RICOH

R2061x SERIES

3 Wire Interface Real-Time Clock ICs with Battery Backup Switch-Over Function

NO.EA-112-160217

OUTLINE

The R2061x is a CMOS real-time clock IC connected to the CPU by three signal lines, CE, SCLK, and SIO, and configured to perform serial transmission of time and calendar data to the CPU. Further, battery backup switchover circuit and a voltage detector. The periodic interrupt circuit is configured to generate interrupt signals with six selectable interrupts ranging from 0.5 seconds to 1 month. The 2 alarm interrupt circuits generate interrupt signals at preset times. As the oscillation circuit is driven under constant voltage, fluctuation of the oscillator frequency due to supply voltage is small, and the time keeping current is small (TYP. 0.4μ A at 3V). The oscillation halt sensing circuit can be used to judge the validity of internal data in such events as power-on; The supply voltage monitoring circuit is configured to record a drop in supply voltage below two selectable supply voltage monitoring threshold settings. The oscillation frequency of the quartz crystal unit. Battery backup switchover function is the automatic switchover circuit between a main power supply and a backup battery of primary or secondary battery. Switchover is executed by monitoring the voltage of a main power supply, therefore the voltage of a backup battery voltage is not relevant. Since the package for these ICs is SSOP16 (5.0x6.4x1.25: R2061Sxx) and QFN023023-16(2.3 × 2.3 × 0.4:R2061Lxx), high density mounting of ICs on boards is possible.

FEATURES

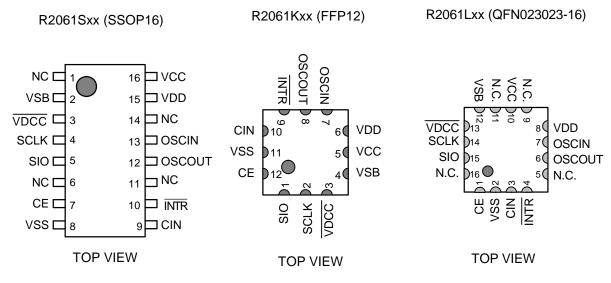
- Minimum Timekeeping supply voltage Typ. 0.75V (Max. 1.00V); VDD pin
- Low power consumption Typ. 0.4μA (Max. 1.0μA) at VDD=3V
- Built-in Backup switchover circuit (can be used for a primary battery, a secondary battery, or an electric double layer capacitor)
- Three signal lines (CE, SCLK, and SIO) required for connection to the CPU.

(Maximum clock frequency of 1MHz (with Vcc = 3V))

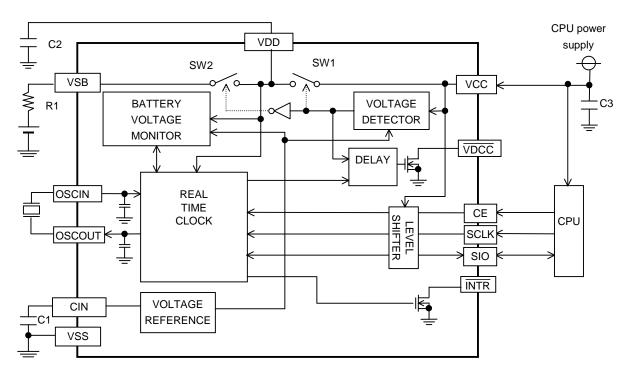
- Time counters (counting hours, minutes, and seconds) and calendar counters (counting years, months, days, and weeks) (in BCD format)
- Interrupt circuit configured to generate interrupt signals (with interrupts ranging from 0.5 seconds to 1 month) to the CPU and provided with an interrupt flag and an interrupt halt
- 2 alarm interrupt circuits (Alarm_W for week, hour, and minute alarm settings and Alarm_D for hour and minute alarm settings)
- Built-in voltage detector with delay
- With Power-on flag to prove that the power supply starts from 0V
- · Supply voltage monitoring circuit with two supply voltage monitoring threshold settings
- Automatic identification of leap years up to the year 2099
- Selectable 12-hour and 24-hour mode settings
- Built-in oscillation stabilization capacitors (CG and CD)
- High precision oscillation adjustment circuit
- CMOS process
- Package SSOP16 (5.0mm x 6.4mm x 1.25mm : R2061Sxx)
 - FFP12(2.0mm x 2.0mm x 1.0mm :R2061Kxx)
 - QFN023023-16(2.3mm x 2.3mm x 0.4mm :R2061Lxx)

NO.EA-112-160217

PIN CONFIGURATION



BLOCK DIAGRAM



SELECTION GUIDE

In the R2061xxx Series, the package and the output voltage can be designated.

Part Number is designated as follows:

R2061 L 01 - E2 - F \leftarrow Part Number $\uparrow \uparrow \uparrow \uparrow$ R2061 a bb - cc - d

| Code | Description |
|------|--|
| | Designation of the package. |
| | K: FFP12 |
| а | S: SSOP16 |
| | L: QFN023023-16 |
| bb | Serial number of Voltage detector setting etc. |
| сс | Designation of the taping type. Only E2 is available. |
| d | Designation of the lead plating (SSOP16 only). F: Lead free plating |

| Part Number | Package | -VDET1 (switch-over threshold) |
|---------------|--------------|-----------------------------------|
| R2061K01-E2 | FFP12 | 1.70(Typ.) |
| R2061K03-E2 | FFP12 | 2.80(Typ.) |
| R2061L01-E2 | QFN023023-16 | 1.70(Typ.) |
| R2061L03-E2 | QFN023023-16 | 2.80(Typ.) |
| R2061S02-E2-F | SSOP16 | 2.40(Typ.) |

PIN DESCRIPTION

| Symbol | Item | Description |
|-----------------|---|--|
| CE | Chip enable Input | The CE pin is used for interfacing with the CPU. Should be held high to allow access to the CPU. Incorporates a pull-down resistor. Should be held low or open when the CPU is powered off. Allows a maximum input voltage of 5.5 volts regardless of supply voltage. |
| SCLK | Serial Clock Input | The SCLK pin is used to input clock pulses synchronizing the input and output of data to and from the SIO pin. Allows a maximum input voltage of 5.5 volts regardless of supply voltage. |
| SIO | Serial Input / Output | The SIO pin is used to input or output data intended for writing or reading in synchronization with the SCLK pin. |
| INTR | Interrupt Output | The INTR pin is used to output alarm interrupt (Alarm_W) and alarm interrupt (Alarm_D) and output periodic interrupt signals to the CPU signals. Disabled at power-on from 0V. Nch. open drain output. |
| VCC | Main Battery input | Supply power to the IC. |
| VSB | Power Supply Input for Backup Battery | Connect a primary battery for backup. Normally, power is supplied from VCC to the IC. If VCC level is equal or less than –VDET1, power is supplied from this pin. |
| OSCIN OSCOUT | Oscillation Circuit Input / Output | The OSCIN and OSCOUT pins are used to connect the 32.768-kHz quartz crystal unit (with all other oscillation circuit components built into the R2061x). |
| VDD | Positive Power Supply Input | The VDD pin is connected to the power supply. Connect a capacitor as much as 0.1μ F between VDD and VSS. In the case of using a secondary battery, connecting the secondary battery to this pin is possible. |
| VDCC | VCC Power Supply Monitoring Result Output | While monitoring VCC Power supply, if the voltage is equal or lower than $-V_{DET1}$, this output level is "L". When \overline{VDCC} becomes "L", SW1 turns off and SW2 turns on. As a result, power is supplied from VSB pin to the internal real time clock. When VCC is equal to $+V_{DET1}$ or more, SW1 turns on and SW2 turns off. After t DELAY passed, \overline{VDCC} output becomes off, or "H". Nch Open-drain output. |
| CIN | Noise Bypass Pin | To stabilize the internal reference, connect a capacitor as much as 0.1uF between this pin and VSS. |
| VSS | Negative Power Sup Supply Input | The VSS pin is grounded. |
| N.C. | | No Connection |

ABSOLUTE MAXIMUM RATINGS

(Vss=0V)

| Symbol | ltem | Pin Name | Description | Unit |
|--------|------------------------|-------------|------------------------------|------|
| Vcc | Supply Voltage 1 | VCC | -0.3 to +6.5 | V |
| Vdd | Supply Voltage 2 | VDD | -0.3 to +6.5 | V |
| Vsв | Supply Voltage 3 | VSB | -0.3 to +6.5 | V |
| Vı | Input Voltage 1 | CE, SCLK | -0.3 to +6.5 | V |
| | Input Voltage 2 | SIO | -0.3 to Vcc+0.3 | V |
| | Input Voltage 3 | CIN | -0.3 to V _{DD} +0.3 | V |
| Vo | Output Voltage 1 | INTR, VDCC | -0.3 to +6.5 | V |
| | Output Voltage 2 | SIO | -0.3 to Vcc+0.3 | V |
| ООТ | Maximum Output Current | VDD | 10 | mA |
| PD | Power Dissipation | Topt = 25°C | 300 | mW |
| Topt | Operating Temperature | | -40 to +85 | °C |
| Tstg | Storage Temperature | | -55 to +125 | °C |

RECOMMENDED OPERATING CONDITIONS

| | | | (Vss= | 0V, Topt=-4 | 0 to +85° | C) |
|---------|---|---|---------------|-------------|-----------|------|
| Symbol | ltem | Pin Name | Min, | Тур. | Max. | Unit |
| Vaccess | Supply Voltage | VCC power supply voltage for interfacing with CPU | -Vdet1 *1) | | 5.5 | V |
| Vclk | Minimum Timekeeping Voltage CGout,CDout=0pF *2), *3) | | | 0.75 | 1.00 | V |
| fхт | Oscillation Frequency | | | 32.768 | | kHz |
| Vpup | Pull-up Voltage | INTR, VDCC | | | 5.5 | V |

*1) -VDET1 in Vaccess specification is guaranteed by design.

*2) CGout is connected between OSCIN and VSS, CDout is connected between OSCOUT and VSS. R2061x incorporates the capacitors between OSCIN and VSS, between OSCOUT and VSS. Then normally, CGout and CDout are not necessary.

