CNN Accelerator IP Core

User Guide

Contents

Figures

Tables

1. Introduction

The Lattice Semiconductor CNN Accelerator IP Core is a calculation engine for Deep Neural Network with fixed point weight or binarized weight. It calculates full layers of Neural Network including convolution layer, pooling layer, batch normalization layer, and full connect layer by executing sequence code with weight value which is generated by Lattice Neural Network Compiler. The engine is optimized for convolutional neural network, so it can be used for vision-based application such as classification or object detection and tracking. The IP Core does not require an extra processor; it can perform all required calculations by itself.

The design is implemented in Verilog HDL. It can be targeted to ECP5 and ECP5-5G FPGA devices, and implemented using the Lattice Diamond® Software Place and Route tool integrated with the Synplify Pro® synthesis tool.

1.1. Quick Facts

Table 1.1 presents a summary of the CNN Accelerator IP Core.

Table 1.1. Quick Facts

IP Requirements	FPGA Families Supported	ECP5, ECP5-5G
Resource Utilization	Targeted Device	Full configuration: 85k devices in ECP5 families Reduced configuration: All devices in ECP5 families
	Supported User Interface	AXI3, Native interfaces as described in Interface Descriptions section.
	Resources	See Table A.1.
Design Tool Support	Lattice Implementation	Lattice Diamond Design Suite 3.10
	Synthesis	Lattice Synthesis Engine
		Synopsys® Synplify Pro, M-2017.03LR-SP1-1
	Simulation	For a list of supported simulators, see the Lattice Diamond User Guide.

1.2. Features

The key features of the CNN Accelerator IP Core include:
- Support for convolution layer, max pooling layer, batch normalization layer, and full connect layer
- Configurable bit width of weight (16-bit, 1-bit)
- Configurable bit width of activation (16/8-bit, 1-bit)
- Dynamic support for 16-bit and 8-bit width of activation
- Configurable number of memory blocks for tradeoff between resource and performance
- Configurable number of convolution engines for tradeoff between resource and performance
- Optimization for 3 x 3 2D convolution calculation
- Dynamic support for various 1D convolution from 1 to 72 taps
- Support for max pooling with overlap (For example, kernel 3, stride 2)

2. Functional Descriptions

2.1. Overview

The CNN Accelerator IP Core performs a series of calculations per command sequence that is generated by the Lattice Neural Network Compiler tool. Commands must be written at DRAM address specified by the i_code_base_addr signal which is accessible through AXI BUS. Input data may be read from DRAM at a pre-defined address or directly written through the input data write port. After command code and input data are available, CNN Accelerator IP Core starts calculation at the rising edge of start signal. During calculation, intermediate data and final result may be transferred to DRAM or fed out through the result write port. All operations are fully-programmable by command code.

Figure 2.1. Functional Block Diagram

2.2. Interface Descriptions

Figure 2.2 shows the interface diagram for the CNN Accelerator IP Core. The diagram shows all of the available ports for the IP core.
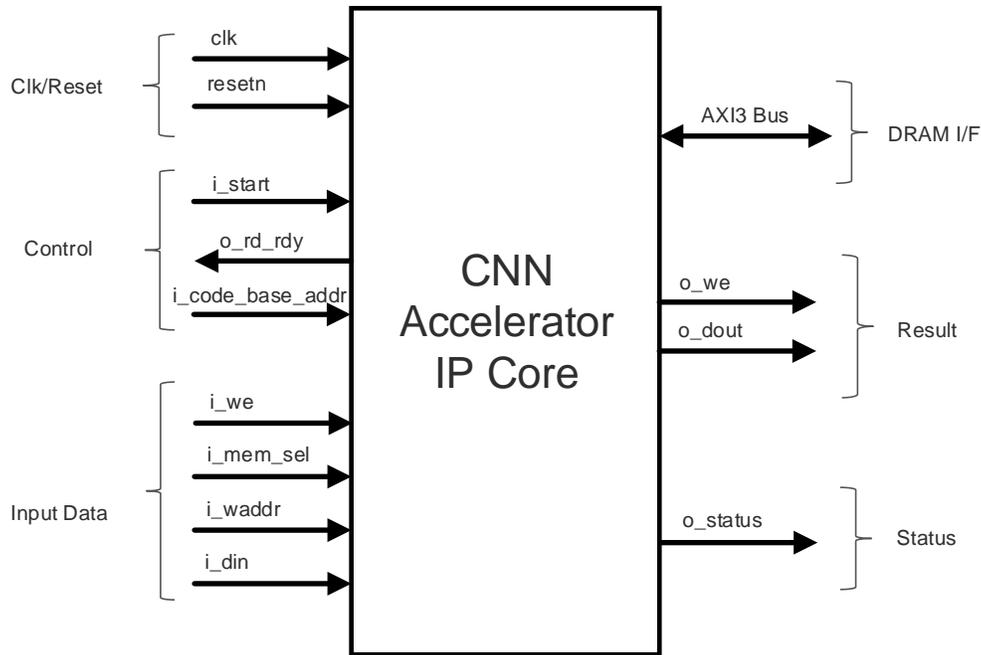

