# Adjustable Constant Current Regulator & LED Driver

## 50 V, 150 - 350 mA ± 10%, 4.2 W Package

The adjustable constant current regulator (CCR) is a simple, economical and robust device designed to provide a cost effective solution for regulating current in LEDs. The CCR is based on Self-Biased Transistor (SBT) technology and regulates current over a wide voltage range. It is designed with a negative temperature coefficient to protect LEDs from thermal runaway at extreme voltages and currents.

The CCR turns on immediately and is at 14% of regulation with only 0.5 V Vak. The  $R_{adj}$  pin allows  $I_{reg(SS)}$  to be adjusted to higher currents by attaching a resistor between  $R_{adj}$  (Pin 3) and the Cathode (Pin 4). The  $R_{adj}$  pin can also be left open (No Connect) if no adjustment is required. It requires no external components allowing it to be designed as a high or low–side regulator. The high anode-cathode voltage rating withstands surges common in Automotive, Industrial and Commercial Signage applications. This device is available in a thermally robust package and is qualified to stringent AEC–Q101 standard, which is lead-free RoHS compliant and uses halogen-free molding compound.

#### Features

- Robust Power Package: 4.2 Watts
- Adjustable up to 350 mA
- Wide Operating Voltage Range
- Immediate Turn-On
- Voltage Surge Suppressing Protecting LEDs
- UL94-V0 Certified
- SBT (Self-Biased Transistor) Technology
- Negative Temperature Coefficient
- Eliminates Additional Regulation
- NSV Prefix for Automotive and Other Applications Requiring Unique Site and Control Change Requirements; AEC–Q101 Qualified and PPAP Capable
- These Devices are Pb–Free, Halogen Free/BFR Free and are RoHS Compliant

#### Applications

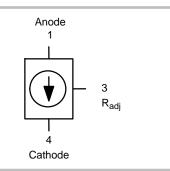
- Automobile: Chevron Side Mirror Markers, Cluster, Display & Instrument Backlighting, CHMSL, Map Light
- AC Lighting Panels, Display Signage, Decorative Lighting, Channel Lettering
- Application Notes AND8391/D, AND9008/D Power Dissipation Considerations
- Application Note AND8349/D Automotive CHMSL



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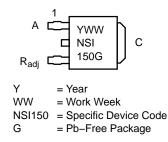
I<sub>reg(SS)</sub> = 150 – 350 mA @ Vak = 7.5 V





CASE 369C

#### MARKING DIAGRAM



#### ORDERING INFORMATION

Device	Package	Shipping <sup>†</sup>
NSI50150ADT4G	DPAK (Pb–Free)	2500/Tape & Reel
NSV50150ADT4G	DPAK (Pb–Free)	2500/Tape & Reel

+For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

#### MAXIMUM RATINGS (T<sub>A</sub> = 25°C unless otherwise noted)

Rat	ing	Symbol	Value	Unit
Anode-Cathode Voltage		Vak Max	50	V
Reverse Voltage		V <sub>R</sub>	500	mV
Operating and Storage Junction	Femperature Range	T <sub>J</sub> , T <sub>stg</sub>	-55 to +175	°C
ESD Rating:	Human Body Model Machine Model		Class 3B (8000 V) Class C (400 V)	

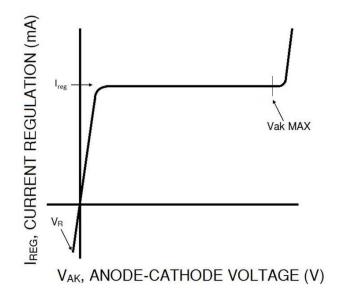
Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

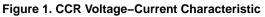
#### ELECTRICAL CHARACTERISTICS (T<sub>A</sub> = 25°C unless otherwise noted)

Characteristic	Symbol	Min	Тур	Мах	Unit
Steady State Current @ Vak = 7.5 V (Note 1)	I <sub>reg(SS)</sub>	135	150	165	mA
Voltage Overhead (Note 2)	Voverhead		1.8		V
Pulse Current @ Vak = 7.5 V (Note 3)	I <sub>reg(P)</sub>	140.5	158	175.35	mA

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

1.  $I_{reg(SS)}$  steady state is the voltage (Vak) applied for a time duration  $\ge$  170 sec, using FR-4 @ 1000 mm<sup>2</sup> 2 oz. Copper traces, in still air. 2.  $V_{overhead} = V_{in} - V_{LEDs}$ .  $V_{overhead}$  is typical value for 48%  $I_{reg(SS)}$ . 3.  $I_{reg(P)}$  non-repetitive pulse test. Pulse width t  $\le$  1 msec.





