



## Main

|                              |   |
|------------------------------|---|
| Range of product             | Altivar 32                                |
| Product or component type    | Variable speed drive                      |
| Product destination          | Asynchronous motors<br>Synchronous motors |
| Product specific application | Complex machines                          |
| Function available           | Configure over bluetooth                  |
| Assembly style               | With heat sink                            |
| Component name               | ATV32                                     |
| EMC filter                   | Class C2 EMC filter integrated            |
| Phase                        | 1 phase                                   |
| [Us] rated supply voltage    | 200...240 V - 15...10 %                   |
| Supply voltage limits        | 170...264 V                               |
| Supply frequency             | 50...60 Hz - 5...5 %                      |
| Network frequency            | 47.5...63 Hz                              |
| Motor power kW               | 0.18 kW 200...240 V                       |
| Motor power hp               | 0.25 hp 200...240 V                       |

## Complementary

|                                    |  |
|------------------------------------|--|
| Line current                       | 2.8 A 240 V 1 phase 0.18 kW 0.25 hp<br>3.4 A 200 V 1 phase 0.18 kW 0.25 hp   |
| Apparent power                     | 0.7 kVA 240 V 1 phase 0.18 kW 0.25 hp  |
| Prospective line I <sub>sc</sub>   | <= 1 kA 1 phase  |
| Nominal output current             | 1.5 A 4 kHz 240 V 0.18 kW 0.25 hp  |
| Maximum transient current          | 2.3 A 60 s 0.18 kW 0.25 hp   |
| Output frequency                   | 0.0005...0.599 kHz   |
| Nominal switching frequency        | 4 kHz  |
| Switching frequency                | 2...16 kHz adjustable  |
| Speed range                        | 1...100 asynchronous motor in open-loop mode   |
| Speed accuracy                     | +/- 10 % of nominal slip 0.2 T <sub>n</sub> to T <sub>n</sub>  |
| Torque accuracy                    | +/- 15 %   |
| Transient overtorque               | 170...200 %  |
| Braking torque                     | <= 170 % with braking resistor   |
| Asynchronous motor control profile | Voltage/frequency ratio, 2 points<br>Voltage/frequency ratio, 5 points<br>Flux vector control without sensor - Energy Saving, NoLoad law<br>Flux vector control without sensor, standard<br>Voltage/frequency ratio - Energy Saving, quadratic U/f |
| Synchronous motor control profile  | Vector control without sensor  |
| Regulation loop                    | Adjustable PID regulator   |
| Motor slip compensation            | Automatic whatever the load<br>Not available in voltage/frequency ratio (2 or 5 points)<br>Adjustable 0...300 %  |
| Local signalling                   | 1 LED red drive voltage<br>1 LED blue bluetooth<br>1 LED green CANopen run<br>1 LED red CANopen error<br>1 LED red drive fault   |
| Output voltage                     | <= power supply voltage  |
| Noise level                        | 43 dB 86/188/EEC   |
| Insulation                         | Electrical between power and control   |
| Electrical connection              | Screw terminal 0.5...1.5 mm <sup>2</sup> AWG 18...AWG 14 control<br>Removable screw terminals 1.5...2.5 mm <sup>2</sup> AWG 14...AWG 12 motor/braking resistor   |