Figure 2.2. CNN Accelerator IP Core Interface Diagram

Table 2.1. CNN Accelerator IP Core Signal Descriptions

Pin Name	Direction	Function Description
Clock/Reset		
clk	Input	System clock Frequency can be chosen by trade-off between power and performance.
resetn	Input	Active low system reset that is synchronous to clk signal and is asynchronous to aclk signal. [0]: Resets all ports and sets internal registers to their default values. [1]: Reset is NOT active
Control and Status		
i_code_base_addr[31:0]	Input	This signal specifies the base/start address that is read by CNN Accelerator IP Core to get the command code. External logic should write the command code to this address. This signal must be set before start of operation.
i_start	Input	Start execution signal. Level sensitive. Must deassert after o_rd_rdy going 0.
o_rd_rdy	Output	Ready signal. [0]: Engine is busy/running. [1]: Engine is idle and ready to get input. External logic should write input data to internal memory only during o_rd_rdy is high.
o_status	Output	Debug information [0]: If bit value is 1, engines are running except full connect engine. [1]: If bit value is 1, full connect engine is running. [2]: If bit value is 1, AXI bus transfer is ongoing. [3]: If bit value is 1, during engine is running. [4]: If bit value is 1, command FIFO is reading. [5]: If bit value is 1, during DRAM access. [6]: If bit value is 1, DRAM command is issued.

Pin Name	Direction	Function Description
		[7]: If bit value is 1, engine is waiting for FIFO fill.
Input Data		
i_mem_sel[3:0]	Input	Memory select signal for routing the write access to one of the 16 internal memories from Memory Pool. [0]: MEM0 is selected for write [1]: MEM1 is selected for write … [15]: MEM15 is selected for write
i_we	Input	Write enable signal for internal memory [0]: No write transaction [1]: Write transaction is enabled, i_din and i_waddr are valid
i_waddr[12:0]	Input	Write address signal for internal memory
i_din[15:0]	Input	Input data signal for internal memory
Result		
o_we	Output	Write enable of result, indicates result data is valid [0]: Result data is NOT valid [1]: Result data is valid
o_dout[15:0]	Output	Result data
DRAM I/F (AXI3 Bus)		
aclk	Input	AXI3 clock signal. Fully asynchronous from clk. Recommend to use DRAM system clock.
A2M_AWID[7:0]	Output	AXI3 write address channel, write address ID signal *Constant output: 0x10*
A2M_AWADDR[31:0]	Output	AXI3 write address channel, write address signal
A2M_AWLEN[7:0]	Output	AXI3 write address channel, burst length signal
A2M_AWSIZE[2:0]	Output	AXI3 write address channel, burst size signal *Constant output: 3'b011 (8 bytes per beat)*
A2M_AWBURST[1:0]	Output	AXI3 write address channel, burst type signal *Constant output: 3'b01 (INCR)*
A2M_AWLOCK[1:0]	Output	AXI3 write address channel, lock type signal *Constant output: 3'b00 (Normal Access)*
A2M_AWCACHE[3:0]	Output	AXI3 write address channel, memory type signal *Constant output: 0x00 (Device Non-bufferable)*
A2M_AWPROT[2:0]	Output	AXI3 write address channel, protection type signal *Constant output: 3'b000 (Secure Access)*
A2M_AWVALID	Output	AXI3 write address channel, write address valid signal
A2M_AWREADY	Input	AXI3 write address channel, write address ready signal
A2M_WID[7:0]	Output	AXI3 write data channel, write ID tag signal *Constant output: 0x10*
A2M_WDATA[63:0]	Output	AXI3 write data channel, write data signal
A2M_WSTRB[7:0]	Output	AXI3 write data channel, write strobe signal *Constant output: 0xFF*
A2M_WLAST	Output	AXI3 write data channel, write last signal
A2M_WVALID	Output	AXI3 write data channel, write valid signal
A2M_WREADY	Input	AXI3 write data channel, write ready signal
A2M_BID[7:0]	Input	AXI3 write response channel, response ID tag signal
A2M_BRESP[1:0]	Input	AXI3 write response channel, write response signal
A2M_BVALID	Input	AXI3 write response channel, write response valid signal
A2M_BREADY	Output	AXI3 write response channel, response ready signal *Constant output: 1'b1 (AXI3 write response channel is ignored)*
A2M_ARID[7:0]	Output	AXI3 read address channel, read address ID signal