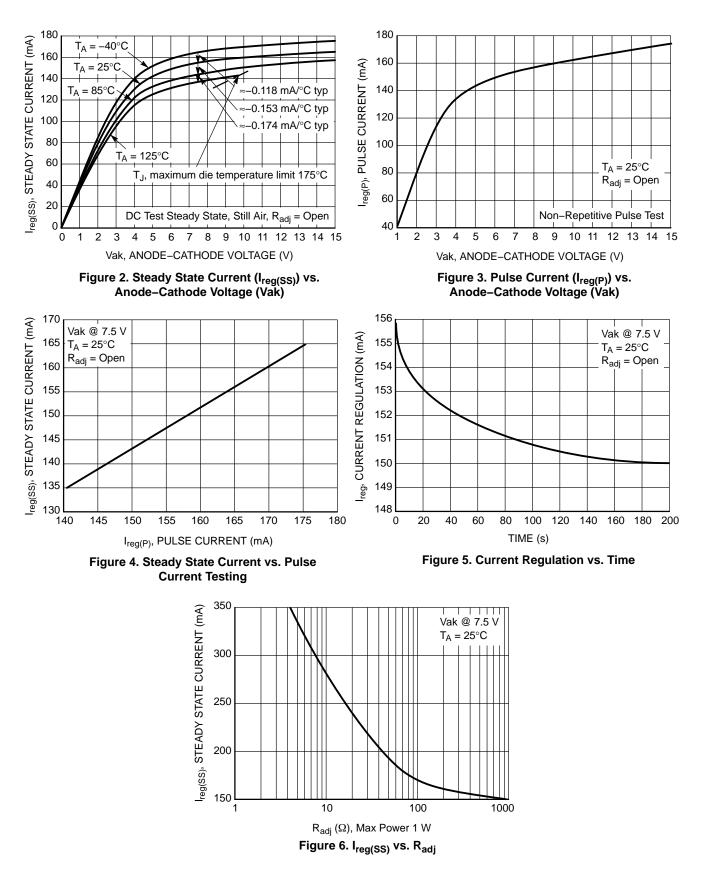
#### THERMAL CHARACTERISTICS

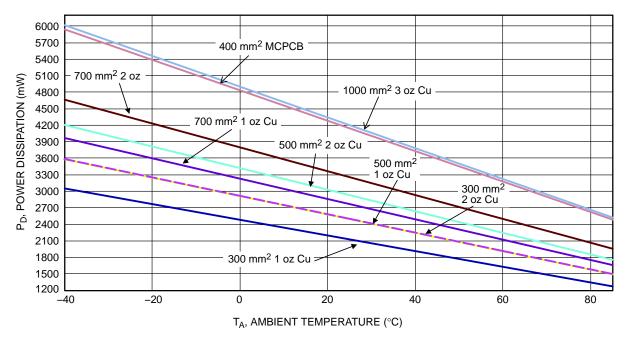
Characteristic	Symbol	Мах	Unit
Total Device Dissipation (Note 4) $T_A = 25^{\circ}C$ Derate above $25^{\circ}C$	P <sub>D</sub>	2125 14.16	mW mW/°C
Thermal Resistance, Junction-to-Ambient (Note 4)	R <sub>0JA</sub>	70.6	°C/W
Thermal Resistance, Junction-to-Tab (Note 4)	R <sub>ψJ-TAB</sub>	6.8	°C/W
Total Device Dissipation (Note 5) $T_A = 25^{\circ}C$ Derate above 25°C	PD	2500 16.67	mW mW/°C
Thermal Resistance, Junction-to-Ambient (Note 5)	R <sub>0JA</sub>	60	°C/W
Thermal Resistance, Junction-to-Tab (Note 5)	$R_{\psi J-TAB}$	6.3	°C/W
Total Device Dissipation (Note 6) $T_A = 25^{\circ}C$ Derate above $25^{\circ}C$	PD	2496 16.64	mW mW/°C
Thermal Resistance, Junction-to-Ambient (Note 6)	$R_{ heta JA}$	60.1	°C/W
Thermal Resistance, Junction-to-Tab (Note 6)	R <sub>yJ-TAB</sub>	6.5	°C/W
Total Device Dissipation (Note 7) $T_A = 25^{\circ}C$ Derate above 25°C	P <sub>D</sub>	2930 19.53	mW mW/°C
Thermal Resistance, Junction-to-Ambient (Note 7)	$R_{ hetaJA}$	51.2	°C/W
Thermal Resistance, Junction-to-Tab (Note 7)	R <sub>ψJ-TAB</sub>	5.9	°C/W
Total Device Dissipation (Note 8) $T_A = 25^{\circ}C$ Derate above $25^{\circ}C$	PD	2771 18.47	mW mW/°C
Thermal Resistance, Junction-to-Ambient (Note 8)	$R_{ hetaJA}$	54.1	°C/W
Thermal Resistance, Junction-to-Tab (Note 8)	R <sub>yJ-TAB</sub>	6.2	°C/W
Total Device Dissipation (Note 9) $T_A = 25^{\circ}C$ Derate above $25^{\circ}C$	PD	3256 21.71	mW mW/°C
Thermal Resistance, Junction-to-Ambient (Note 9)	$R_{ heta JA}$	46.1	°C/W
Thermal Resistance, Junction-to-Tab (Note 9)	R <sub>yJ-TAB</sub>	5.7	°C/W
