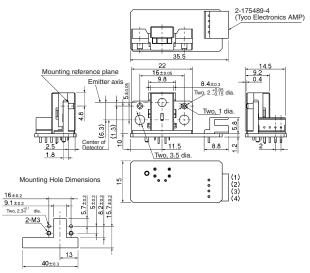
# Micro-displacement Sensor **Z4D-B01**

#### ■ Dimensions

Note: All units are in millimeters unless otherwise indicated.



Recommended Mating Connectors: Tyco Electronics AMP

175778-4 (crimp connector) 173977-4 (press-fit connector)

#### ■ Features

- Easier control enabled by built-in processor circuit.
- Resolution: ±10 μm.
- Operating area: 6.5±1 mm.
- · Adapts well to changes in reflection factor using division processing.

F	Pin no.	Remarks
Γ	1	PLS
	2	V <sub>CC</sub>
F	3	OUT
[	4	GND

Unless otherwise specified, the tolerances are as shown below.

Dimensions	Tolerance						
3 mm max.	±0.3						
3 < mm ≤ 6	±0.375						
6 < mm ≤10	±0.45						
10 < mm ≤ 18	±0.55						
18 < mm ≤ 30	±0.65						
30 < mm ≤ 50	±0.8						

### ■ Ordering Information

Description	Model					
Micro-displacement sensor	Z4D-B01					

# ■ Absolute Maximum Ratings (Ta = 25°C)

Item	Symbol	Value	Unit	Remarks				
Supply voltage	V <sub>cc</sub>	7	VDC					
LED pulse light emission control signal	PLS	7	VDC	LED				
LED light emission pulse	t <sub>FP</sub>	100	ms					
Operating temperature	T <sub>opr</sub>	-10 to 65	°C	No icing or condensation				
Storage temperature	T <sub>stg</sub>	-25 to 80	°C					

## ■ Electrical and Optical Characteristics (Ta = -10°C to 65°C)

ltem	Symbol	Rated value	Remarks				
Supply voltage	V <sub>cc</sub>	5 VDC±10%	Ripple (p-p): 10 mV p-p max.				
Output voltage	OUT	0.2 VDC to (V <sub>CC</sub> -0.3) V	(see note 1)				
Response time	tr	100 μs max.	(see note 2)				
LED pulse light emission control signal	PLS	3.5 VDC to V <sub>CC</sub>	(see note 3)				

Note: 1. Load impedance (between OUT-GND) is set at more than 10 k $\Omega$ .

- 2. The time for output voltage to rise from 10% to 90% of the full output range.
- Apply the voltage ranging from 3.5 V to V<sub>CC</sub> on the LED pulse light emission control signal terminal. In this case, a maximum of 2 mA (TYP 1 mA) current is sunk.

#### ■ Characteristics (Ta = -10°C to 65°C)

Object: N8.5 Munsell paper with a reflection factor of 70%.

Item	Value
Operating area (see note 1)	6.5 ±1 mm
Sensitivity variation (see note 2)	-1.4 mV/μm±10% max.
Resolution (see note 3)	$\pm 10 \ \mu m \ max. \ (Ta = 25^{\circ}C)$
Linearity (see note 4)	2% F.S. (full scale) max.

- Note: 1. Distance from the mounting reference plane.
  - 2. "Sensitivity" is defined as "inclination of divided output line" and the variation value between individual products of fluctuating divided output voltage per unit length.

Sensitivity = 
$$\frac{V_2 - V_0}{2000}$$
 (mV/mm)

Where

V0: Output voltage when d = 5.5 mm

V2: Output voltage when d = 7.5 mm

d: Distance from reference mounting plane to an object.

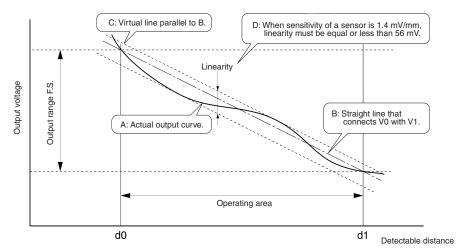
3. Value of electrical noise range of divided output signal converted to distance under the following conditions.



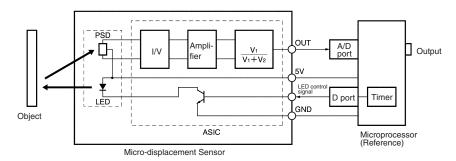
- (1) Ripple noise of power supply: 10 mV p-p max.
- (2) Sampling time of the sample and hold circuit: 50 μsec
- (3) Distance to object: Distance from the reference mounting plane is 6.5 mm±1 mm.
  - \*\* When the testing conditions are deviated from the above conditions, resolution changes. For details, please consult OMRON sales representative.
- 4. The peak-to-peak value of the output error from the ideal line.

Calculation, based on a linearity of 2% F.S., is as follows:

- (1) The conversion value based on the full scale distance: 2 mm  $\times$  0.02 = 0.04 mm (40  $\mu$ m)
- (2) The conversion value based on the output voltage: 1.4 mV/μm × 40 μm = 56 mV (When the product sensitivity variation is 1.4 mV/μm.)

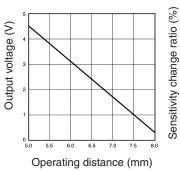


# **■** Circuit Diagram

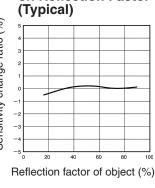


## **■** Engineering Data

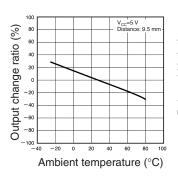
Operating Distance Characteristics (Typical)



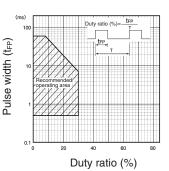
Dependency of Object on Reflection Factor (Typical)



Temperature Characteristics (Typical)

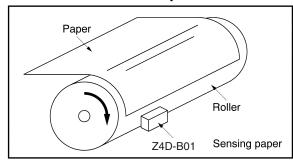


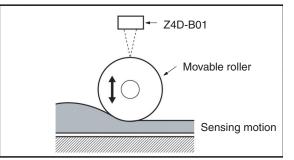
#### Pulsed Forward Current Rated Curve



## **■** Typical Application

#### Paper thickness detection for printers







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- paid by Buyer;

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