*3) Quartz crystal unit: CL=6-8pF, R1=30KΩ

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DC ELECTRICAL CHARACTERISTICS

• R2061K01, R2061L01

(Unless otherwise specified: Vss=0V, Vsb=3.0V, Vcc=2.0V, 0.1uF between VDD and VSS, CIN and VSS,

| Symbol | Item | Pin Name | Conditions | Min. | Тур. | Max. | Unit |
|----------------------------------|---|-----------------|--|---------------------------|---------------------------|---------|------------|
| VIH1 | "H" Input Voltage 1 | CE, SCLK | | 0.8xVcc | | 5.5 | |
| VIH2 | "H" Input Voltage 2 | SIO | 7 | 0.8xVcc | | Vcc+0.3 | V |
| VIL | "L" Input Voltage | CE, SIO SCLK | _ | -0.3 | | 0.2xVcc | |
| Іон | "H" Output Current | SIO | Voн=Vcc-0.5V | | | -0.5 | mA |
| OL1 | "L" Output Current 1 | SIO | Vol=0.4V | 0.5 | | | |
| OL2 | "L" Output Current 2 | INTR | | 2.0 | | | mA |
| OL3 | "L" Output Current 3 | INTR | VDD,VSB,VCC=1.4V Vol=0.4V | 0.2 | | | |
| lıL | Input Leakage Current | SCLK | VI=5.5V or Vss | -1.0 | | 1.0 | μΑ |
| Rdnce | Pull-down Input register | CE | | 40 | 120 | 400 | kΩ |
| loz1 | Output Off-state Current 1 | SIO | Vo=5.5V or Vss | -1.0 | | 1.0 | μΑ |
| loz2 | Output Off-state Current 2 | INTR , VDCC | Vo=5.5V or Vss | -1.0 | | 1.0 | μA |
| lsв | Time Keeping Current at Backup mode | VSB | Vcc=0V, Vsb=3.0V, Vdd, Output=OPEN | | 0.4 | 1.0 | μA |
| ISBL | Leakage Current of Backup pin at VCC_on | VSB | Vcc=3.0V, VsB=5.5V or 0V, VbD, Output=OPEN | -1.0 | | 1.0 | μA |
| Vdeth | Supply Voltage Monitoring Voltage "H" | VSB | Topt=25°C | 1.90 | 2.10 | 2.30 | V |
| Vdetl | Supply Voltage Monitoring Voltage "L" | VDD | Topt=25°C | 1.20 | 1.35 | 1.50 | V |
| -Vdet1 | Detector Threshold Voltage (falling edge of VCC) | VCC | Topt=25°C | 1.657 | 1.700 | 1.743 | V |
| +Vdet1 | Detector Released Voltage (rising edge of VCC) | VCC | Topt=25°C | 1.731 | 1.785 | 1.839 | V |
| <u>ΔV_{DET}</u> ΔTopt | Detector Threshold and Released Voltage Temperature coefficient | VCC, VSB | Topt=-40 to 85°C *1) | | ±100 | | ppm /°C |
| Vddout1 | VDD Output Voltage 1 | VDD | Topt=25°C, Vcc=2.0V, Iout=0.5mA | Vcc- 0.12 | Vcc- 0.04 | | V |
| Vddout2 | VDD Output Voltage 2 | VDD | Topt=25°C, Vcc=1.4V, VsB=3.0V, lout=0.1mA | V _{SB} - 0.08 | V _{SB} - 0.02 | | V |
| CG | Internal Oscillation Capacitance 1 | OSCIN | | | 10 | | pF |
| CD | Internal Oscillation Capacitance 2 | OSCOUT | | | 10 | | |

*1) Guaranteed by design.

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• R2061S02

(Unless otherwise specified: Vss=0V,VsB=Vcc=3.0V, 0.1uF between VDD and VSS, CIN and VSS, Topt=-40 to +85°C)

| Symbol | Item | Pin Name | Conditions | Min. | Тур. | Max. | Unit |
|--|---|-----------------|--|---------------------------|---------------------------|---------|------------|
| VIH1 | "H" Input Voltage 1 | CE, SCLK | | 0.8xVcc | | 5.5 | |
| VIH2 | "H" Input Voltage 2 | SIO | | 0.8xVcc | | Vcc+0.3 | V |
| VIL | "L" Input Voltage | CE, SCLK SIO | | -0.3 | | 0.2xVcc | |
| Іон | "H" Output Current | SIO | Vон=Vcc-0.5V | | | -0.5 | mA |
| OL1 | "L" Output Current 1 | SIO | Vol=0.4V | 0.5 | | | |
| OL2 | "L" Output Current 2 | INTR | | 2.0 | | | mA |
| IOL3 | "L" Output Current 3 | VDCC | Vdd,Vsb,Vcc=2.0V Vol=0.4V | 0.5 | | | |
| lı∟ | Input Leakage Current | SCLK | VI=5.5V or Vss | -1.0 | | 1.0 | μA |
| Rdnce | Pull-down Input register | CE | | 40 | 120 | 400 | kΩ |
| loz1 | Output Off-state Current 1 | SIO | Vo=5.5V or Vss | -1.0 | | 1.0 | μA |
| loz2 | Output Off-state Current 2 | INTR, VDCC | Vo=5.5V or Vss | -1.0 | | 1.0 | μΑ |
| ISB | Time Keeping Current at Backup mode | VSB | Vcc=0V, Vsb=3.0V, Vdd, Output=OPEN | | 0.4 | 1.0 | μA |
| ISBL | Leakage Current of Backup pin at VCC_on | VSB | Vcc=3.0V, VsB=5.5V or 0V, VDD, Output=OPEN | -1.0 | | 1.0 | μΑ |
| Vdeth | Supply Voltage Monitoring Voltage "H" | VSB | Topt=25°C | 1.90 | 2.10 | 2.30 | V |
| Vdetl | Supply Voltage Monitoring Voltage "L" | VDD | Topt=25°C | 1.20 | 1.35 | 1.50 | V |
| -Vdet1 | Detector Threshold Voltage (falling edge of VCC) | VCC | Topt=25°C | 2.34 | 2.40 | 2.46 | V |
| +Vdet1 | Detector Released Voltage (rising edge of VCC) | VCC | Topt=25°C | 2.44 | 2.52 | 2.60 | V |
| $\frac{\Delta V_{\text{DET}}}{\Delta \text{Topt}}$ | Detector Threshold and Released Voltage Temperature coefficient | VCC, VSB | Topt=-40 to 85°C *1) | | ±100 | | ppm /°C |
| Vddout1 | VDD Output Voltage 1 | VDD | Topt=25°C, Vcc=3.0V, Iout=1.0mA | Vcc- 0.12 | Vcc- 0.04 | | V |
| Vddout2 | VDD Output Voltage 2 | VDD | Topt=25°C, Vcc=2.0V, VsB=3.0V, Iout=0.1mA | V _{SB} - 0.08 | V _{sв} - 0.02 | | V |
| CG | Internal Oscillation Capacitance 1 | OSCIN | | | 10 | | pF |
| CD | Internal Oscillation Capacitance 2 *1) Guaranteed by design. | OSCOUT | | | 10 | | |

*1) Guaranteed by design.

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• R2061K03, R2061L03

(Unless otherwise specified: Vss=0V, Vsb=3.0V, Vcc=3.3V, 0.1uF between VDD and VSS, CIN and VSS, Topt=-40 to +85°C)

| Symbol | ltem | Pin Name | Conditions | Min. | Тур. | Max. | Unit |
|--|--|----------------|--|---------------------------|---------------------------|---------|------------|
| VIH1 | "H" Input Voltage 1 | CE, SCLK | | 0.8x | | 5.5 | N/ |
| 14 | | | - | Vcc | | | V |
| VIH2 | "H" Input Voltage 2 | SIO | | 0.8x | | Vcc+0.3 | |
| VIL | "L" Input Voltage | CE, SCLK | - | Vcc -0.3 | | 0.2xVcc | |
| | | SIO | | -0.3 | | | |
| Іон | "H" Output Current | SIO | Vон=Vcc-0.5V | | | -0.5 | mA |
| OL1 | "L" Output Current 1 | SIO | Vol=0.4V | 0.5 | | | |
| OL2 | "L" Output Current 2 | INTR | | 2.0 | | | mA |
| IOL3 | "L" Output Current 3 | VDCC | Vdd,Vsb,Vcc=2.0V Vol=0.4V | 0.5 | | | |
| lı∟ | Input Leakage Current | SCLK | V=5.5V or Vss | -1.0 | | 1.0 | μΑ |
| RDNCE | Pull-down Input register | CE | | 40 | 120 | 400 | kΩ |
| loz1 | Output Off-state Current 1 | SIO | Vo=5.5V or VSS | -1.0 | | 1.0 | μΑ |
| loz2 | Output Off-state Current 2 | INTR , VDCC | Vo=5.5V or Vss | -1.0 | | 1.0 | μA |
| ISB | Time Keeping Current at Backup mode | VSB | V _{CC} =0V, V _{SB} =3.0V, V _{DD} , Output=OPEN | | 0.4 | 1.0 | μΑ |
| Isbl | Leakage Current of Backup pin at VCC_on | VSB | Vcc=3.3V, VsB=5.5V or 0V, VDD, Output=OPEN | -1.0 | | 1.0 | μΑ |
| Vdeth | Supply Voltage Monitoring Voltage "H" | VSB | Topt=25°C | 1.90 | 2.10 | 2.30 | V |
| Vdetl | Supply Voltage Monitoring Voltage "L" | VDD | Topt=25°C | 1.20 | 1.35 | 1.50 | V |
| -Vdet1 | Detector Threshold Voltage (falling edge of VCC) | VCC | Topt=25°C | 2.73 | 2.80 | 2.87 | V |
| +Vdet1 | Detector Released Voltage (rising edge of VCC) | VCC | Topt=25°C | 2.85 | 2.94 | 3.03 | V |
| $\frac{\Delta V_{\text{DET}}}{\Delta \text{Topt}}$ | Detector Threshold and Released Voltage Temperature coefficient | VCC, VSB | Topt=-40 to 85°C *1) | | ±100 | | ppm /°C |
| Vddout1 | VDD Output Voltage 1 | VDD | Topt=25°C, Vcc=3.3V, I _{out} =1.0mA | Vcc- 0.12 | Vcc- 0.04 | | V |
| Vddout2 | VDD Output Voltage 2 | VDD | Topt=25°C, Vcc=2.0V, VsB=3.0V, lout=0.1mA | V _{SB} - 0.08 | V _{SB} - 0.02 | | V |
| CG | Internal Oscillation Capacitance 1 | OSCIN | | | 10 | | pF |
| CD | Internal Oscillation Capacitance 2 | OSCOUT | | | 10 | | |

*1) Guaranteed by design.

AC ELECTRICAL CHARACTERISTICS

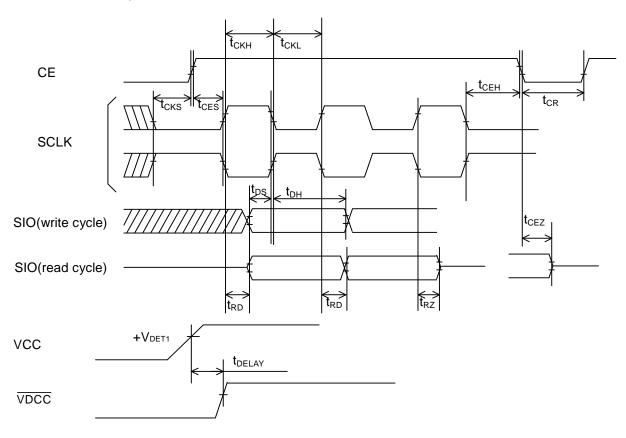
Unless otherwise specified: Vss=0V,Topt=-40 to +85°C

Input and Output Conditions: VIH=0.8×Vcc, VIL=0.2×Vcc, VOH=0.8×Vcc, VOL=0.2×Vcc, CL=50pF

| Sym | Item | Condi- | V | dd≥ 1.7V *1 | 1) | Unit |
|--------------------|---|-----------------|------|--------------------|------|------|
| -bol | | Tions | Min. | Тур. | Max. | |
| tces | CE Set-up Time | | 400 | | | ns |
| t CEH | CE Hold Time | | 400 | | | ns |
| t CR | CE Recovery Time | | 62 | | | μS |
| fsclk | SCLK Clock Frequency | | | | 1.0 | MHz |
| t _{скн} | SCLK Clock "H" Time | | 400 | | | ns |
| t cĸ∟ | SCLK Clock "L" Time | | 400 | | | ns |
| tcкs | SCLK Set-up Time | | 200 | | | ns |
| t RD | Data Output Delay Time | | | | 300 | ns |
| t _{RZ} | Data Output Floating Time | | | | 300 | ns |
| t _{CEZ} | Data Output Delay Time After Falling of CE | | | | 300 | ns |
| t _{DS} | Input Data Set-up Time | | 200 | | | ns |
| t _{DH} | Input Data Hold Time | | 200 | | | ns |
| t _{DELAY} | Output Delay Time of Voltage Detector | Time Keeping | 100 | 105 | 110 | ms |

*1) VCC voltage interfacing with CPU is defined by Vaccess (P.5 RECOMMENDED OPERATING CONDITIONS)

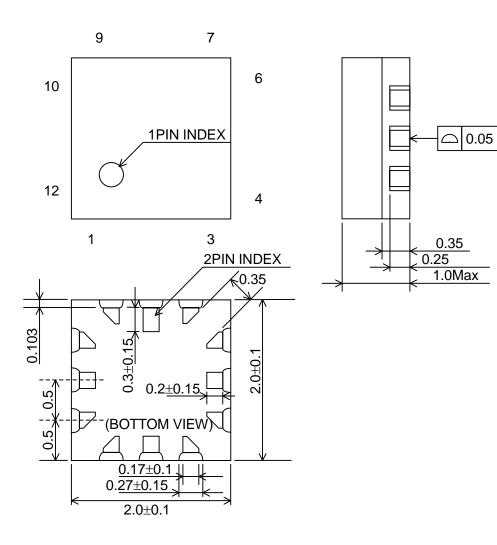
*) For reading/writing timing, see "P.31 Interfacing with the CPU •Considerations in Reading and Writing Time Data under special condition".