Total Device Dissipation (Note 10) $T_A = 25^{\circ}C$ Derate above 25°C	P <sub>D</sub>	4202 28.01	mW mW/°C
Thermal Resistance, Junction-to-Ambient (Note 10)	$R_{ extsf{ heta}JA}$	35.7	°C/W
Thermal Resistance, Junction-to-Tab (Note 10)	$R_{\psiJ-TAB}$	5.4	°C/W
Total Device Dissipation (Note 11) $T_A = 25^{\circ}C$ Derate above $25^{\circ}C$	P <sub>D</sub>	4144 27.62	mW mW/°C
Thermal Resistance, Junction-to-Ambient (Note 11)	$R_{ heta JA}$	36.2	°C/W
Thermal Resistance, Junction-to-Tab (Note 11)	$R_{\psiJ-TAB}$	1.0	°C/W
Junction and Storage Temperature Range	T <sub>J</sub> , T <sub>stg</sub>	-55 to +150	°C

4. FR-4 @ 300 mm<sup>2</sup>, 1 oz. copper traces, still air.
5. FR-4 @ 300 mm<sup>2</sup>, 2 oz. copper traces, still air.
6. FR-4 @ 500 mm<sup>2</sup>, 1 oz. copper traces, still air.
7. FR-4 @ 500 mm<sup>2</sup>, 2 oz. copper traces, still air.
8. FR-4 @ 700 mm<sup>2</sup>, 1 oz. copper traces, still air.
9. FR-4 @ 700 mm<sup>2</sup>, 2 oz. copper traces, still air.
10. FR-4 @ 1000 mm<sup>2</sup>, 3 oz. copper traces, still air.
11. 400 mm<sup>2</sup>, DENKA K1, 1.5 mm AL, 2 kV thermally conductive dielectric, 2 oz. Cu, or equivalent.

#### **TYPICAL PERFORMANCE CURVES**

(Minimum FR-4 @ 1000 mm<sup>2</sup>, 3 oz. Copper Trace, Still Air)







#### **APPLICATIONS INFORMATION**

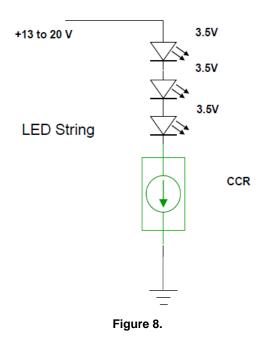
The CCR is a self biased transistor designed to regulate the current through itself and any devices in series with it. The device has a slight negative temperature coefficient, as shown in Figure 2 – Tri Temp. (i.e. if the temperature increases the current will decrease). This negative temperature coefficient will protect the LEDS by reducing the current as temperature rises.

