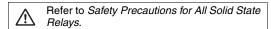
G3J-T-C

CSM\_G3J-T-C\_DS\_E\_4\_1

# New Models with AC Power Supply Input and Monitor Output Equivalent to Non-contact SPST-NO Join the G3J-T Series

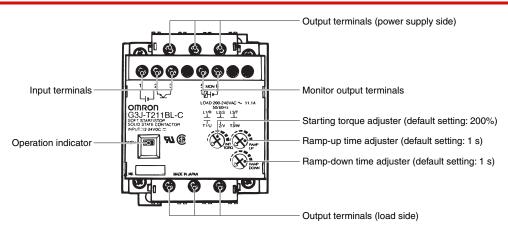
- · Limiting the starting current saves energy.
- Certified for UL and CSA.
- Mounts with screws or to DIN Track.
- Compact design with heat sinks (3.7-kW models:  $100 \times 100 \times 130$  mm (W × H × D)).
- Built-in snubber circuit and thyristor.
- Built-in operation indicator.





For the most recent information on models that have been certified for safety standards, refer to your OMRON website.

## **Appearance**



# **Ordering Information**

## **■** List of Models

Number of elements	Isolation method	Rated power supply voltage	Input method		onitor capacity C3)	Monitor output	Model
3	Phototriac		No-voltage input	, ,	200 to 220 VAC	-	G3J-T217BL-C AC100-240
	coupler		(open and short- circuited input)	2.2 kW (11.1 A)		output	G3J-T211BL-C AC100-240
				0.75 kW (4.8 A)	]		G3J-T205BL-C AC100-240
		12 to 24 VDC		3.7 kW (17.4 A)	]	DC	G3J-T217BL-C DC12-24
				2.2 kW (11.1 A)		switching output	G3J-T211BL-C DC12-24
				0.75 kW (4.8 A)		σαιραί	G3J-T205BL-C DC12-24

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# **Specifications**

## **■** Certified Standards

UL 508, CSA 22.2 No. 14

# ■ Ratings (at an Ambient Temperature of 25°C)

## **Power Supply**

Item	Operating input power supply specifications		DC Model
Rated po	ower supply voltage	100 to 240 VAC	12 to 24 VDC
Operatin	ig voltage range	85 to 264 VAC	10.2 to 26.4 VDC
Current	consumption	40 mA max. (at 100 to 240 VAC)	70 mA max. (at 12 to 24 VDC)

## **Operating (Input) Circuit**

### **AC Model**

Input method	No- voltage	Short-circuiting/opening terminals 3 and 1 or terminals 3 and 2		
	input	SSR input short-circuited: SSR input open:	Maximum impedance of 1 k $\Omega$ , Maximum residual voltage of 1 V Minimum impedance of 100 k $\Omega$	
		Relay input:	For minute signals	

### **DC Model**

Input current		10 mA max. (at 12 to 24 VDC)		
Input method	No- voltage Short-circuiting/opening terminals 3 and 1 terminals 3 and 2			
input		SSR input turned ON:	Maximum residual voltage of 2 V between short-circuited terminals	
		SSR input turned OFF	:Maximum leakage current of 0.15 mA	
		Relay input: For minute signal		