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|                                     |   |
|-------------------------------------|---|
|                                     | Screw terminal 1.5...4 mm <sup>2</sup> AWG 14...AWG 10 power supply   |
| Tightening torque                   | 4.42 lbf.in (0.5 N.m) 4.4 lb/ft control<br>6.19 lbf.in (0.7 N.m) 7.1 lb/ft motor/braking resistor<br>5.31 lbf.in (0.6 N.m) 5.3 lb/ft power supply   |
| Supply                              | Internal supply for reference potentiometer (1 to 10 kOhm) 10.5 V DC +/- 5 % <= 10 mA overload and short-circuit protection   |
| Analogue input number               | 3   |
| Analogue input type                 | Voltage AI1 0...10 V DC 30000 Ohm 10 bits<br>Bipolar differential voltage AI2 +/- 10 V DC 30000 Ohm 10 bits<br>Current AI3 0...20 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration) 250 Ohm 10 bits  |
| Sampling duration                   | 2 ms AI1, AI2, AI3 analog<br>2 ms AO1 analog  |
| Response time                       | 8 ms +/- 0.7 ms LI1...LI6 logic<br>2 ms R1A, R1B, R1C relay<br>2 ms R2A, R2C relay  |
| Accuracy                            | +/- 0.2 % AI1, AI2, AI3 for a temperature of -10...60 °C<br>+/- 0.5 % AI1, AI2, AI3 for a temperature of 25 °C<br>+/- 1 % AO1 for a temperature of 25 °C<br>+/- 2 % AO1 for a temperature of -10...60 °C  |
| Linearity error                     | +/- 0.2...0.5 % of maximum value AI1, AI2, AI3<br>+/- 0.3 % AO1   |
| Analogue output number              | 1   |
| Analogue output type                | Software-configurable current AO1 0...20 mA 800 Ohm 10 bits<br>Software-configurable voltage AO1 0...10 V 470 Ohm 10 bits   |
| Discrete output number              | 3   |
| Discrete output type                | Configurable relay logic R1A, R1B, R1C NO/NC 100000 cycles<br>Configurable relay logic R2A, R2B NO 100000 cycles<br>Logic LO  |
| Minimum switching current           | 5 mA 24 V DC configurable relay logic   |
| Maximum switching current           | 3 A 250 V AC resistive (cos phi = 1 R1<br>4 A 30 V DC resistive (cos phi = 1 R1<br>2 A 250 V AC inductive (cos phi = 0.4 R1, R2<br>2 A 30 V DC inductive (cos phi = 0.4 R1, R2<br>5 A 250 V AC resistive (cos phi = 1 R2<br>5 A 30 V DC resistive (cos phi = 1 R2 |
| Discrete input number               | 7   |
| Discrete input type                 | Programmable (sink/source) LI1...LI4 24...30 V DC level 1 PLC<br>Programmable as pulse input 20 kpps LI5 24...30 V DC level 1 PLC<br>Switch-configurable PTC probe LI6 24...30 V DC<br>Safe torque off STO 24...30 V DC 1500 Ohm                                  |
| Discrete input logic                | Positive logic (source) LI1...LI6 < 5 V > 11 V<br>Negative logic (sink) LI1...LI6 > 19 V < 13 V   |
| Acceleration and deceleration ramps | S<br>U<br>CUS<br>Deceleration ramp automatic stop DC injection<br>Deceleration ramp adaptation<br>Linear<br>Ramp switching  |
| Braking to standstill               | By DC injection   |
| Protection type                     | Input phase breaks drive<br>Overcurrent between output phases and earth drive<br>Overheating protection drive<br>Short-circuit between motor phases drive<br>Thermal protection drive   |
| Communication port protocol         | CANopen<br>Modbus   |
| Connector type                      | 1 RJ45 Modbus/CANopen on front face   |
| Physical interface                  | 2-wire RS 485 Modbus  |
| Transmission frame                  | RTU Modbus  |
| Type of polarization                | No impedance Modbus   |
| Number of addresses                 | 1...247 Modbus<br>1...127 CANopen   |
| Method of access                    | Slave CANopen   |
| Electromagnetic compatibility       | 1.2/50 µs - 8/20 µs surge immunity test level 3 IEC 61000-4-5<br>Electrical fast transient/burst immunity test level 4 IEC 61000-4-4  |

Electrostatic discharge immunity test level 3 IEC 61000-4-2  
 Radiated radio-frequency electromagnetic field immunity test level 3 IEC 61000-4-3  
 Conducted radio-frequency immunity test level 3 IEC 61000-4-6  
 Voltage dips and interruptions immunity test IEC 61000-4-11