Pin Name	Direction	Function Description
		0x00: AXI Master for Memory Pool
		0x10: AXI Rd Master in Control Unit
		Refer to Figure 2.1 for the AXI Masters
A2M_ARADDR[31:0]	Output	AXI3 read address channel, read address signal
A2M_ARLEN[7:0]	Output	AXI3 read address channel, burst length signal
A2M_ARSIZE[2:0]	Output	AXI3 read address channel, burst size signal
		Constant output: 3'b011 (8 bytes per beat)
A2M_ARBURST[1:0]	Output	AXI3 read address channel, burst type signal
		Constant output: 3'b01 (INCR)
A2M_ARLOCK[1:0]	Output	AXI3 read address channel, lock type signal
		Constant output: 3'b00 (Normal Access)
A2M_ARCACHE[3:0]	Output	AXI3 read address channel, memory type signal
		Constant output: 0x01 (Device Bufferable)
A2M_ARPROT[2:0]	Output	AXI3 read address channel, protection type signal
		Constant output: 3'b010 (Non-secure Access)
A2M_ARVALID	Output	AXI3 read address channel, read address valid signal
A2M_ARREADY	Input	AXI3 read address channel, read address ready signal
A2M_RID[7:0]	Input	AXI3 Read data channel, read ID tag signal
A2M_RDATA[63:0]	Input	AXI3 Read data channel, read data signal
A2M_RRESP[1:0]	Input	AXI3 Read data channel, read response signal
A2M_RLAST	Input	AXI3 Read data channel, read last signal
A2M_RVALID	Input	AXI3 Read data channel, read valid signal
A2M_RREADY	Output	AXI3 Read data channel, read ready signal

2.2.1. Control and Status Interface

After reset or when engine is idle, o_rd_rdy is high. During this state, external logic may perform the following:

1. Write input data through Input Data interface
2. Set the start address of command code to i_code_base_addr signal

After the above steps, external logic must assert i_start signal. Engine starts execution when it gets i_start = 1 and o_rd_rdy goes 0. During execution, each bit of o_status indicates activity of sub calculation engine or AXI BUS. After finishing execution, that is by getting finish command, the CNN Accelerator IP Core asserts o_rd_rdy and waits for the next execution. Repeat from asserting i_start. This is shown in Figure 2.3.
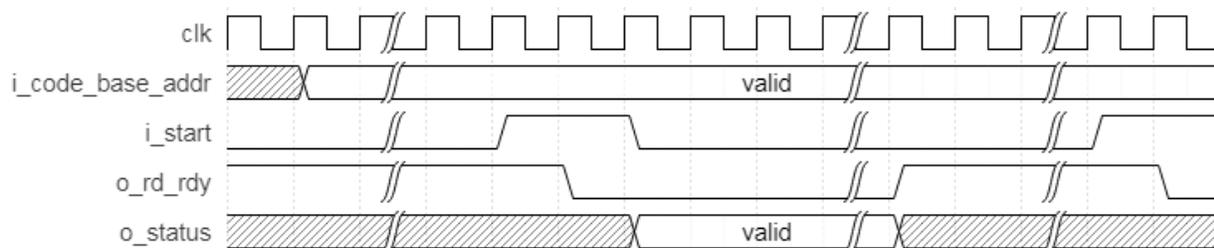