## Main Circuit (for Both AC and DC Models)

Item		Model	G3J-T217BL-C	G3J-T211BL-C	G3J-T205BL-C	
Rated load voltage			200 to 240 VAC			
Rated voltage range			180 to 264 VAC			
Rated carry current (See note 1.)			17.4 A (at 40°C)	11.1 A (at 40°C)	4.8 A (at 40°C)	
Minimum load current			0.5 A			
Inrush current resistance (peak value)			500 A (60 Hz, 1 cycle)	350 A (60 Hz, 1 cycle)	150 A (60 Hz, 1 cycle)	
Overload re	esistance		Refer to Engineering Data on page 5			
Closed current (effective value) AC3 AC4		174 A	111 A	48 A		
		AC4	208.8 A	133.2 A	57.6 A	
Breaking current (effective value) AC3 AC4		139.2 A	88.8 A	38.4 A		
		174 A	111 A	48 A		
Applicable	3-phase inductive motor (See note 2.)		200 to 220 VAC	200 to 220 VAC	200 to 220 VAC	
load	(AC3, AC4, AC53-a)		3.7 kW (17.4 A)	2.2 kW (11.1 A)	0.75 kW (4.8 A)	
	Resistive load (AC1) (See note 3.)		200 to 240 VAC	200 to 240 VAC	200 to 240 VAC	
			17.4 A	11.1 A	4.8 A	

- Note: 1. The rated carry load depends on the ambient temperature. For details, refer to the Load Current vs. Ambient Temperature graph in *Engineering Data*.
  - 2. Satisfies switching test conditions of AC3, AC4, and AC53-a. (Refer to Engineering Data on page 5 for the test conditions.)
  - 3. Single-phase loads cannot be used.

## **Monitor Output**

Item	Operating input power supply specifications		DC model
Rated po	ower supply voltage	100 to 240 VAC	12 to 24 VDC
Operating voltage range		85 to 264 VAC	10.2 to 26.4 VDC
Rated carry current		50 mA	0.2 A
Minimum load current		3 mA	3 mA

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## ■ Characteristics (for Both AC and DC Models)

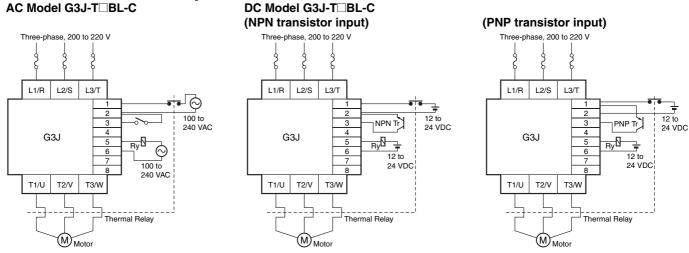
Item Model	G3J-T217BL-C	G3J-T211BL-C	G3J-T205BL-C		
Ramp-up time	Set within a range of approx. 1 to 25 s.				
Ramp-down time	Set within a range of approx. 1 to 25 s.				
Starting torque (See note 1.)	Starting torque (See note 1.) Set within a range of 200% to 450% In.				
Monitor output operate time (See note 2.)	After control signal input: AC model: 300 ms max. (TYP 50 ms), DC model: 50 ms max.				
Monitor output release time (See note 2.)	After ramp-down time completion (after main circuit current turns OFF): 60 ms max.				
Output ON voltage drop (main circuit)	1.6 V (RMS) max.				
Output ON voltage drop (monitor output)	AC model: 3.5 VAC max., DC model: 2.0 VDC max.				
Leakage current (main circuit)	kage current (main circuit) 10 mA max. (at 200 VAC)				
Leakage current (monitor output)	eakage current (monitor output)  AC model: 1.5 mA max. (at 200 VAC), DC model: 0.15 mA max. (at 24 VDC)				
nsulation resistance 100 MΩ min. (at 500 VDC)					
Dielectric strength	2,500 VAC, 60 Hz for 1 min				
Vibration resistance	10 to 55 to 10 Hz, 0.75-mm single amplitude (1.5-mm double amplitude)				
Shock resistance	294 m/s <sup>2</sup>				
Storage temperature	-30 to 70°C (with no icing or condensation)				
Ambient operating temperature	-20 to 60°C (with no icing or condensation)				
Ambient operating humidity	45 to 85 %				
Weight	Approx. 890 g         Approx. 760 g         Approx. 760 g				

Note: 1. Provided that the starting torque is 600% In when the motor is started at full voltage.