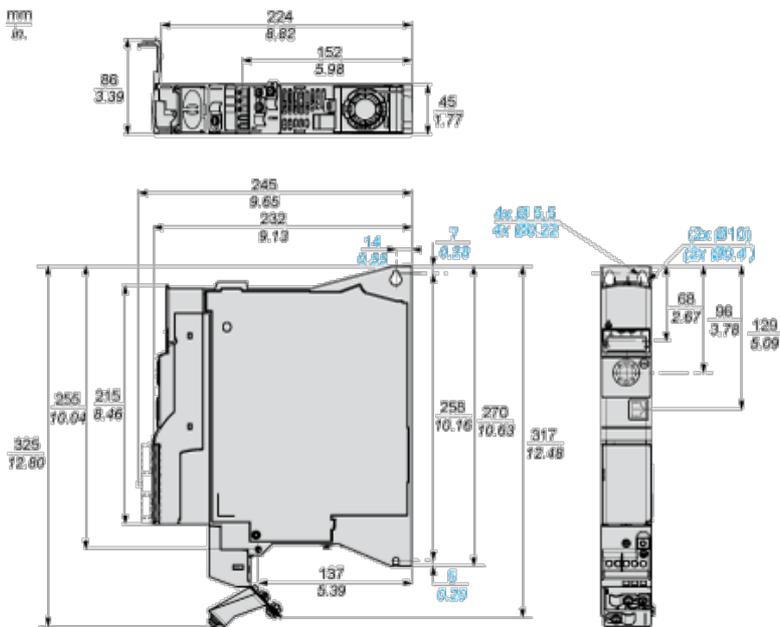
|                |  |
|----------------|--|
| Width          | 1.77 in (45 mm)  |
| Height         | 12.8 in (325 mm)   |
| Depth          | 9.65 in (245 mm)   |
| Product weight | 5.29 lb(US) (2.4 kg)   |
| Option card    | Communication card CANopen daisy chain<br>Communication card CANopen open style<br>Communication card DeviceNet<br>Communication card Ethernet/IP<br>Communication card Profibus DP V1 |

## Environment

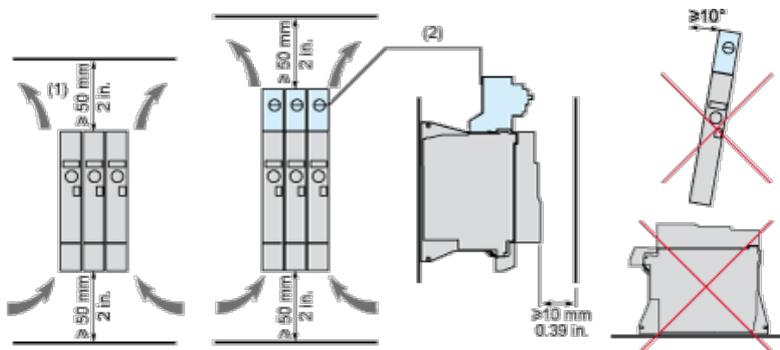
|                                       |  |
|---------------------------------------|--|
| standards                             | EN 55011 class A group 1<br>EN 61800-3 environments 1 category C2<br>EN 61800-3 environments 2 category C2<br>EN/IEC 61800-3<br>EN/IEC 61800-5-1 |
| product certifications                | CSA<br>C-Tick<br>GOST<br>NOM 117<br>UL   |
| marking                               | CE   |
| pollution degree                      | 2 EN/IEC 61800-5-1   |
| IP degree of protection               | IP20 EN/IEC 61800-5-1  |
| vibration resistance                  | 1 gn 13...200 Hz EN/IEC 60068-2-6<br>1.5 mm peak to peak 3...13 Hz EN/IEC 60068-2-6  |
| shock resistance                      | 15 gn 11 ms EN/IEC 60068-2-27  |
| relative humidity                     | 5...95 % without condensation IEC 60068-2-3<br>5...95 % without dripping water IEC 60068-2-3   |
| ambient air temperature for operation | 14...122 °F (-10...50 °C) without derating<br>122...140 °F (50...60 °C) with derating factor   |
| ambient air temperature for storage   | -13...158 °F (-25...70 °C)   |
| operating altitude                    | <= 3280.84 ft (1000 m) without derating<br>3280.84...6561.68 ft (1000...2000 m) with current derating 1 % per 100 m                              |
| operating position                    | Vertical +/- 10 degree   |