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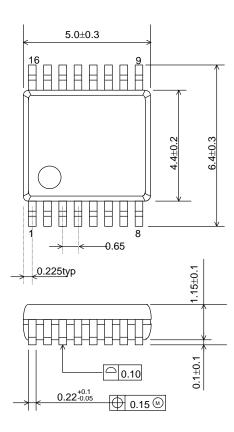
PACKAGE DIMENSIONS

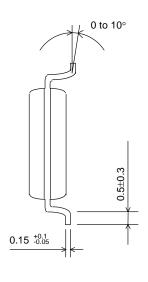
• R2061Kxx (Discontinued)



unit: mm

• R2061Sxx



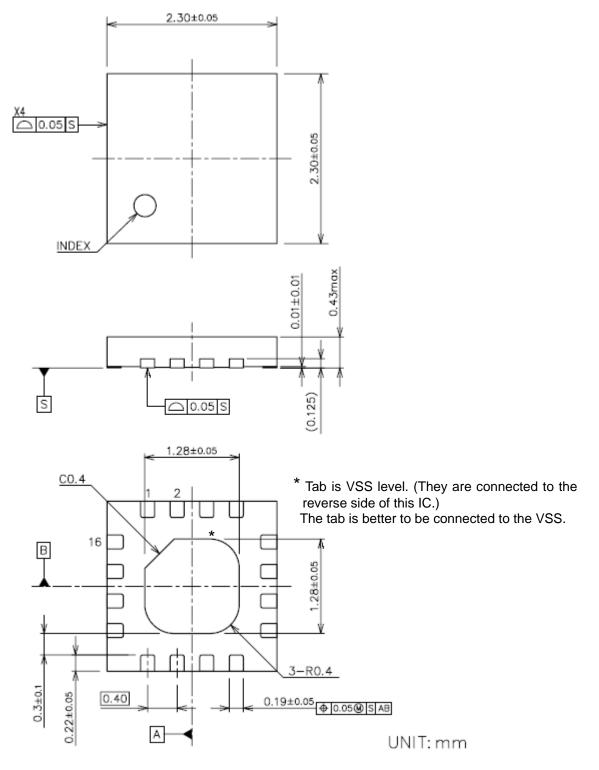


unit: mm

RICOH

NO.EA-112-160217

• R2061Lxx



X The side of the all terminals have no plating treatment. Therefore, it may not be able to form solder fillet on the side of the terminals.

GENERAL DESCRIPTION

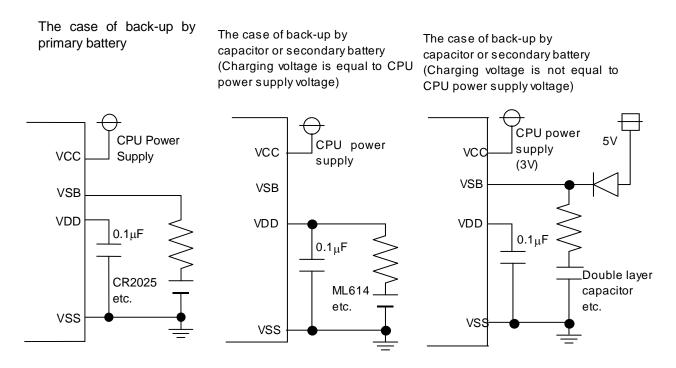
Battery Backup Switchover Function

The R2061x have two power supply input, or VCC and VSB. With monitoring VCC pin input voltage, which voltage between the two is supplied to the internal power supply is decided.

Refer to the next table to see the state of the backup battery and internal power supply's state of the IC by each condition.

| Vcc≥Vdet1 | Vcc <vdet1< th=""></vdet1<> |
|----------------------------|-----------------------------|
| VCC→RTC, VDD | VSB→RTC, VDD |
| $\overline{VDCC} = OFF(H)$ | VDCC=L |

As a backup battery, not only a primary battery such as CR2025, LR44, or a secondary battery such as ML614, TC616, but also an electric double layered capacitor or an aluminum capacitor can be used. Switchover point is judged with the voltage of the main power (VCC), therefore, if the backup voltage is higher than main supply voltage, switchover can be realized without extra load to the backup power supply.



Interface with CPU

The R2061x is connected to the CPU by three signal lines CE (Chip Enable), SCLK (Serial Clock), and SIO (Serial Input / Output), through which it reads and writes data from and to the CPU. The CPU can be accessed when the CE pin is held high. Access clock pulses have a maximum frequency of 1 MHz, allowing high-speed data transfer to the CPU. VCC falls down under -V_{DET1}, the R2061x stops accessing with CPU.

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• Clock and Calendar Function

The R2061x reads and writes time data from and to the CPU in units ranging from seconds to the last two digits of the calendar year. The calendar year will automatically be identified as a leap year when its last two digits are a multiple of 4. Consequently, leap years up to the year 2099 can automatically be identified as such.

*) The year 2000 is a leap year while the year 2100 is not a leap year.

Alarm Function

The R2061x incorporates the alarm interrupt circuit configured to generate interrupt signals to the CPU at preset times. The alarm interrupt circuit allows two types of alarm settings specified by the Alarm_W registers and the Alarm_D registers. The Alarm_W registers allow week, hour, and minute alarm settings including combinations of multiple day-of-week settings such as "Monday, Wednesday, and Friday" and "Saturday and Sunday". The Alarm_D registers allow hour and minute alarm settings. The Alarm_W outputs from INTR pin, and the Alarm_D outputs also from INTR pin. Each alarm function can be checked from the CPU by using a polling function.

High-precision Oscillation Adjustment Function

The R2061x has built-in oscillation stabilization capacitors (CG and CD), that can be connected to an external quartz crystal unit to configure an oscillation circuit. Two kinds of accuracy for this function are alternatives. To correct deviations in the oscillator frequency of the crystal, the oscillation adjustment circuit is configured to allow correction of a time count gain or loss (up to ± 1.5 ppm or ± 0.5 ppm at 25°C) from the CPU. The maximum range is approximately ± 189 ppm (or ± 63 ppm) in increments of approximately 3ppm (or 1ppm). Such oscillation frequency adjustment in each system has the following advantages:

* Allows timekeeping with much higher precision than conventional RTCs while using a quartz crystal unit with a wide range of precision variations.

- * Corrects seasonal frequency deviations through seasonal oscillation adjustment.
- * Allows timekeeping with higher precision particularly with a temperature sensing function out of RTC, through oscillation adjustment in tune with temperature fluctuations.

• Power-on Reset, Oscillation Halt Sensing Function and Supply Voltage Monitoring Function

The R2061x has 3 power supply pins (VCC, VSB, VDD), among them, VCC pin and VDD pin have monitoring function of supply voltage. VCC power supply monitoring circuit makes \overline{VDCC} pin "L" when VCC power supply pin becomes equal or lower than $-V_{DET1}$. At the power-on of VCC, this circuit makes \overline{VDCC} pin turn off, or "H" after the delay time, t_{DELAY} from when the VCC power supply pin becomes equal or more than $+V_{DET1}$.

The R2061x incorporates an oscillation halt sensing circuit equipped with internal registers configured to record any past oscillation halt, the oscillation halt sensing circuit, VDD monitoring flag, and power-on reset flag are useful for judging the validity of time data.

Power on reset function reset the control resisters when the system is powered on from 0V. At the same time, the fact is memorized to the resister as a flag, thereby identifying whether they are powered on from 0V or battery backed-up.

The R2061x also incorporates a supply voltage monitoring circuit equipped with internal registers configured to record any drop in supply voltage below a certain threshold value. Supply voltage monitoring threshold settings can be selected between 2.1V and 1.35V through internal register settings. The sampling rate is normally 1s. The oscillation halt sensing circuit is configured to confirm the established invalidation of time data in contrast to the supply voltage monitoring circuit intended to confirm the potential invalidation of time data. Further, the supply voltage monitoring circuit can be applied to battery supply voltage monitoring.

• Periodic Interrupt Function

The R2061x incorporates the periodic interrupt circuit configured to generate periodic interrupt signals aside from interrupt signals generated by the periodic interrupt circuit for output from the \overline{INTR} pin. Periodic interrupt signals have five selectable frequency settings of 2 Hz (once per 0.5 seconds), 1 Hz (once per 1 second), 1/60 Hz (once per 1 minute), 1/3600 Hz (once per 1 hour), and monthly (the first day of every month). Further, periodic interrupt signals also have two selectable waveforms, a normal pulse form (with a frequency of 2 Hz or 1 Hz) and special form adapted to interruption from the CPU in the level mode (with second, minute, hour, and month interrupts). The condition of periodic interrupt signals can be monitored with using a polling function.

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Address Mapping

| | Address | Register Name | | | | Da | t a | | | |
|-----|----------|------------------------|-------|--------------|------------|--------|--------------|-------|-------|--------------|
| | A3A2A1A0 | | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| 0 | 0000 | Second Counter | - | S40 | S20 | S10 | S8 | S4 | S2 | S1 |
| | |] | *2) | | | - | | | | |
| 1 | 0001 | Minute Counter | | M40 | M20 | M10 | M8 | M4 | M2 | M1 |
| 2 | 0010 | Hour Counter | - | - | H20 | H10 | H8 | H4 | H2 | H1 |
| | |] | | | <u>P/Ā</u> | | | | | |
| 3 | 0011 | Day-of-week Counter | | . | | | . | W4 | W2 | W1 |
| 4 | 0100 | Day-of-month Counter | | | D20 | D10 | D8 | D4 | D2 | D1 |
| 5 | 0101 | Month Counter and | 19/20 | - | | MO10 | MO8 | MO4 | MO2 | MO1 |
| | | Century Bit | | | - | | - | | | - |
| 6 | 0110 | Year Counter | Y80 | Y40 | Y20 | Y10 | Y8 | Y4 | Y2 | Y1 |
| 7 | 0111 | Oscillation Adjustment | DEV | F6 | _ F5 | F4 | F3 | F2 | F1 | <u> </u> |
| | | Register *3) | *4) | : | : | : | : | | | |
| 8 | 1000 | Alarm_W | - | - WM40 | WM20 | WM10 | WM8 | WM4 | WM2 | WM1 |
| | | (Minute Register) | | | | | | | | |
| 9 | 1001 | Alarm_W | - | | WH20 | _ WH10 | WH8 | WH4 | WH2 | <u>:</u> WH1 |
| | | (Hour Register) | | | WP/ A | | | | | |
| A | 1010 | Alarm_W | - | WW6 | WW5 | WW4 | WW3 | _ WW2 | WW1 | _ WW0 |
| | | (Day-of-week Register) | | | | | | , | | · · |
| В | 1011 | Alarm_D | - | DM40 | DM20 | DM10 | DM8 | DM4 | DM2 | DM1 |
| | | (Minute Register) | | | | | | , | | |
| С | 1100 | Alarm_D | - | - | DH20 | DH10 | DH8 | DH4 | DH2 | DH1 |
| | | (Hour Register) | | | DP/A | • • | | | | |
| _ D | 1101 | | | . | <u>.</u> | | . | | | |
| Ē | 1110 | Control Register 1 *3) | WALE | DALE | 12 /24 | SCRA- | TEST | CT2 | CT1 | СТ0 |
| | | | | | | TCH2 | 1 | 1 | , | |
| F | 1111 | Control Register 2 *3) | VDSL | VDET | XST | PON | | CTFG | WAFG | DAFG |
| | | 1 | | l | | *5) | TCH1 | | | |

Notes:

- * 1) All the data listed above accept both reading and writing.
- * 2) The data marked with "-" is invalid for writing and reset to 0 for reading.
- * 3) When the PON bit is set to 1 in Control Register 2, all the bits are reset to 0 in Oscillation Adjustment Register, Control Register 1 and Control Register 2 excluding the \overline{XSI} bit.
- * 4) When DEV=0, the oscillation adjustment circuit is configured to allow correction of a time count gain or loss up to ±1.5ppm.
 When DEV=1, the oscillation adjustment circuit is configured to allow correction of a time count gain

When DEV=1, the oscillation adjustment circuit is configured to allow correction of a time count gain or loss up to or ± 0.5 ppm.