Figure 2.3. Control and Status Interface Timing Diagram

2.2.2. Input Data Interface

Input data can be written to DRAM by external logic. In this case, loading from DRAM for input data must be in command codes. Also, if input data is small enough to hold internal memory, writing to DRAM and reading back to CNN Accelerator IP Core may be waste of cycle time and energy. In that case, external logic can write input data to internal memory of CNN Accelerator IP Core during idle state (o_rd_rdy is high). Interface is based on simple SRAM interface with memory ID as shown in Figure 2.4. Memory ID and address must be matched to command code. Because it is SRAM interface, there is no required order or rule; any random access including memory ID. Overwriting of same address is also accepted.
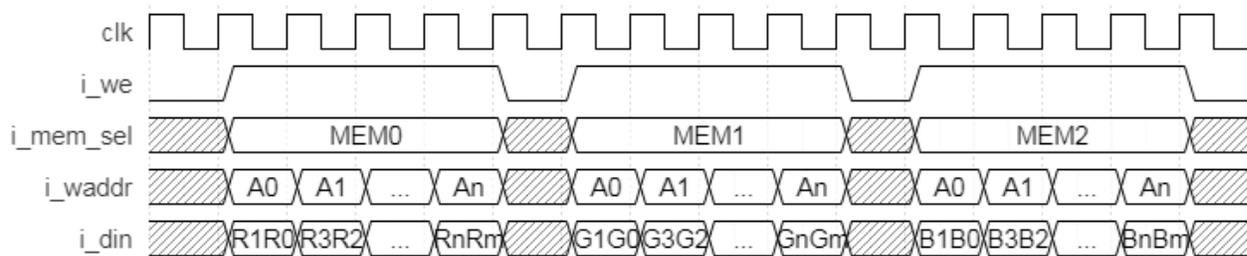

Figure 2.4. Input Data Interface Timing Diagram

2.2.3. Result Interface

Result, that is, final Blob data of neural network can be written to DRAM per command code. In this case, external logic should read result data from DRAM. However, command code can also simply feed result data to external logic through this interface. Interface consists o_we as valid indicator and o_dout as 16-bit data as shown in Figure 2.5. Usually, it is a single burst series of 16-bit data. Also, it is fully programmable by command code.

Figure 2.5. Result Interface Timing Diagram

2.2.4. DRAM Interface

Command code must be written in DRAM before execution of CNN Accelerator IP Core. Input data may be written in DRAM too. During execution of CNN Accelerator IP Core, it reads command code from DRAM and does calculation with internal sub execution engine per command code. Intermediate data may be transferred from/to DRAM per command code.

Please refer to AXI3 Protocol Specification for the timing diagram of DRAM Interface.

2.3. Clock Domain

The clk and aclk domains are shown Figure 2.6. The difference in clock is absorbed by Lattice Dual Clocked FIFO IP (FIFO_DC) and is implemented in AXI Rd Master and AXI Master sub-blocks.

Figure 2.6. Reset Timing Diagram

2.4. Reset Behavior

When resetn signal asserts, output ports return to logic 0 in the next cycle. When resetn deasserts, output ready signals assert in the next cycle. A timing diagram of reset during AXI3 access is shown as an example in Figure 2.7. Not all AXI3 output signals are shown in this figure. The clk and aclk signals are 50% out-of-phase to show asynchronous relationship. The minimum resetn assert period is 1 cycle of the slower clock between clk and aclk.

Figure 2.7. Reset Timing Diagram

Some AXI3 output signals are constant outputs; these are not affected by reset. Please refer to Table 2.1 for the AXI3 output signals that are constant.

2.5. Register Description

CNN Accelerator IP Core has no user-configurable register.

2.6. Operation Sequence

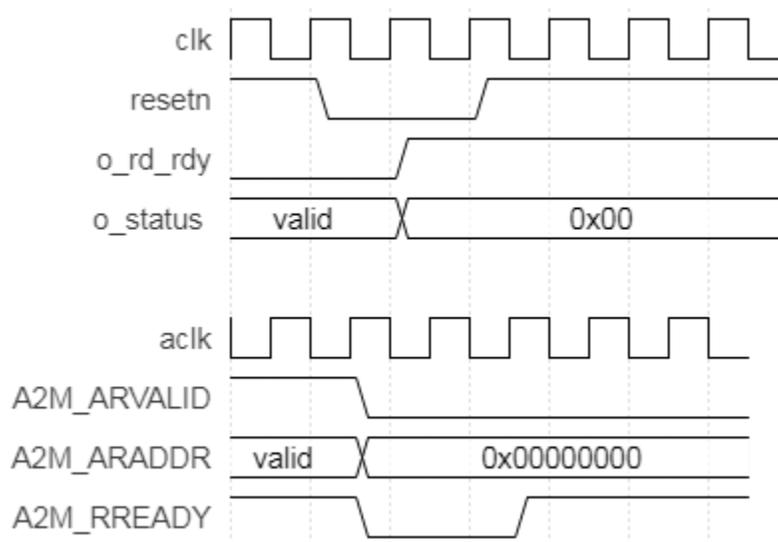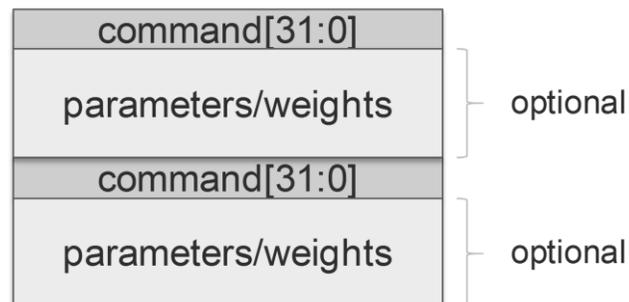Operation sequence must be executed in the following steps:

1. Assert Reset.

2. Deassert Reset, i_start must be deasserted.

3. Write command sequence code which is generated by the Lattice Neural Network tool into DRAM starting at the address specified by i_code_base_addr signal.

4. Check whether o_rd_rdy is high or not. o_rd_rdy must be high. Otherwise, go back to step 1.

5. Write input data into DRAM at the proper address, which is decided by command sequence, or directly write into the internal memory block of the CNN Accelerator IP Core through input data ports.

6. Assert i_start and check o_rd_rdy. o_rd_rdy signal should be 0 after asserting i_start.

7. Deassert i_start.

8. Check o_we if code has direct output commands. Collect o_dout while o_we == 1.

9. Check o_rd_rdy and read result from DRAM if command code has storing result to DRAM code after o_rd_rdy going high.

10. Repeat from step 5.

2.6.1. Command Format

Command is a sequence of 32-bit data with or without additional parameters or weights as shown in Figure 2.8. It should be loaded at DRAM address specified by i_code_base_addr signal before execution. Command is generated by the Lattice Neural Network Compiler tool. For more information, refer to Lattice Neural Network Compiler Software User Guide (FPGA-UG-02052).

Figure 2.8. Command format

2.6.2. Input Data Format

Input data is a sequence of 8-bit or 16-bit data. Memory index and address are decided by Neural Network. Therefore, the external block should process input raw data and write input data to Lattice CNN Accelerator IP Core through input data write interface. Since CNN Accelerator IP Core has only 16-bit width interface, external block should pack two of 8-bit data if 8-bit width is used for input data layer.

For example, face detection neural network may take 32 x 32 of R, G, B planes at memory index 0 with address 0x0000 for Red plane, 0x0400 for Green plane and 0x0800 for Blue plane. Another example is object detection neural network may take 90 x 90 of R, G, B planes which are assigned to memory index 0, 1 and 2, respectively. Because memory assignment is defined by neural network, external block should handle input raw data, and write it to proper position of internal memory of CNN Accelerator IP Core.

Writing input data to DRAM and using Load command to fetch input data are also possible in the case of large input data. The IP core expects data in little-endian order.

2.6.3. Output Data Format

Output data is a sequence of 16-bit data which is controlled by commands. Amount of data is also decided by Neural Network, that is, by output blobs. External block should interpret output sequence and generate usable information. For example, face detection outputs 2-beat burst (two consecutive) of 16-bit data, the first is confidence of non-face while the second one is confidence of face. Whenever the latter is larger than the former, conclusion is Face. The IP core outputs data in little-endian order.

2.7. Supported Commands

Command sequences are generated by Lattice Neural Network Compiler Software User Guide (FPGA-UG-02052).

3. Parameter Settings

The Clarity Designer tool is used to create IP and architectural modules in the Diamond software. You may refer to the IP Generation and Evaluation section on how to generate the IP.

Table 3.1 provides the list of user configurable attributes for the CNN Accelerator IP Core. The attribute values are specified using the IP core Configuration user interface in Clarity Designer as shown in Figure 3.1.