## Size A

### Dimensions



### Mounting and Clearance



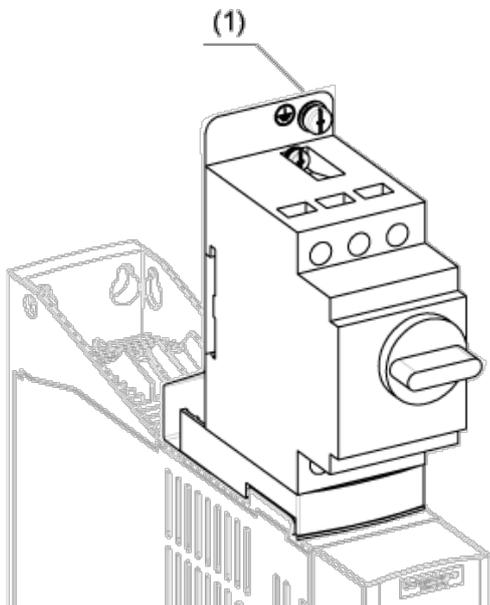
- (1) Minimum value corresponding to thermal constraints. A 150 mm clearance may help to connect the ground.
- (2) Optional GV2 circuit-breaker

### Option: Protection Device, GV2 circuit-breaker

The drive is prepared to be equipped with an optional GV2 circuit-breaker.

The GV2 circuit-breaker is directly mounted on the drive. Mechanical and electrical link are made using the optional adapter. The options are supplied with detailed mounting instruction sheet.

**NOTE:** The product overall dimension, including GV2 adapter and EMC plate mounted, becomes 424 mm (16.7 in.)

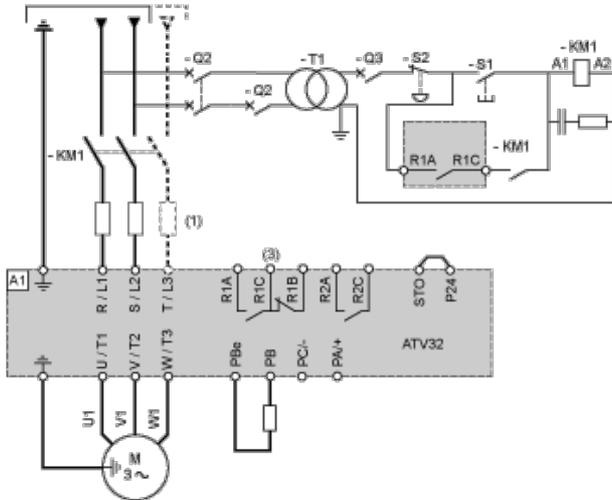


- (1) Ground screw (HS type 2 - 5x12)

## Connection Diagrams

### Single or Three-phase Power Supply - Diagram with Line Contactor

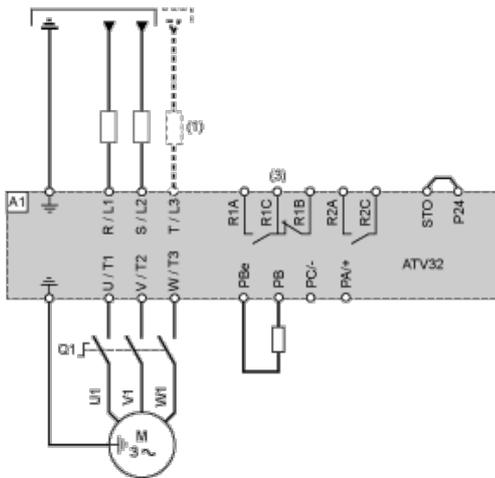
Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



- (1) Line choke (if used)
- (3) Fault relay contacts, for remote signaling of drive status

### Single or Three-phase Power Supply - Diagram with Switch Disconnect

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



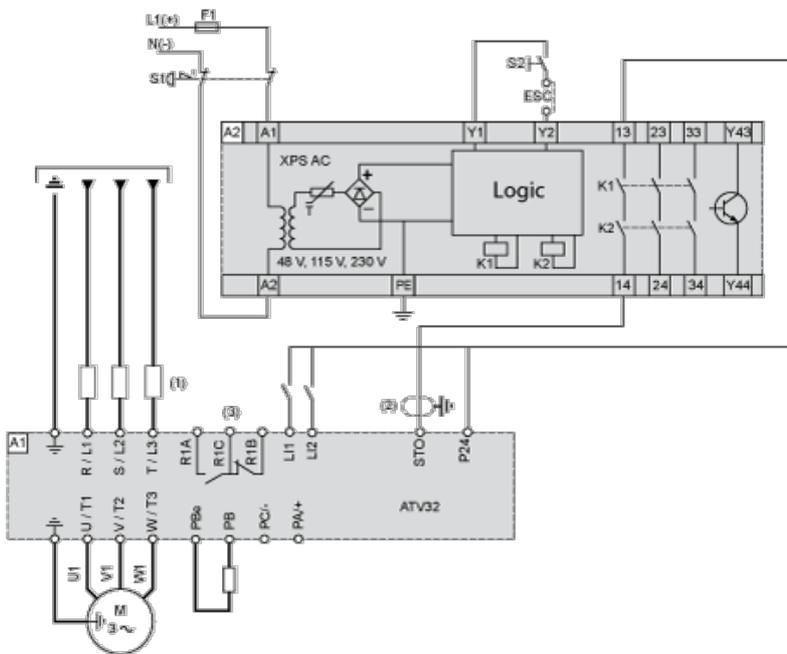
- (1) Line choke (if used)
- (3) Fault relay contacts, for remote signaling of drive status