* 5) PON is a power-on-reset flag.

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Register Settings

• Control Register 1 (ADDRESS Eh)

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
|------|------|--------|------|------|-----|-----|-----|---------------------|
| WALE | DALE | 12 /24 | SCRA | TEST | CT2 | CT1 | CT0 | (For Writing) |
| | | | TCH2 | | | | | |
| WALE | DALE | 12 /24 | SCRA | TEST | CT2 | CT1 | CT0 | (For Reading) |
| | | | TCH2 | | | | | |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Default Settings *) |

*) Default settings: Default value means read / written values when the PON bit is set to "1" due to VDD power-on from 0 volts.

(1) WALE, DALE Alarm_W Enable Bit, Alarm_D Enable Bit

| WALE,DALE | Description | |
|-----------|--|-----------|
| 0 | Disabling the alarm interrupt circuit (under the control of the settings | (Default) |
| | of the Alarm_W registers and the Alarm_D registers). | |
| 1 | Enabling the alarm interrupt circuit (under the control of the settings | |
| | of the Alarm_W registers and the Alarm_D registers) | |

(2) 12/24

12/24-hour Mode Selection Bit

| 12/24 | Description | |
|-------|--|-----------|
| 0 | Selecting the 12-hour mode with a.m. and p.m. indications. | (Default) |
| 1 | Selecting the 24-hour mode | |
| _ | | |

Setting the 12/24 bit to 0 and 1 specifies the 12-hour mode and the 24-hour mode, respectively.

| 24-hour mode | 12-hour mode | 24-hour mode | 12-hour mode |
|--------------|--------------|--------------|--------------|
| 00 | 12 (AM12) | 12 | 32 (PM12) |
| 01 | 01 (AM 1) | 13 | 21 (PM 1) |
| 02 | 02 (AM 2) | 14 | 22 (PM 2) |
| 03 | 03 (AM 3) | 15 | 23 (PM 3) |
| 04 | 04 (AM 4) | 16 | 24 (PM 4) |
| 05 | 05 (AM 5) | 17 | 25 (PM 5) |
| 06 | 06 (AM 6) | 18 | 26 (PM 6) |
| 07 | 07 (AM 7) | 19 | 27 (PM 7) |
| 08 | 08 (AM 8) | 20 | 28 (PM 8) |
| 09 | 09 (AM 9) | 21 | 29 (PM 9) |
| 10 | 10 (AM10) | 22 | 30 (PM10) |
| 11 | 11 (AM11) | 23 | 31 (PM11) |

Setting the $\frac{12}{24}$ bit should precede writing time data

(3) SCRATCH2 Scratch Bit 2

| SCRATCH2 | Description | |
|----------|-------------|-----------|
| 0 | | (Default) |
| 1 | | |

The SCRATCH2 bit is intended for scratching and accepts the reading and writing of 0 and 1. The SCRATCH2 bit will be set to 0 when the PON bit is set to 1 in the Control Register 1.

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(4) TEST Test Bit

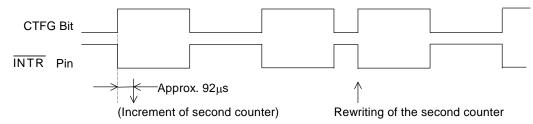
| TEST | Description | |
|------|------------------------|-----------|
| 0 | Normal operation mode. | (Default) |
| 1 | Test mode. | |

The TEST bit is used only for testing in the factory and should normally be set to 0.

(5) CT2,CT1, and CT0 Periodic Interrupt Selection Bits

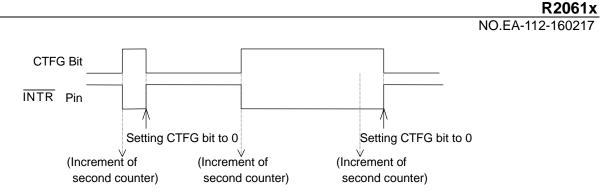
| CT2 | CT1 | CT0 | | Description | | | |
|-----|-----|-----|-------------------|---|-----------|--|--|
| | | | Wave form mode | Interrupt Cycle and Falling Timing | | | |
| 0 | 0 | 0 | - | OFF(H) | (Default) | | |
| 0 | 0 | 1 | - | Fixed at "L" | | | |
| 0 | 1 | 0 | Pulse Mode *1) | 2Hz(Duty50%) | | | |
| 0 | 1 | 1 | Pulse Mode *1) | 1Hz(Duty50%) | | | |
| 1 | 0 | 0 | Level Mode *2) | Once per 1 second (Synchronized with second counter increment) | | | |
| 1 | 0 | 1 | Level Mode *2) | Once per 1 minute (at 00 seconds of every minute) | | | |
| 1 | 1 | 0 | Level Mode *2) | Once per hour (at 00 minutes and 00 seconds of every hour) | | | |
| 1 | 1 | 1 | Level Mode *2) | Once per month (at 00 hours, 00 minutes, and 00 seconds of first day of every month) | | | |

* 1) Pulse Mode: 2-Hz and 1-Hz clock pulses are output in synchronization with the increment of the second counter as illustrated in the timing chart below.



In the pulse mode, the increment of the second counter is delayed by approximately 92 μ s from the falling edge of clock pulses. Consequently, time readings immediately after the falling edge of clock pulses may appear to lag behind the time counts of the real-time clocks by approximately 1 second. Rewriting the second counter will reset the other time counters of less than 1 second, driving the INTR pin low.

* 2) Level Mode: Periodic interrupt signals are output with selectable interrupt cycle settings of 1 second, 1 minute, 1 hour, and 1 month. The increment of the second counter is synchronized with the falling edge of periodic interrupt signals. For example, periodic interrupt signals with an interrupt cycle setting of 1 second are output in synchronization with the increment of the second counter as illustrated in the timing chart below.



At the level mode, the moment right after writing CT2-CT0, INTR pin becomes "L" in very short moment. In such a case, ignore it or confirm it by CTFG bit.

- *1), *2) When the oscillation adjustment circuit is used, the interrupt cycle will fluctuate once per 20sec. or 60sec. as follows:
- Pulse Mode: The "L" period of output pulses will increment or decrement by a maximum of ±3.784 ms. For example, 1-Hz clock pulses will have a duty cycle of 50 ±0.3784%.
- Level Mode: A periodic interrupt cycle of 1 second will increment or decrement by a maximum of ± 3.784 ms.

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• Control Register 2 (Address Fh)

| | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
|---|--|------|------------|-----|------|------|------|------|---------------------|
| | VDSL | VDET | XST | PON | SCRA | CTFG | WAFG | DAFG | (For Writing) |
| | | | | | TCH1 | | | | |
| | VDSL | VDET | XST | PON | SCRA | CTFG | WAFG | DAFG | (For Reading) |
| | | | | | TCH1 | | | | |
| | 0 | 0 | Indefinite | 1 | 0 | 0 | 0 | 0 | Default Settings *) |
| , | *) Default actinger. Default value many road (written values when the DON bit is act to "1" due to VDD | | | | | | | | |

b) Default settings: Default value means read / written values when the PON bit is set to "1" due to VDD power-on from 0 volts.

(1) VDSL

VDD Supply Voltage Monitoring Threshold Selection Bit

| VDSL | Description | |
|------|---|-----------|
| 0 | Selecting the VDD supply voltage monitoring threshold setting of | (Default) |
| | 2.1v. | |
| 1 | Selecting the VDD supply voltage monitoring threshold setting of 1.35v. | |

The VDSL bit is intended to select the VDD supply voltage monitoring threshold settings.

(2) VDET

Supply Voltage Monitoring Result Indication Bit

| VDET | Description | |
|------|---|-----------|
| 0 | Indicating supply voltage above the supply voltage monitoring threshold settings. | (Default) |
| 1 | Indicating supply voltage below the supply voltage monitoring threshold settings. | |

Once the VDET bit is set to 1, the supply voltage monitoring circuit will be disabled while the VDET bit will hold the setting of 1. The VDET bit accepts only the writing of 0, which restarts the supply voltage monitoring circuit. Conversely, setting the VDET bit to 1 causes no event.

(3) XST Oscillation Halt Sensing Monitor Bit

| XST | Description |
|-----|---|
| 0 | Sensing a halt of oscillation |
| 1 | Sensing a normal condition of oscillation |

The \overline{XST} accepts the reading and writing of 0 and 1. The \overline{XST} bit will be set to 0 when the oscillation halt sensing. The \overline{XST} bit will hold 0 even after the restart of oscillation.

(4) PON Power-on-reset Flag Bit

| | PON | Description | |
|---|-----|-------------------------------|-----------|
| [| 0 | Normal condition | |
| [| 1 | Detecting VDD power-on -reset | (Default) |

The PON bit is for sensing power-on reset condition.

* The PON bit will be set to 1 when VDD power-on from 0 volts. The PON bit will hold the setting of 1 even after power-on.

* When the PON bit is set to 1, all bits will be reset to 0, in the Oscillation Adjustment Register, Control Register 1, and Control Register 2, except \overline{XSI} and PON. As a result, \overline{INIR} pin stops outputting. * The PON bit accepts only the writing of 0. Conversely, setting the PON bit to 1 causes no event.

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(5) SCRATCH1 Scratch Bit 1 SCRATCH1 Description 0 0 1 0

The SCRATCH1 bit is intended for scratching and accepts the reading and writing of 0 and 1. The SCRATCH1 bit will be set to 0 when the PON bit is set to 1 in the Control Register 2.

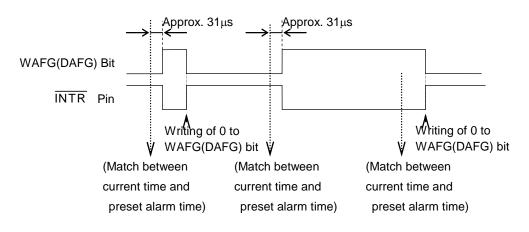
| (6) CTF | G | Periodic Interrupt Flag Bit | |
|---------|------|---------------------------------|-----------|
| | CTFG | Description | |
| | 0 | Periodic interrupt output = "H" | (Default) |
| | 1 | Periodic interrupt output = "L" | |

The CTFG bit is set to 1 when the periodic interrupt signals are output from the INTR pin ("L"). The CTFG bit accepts only the writing of 0 in the level mode, which disables ("H") the INTR pin until it is enabled ("L") again in the next interrupt cycle. Conversely, setting the CTFG bit to 1 causes no event.