Table 3.1. Attributes Table

Attribute	Selectable Values	Default	Dependency on Other Attributes
Machine Learning Type	CNN, BNN	CNN	—
No. of Convolution Engines	1 - 8	8	—
No. of Internal Storage of Blob	2 - 16	16	—
BNN Blob Type	+1/-1, +1/0	+1/-1	Valid only when Machine Learning Type = "BNN"

Figure 3.1. CNN Accelerator IP Core Configuration User Interface

Table 3.2. Attributes Descriptions

Attribute	Description
Machine Learning Type	This option allows you to choose between CNN engine and BNN engine. CNN engine always uses 16-bit fixed point weight, while BNN only uses 1-bit weight. Based on required performance, accuracy and available capacity, you should select Machine Learning Type.
No. of Convolution Engines	This option allows you to specify the number of convolution engines. For 1D convolution: ● 1-9 taps can be performed for each engine ● Up to 72 taps by chaining 8 engines For 2D Convolution: ● 3 x 3 convolution per cycle per engine You should trade-off between required size and performance.
No. of Internal Storage of Blob	Each storage can store up to 16 kB. You should trade-off between required size and performance. In order to fully utilize convolution engines, number of storage must be larger than number of convolution engines. Recommend set 2x of number of convolution engines.
BNN Blob Type	Selects the type of binary blob data, either +1/-1 or +1/0. This setting should be matched to the Lattice Neural Network Compiler.

4. IP Generation and Evaluation

This section provides information on how to generate the IP using the Lattice Diamond software, and how to run simulation, synthesis and hardware evaluation. For more details on the Lattice Diamond software, you may refer to the Lattice Diamond User Guide and Lattice Diamond Tutorial.

4.1. Licensing the IP

An IP core-specific device-specific license string is required to enable full, unrestricted use of the Lattice CNN Accelerator IP Core in a complete, top-level design. You may refer to the instructions on how to obtain licenses for Lattice IP cores at http://www.latticesemi.com/Products/DesignSoftwareAndIP.aspx.

You may download and generate the CNN Accelerator IP Core and fully evaluate the core through functional simulation and implementation (synthesis, map, place and route) without an IP license string. The CNN Accelerator IP Core supports Lattice's IP hardware evaluation capability, which makes it possible to create versions of the IP core which operate in hardware for a limited time (approximately four hours) without requiring an IP license string. See Hardware Evaluation section for further details. However, a license string is required to enable timing simulation to open the design in the Diamond software, and to generate bitstream file that does not include the hardware evaluation timeout limitation.

Note: All IP has a license whether in eval mode or full mode. Difference is license string.

4.2. Generation and Synthesis

4.2.1. Getting Started

The CNN Accelerator IP Core is available for download in the Lattice IP Server using the Diamond Clarity Designer tool. The IP files can be automatically installed using InstallShield® technology in any customer-specified directory. After the IP core is installed, the IP core is listed in the Catalog tab of the Clarity Designer user interface, under DSP category as shown in Figure 4.1.
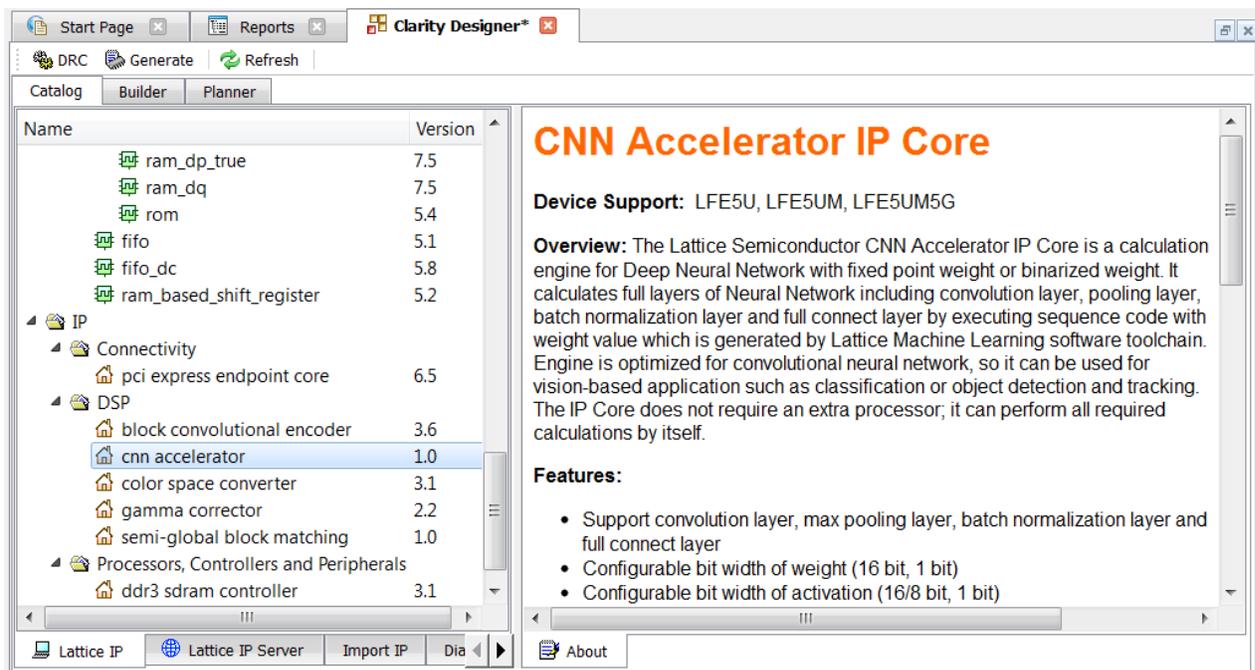