### Diagram with Preventa Safety Module (Safe Torque Off Function)

Connection diagrams conforming to standards EN 954-1 category 3 and IEC/EN 61508 capacity SIL2, stopping category 0 in accordance with standard IEC/EN 60204-1.

When the emergency stop is activated, the drive power supply is cut immediately and the motor stops in freewheel, according to category 0 of standard IEC/EN 60204-1.

A contact on the Preventa XPS AC module must be inserted in the brake control circuit to engage it safely when the STO (Safe Torque Off) safety function is activated.



- (1) Line choke (if used)
- (2) It is essential to connect the shielding to the ground.
- (3) Fault relay contacts, for remote signaling of drive status

The STO safety function integrated into the product can be used to implement an "EMERGENCY STOP" (IEC 60204-1) for category 0 stops.

With an additional, approved EMERGENCY STOP module, it is also possible to implement category 1 stops.

#### STO function

The STO safety function is triggered via 2 redundant inputs. The circuits of the two inputs must be separate so that there are always two channels. The switching process must be simultaneous for both inputs (offset < 1 s).

The power stage is disabled and an error message is generated. The motor can no longer generate torque and coasts down without braking. A restart is possible after resetting the error message with a "Fault Reset".

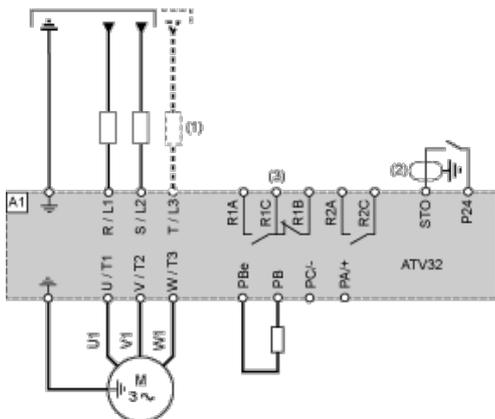
The power stage is disabled and an error message is generated if only one of the two inputs is switched off or if the time offset is too great. This error message can only be reset by switching off the product.

#### Diagram without Preventa Safety Module

Connection diagrams conforming to standards EN 954-1 category 2 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.

The connection diagram below is suitable for use with machines with a short freewheel stop time (machines with low inertia or high resistive torque).

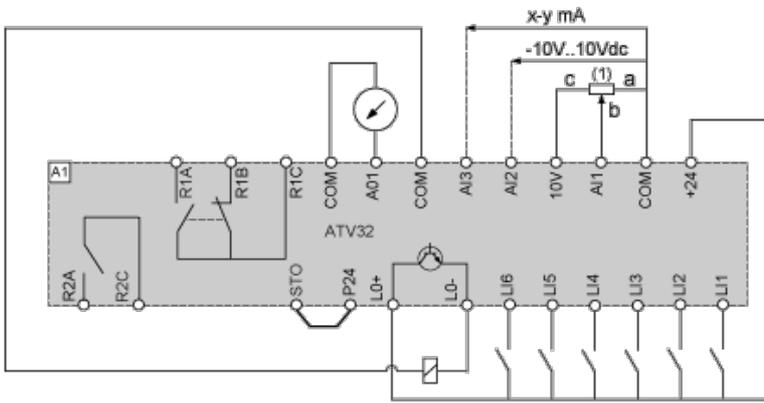
When the emergency stop is activated, the drive power supply is cut immediately and the motor stops in freewheel, according to category 0 of standard IEC/EN 60204-1.