(7) WAFG,DAFG Alarm_W Flag Bit and Alarm_D Flag Bit

| | WAFG,DAFG | Description | |
|------|------------------|---|-----------|
| | 0 | Indicating a mismatch between current time and preset alarm time | (Default) |
| | 1 | Indicating a match between current time and preset alarm time | |
| w) م | AEG and DAEG bit | s are valid only when the WALE and DALE have the setting of 1, which is | caused |

The WAFG and DAFG bits are valid only when the WALE and DALE have the setting of 1, which is caused approximately 31µs after any match between current time and preset alarm time specified by the Alarm_W registers and the Alarm_D registers. The WAFG (DAFG) bit accepts only the writing of 0. INIR pin outputs off ("H") when this bit is set to 0. And INIR pin outputs "L" again at the next preset alarm time. Conversely, setting the WAFG and DAFG bits to 1 causes no event. The WAFG and DAFG bits will have the reading of 0 when the alarm interrupt circuit is disabled with the WALE and DALE bits set to 0. The settings of the WAFG and DAFG bits are synchronized with the output of the INIR pin as shown in the timing chart below.



*)

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• Time Counter (Address 0-2h)

Second Counter (Address 0h)

| D7 D6 D5 D4 D3 D2 D1 D0 | |
|---|----------------|
| | |
| - S40 S20 S10 S8 S4 S2 S1 (For V | Vriting) |
| | Reading) |
| 0 Indefinite Indefinite Indefinite Indefinite Indefinite Indefinite Defau | It Settings *) |

Minute Counter (Address 1h)

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
|----|------------|------------|------------|------------|------------|------------|------------|--------------------|
| - | M40 | M20 | M10 | M8 | M4 | M2 | M1 | (For Writing) |
| 0 | M40 | M20 | M10 | M8 | _M4 | M2 | M1 | (For Reading) |
| 0 | Indefinite | Default Settings * |

Hour Counter (Address 2h)

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
|----|----|------------|------------|------------|------------|------------|------------|---------------------|
| - | - | P/A | H10 | H8 | H4 | H2 | H1 | (For Writing) |
| | | or H20 | | | | | | |
| 0 | 0 | P/A | H10 | H8 | H4 | H2 | H1 | (For Reading) |
| | | or H20 | | | | | | |
| 0 | 0 | Indefinite | Indefinite | Indefinite | Indefinite | Indefinite | Indefinite | Default Settings *) |

*) Default settings: Default value means read / written values when the PON bit is set to "1" due to VDD power-on from 0 volts.

* Time digit display (BCD format) as follows:

The second digits range from 00 to 59 and are carried to the minute digit in transition from 59 to 00. The minute digits range from 00 to 59 and are carried to the hour digits in transition from 59 to 00. The hour digits range as shown in "P17 • Control Register 1 (ADDRESS Eh) (2) $\overline{12}/24$: $\overline{12}/24$ -hour Mode Selection Bit" and are carried to the day-of-month and day-of-week digits in transition from PM11 to AM12 or from 23 to 00.

* Any writing to the second counter resets divider units of less than 1 second.

* Any carry from lower digits with the writing of non-existent time may cause the time counters to malfunction. Therefore, such incorrect writing should be replaced with the writing of existent time data.

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• Day-of-week Counter (Address 3h)

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
|----|----|----|----|----|------------|------------|------------|---------------------|
| - | - | - | - | - | W4 | W2 | W1 | (For Writing) |
| 0 | 0 | 0 | 0 | 0 | W4 | | | (For Reading) |
| 0 | 0 | 0 | 0 | 0 | Indefinite | Indefinite | Indefinite | Default Settings *) |

*) Default settings: Default value means read / written values when the PON bit is set to "1" due to VDD power-on from 0 volts.

* The day-of-week counter is incremented by 1 when the day-of-week digits are carried to the day-of-month digits.

* Day-of-week display (incremented in septimal notation):

 $(W4, W2, W1) = (0, 0, 0) \rightarrow (0, 0, 1) \rightarrow \dots \rightarrow (1, 1, 0) \rightarrow (0, 0, 0)$

* Correspondences between days of the week and the day-of-week digits are user-definable (e.g. Sunday = 0, 0, 0)

* The writing of (1, 1, 1) to (W4, W2, W1) is prohibited except when days of the week are unused.

• Calendar Counter (Address 4-6h)

Day-of-month Counter (Address 4h)

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
|----|----|------------|------------|------------|------------|------------|------------|---------------------|
| - | - | D20 | D10 | D8 | D4 | D2 | D1 | (For Writing) |
| 0 | 0 | D20 | D10 | D8 | D4 | D2 | D1 | (For Reading) |
| 0 | 0 | Indefinite | Indefinite | Indefinite | Indefinite | Indefinite | Indefinite | Default Settings *) |

Month Counter + Century Bit (Address 5h)

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
|------------|----|----|------------|------------|------------|------------|------------|---------------------|
| 19/20 | - | - | MO10 | MO8 | MO4 | MO2 | MO1 | (For Writing) |
| 19/20 | 0 | 0 | MO10 | MO8 | MO4 | MO2 | MO1 | (For Reading) |
| Indefinite | 0 | 0 | Indefinite | Indefinite | Indefinite | Indefinite | Indefinite | Default Settings *) |

Year Counter (Address 6h)

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
|------------|------------|------------|------------|------------|------------|------------|------------|---------------------|
| Y80 | Y40 | Y20 | Y10 | Y8 | Y4 | Y2 | Y1 | (For Writing) |
| Y80 | Y40 | Y20 | Y10 | ¥8 | Y4 | Y2 | Y1 | (For Reading) |
| Indefinite | Default Settings *) |

*) Default settings: Default value means read / written values when the PON bit is set to "1" due to VDD power-on from 0 volts.

* The calendar counters are configured to display the calendar digits in BCD format by using the automatic calendar function as follows:

The day-of-month digits (D20 to D1) range from 1 to 31 for January, March, May, July, August, October, and December; from 1 to 30 for April, June, September, and November; from 1 to 29 for February in leap years; from 1 to 28 for February in ordinary years. The day-of-month digits are carried to the month digits in reversion from the last day of the month to 1. The month digits (MO10 to MO1) range from 1 to 12 and are carried to the year digits in reversion from 12 to 1.

The year digits (Y80 to Y1) range from 00 to 99 (00, 04, 08, ..., 92, and 96 in leap years) and are carried

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to the $\overline{19}/20$ digits in reversion from 99 to 00.

The $\overline{19}/20$ digits cycle between 0 and 1 in reversion from 99 to 00 in the year digits.

* Any carry from lower digits with the writing of non-existent calendar data may cause the calendar counters to malfunction. Therefore, such incorrect writing should be replaced with the writing of existent calendar data.

Oscillation Adjustment Register (Address 7h)

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
|-----|----|----|----|----|----|----|----|---------------------|
| DEV | F6 | F5 | F4 | F3 | F2 | F1 | F0 | (For Writing) |
| DEV | F6 | F5 | F4 | F3 | F2 | F1 | F0 | (For Reading) |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Default Settings *) |

*) Default settings: Default value means read / written values when the PON bit is set to "1" due to VDD power-on from 0 volts.

DEV bit

When DEV is set to 0, the Oscillation Adjustment Circuit operates 00, 20, 40 seconds.

When DEV is set to 1, the Oscillation Adjustment Circuit operates 00 seconds.

F6 to F0 bits

The Oscillation Adjustment Circuit is configured to change time counts of 1 second on the basis of the settings of the Oscillation Adjustment Register at the timing set by DEV.

- * The Oscillation Adjustment Circuit will not operate with the same timing (00, 20, or 40 seconds) as the timing of writing to the Oscillation Adjustment Register.
- The F6 bit setting of 0 causes an increment of time counts by ((F5, F4, F3, F2, F1, F0) 1) x 2.
 The F6 bit setting of 1 causes a decrement of time counts by ((F5, F4, F3, F2, F1, F0) + 1) x 2.
 The settings of "*, 0, 0, 0, 0, 0, 0, *" ("*" representing either "0" or "1") in the F6, F5, F4, F3, F2, F1, and F0 bits cause neither an increment nor decrement of time counts.

Example:

If (DEV, F6, F5, F4, F3, F2, F1, F0) is set to (0, 0, 0, 0, 0, 1, 1, 1), when the second digits read 00, 20, or

40, an increment of the current time counts of $32768 + (7 - 1) \times 2$ to 32780 (a current time count loss). If (DEV, F6, F5, F4, F3, F2, F1, F0) is set to (0, 0, 0, 0, 0, 0, 0, 1), when the second digits read 00, 20, 40, neither an increment nor a decrement of the current time counts of 32768.

If (DEV, F6, F5, F4, F3, F2, F1, F0) is set to (1, 1, 1, 1, 1, 1, 1, 0), when the second digits read 00, a decrement of the current time counts of 32768 + (- 2) x 2 to 32764 (a current time count gain).

An increase of two clock pulses once per 20 seconds causes a time count loss of approximately 3 ppm (2 / $(32768 \times 20 = 3.051 \text{ ppm})$. Conversely, a decrease of two clock pulses once per 20 seconds causes a time count gain of 3 ppm. Consequently, when DEV is set to "0", deviations in time counts can be corrected with a precision of ± 1.5 ppm. In the same way, when DEV is set to "1", deviations in time counts can be correct deviations in time counts and not the oscillation frequency of the 32.768-kHz clock pulses. For further details, see "P36 Configuration of Oscillation Circuit and Correction of Time Count Deviations

Oscillation Adjustment Circuit".

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Alarm_W Registers (Address 8-Ah)

Alarm_W Minute Register (Address 8h)

| | _ | | · · · · · · · · · · · · · · · · · · · | - / | | | | | |
|---|----|------------|---------------------------------------|------------|------------|------------|------------|------------|---------------------|
| | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
| ſ | - | WM40 | WM20 | WM10 | WM8 | WM4 | WM2 | WM1 | (For Writing) |
| ľ | 0 | WM40 | WM20 | WM10 | WM8 | WM4 | WM2 | WM1 | (For Reading) |
| | 0 | Indefinite | Indefinite | Indefinite | Indefinite | Indefinite | Indefinite | Indefinite | Default Settings *) |

Alarm_W Hour Register (Address 9h)

| | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
|---|----|----|------------|------------|------------|------------|------------|------------|---------------------|
| Ī | - | - | WH20 | WH10 | WH8 | WH4 | WH2 | WH1 | (For Writing) |
| | | | WP/A | | | | | | |
| | 0 | 0 | WH20 | WH10 | WH8 | WH4 | WH2 | WH1 | (For Reading) |
| | | | WP/Ā | | | | | | |
| ĺ | 0 | 0 | Indefinite | Indefinite | Indefinite | Indefinite | Indefinite | Indefinite | Default Settings *) |

Alarm_W Day-of-week Register (Address Ah)

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
|----|------------|------------|------------|------------|------------|------------|------------|----------|
| - | WW6 | WW5 | WW4 | WW3 | WW2 | WW1 | WW0 | (For Wri |
| 0 | WW6 | WW5 | WW4 | WW3 | WW2 | WW1 | WW0 | (For Rea |
| 0 | Indefinite | Default |

or Writing) or Reading) efault Settings *)

*) Default settings: Default value means read / written values when the PON bit is set to "1" due to VDD power-on from 0 volts.