Figure 4.1. CNN Accelerator IP Core in Clarity Designer Catalog Tab

4.2.2. Configuring the IP Core in Clarity

The CNN Accelerator IP Core should be configured and generated before it can be used in the Diamond project. This is done via the CNN Accelerator IP Core configuration user interface (see Figure 3.1); it provides options for setting the desired parameters and invoking the IP core generator.

To configure the CNN Accelerator IP Core:

1. Double-click the CNN Accelerator IP Core in the Catalog tab of the Diamond Clarity tool.
2. Specify the following in the dialog box:
   - Instance Path
   - Instance Name
   Note: All generated files are placed under the directory <Instance Path>/<Instance Name>.
3. Enter configuration parameters.
4. Click **Customize.** This closes the dialog box and launches the CNN Accelerator IP Core configuration user interface.
5. Enter the desired parameters in the CNN Accelerator IP Core configuration user interface. Ensure that same parameters are used in the Lattice Neural Network Compiler to be able to generate compatible command sequence code.
6. Click the **Generate** button, and close the user interface to generate the IP core and supporting files.

Table 4.1 provides a list of key files and directories created by the IPexpress tool and how they are used.

Table 4.1. File List

Attribute	Description
<Instance Name>.lpc	This file contains the tool options used to recreate or modify the core in the Clarity tool.
<Instance Name>.ngo	This file provides the synthesized IP core.
<Instance Name>_bb.v	This file provides the synthesis black box for the user's synthesis.
<Instance Name>_inst.v	This file provides an instance template for the IP core.
<Instance Name>_top.v	This file provides an example RTL top file that instantiates the IP core.
beh_rtl.v[*]	This file provides cycle-accurate simulation model for the IP core. The top level module name in this file is <Instance Name>.
generate_core.tcl	This file is created when the user interface **Generate** button is pushed. This file may be run from command line.
<Instance Name>_generate.log	This is the synthesis and map log file.
<Instance Name>_gen.log	This is the IP Core generation log file.

*Note: This file is located in the following path:
<Instance Path>/<Instance Name>/ml_engine_ecp5_eval/<Instance Name>/src/beh_rtl/<device>

4.2.3. Instantiating the IP Core

The generated CNN Accelerator IP Core package includes black-box (<Instance Name>_bb.v) and instance (<Instance Name>_inst.v) templates that can be used to instantiate the core in a top-level design. A sample of RTL top-level reference source file (<Instance Name>_top.v) that can be used as an instantiation template for the IP core is also provided. You may also use this top-level reference as the starting template for the top-level for their complete design.

4.3. Running Functional Simulation

The CNN Accelerator IP Core does NOT contain a sample test bench for performing simple simulation test. However, a cycle-accurate simulation model (beh_rtl.v) is provided as shown in Table 4.1. This may be instantiated in a test bench. To successfully elaborate the simulation model:

1. Instantiate GSR and PUR in testbench top RTL file.
   The following codes may be copied and paste to testbench top RTL file:
   ```
   PUR PUR_INST(<active_low_reset_signal>);
   GSR GSR_INST(<active_low_reset_signal>);
   ```

2. Compile the simulation primitives of selected device. These are located in the following path:
   <Diamond Install Path>/cae_library/simulation/verilog/<device>

4.4. Hardware Evaluation

The CNN Accelerator IP Core supports Lattice's IP hardware evaluation capability, which makes it possible to create versions of the IP core that operate in hardware for a limited period of time (approximately four hours) without requiring the purchase of an IP license. It may also be used to evaluate the core in hardware in user-defined designs. Choose **Project > Active Strategy > Translate Design Settings**. The hardware evaluation capability may be enabled/disabled in the Strategy dialog box. It is enabled by default.