The CCR turns on immediately and is typically at 20% of regulation with only 0.5 V across it.

The device is capable of handling voltage for short durations of up to 50 V so long as the die temperature does not exceed 175°C. The determination will depend on the thermal pad it is mounted on, the ambient temperature, the pulse duration, pulse shape and repetition.

#### Single LED String

The CCR can be placed in series with LEDs as a High Side or a Low Side Driver. The number of the LEDs can vary from one to an unlimited number. The designer needs to calculate the maximum voltage across the CCR by taking the maximum input voltage less the voltage across the LED string (Figures 8 and 9).



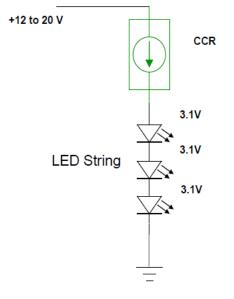


Figure 9.

#### **Higher Current LED Strings**

Two or more fixed current CCRs can be connected in parallel. The current through them is additive (Figure 10).

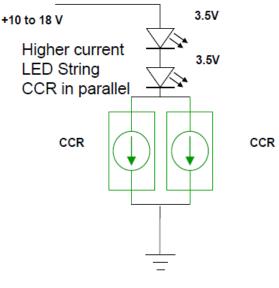
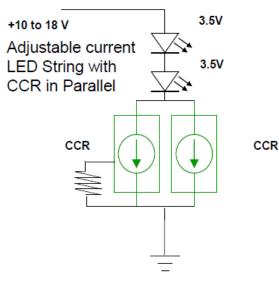


Figure 10.

#### **Other Currents**

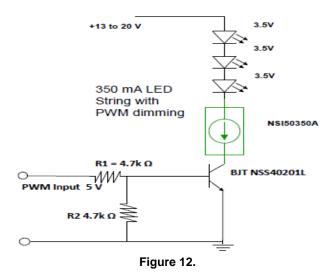
The adjustable CCR can be placed in parallel with any other CCR to obtain a desired current. The adjustable CCR provides the ability to adjust the current as LED efficiency increases to obtain the same light output (Figure 11).



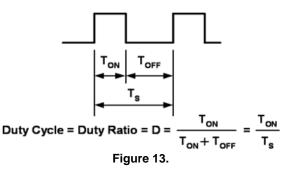


#### **Dimming using PWM**

The dimming of an LED string can be easily achieved by placing a BJT in series with the CCR (Figure 12).

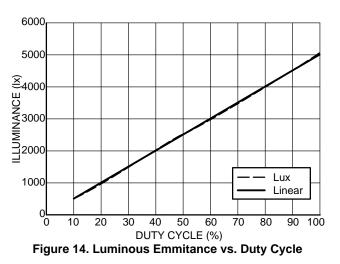


The method of pulsing the current through the LEDs is known as Pulse Width Modulation (PWM) and has become the preferred method of changing the light level. LEDs being a silicon device, turn on and off rapidly in response to the current through them being turned on and off. The switching time is in the order of 100 nanoseconds, this equates to a maximum frequency of 10 Mhz, and applications will typically operate from a 100 Hz to 100 kHz. Below 100 Hz the human eye will detect a flicker from the light emitted from the LEDs. Between 500 Hz and 20 kHz the circuit may generate audible sound. Dimming is achieved by turning the LEDs on and off for a portion of a single cycle. This on/off cycle is called the Duty cycle (D) and is expressed by the amount of time the LEDs are on (Ton) divided by the total time of an on/off cycle (Ts) (Figure 13).



The current through the LEDs is constant during the period they are turned on resulting in the light being consistent with no shift in chromaticity (color). The brightness is in proportion to the percentage of time that the LEDs are turned on.

Figure 14 is a typical response of Luminance vs Duty Cycle.



#### **Reducing EMI**

Designers creating circuits switching medium to high currents need to be concerned about Electromagnetic Interference (EMI). The LEDs and the CCR switch extremely fast, less than 100 nanoseconds. To help eliminate EMI, a capacitor can be added to the circuit across R2. (Figure 12) This will cause the slope on the rising and falling edge on the current through the circuit to be extended. The slope of the CCR on/off current can be controlled by the values of R1 and C1.