* The D5 bit of the Alarm_W Hour Register represents WP/ \overline{A} when the 12-hour mode is selected (0 for a.m. and 1 for p.m.) and WH20 when the 24-hour mode is selected (tens in the hour digits).

* The Alarm_W Registers should not have any non-existent alarm time settings.

(Note that any mismatch between current time and preset alarm time specified by the Alarm_W registers may disable the alarm interrupt circuit.)

* When the 12-hour mode is selected, the hour digits read 12 and 32 for 0 a.m. and 0 p.m., respectively. (See "P17 •Control Register 1 (ADDRESS Eh) (2) $\frac{12}{12}/24$: $\frac{12}{12}/24$ -hour Mode Selection Bit")

* WW0 to WW6 correspond to W4, W2, and W1 of the day-of-week counter with settings ranging from (0, 0, 0) to (1, 1, 0).

* WW0 to WW6 with respective settings of 0 disable the outputs of the Alarm_W Registers.

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Example of Alarm Time Setting

| Alarm | Day-of-week | | | | | 12-hour mode | | | 24-hour mode | | | | | | |
|-------------------------|-------------|------|------|------|-----|--------------|------|-----|--------------|------|------|-----|-----|------|------|
| Preset alarm time | Sun. | Mon. | Tue. | Wed. | Th. | Fri. | Sat. | 10 | 1 | 10 | 1 | 10 | 1 | 10 | 1 |
| | | - | | | - | - | | hr. | hr. | min. | min. | hr. | hr. | min. | min. |
| | WW0 | WW1 | WW2 | WW3 | WW4 | WW5 | WW6 | | | | ! | | | ! | ! |
| 00:00 a.m. on all days | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 2 | 0 | 0 | 0 | 0 | 0 | 0 |
| 01:30 a.m. on all days | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 3 | 0 | 0 | 1 | 3 | 0 |
| 11:59 a.m. on all days | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 5 | 9 | 1 | 1 | 5 | 9 |
| 00:00 p.m. on Mon. to | 0 | 1 | 1 | 1 | 1 | 1 | 0 | 3 | 2 | 0 | 0 | 1 | 2 | 0 | 0 |
| Fri. | | | | | | | | | : | : | : | | : | : | 1 |
| 01:30 p.m. on Sun. | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 2 | 1 | 3 | 0 | 1 | 3 | 3 | 0 |
| 11:59 p.m. | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 3 | 1 | 5 | 9 | 2 | 3 | 5 | 9 |
| on Mon. ,Wed., and Fri. | | | : | | : | | | | | | 1 | | | 1 | : |

Note that the correspondence between WW0 to WW6 and the days of the week shown in the above table is only an example and not mandatory.

• Alarm_D Register (Address B-Ch)

Alarm_D Minute Register (Address Bh)

| | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
|---|----|------------|------------|------------|------------|------------|------------|------------|---------------------|
| Ī | - | DM40 | DM20 | DM10 | DM8 | DM4 | DM2 | DM1 | (For Writing) |
| ĺ | 0 | DM40 | DM20 | DM10 | DM8 | DM4 | DM2 | DM1 | (For Reading) |
| | 0 | Indefinite | Default Settings *) |

Alarm_D Hour Register (Address Ch)

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | _ |
|----|----|------------|------------|------------|------------|------------|------------|---------------------|
| - | - | DH20 | DH10 | DH8 | DH4 | DH2 | DH1 | (For Writing) |
| | | DP/Ā | | | | | | |
| 0 | 0 | DH20 | DH10 | DH8 | DH4 | DH2 | DH1 | (For Reading) |
| | | DP/A | | | | | | |
| 0 | 0 | Indefinite | Indefinite | Indefinite | Indefinite | Indefinite | Indefinite | Default Settings *) |

*) Default settings: Default value means read / written values when the PON bit is set to "1" due to VDD power-on from 0 volts.

* The D5 bit represents DP/ \overline{A} when the 12-hour mode is selected (0 for a.m. and 1 for p.m.) and DH20 when the 24-hour mode is selected (tens in the hour digits).

* The Alarm_D registers should not have any non-existent alarm time settings.
 (Note that any mismatch between current time and preset alarm time specified by the Alarm_D registers may disable the alarm interrupt circuit.)

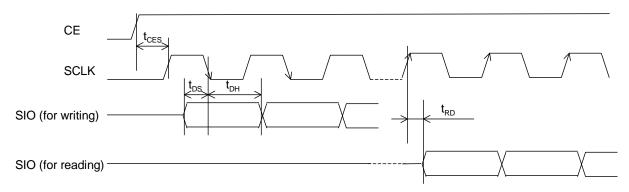
* When the 12-hour mode is selected, the hour digits read 12 and 32 for 0a.m. and 0p.m., respectively. (See "P17 •Control Register 1 (ADDRESS Eh) (2) 12/24: 12/24-hour Mode Selection Bit")

Interfacing with the CPU

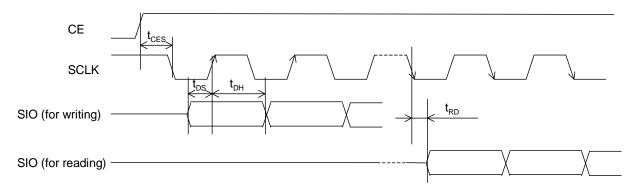
• DATA TRANSFER FORMATS

(1) Timing between CE Pin Transition and Data Input / Output

The R2061x adopts a 3-wire serial interface by which they use the CE (Chip Enable), SCLK (Serial Clock), and SIO (Serial Input/Output) pins to receive and send data to and from the CPU. The 3-wire serial interface provides two types of input/output timings with which the SIO pin output and input are synchronized with the rising or falling edges of the SCLK pin input, respectively, and vice versa. The R2061x is configured to select either one of two different input/output timings depending on the level of the SCLK pin in the low to high transition of the CE pin. Namely, when the SCLK pin is held low in the low to high transition of the CE pin, the models will select the timing with which the SIO pin output is synchronized with the rising edge of the SCLK pin input, and the input is synchronized with the falling edge of the SCLK pin input, as illustrated in the timing chart below.



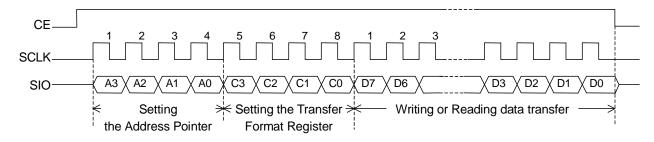
Conversely, when the SCLK pin is held high in the low to high transition of the CE pin, the models will select the timing with which the SIO pin output is synchronized with the falling edge of the SCLK pin input, and the input is synchronized with the rising edge of the SCLK pin input, as illustrated in the timing chart below.



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(2) Data Transfer Formats

Data transfer is commenced in the low to high transition of the CE pin input and completed in its high to low transition. Data transfer is conducted serially in multiple units of 1 byte (8 bits). The former 4 bits are used to specify in the Address Pointer a head address with which data transfer is to be commenced from the host. The latter 4 bits are used to select either reading data transfer or writing data transfer, and to set the Transfer Format Register to specify an appropriate data transfer format. All data transfer formats are designed to transfer the most significant bit (MSB) first.



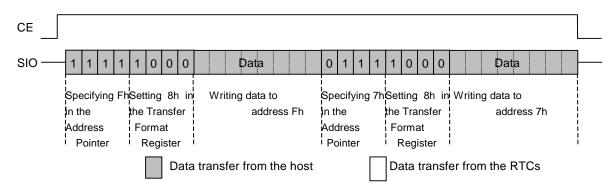
Two types of data transfer formats are available for reading data transfer and writing data transfer each.

• Writing Data Transfer Formats

(1) 1-byte Writing Data Transfer Format

The first type of writing data transfer format is designed to transfer 1-byte data at a time and can be selected by specifying in the address pointer a head address with which writing data transfer is to be commenced and then writing the setting of 8h to the transfer format register. This 1-byte writing data transfer can be completed by driving the CE pin low or continued by specifying a new head address in the address pointer and setting the data transfer format.

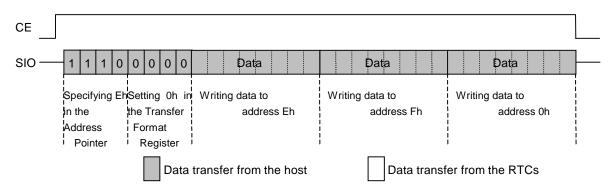
Example of 1-byte Writing Data Transfer (For Writing Data to Addresses Fh and 7h)



(2) Burst Writing Data Transfer Format

The second type of writing data transfer format is designed to transfer a sequence of data serially and can be selected by specifying in the address pointer a head address with which writing data transfer is to be commenced and then writing the setting of 0h to the transfer format register. The address pointer is incremented for each transfer of 1-byte data and cycled from Fh to 0h. This burst writing data transfer can be completed by driving the CE pin low.

Example of Burst Writing Data Transfer (For Writing Data to Addresses Eh, Fh, and 0h)

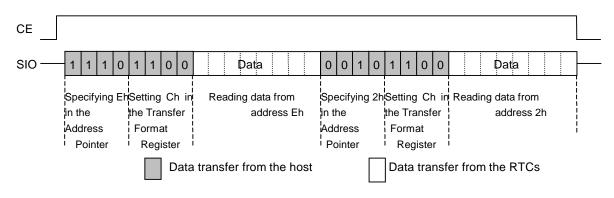


• Reading Data Transfer Formats

(1) 1-byte Reading Data Transfer Format

The first type of reading data transfer format is designed to transfer 1-byte data at a time and can be selected by specifying in the Address Pointer a head address with which reading data transfer is to be commenced and then the setting of writing Ch to the Transfer Format Register. This 1-byte reading data transfer can be completed by driving the CE pin low or continued by specifying a new head address in the Address Pointer and selecting this type of reading data Transfer Format.

Example of 1-byte Reading Data Transfer (For Reading Data from Addresses Eh and 2h)

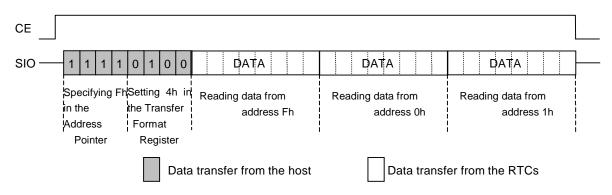


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(2) Burst Reading Data Transfer Format

The second type of reading data transfer format is designed to transfer a sequence of data serially and can be selected by specifying in the address pointer a head address with which reading data transfer is to be commenced and then writing the setting of 4h to the transfer format register. The address pointer is incremented for each transfer of 1-byte data and cycled from Fh to 0h. This burst reading data transfer can be completed by driving the CE pin low.

Example of Burst Reading Data Transfer (For Reading Data from Addresses Fh, 0h, and 1h)

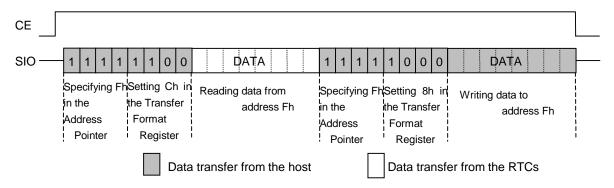


(3) Combination of 1-byte Reading and writing Data Transfer Formats

The 1-byte reading and writing data transfer formats can be combined together and further followed by any other data transfer format.

