustration of Two Columns and Three Rows of Pixels**

This image sensor is capable of detecting up to 40,000 electrons with a small signal noise floor of 1 electron all within one image. Each  $7.4 \mu m$  square pixel, as shown in Figure 13 above, consists of a light sensitive photodiode and a portion of the vertical CCD (VCCD). Not shown is a microlens positioned above each photodiode to focus light away from the VCCD and into the photodiode. Each photon incident upon a pixel will generate an electron in the photodiode with a probability equal to the quantum efficiency.

The photodiode may be cleared of electrons (electronic shutter) by pulsing the SUB pin of the image sensor up to a voltage of 30 V to 40 V (VSUBREF + 22 to VSUBREF  $+ 28$  V) for a time of at least 1 µs. When the SUB pin is above 30 V, the photodiode can hold no electrons, and the electrons flow downward into the substrate. When the voltage on SUB drops below 30 V, the integration of electrons in the photodiode begins. The HCCD clocks should be stopped when the electronic shutter is pulsed, to avoid having the large voltage pulse on SUB coupling into the video outputs and altering the EMCCD gain.

It should be noted that there are certain conditions under which the device will have no anti-blooming protection: when the V1T and V1B pins are high, very intense illumination generating electrons in the photodiode will flood directly into the VCCD. When the electronic shutter pulse overlaps the V1T and V1B high-level pulse that transfers electrons from the photodiode to the VCCD, then photo-electrons will flow to the substrate and not the VCCD. This condition may be desirable as a means to obtain very short integration times.

The VCCD is shielded from light by metal to prevent detection of more photons. For very bright spots of light, some photons may leak through or around the metal light shield and result in electrons being transferred into the VCCD. This is called image smear.

#### **Image Readout**

At the start of image readout, the voltage on the V1T and V1B pins is pulsed from 0 V up to the high level for at least  $1 \mu s$  and back to  $0 \nu$ , which transfers the electrons from the photodiodes into the VCCD. If the VCCD is not empty, then the electrons will be added to what is already in the VCCD. The VCCD is read out one row at a time. During a VCCD row transfer, the HCCD clocks are stopped. All gates of type H1 stop at the high level and all gates of type H2 stop at the low level. After a VCCD row transfer, charge packets of electrons are advanced one pixel at a time towards the output amplifiers by each complimentary clock cycle of the H1 and H2 gates.

The charge multiplier has a maximum charge handling capacity (after gain) of 20,000 electrons. This is not the average signal level. It is the maximum signal level. Therefore, it is advisable to keep the average signal level at 15,000 electrons or less to accommodate a normal distribution of signal levels. For a charge multiplier gain of 20x, no more than  $15,000/20 = 750$  electrons should be allowed to enter the charge multiplier. Overfilling the charge multiplier beyond 20,000 electrons will shorten its useful operating lifetime.

To prevent overfilling the charge multiplier, a non-destructive floating gate output amplifier (VOUT1) is provided on each quadrant of the image sensor as shown in Figure 14 below.





The non-destructive floating gate output amplifier is able to sense how much charge is present in a charge packet without altering the number of electrons in that charge packet. This type of amplifier has a low charge-to-voltage conversion gain (about  $7.8 \mu V/e^-$ ) and high noise (about 42 electrons), but it is being used only as a threshold detector, and not an imaging detector. Even with 42 electrons of noise, it is adequate to determine whether a charge packet is greater than or less than the recommended threshold of 120 electrons.

After one row has been transferred from the VCCD into the HCCD, the HCCD clock cycles should begin. After 8 clock cycles, the first dark VCCD column pixel will arrive at VOUT1. After another 24 (34 total) clock cycles, the first photo-active charge packet will arrive at VOUT1.

The transfer sequence of a charge packet through the floating gate amplifier is shown in Figure 15 below. The time steps of this sequence are labeled A through D, and are indicated in the timing diagram shown as Figure [16.](#page-24-0) The RG1 gate is pulsed high during the time that the H2X gate is pulsed high. This holds the floating gate at a constant voltage so the H2X gate can pull the charge packet out of the floating gate. The RG1 pulse should be at least as wide as the H2X pulse, and the H2X pulse width should be at least 12 ns. The rising edge of H2X relative to the falling edge of H1S is critical, specifically, the H2X pulse cannot begin its rising edge transition until the H1S edge is less than 0.4 V. If the H2X rising edge comes too soon then there may be some backward flow of charge for signals above 10,000 electrons.



NOTE: The differently shaded rectangles represent two separate charge packets. The direction of charge transfer is from right to left. Gates after H2X are connected to H1 or H2. Gates before H2X are connected to H1S or H2S.