The selected delay / slope will impact the frequency that is selected to operate the dimming circuit. The longer the delay, the lower the frequency will be. The delay time should not be less than a 10:1 ratio of the minimum on time. The frequency is also impacted by the resolution and dimming

steps that are required. With a delay of 1.5 microseconds on the rise and the fall edges, the minimum on time would be 30 microseconds. If the design called for a resolution of 100 dimming steps, then a total duty cycle time (Ts) of 3 milliseconds or a frequency of 333 Hz will be required.

#### **Thermal Considerations**

As power in the CCR increases, it might become necessary to provide some thermal relief. The maximum power dissipation supported by the device is dependent upon board design and layout. Mounting pad configuration on the PCB, the board material, and the ambient temperature affect the rate of junction temperature rise for the part. When the device has good thermal conductivity through the PCB, the junction temperature will be relatively low with high power applications. The maximum dissipation the device can handle is given by:

$$\mathsf{P}_{\mathsf{D}(\mathsf{MAX})} = \frac{\mathsf{T}_{\mathsf{J}(\mathsf{MAX})} - \mathsf{T}_{\mathsf{A}}}{\mathsf{R}_{\mathsf{\theta},\mathsf{JA}}}$$

Referring to the thermal table on page 2 the appropriate  $R_{\theta JA}$  for the circuit board can be selected.

#### **AC Applications**

The CCR is a DC device; however, it can be used with full wave rectified AC as shown in application notes AND8433/D and AND8492/D and design notes DN05013/D and DN06065/D. Figure 15 shows the basic circuit configuration.

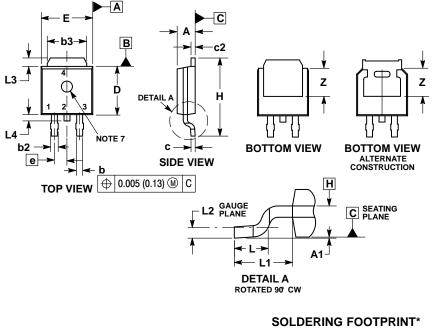


Figure 15. Basic AC Application

#### PACKAGE DIMENSIONS

DPAK (SINGLE GAUGE) CASE 369C

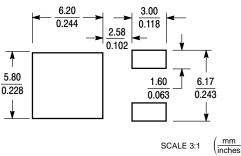
ISSUE E



NOTES:

- 1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
- 2. CONTROLLING DIMENSION: INCHES. 3. THERMAL PAD CONTOUR OPTIONAL WITHIN DI-
- THERMAL PAD CONTOUR OPTIONAL WITHIN DI-MENSIONS b3, L3 and Z.
   DIMENSIONS D AND E DO NOT INCLUDE MOLD
- DIMENSIONS D AND E DO NOT INCLUDE MOLD FLASH, PROTRUSIONS, OR BURRS. MOLD FLASH, PROTRUSIONS, OR GATE BURRS SHALL
- NOT EXCEED 0.006 INCHES PER SIDE. 5. DIMENSIONS D AND E ARE DETERMINED AT THE OUTERMOST EXTREMES OF THE PLASTIC BODY.
- 6. DATUMS A AND B ARE DETERMINED AT DATUM PLANE H.
- 7. OPTIONAL MOLD FEATURE.

	INC	HES	MILLIMETERS				
DIM	MIN	MAX	MIN	MAX			
Α	0.086	0.094	2.18	2.38			
A1	0.000	0.005	0.00	0.13			
b	0.025	0.035	0.63	0.89			
b2	0.028	0.045	0.72	1.14			
b3	0.180	0.215	4.57	5.46			
С	0.018	0.024	0.46	0.61			
c2	0.018	0.024	0.46	0.61			
D	0.235	0.245	5.97	6.22			
Е	0.250	0.265	6.35	6.73			
е	0.090 BSC		2.29 BSC				
н	0.370	0.410	9.40	10.41			
L	0.055	0.070	1.40	1.78			
L1	0.114 REF		2.90 REF				
L2	0.020 BSC		0.51 BSC				
L3	0.035	0.050	0.89	1.27			
L4		0.040		1.01			
Z	0.155		3.93				



\*For additional information on our Pb–Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

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