5. Ordering Part Number

The Ordering Part Numbers (OPN) for CNN Accelerator IP Core targeting ECP5 and ECP5-5G FPGA devices are the following:

- CNN-ACCEL-E5-U – Project License
- CNN-ACCEL-E5-UT – Site License

References

For more information on the FPGA device, visit: http://www.latticesemi.com/Products/FPGAandCPLD/ECP5.

For complete information on Lattice Diamond Project-Based Environment, Design Flow, Implementation Flow and Tasks, as well as on the Simulation Flow, see the Lattice Diamond User Guide.

Technical Support Assistance

Submit a technical support case through www.latticesemi.com/techsupport.

Appendix A. Resource Utilization

Table A.1 shows configuration and resource utilization for the ECP5UM using Lattice Diamond 3.10.0.111.0. The following settings are used in generating this data:

- Synthesis Tool: Synplify Pro
- Device Part No.: LFE5UM-85F-8BG756I
- BNN Blob Type: +1/0 (For Machine Learning Type: BNN)

Table A.1. Performance and Resource Utilization[1]

No. of Convolution Engines	No. of Internal Storage of Blob[2]	Register	LUTs	Slices	Block RAMs	clk Fmax[3] (MHz)
Machine Learning Type: CNN						
1	2	3607	4829	3601	25	150.218
4	8	9064	13661	9890	76	144.509
8	16	16482	25889	18456	144	121.892
Machine Learning Type: BNN						
1	2	3472	4871	3524	25	119.26
4	8	9764	15294	10808	76	117.426
8	16	17898	28600	20094	144	109.242

Notes:

1. Performance may vary when using a different software version or targeting a different device density or speed grade.
2. It is recommended to use No. of Internal Storage of Blob = 2 * No. of Convolution Engines.
3. Fmax is generated when the FPGA design only contains the CNN Accelerator IP Core. These values may be reduced when user logic is added to the FPGA design.

For more information on Lattice Diamond Software, visit the Lattice web site at www.latticesemi.com/Products/DesignSoftwareAndIP.

Revision History

Revision 1.1, September 2018

Section	Change Summary
Functional Description	Updated Overview section. Updated status signal description in Table 2.1. CNN Accelerator IP Core Signal Descriptions.
Appendix A. Resource Utilization	Updated Table A.1. Performance and Resource Utilization[1] per result of CNN Accelerator IP Core v1.1.
Revision History	Updated revision history table to new template.

Revision 1.0, May 2018

Section	Change Summary
All	Initial release

7th Floor, 111 SW 5th Avenue
Portland, OR 97204, USA
T 503.268.8000
www.latticesemi.com

Данный компонент на территории Российской Федерации

Вы можете приобрести в компании MosChip.

Для оперативного оформления запроса Вам необходимо перейти по данной ссылке:

http://moschip.ru/get-element

Вы можете разместить у нас заказ для любого Вашего проекта, будь то серийное   производство или разработка единичного прибора.

В нашем ассортименте представлены ведущие мировые производители активных и пассивных электронных компонентов.

Нашей специализацией является поставка электронной компонентной базы двойного назначения, продукции таких производителей как XILINX, Intel (ex.ALTERA), Vicor, Microchip, Texas Instruments, Analog Devices, Mini-Circuits, Amphenol, Glenair.

Сотрудничество с глобальными дистрибьюторами электронных компонентов, предоставляет возможность заказывать и получать с международных складов практически любой перечень компонентов в оптимальные для Вас сроки.

На всех этапах разработки и производства наши партнеры могут получить квалифицированную поддержку опытных инженеров.

Система менеджмента качества компании отвечает требованиям в соответствии с ГОСТ Р ИСО 9001, ГОСТ РВ 0015-002 и ЭС РД 009

Офис по работе с юридическими лицами:

105318, г.Москва, ул.Щербаковская д.3, офис 1107, 1118, ДЦ «Щербаковский»

Телефон: +7 495 668-12-70 (многоканальный)

Факс: +7 495 668-12-70 (доб.304)

E-mail: info@moschip.ru

Skype отдела продаж:
moschip.ru   moschip.ru_6
moschip.ru_4   moschip.ru_9