2. The monitor output will be ON while load current is flowing to the main circuit.

## **Connections**

# ■ Connection Examples AC Model G3J-T□BL-C

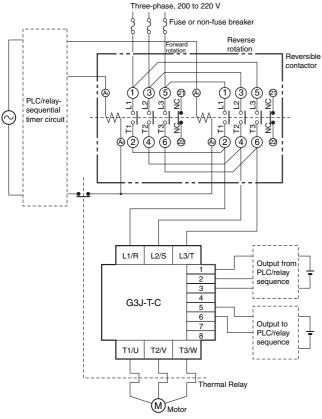


**Note:** Harmonized protection for motor overload is ensured by using a thermal relay. Be sure, however, to install protective devices on the power supply side, such as fuses and non-fuse breakers, as protection against accidents due to short-circuiting.

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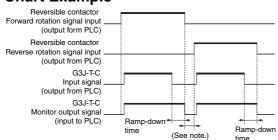
# Example of Forward/Reverse Rotation Using Monitor Output

#### G3J-T-C



Note: Be sure to use a fuse or non-fuse breaker to protect the G3J.

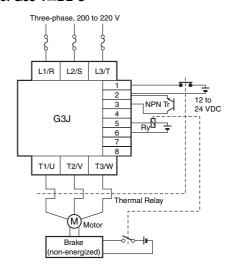
## **Time Chart Example**



**Note:** Switch between forward and reverse rotation only after the motor rotation has come to a complete stop.

# Monitor Output Usage Example (Motor Stop Hold)

#### DC Model G3J-T□BL-C



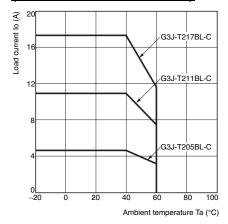
# **Monitor Output Applications**

- The monitor output will be ON while current is flowing to the main circuit. Use the monitor output, e.g., to switch the operation indicator, or to switch control signals during forward/reverse rotation or when a mechanical brake is used.
- Be sure to use a surge absorber when connecting an inductive load to the monitor output.

Do not use two G3J-T or G3J-C Contactors together for reversible operation.

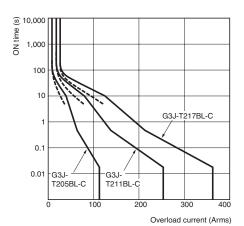
# **Engineering Data**

## **Load Current vs. Ambient Temperature** (at Continuous Power)



## **Overload Resistance**

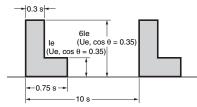
60 Hz, Ta of 25°C, non-repetitive (1/2 max. for repetitive application)



Note: dotted lines are for hot start.

## Switching Frequency Conditions (AC3/AC4/AC53-a)

## **AC3 Class (Immediate Start)**



le: Rated carry current

Ue: Rated load voltage (200/400 V)

Testing for the soft-start model was performed at the following conditions:

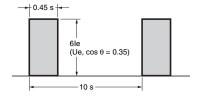
Ramp-up time = 1 s

Starting torque = 450% In Testing for the soft start/stop model was performed at the following conditions:

Ramp-up time = 1 s

Ramp-down time = 1 s Starting torque = 450% In

#### **AC4 Class (Inching)**



le: Rated carry current

Ue: Rated load voltage (200/400 V)

Testing for the soft-start model was performed at the following conditions:

Ramp-up time = 1 s

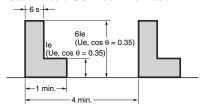
Starting torque = 450% In
Testing for the soft start/stop model was performed at the following conditions:

Ramp-up time = 1 s

Ramp-down time = 1 s

Starting torque = 450% In

### AC53-2: 6-6: 25-15, **Actual Load Service Life Test**



le: Rated carry current

Ue: Rated load voltage (200/400 V)

Testing for the soft-start model was performed at

the following conditions:

Ramp-up time = 1 s

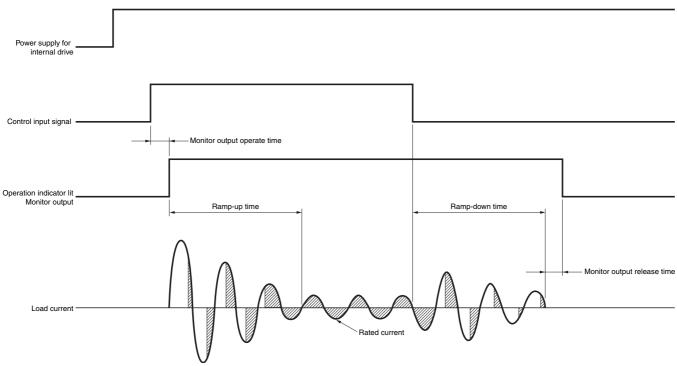
Starting torque = 450% In
Testing for the soft start/stop model was performed at the following conditions:

Ramp-up time = 1 s

Ramp-down time = 1 s

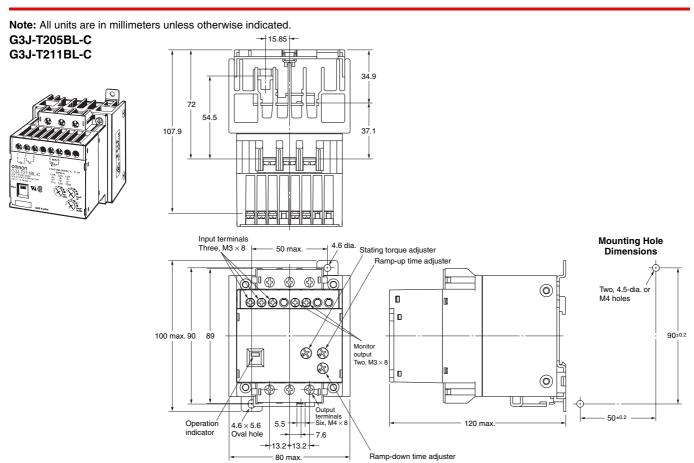
Starting torque = 450% In

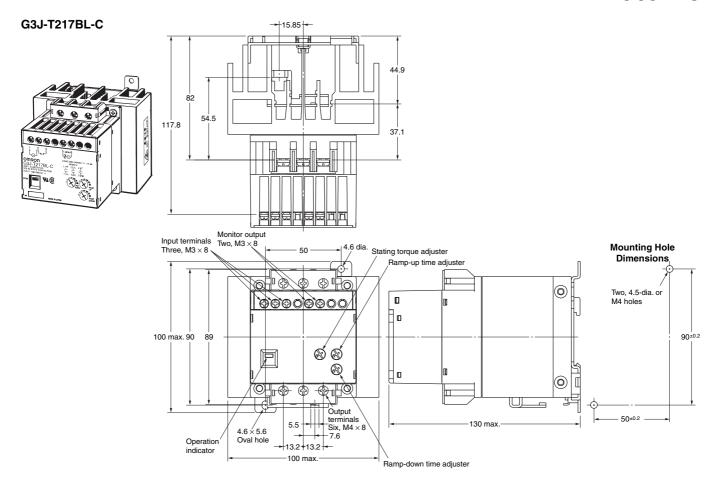
## **Time Chart**



- Note: 1. The soft-start time and soft-stop time depend on the load characteristics (e.g., inertia and friction factor) in addition to the starting torque, ramp-up time, and ramp-down time. Therefore, the soft-start time or soft-stop time will not increase beyond a certain point if the ramp-up time and ramp-down time are increased.
  - 2. Due to the soft-stop control characteristics, the load current continues flowing even after the motor stops. Set to the optimum value according to the application.
  - 3. The operation indicator will light synchronized with the monitor output.

## **Dimensions**





# **Safety Precautions**

Refer to Safety Precautions for All Solid State Relays.

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To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

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