<span id="page-24-0"></span>

**Figure 16. Timing Signals that Control the Transfer of Charge through the Floating Gate Amplifier**

The charge packet is transferred under the floating gate on the falling edge of H2L. When this transfer takes place the floating gate is not connected to any voltage source. The presence of charge under the gate causes a change in voltage on the floating gate according to  $V = Q/C$ , where Q is the size of the charge packet and C is the capacitance of the floating gate. With an output sensitivity of  $7.8 \mu V/e^-$ , each electron on the floating gate would give a  $7.8 \mu V$ change in VOUT1 voltage. Therefore if the decision threshold is to only allow charge packets of 126 electrons or less into the charge multiplier, this would correspond to  $120 \times 7.8 = 936$  µV. If the video output is less than 936 µV, then the camera must set the timing of the H2SW2 and H2SW3 pins to route the charge packet to the charge multiplier. This action must take place 28 clock cycles after the charge packet was under the floating gate amplifier. The 28 clock cycle delay is to allow for pipeline delays of the A/D converter inside the analog front end. The timing generator must examine the output of the analog front end

and dynamically alter the timing on H2SW2 and H2SW3. To route a charge packet to the charge multiplier (VOUT3), H2SW2 is held at GND and H2SW3 is clocked with the same timing as H2 for that one clock cycle. To route a charge packet to the low gain output amplifier (VOUT2), H2SW3 is held at GND and H2SW2 is clocked with the same timing as H2S for that one clock cycle.

When operating the device at maximum (40 MHz) data rate, all the charge must be routed through the low gain amplifier (VOUT2). This is best accomplished with the floating gate reset (RG1) held at its high level while clocking the HCCD, and the H2X gate clocked with the same timing as H2S and H2B. During the line timing patterns L1 or L2, the RG1 gate should be clocked low. There is a diode on the sensor that sets the DC offset of the RG1 gate when it is clocked low. If the RG1 is not clocked low once per line then the RG1 DC offset will drift. This timing scheme is represented in the diagram shown below:





#### **EMCCD OPERATION**



NOTE: Charge flows from right to left.

#### **Figure 18. The Charge Multiplication Process**

The charge multiplication process, shown in Figure 18 above, begins at time step A, when an electron is held under the H1SEM gate. The H2BEM and H1BEM gates block the electron from transferring to the next phase until the H2SEM has reached its maximum voltage. When the H2BEM is clocked from 0 to +5 V, the channel potential under H2BEM increases until the electron can transfer from H1SEM to H2SEM. When the H2SEM gate is above 10 V, the electric field between the H2BEM and H2SEM gates gives the electron enough energy to free a second electron which is collected under H2SEM. Then the voltages on H2BEM and

H2SEM are both returned to 0 V at the same time that H1SEM is ramped up to its maximum voltage. Now the process can repeat again with charge transferring into the H1SEM gate.

The alignment of clock edges is shown in Figure [19.](#page-26-0) The rising edge of the H1BEM and H2BEM gates must be delayed until the H1SEM or H2SEM gates have reached their maximum voltage. The falling edge of H1BEM and H2BEM must reach 0 V before the H1SEM or H2SEM reach 0 V. There are a total of 1,800 charge multiplying transfers through the EMCCD on each quadrant.

<span id="page-26-0"></span>

**Figure 19. The Timing Diagram for Charge Multiplication**

The amount of gain through the EMCCD will depend on temperature and H1SEM and H2SEM voltage as shown in Figure 20. Gain also depends on substrate voltage, as shown in Figure [21,](#page-27-0) and on the input signal, as shown in Figure [22.](#page-27-0)





**Figure 20. The Variation of Gain vs. EMCCD High Voltage and Temperature**

<span id="page-27-0"></span>

**Figure 21. The Requirement EMCCD Voltage for Gain of 20x vs. Substrate Voltage**



NOTE: The EMCCD voltage was set to provide 20x gain with an input of 180 electrons.

**Figure 22. EMCCD Gain vs. Input Signal**

If more than one output is used, then the EMCCD high level voltage must be independently adjusted for each quadrant. This is because each quadrant will require a slightly different voltage to obtain the same gain. In addition, the voltage required for a given gain differs

unpredictably from one image sensor to the next, as in Figure [23](#page-28-0). Because of this, the gain vs. voltage relationship must be calibrated for each image sensor, although within each quadrant, the H1SEM and H2SEM high level voltage should be equal.

<span id="page-28-0"></span>

**Figure 23. An Example Showing How Two Image Sensors Can Have Different Gain vs. Voltage Curves**

The effective output noise of the image sensor is defined as the noise of the output signal divided by the gain. This is measured with zero input signal to the EMCCD. Figure 24 shows the EMCCD by itself has a very low noise that goes as the noise at gain = 1 divided by the gain. The EMCCD has very little clock-induced charge and does not require

elaborate sinusoidal waveform clock drivers. Simple square wave clock drivers with a resistor between the driver and sensor for a small RC time constant are all that is needed. However, the pixel array may acquire spurious charge as a function of VCCD clock driver characteristics.