- (1) Line choke (if used)
- (2) It is essential to connect the shielding to the ground.
- (3) Fault relay contacts, for remote signaling of drive status

The STO safety function integrated into the product can be used to implement an "EMERGENCY STOP" (IEC 60204-1) for category 0 stops.

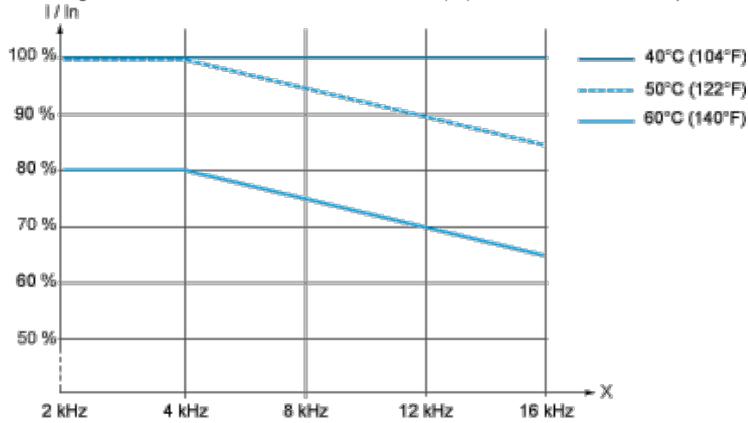
#### Control Connection Diagram in Source Mode



(1) Reference potentiometer SZ1RV1202 (2.2 kΩ) or similar (10 kΩ maximum)

## Derating Curves

Derating curve for the nominal drive current ( $I_n$ ) as a function of temperature and switching frequency.



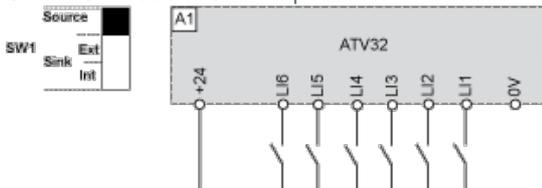
X Switching frequency

Above 4 kHz, the drive will reduce the switching frequency automatically in the event of an excessive temperature rise.

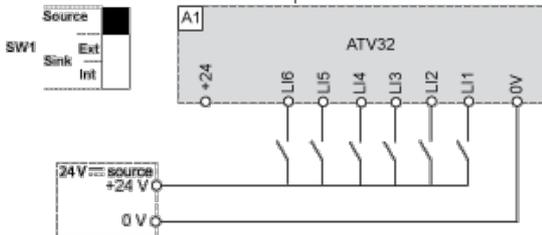
## Sink / Source Switch Configuration (SW1)

The logic input switch (SW1) is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

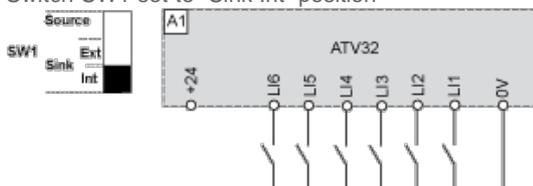
Switch SW1 set to "Source" position



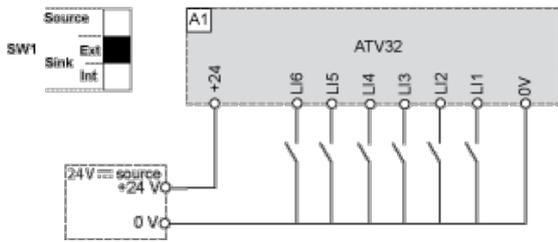
Switch SW1 set to "Source" position and use of an external power supply for the LIs



Switch SW1 set to "Sink Int" position



Switch SW1 set to "Sink Ext" position



## Данный компонент на территории Российской Федерации

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### Офис по работе с юридическими лицами:

105318, г.Москва, ул.Щербаковская д.3, офис 1107, 1118, ДЦ «Щербаковский»

Телефон: +7 495 668-12-70 (многоканальный)

Факс: +7 495 668-12-70 (доб.304)

E-mail: [info@moschip.ru](mailto:info@moschip.ru)

Skype отдела продаж:

moschip.ru

moschip.ru\_4

moschip.ru\_6

moschip.ru\_9