Example of Reading Modify Writing Data Transfer

(For Reading and Writing Data from and to Address Fh)



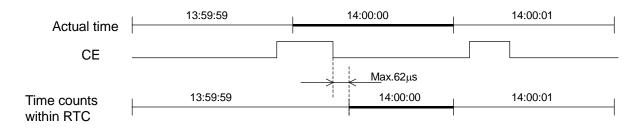
The reading and writing data transfer formats correspond to the settings in the transfer format register as shown in the table below.

| | 1 Byte | Burst |
|--------------|-----------|-----------|
| Writing data | 8h | 0h |
| transfer | (1,0,0,0) | (0,0,0,0) |
| Reading data | Ch | 4h |
| transfer | (1,1,0,0) | (0,1,0,0) |

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• Considerations in Reading and Writing Time Data under special condition

Any carry to the second digits in the process of reading or writing time data may cause reading or writing erroneous time data. For example, suppose a carry out of 13:59:59 into 14:00:00 occurs in the process of reading time data in the middle of shifting from the minute digits to the hour digits. At this moment, the second digits, the minute digits, and the hour digits read 59 seconds, 59 minutes, and 14 hours, respectively (indicating 14:59:59) to cause the reading of time data deviating from actual time virtually 1 hour. A similar error also occurs in writing time data. To prevent such errors in reading and writing time data, the R2061x has the function of temporarily locking any carry to the second digits during the high interval of the CE pin and unlocking such a carry in its high to low transition. Note that a carry to the second digits can be locked for only 1 second, during which time the CE pin should be driven low.



The effective use of this function requires the following considerations in reading and writing time data:

- (1) Hold the CE pin high in each session of reading or writing time data.
- (2) Ensure that the high interval of the CE pin lasts within 1 second. Should there be any possibility of the host going down in the process of reading or writing time data, make arrangements in the peripheral circuitry as to drive the CE pin low or open at the moment that the host actually goes down.
- (3) Leave a time span of 31µs or more from the low to high transition of the CE pin to the start of access to addresses 0h to 6h in order that any ongoing carry of the time digits may be completed within this time span. For further details, see the next page.
- (4) Leave a time span of 62µs or more from the high to low transition of the CE pin to its low to high transition in order that any ongoing carry of the time digits during the high interval of the CE pin may be adjusted within this time span.

The considerations listed in (1), (3), and (4) above are not required when the process of reading or writing time data is obviously free from any carry of the time digits.

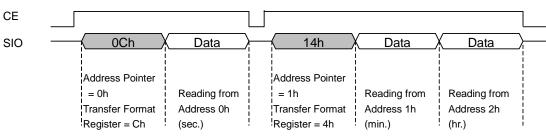
(e.g. reading or writing time data in synchronization with the periodic interrupt function in the level mode or the alarm interrupt function).

Bad examples of reading and writing time data are illustrated on the next page.

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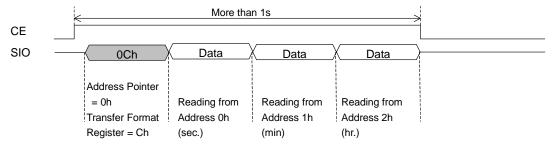
Bad Example (1)

Where the CE pin is once driven low in the process of reading time data



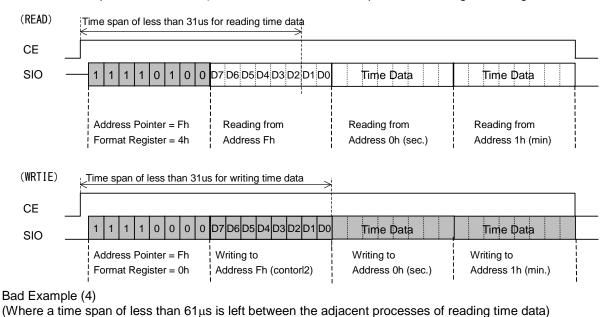
Bad Example (2)

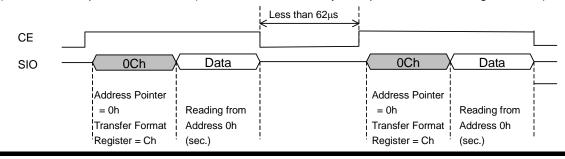
The high interval of the CE pin is more than 1sec.



Bad Example (3)

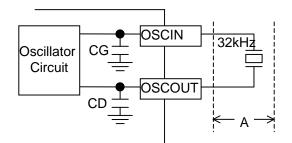
Where a time span of less than 31 µs is left until the start of the process of writing or reading time data





Configuration of Oscillation Circuit and Correction of Time Count Deviations

• Configuration of Oscillation Circuit



Typical externally-equipped element X'tal : 32.768kHz (R1=30kΩ typ) (CL=6pF to 8pF) Standard values of internal elements CG,CD 10pF typ

The oscillation circuit is driven at a constant voltage of approximately 1.2 volts relative to the level of the VSS pin input. As such, it is configured to generate an oscillating waveform with a peak-to-peak voltage on the order of 1.2 volts on the positive side of the VSS pin input.

< Considerations in Handling Quartz Crystal Units >

Generally, quartz crystal units have basic characteristics including an equivalent series resistance (R1) indicating the ease of their oscillation and a load capacitance (CL) indicating the degree of their center frequency. Particularly, quartz crystal units intended for use in the R2061x are recommended to have a typical R1 value of $30k\Omega$ and a typical CL value of 6 to 8pF. To confirm these recommended values, contact the manufacturers of quartz crystal units intended for use in these particular models.

< Considerations in Installing Components around the Oscillation Circuit >

1) Install the quartz crystal unit in the closest possible vicinity to the real-time clock ICs.

2) Avoid laying any signal lines or power lines in the vicinity of the oscillation circuit (particularly in the area marked "A" in the above figure).

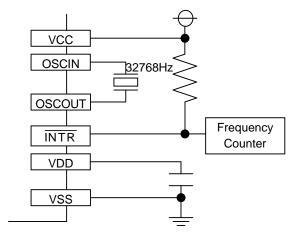
- 3) Apply the highest possible insulation resistance between the OSCIN and OSCOUT pins and the printed circuit board.
- 4) Avoid using any long parallel lines to wire the OSCIN and OSCOUT pins.
- 5) Take extreme care not to cause condensation, which leads to various problems such as oscillation halt.

< Other Relevant Considerations >

- 1) We cannot recommend connecting the external input of 32.768-kHz clock pulses to the OSCIN pin.
- 2) To maintain stable characteristics of the quartz crystal unit, avoid driving any other IC through 32.768-kHz clock pulses output from the OSCOUT pin.

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Measurement of Oscillation Frequency



- * 1) The R2061x is configured to generate 1Hz clock pulses for output from the INTR pin by setting (00XX0011) at address Eh.
- * 2) A frequency counter with 6 (more preferably 7) or more digits on the order of 1ppm is recommended for use in the measurement of the oscillation frequency of the oscillation circuit.

Adjustment of Oscillation frequency

The oscillation frequency of the oscillation circuit can be adjusted by varying procedures depending on the usage of Model R2061x in the system into which they are to be built and on the allowable degree of time count errors.

Course (A)

When the time count precision of each RTC is not to be adjusted, the quartz crystal unit intended for use in that RTC may have any CL value requiring no presetting. The quartz crystal unit may be subject to frequency variations which are selectable within the allowable range of time count precision. Several quartz crystal units and RTCs should be used to find the center frequency of the quartz crystal units by the method described in "P34 • Measurement of Oscillation Frequency" and then calculate an appropriate oscillation adjustment value by the method described in "P36 • Oscillation Adjustment Circuit" for writing this value to the R206x1.

Course (B)

When the time count precision of each RTC is to be adjusted within the oscillation frequency variations of the quartz crystal unit plus the frequency variations of the real-time clock ICs, it becomes necessary to correct deviations in the time count of each RTC by the method described in " P36 • Oscillation Adjustment Circuit". Such oscillation adjustment provides quartz crystal units with a wider range of allowable settings of their oscillation frequency variations and their CL values. The real-time clock IC and the quartz crystal unit intended for use in that real-time clock IC should be used to find the center frequency of the quartz crystal unit by the method described in " P34 • Measurement of Oscillation Frequency" and then confirm the center frequency thus found to fall within the range adjustable by the oscillation adjustment circuit before adjusting the oscillation frequency of the oscillation frequency is to approximately ± 0.5 ppm.

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- * 1) Generally, quartz crystal units for commercial use are classified in terms of their center frequency depending on their load capacitance (CL) and further divided into ranks on the order of ±10, ±20, and ±50ppm depending on the degree of their oscillation frequency variations.
- * 2) Basically, Model R2061x is configured to cause frequency variations on the order of ±5 to ±10ppm at 25°C.
- * 3) Time count precision as referred to in the above flow chart is applicable to normal temperature and actually affected by the temperature characteristics and other properties of quartz crystal units.

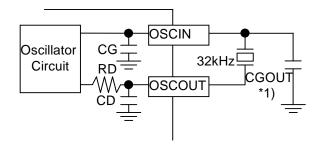
The R2061x, which incorporate the CG and the CD, require adjusting the oscillation frequency of the quartz crystal unit through its CL value.

Generally, the relationship between the CL value and the CG and CD values can be represented by the following equation:

 $CL = (CG \times CD)/(CG + CD) + CS$ where "CS" represents the floating capacity of the printed circuit board.

The quartz crystal unit intended for use in the R2061x is recommended to have the CL value on the order of 6 to 8pF. Its oscillation frequency should be measured by the method described in " P34 • Measurement of Oscillation Frequency". Any quartz crystal unit found to have an excessively high or low oscillation frequency (causing a time count gain or loss, respectively) should be replaced with another one having a smaller and greater CL value, respectively until another one having an optimum CL value is selected. In this case, the bit settings disabling the oscillation adjustment circuit (see " P36 • Oscillation Adjustment Circuit ") should be written to the oscillation adjustment register.

Incidentally, the high oscillation frequency of the quartz crystal unit can also be adjusted by adding an external oscillation stabilization capacitor CGOUT as illustrated in the diagram below.



*1) The CGOUT should have a capacitance ranging from 0 to 15 pF.

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Oscillation Adjustment Circuit

The oscillation adjustment circuit can be used to correct a time count gain or loss with high precision by varying the number of 1-second clock pulses once per 20 seconds or 60 seconds. When DEV bit in the Oscillation Adjustment Register is set to 0, R2061x varies number of 1-second clock pulses once per 20 seconds. When DEV bit is set to 1, R2061x varies number of 1-second clock pulses once per 60 seconds. The oscillation adjustment circuit can be disabled by writing the settings of "*, 0, 0, 0, 0, 0, 0, 0, *" ("*" representing "0" or "1") to the F6, F5, F4, F3, F2, F1, and F0 bits in the oscillation adjustment circuit. Conversely, when such oscillation adjustment is to be made, an appropriate oscillation adjustment value can be calculated by the equation below for writing to the oscillation adjustment circuit.

(1) When Oscillation Frequency (* 1) Is Higher Than Target Frequency (* 2) (Causing Time Count Gain) When DEV=0:

Oscillation adjustment value (*3) = (Oscillation frequency - Target Frequency + 0.1)Oscillation frequency $\times 3.051 \times 10^{-6}$ $\approx (Oscillation Frequency - Target Frequency) \times 10 + 1$ When DEV=1:

Oscillation adjustment value (*3) = (Oscillation frequency - Target Frequency + 0.0333) Oscillation frequency \times 1.017 \times 10⁻⁶ \approx (Oscillation Frequency - Target Frequency) \times 30 + 1

* 1) Oscillation frequency:

32768 times the frequency of 1Hz clock pulse output from the INTR pin at normal temperature in the manner described in " P34 • Measurement of Oscillation Frequency".

* 2) Target frequency:

Desired frequency to be set. Generally, a 32.768-kHz quartz crystal unit has such temperature characteristics as to have the highest oscillation frequency at normal temperature. Consequently, the quartz crystal unit is recommended to have target frequency settings on the order of 32.768 to 32.76810 kHz (+3.05ppm relative to 32.768 kHz). Note that the target frequency differs depending on the environment or location where the equipment incorporating the RTC is expected to be operated.