NOTE: The data represented by this chart includes noise from dark current and spurious charge generation.

# **Figure 24. EMCCD Output Noise vs. EMCCD Gain in Single Output Mode from −30**-**C to +10**-**C**

Because of these pixel array noise sources, it is recommended that the maximum gain used be 100x, which typically gives a noise floor between 0.4e and 0.6e at −10°C. Using higher gains will provide limited benefit and will degrade the signal to noise ratio due to the EMCCD excess noise factor and spurious charge in the VCCD. Furthermore, the image sensor is not limited by dark current noise sources when the temperature is below −10°C. Therefore, cooling below −10°C will not provide a significant improvement to the noise floor, with the negative consequence that lower

temperatures increase the probability of poor charge transfer.

**CAUTION:** The EMCCD should not be operated near saturation for an extended period, as this may result in gain aging and permanently reduce the gain. It should be noted that device degradation associated with gain aging is not covered under the device warranty.

#### **Operating Temperature**

The reasons for lowering the operating temperature are to reduce dark current noise and to reduce image defects. The average dark signal from the VCCD and photodiodes must be less than 1e− in order to have a total system noise less than 1e− when using the EMCCD. The recommended operating temperature is −10°C. This represents the best compromise of low noise performance vs. complexity of cooling the image sensor. Operation below −30°C is not recommended, and temperatures below −30°C may result in poor charge transfer in the HCCD. Operation above 0°C may result in excessive dark current noise.

#### **Charge Switch Threshold**

The floating gate output amplifier (VOUT1) is used to select the routing of a pixel charge packet at the charge switch. Pixels with large signals should be routed to the normal floating diffusion amplifier at VOUT2. Pixels with small signals should be routed to the EMCCD and VOUT3. The routing of pixels is controlled by the timing on H2SW2 and H2SW3. The optimum signal threshold for that transition between VOUT2 and VOUT3 is approximately 3 times the floating gate amplifier noise, or 126 e−. Sending signals larger than 126 e− into the EMCCD will produce images with lower signal to noise ratio than if they were read out of the normal floating diffusion output of VOUT2.

# **TIMING DIAGRAMS**

#### **Pixel Timing**





#### **Figure 25. Pixel Timing Pattern P1**

#### **Black, Clamp, VOUT1, VOUT2, and VOUT3 Alignment at Line Start**

The black level clamping operation of the analog front end (AFE) should take place within the first 28 clock cycles of every row. This applies to all modes of operation.

#### **VCCD Timing**

*Vertical Transfer Times and Pulse Widths*

#### **Table 15. TIMING DEFINITIONS**



*Clock Edge Alignments for V1, V2, V3, V4*



**Figure 26. Timing Pattern F1. VCCD Frame Timing to Transfer Charge from Photodiodes to the VCCD when Using the Bottom HCCD Outputs A or B**



**Figure 27. Timing Pattern F2. VCCD Frame Timing to Transfer Charge from Photodiodes to the VCCD when Using All Four Outputs in Quad Output Mode**



**Figure 28. Line Timing L1. VCCD Line Timing to Transfer One Line of Charge from VCCD to the HCCD when Using the Bottom HCCD Outputs A or B in Single or Dual Output Modes**



**Figure 29. Line Timing L2. VCCD Line Timing to Transfer One Line of Charge from the VCCD to the HCCD when Using All Four Outputs in Quad Output Mode**

#### **Electronic Shutter**



#### **Figure 30. Electronic Shutter Timing Pattern S1**

**CAUTION:** The EMCCD register must not be clocked while the electronic shutter pulse is high.

#### **HCCD and EMCCD Clocks for Electronics Shutter**

The HCCD and EMCCD clocks must be static during the frame, line, and electronic shutter timing sequences.

#### **Table 16. HCCD AND EMCCD CLOCKS FOR ELECTRONICS SHUTTER**



#### **HCCD Timing**

To reverse the direction of charge transfer in a Horizontal CCD, the timing patterns of the H1B and H2B inputs of that

HCCD are exchanged. If a HCCD is not used, all of its gates are to be held at the high level.

#### **Table 17. HCCD TIMING**



#### **Table 18. FRAME RATES**



#### **Image Exposure and Readout**

The flowchart for image exposure and readout is shown in the figure below. The electronic shutter timing may be omitted to obtain an exposure time equal to the image read out time. NEXP is the number of lines exposure time and NV is the number of VCCD clock cycles (row transfers).

#### **Table 19. IMAGE READOUT TIMING**





**Figure 31. The Image Readout Timing Flow Chart**

#### **Long Integrations and Readout**

For extended integrations the output amplifiers need to be powered down. When powered up, the output amplifiers

emit near infrared light that is sensed by the photodiodes. It will begin to be visible in images of 30 second integrations or longer.



**Figure 32. Timing Flow Chart for Long Integration Time**

To power down the output amplifiers set VDD1 and VSS1 to 0 V, and VDD2 $(a,b,c,d)$  and VDD3 $(a,b,c,d)$  to  $+5$  V. VDD2 or VDD3 must not be set to 0 V during the integration of an image. During the time the VDD2 and VDD3 supplies are reduced to +5 V the VDD15 pin is to be kept at +15 V. The substrate voltage reference output SUBV will be valid

as long as VDD15 is powered. The HCCD and EMCCD may be continue to clock during integration. If they are stopped during integration then the EMCCD should be re-started at +7 V amplitude to flush out any undesired signal before increasing the voltage to charge multiplying levels.

#### **THERMOELECTRIC COOLER**

Representative performance plots for the TEC are shown below:

#### **Performance Plots of Integrated TECs**

For the performance plots below, the thermoelectric cooler (TEC) was in a dry package cavity, sealed under nitrogen. The ambient temperature was 27°C. The TEC controller was operated in DC mode (maximum pulse width

of a PWM controller) to maintain the cold side (sensor side) temperature at 0°C, while the input signal to the EMCCD registers was 20 mV, the EMCCD gains were set to 20X, and the horizontal clock rate was 20 MHz. For these conditions, the recommended maximum input current (Imax) is 1.1 A, requiring an input voltage (Vmax) of 11.2 V. Lower cold side temperatures may have different optimum operating conditions.



Figure 33. **AT and Voltage vs. Current** 





The plot shown below separately shows the dependence of cooling performance  $(\Delta T)$  on the thermal resistance of the cooling system.



Figure 35. Maximum **AT vs. Cooling System Thermal Resistance** 

The thermoelectric cooler has an on−board thermistor. The current model has  $\pm 3\%$  tolerance and 10 k $\Omega$  (Ro) at 25°C (298°K, To). Its performance is shown in the plot below and follows the equation, where  $T =$  temperature in  $\rm{°K}$ , over the range of 233 $\rm{°K}$  to 398 $\rm{°K}$ , and RT = thermistor resistance in Ohms.



**Figure 36. Thermistor Resistance vs. Temperature**

$$
T = \frac{1}{\left[ (1.311E - 3) + (2.138E - 4) * ln(R_{T}) + (9.43E - 8) * (ln(R_{T}))^{3} \right]}
$$

#### **STORAGE AND HANDLING**

#### **Table 20. STORAGE CONDITIONS**



26.Long-term exposure toward the maximum temperature will accelerate color filter degradation.

27.T = 25°C. Excessive humidity will degrade Mean Time to Failure (MTTF.)

For information on ESD and cover glass care and cleanliness, please download the *Image Sensor Handling and Best Practices* Application Note (AN52561/D) from [www.onsemi.com.](http://onsemi.com)

For information on soldering recommendations, please download the Soldering and Mounting Techniques Reference Manual (SOLDERRM/D) from [www.onsemi.com.](http://onsemi.com)

For quality and reliability information, please download the *Quality & Reliability* Handbook (HBD851/D) from [www.onsemi.com.](http://onsemi.com)

For information on device numbering and ordering codes, please download the *Device Nomenclature* technical note (TND310/D) from [www.onsemi.com](http://onsemi.com).

For information on Standard terms and Conditions of Sale, please download [Terms and Conditions](http://www.onsemi.com/site/pdf/ONSEMI_T&C.pdf) from [www.onsemi.com.](http://onsemi.com)

# **MECHANICAL INFORMATION**

#### **PGA Completed Assembly (no TEC)**







**Figure 38. Completed Assembly (2 of 3)**



**Figure 39. Completed Assembly (3 of 3)**





**Figure 40. PGA Completed Assembly with Integrated TEC (1 of 4)**



**Figure 41. PGA Completed Assembly with Integrated TEC (2 of 4)**





**Figure 43. PGA Completed Assembly with Integrated TEC (4 of 4)**

#### **Clear Cover Glass for PGA with Integrated TEC**



- 1. Dust, Scratch, Inclusion Defect Max: 10 μm (A-Zone)
- 2. Glass Material is Schott D263T eco
- 3. Anti−reflection Coatings on both Sides of Substrate to meet the following Minimum Transmission Specifications:



- 4. Epoxy is B−staged Form (Ref. KSD−248−0109, Spec KSD−241−0009)
- 5. All Contamination Outside the A−Zone must be Removable with N2 at 40 PSI
- 6. Edge Chips:  $X \le 0.50$  mm,  $Y \le 0.50$  mm,  $Z \le 0.48$  mm

#### **Figure 44. MAR Cover Glass for PGA with Integrated TEC**





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