* 3) Oscillation adjustment value: Value that is to be finally written to the F0 to F6 bits in the Oscillation Adjustment Register and is represented in 7-bit coded decimal notation.

(2) When Oscillation Frequency Is Equal To Target Frequency (Causing Time Count neither Gain nor Loss) Oscillation adjustment value = 0, +1, -64, or -63

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(3) When Oscillation Frequency Is Lower Than Target Frequency (Causing Time Count Loss) When DEV=0:

Oscillation adjustment value = (Oscillation frequency - Target Frequency)Oscillation frequency $\times 3.051 \times 10^{-6}$ $\approx (Oscillation Frequency - Target Frequency) \times 10$ When DEV=1: Oscillation adjustment value = (Oscillation frequency - Target Frequency)

Oscillation frequency \times 1.017 \times 10⁻⁶

 \approx (Oscillation Frequency – Target Frequency) \times 30

Oscillation adjustment value calculations are exemplified below

(A) For an oscillation frequency = 32768.85Hz and a target frequency = 32768.05Hz When setting DEV bit to 0:

Oscillation adjustment value = (32768.85 - 32768.05 + 0.1) / (32768.85 × 3.051 × 10⁻⁶)

≈ (32768.85 - 32768.05) × 10 + 1

 $= 9.001 \approx 9$

In this instance, write the settings (DEV,F6,F5,F4,F3,F2,F1,F0)=(0,0,0,0,1,0,0,1) in the oscillation adjustment register. Thus, an appropriate oscillation adjustment value in the presence of any time count gain represents a distance from 01h.

When setting DEV bit to 1:

Oscillation adjustment value = $(32768.85 - 32768.05 + 0.0333) / (32768.85 \times 1.017 \times 10^{-6})$ $\approx (32768.85 - 32768.05) \times 30 + 1$ = 25.00 ≈ 25

In this instance, write the settings (DEV,F6,F5,F4,F3,F2,F1,F0)=(1,0,0,1,1,0,0,1) in the oscillation adjustment register.

(B) For an oscillation frequency = 32762.22Hz and a target frequency = 32768.05Hz

When setting DEV bit to 0:

Oscillation adjustment value = $(32762.22 - 32768.05) / (32762.22 \times 3.051 \times 10^{-6})$ $\approx (32762.22 - 32768.05) \times 10$ = -58.325 \approx -58

To represent an oscillation adjustment value of - 58 in 7-bit coded decimal notation, subtract 58 (3Ah) from 128 (80h) to obtain 46h. In this instance, write the settings of (DEV,F6,F5,F4,F3,F2,F1,F0) = (0,1,0,0,0,1,1,0) in the oscillation adjustment register. Thus, an appropriate oscillation adjustment value in the presence of any time count loss represents a distance from 80h.

When setting DEV bit to 1:

Oscillation adjustment value = $(32762.22 - 32768.05) / (32762.22 \times 1.017 \times 10^{-6})$ $\approx (32762.22 - 32768.05) \times 30$ = -174.97 \approx -175

Oscillation adjustment value can be set from -62 to 63. Then, in this case, Oscillation adjustment value is out of range.

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(4) Difference between DEV=0 and DEV=1

Difference between DEV=0 and DEV=1 is following,

| | DEV=0 DEV=1 | |
|---------------------|-----------------------|-----------------|
| Maximum value range | -189.2ppm to 189.2ppm | -62ppm to 63ppm |
| Minimum resolution | 3ppm | 1ppm |

Notes:

If following 3 conditions are completed, actual clock adjustment value could be different from target adjustment value that set by oscillator adjustment function.

- 1. Using oscillator adjustment function
- 2. Access to R2061x at random, or synchronized with external clock that has no relation to R2061x, or synchronized with periodic interrupt in pulse mode.
- 3. Access to R2061x more than 2 times per each second on average.

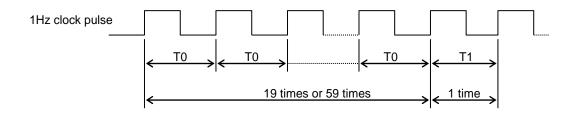
For more details, please contact to Ricoh.

• How to evaluate the clock gain or loss

The oscillator adjustment circuit is configured to change time counts of 1 second on the basis of the settings of the oscillation adjustment register once in 20 seconds or 60 seconds. The way to measure the clock error as follows:

(1) Output a 1Hz clock pulse of Pulse Mode with interrupt pin Set (0,0,x,x,0,0,1,1) to Control Register 1 at address Eh.

(2) After setting the oscillation adjustment register, 1Hz clock period changes every 20seconds (or every 60 seconds) like next page figure.



Measure the interval of T0 and T1 with frequency counter. A frequency counter with 7 or more digits is recommended for the measurement.

(3) Calculate the typical period from T0 and T1 When DEV=0: T = $(19\timesT0+1\timesT1)/20$ When DEV=1: T = $(59\timesT0+1\timesT1)/60$ Calculate the time error from T.

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Power-on Reset, Oscillation Halt Sensing, and Supply Voltage Monitoring

• PON, XST, and VDET

The power-on reset circuit is configured to reset control register1, 2, and clock adjustment register when VDD power up from 0v. The oscillation halt sensing circuit is configured to record a halt on oscillation by 32.768-kHz clock pulses. The supply voltage monitoring circuit is configured to record a drop in supply voltage below a threshold voltage of 2.1 or 1.35v.

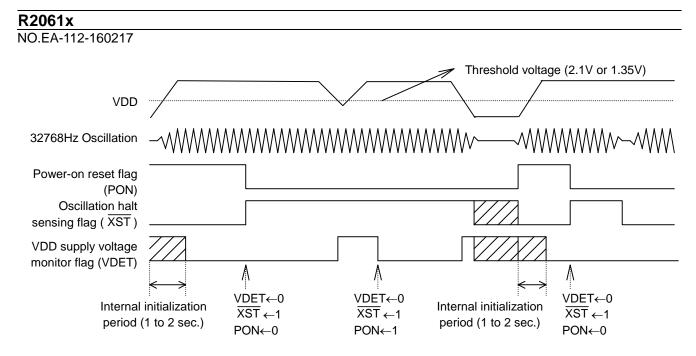
Each function has a monitor bit. I.e. the PON bit is for the power-on reset circuit, and \overline{XSI} bit is for the oscillation halt sensing circuit, and VDET is for the supply voltage monitoring circuit. PON and VDET bits are activated to "H". However, \overline{XSI} bit is activated to "L". The PON and VDET accept only the writing of 0, but \overline{XSI} accepts the writing of 0 and 1. The PON bit is set to 1, when VDD power-up from 0V, but VDET is set to 0, and \overline{XSI} is indefinite.

The functions of these three monitor bits are shown in the table below.

| | PON | प्रज | VDET |
|------------------------------|--|--|--|
| Function | Monitoring for the power- on reset function | Monitoring for the oscillation halt sensing function | a drop in supply voltage below a threshold voltage of 2.1 or 1.35v |
| Address | D4 in Address Fh | D5 in Address Fh | D6 in Address Fh |
| Activated | High | Low | High |
| When VDD power up from 0v | 1 | indefinite | 0 |
| accept the writing | 0 only | Both 0 and 1 | 0 only |

The relationship between the PON, \overline{XST} , and VDET is shown in the table below.

| PON | XST | VDET | Conditions of supply voltage and oscillation | Condition of oscillator, and back- up status |
|-----|-----|------|---|--|
| 0 | 0 | 0 | Halt on oscillation, but no drop in VDD supply voltage below threshold voltage | Halt on oscillation cause of condensation etc. |
| 0 | 0 | 1 | Halt on oscillation and drop in VDD supply voltage below threshold voltage, but no drop to 0V | Halt on oscillation cause of drop in back-up battery voltage |
| 0 | 1 | 0 | No drop in VDD supply voltage below threshold voltage and no halt in oscillation | Normal condition |
| 0 | 1 | 1 | Drop in VDD supply voltage below threshold voltage and no halt on oscillation | No halt on oscillation, but drop in back-up battery voltage |
| 1 | 0 | * | Drop in supply voltage to 0v | Power-up from 0v, |
| 1 | 1 | * | Instantaneous power-down | Time data is unreliable. |



When the PON bit is set to 1 in the control register 2, the DEV, F6 to F0, WALE, DALE, 12/24, SCRATCH2, TEST, CT2, CT1, CT0, VDSL, VDET, SCRATCH1, CTFG, WAFG, and DAFG bits are reset to 0 in the oscillation adjustment register, the control register 1, and the control register 2. The PON bit is also set to 1 at power-on from 0 volts.

< Considerations in Using Oscillation Halt Sensing Circuit >

Be sure to prevent the oscillation halt sensing circuit from malfunctioning by preventing the following:

- 1) Instantaneous power-down on the VDD
- 2) Condensation on the quartz crystal unit
- 3) On-board noise to the quartz crystal unit
- 4) Applying to individual pins voltage exceeding their respective maximum ratings

In particular, note that the \overline{XSI} bit may fail to be set to 0 in the presence of any applied supply voltage as illustrated below in such events as backup battery installation. Further, give special considerations to prevent excessive chattering in the oscillation halt sensing circuit.

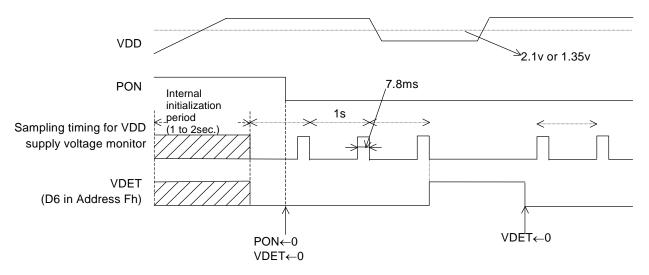
| VDD | |
|-----|--|
| | |

• Voltage Monitoring Circuit

R2061x incorporates two kinds of voltage monitoring function. These are shown in the table below.

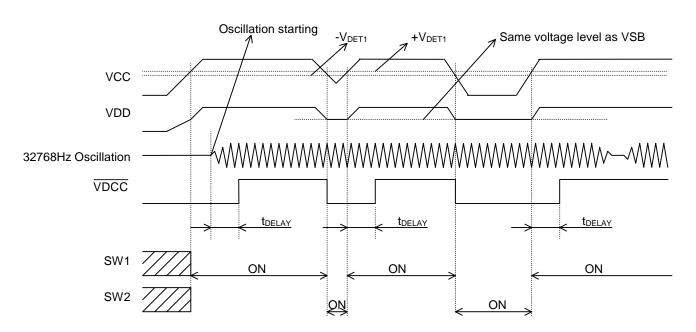
| | VCC Voltage Monitoring Circuit | VDD Voltage Monitoring Circuit (VDET) |
|---|---|---|
| Purpose | CPU reset output | Back-up battery checker |
| Monitoring supply voltage | VCC pin | VDD pin (supply voltage for the internal RTC circuit) |
| Output for result | VDCC pin | Store in the Control Register 2 (D6 in Address Fh) |
| Function | After falling VCC, VDCC outputs "L". tDEALY after rising VCC, VDCC outputs "H" (OFF) Below the threshold voltage, SW1 turns off and SW2 turns on. Over the threshold voltage, SW1 turns on and SW2 turns off. | |
| Detector Threshold (falling edge of power supply voltage) | -Vdet1 | Selecting from VDETH or VDETL by writing to the register (D7 in Address Fh) |
| Detector Released Voltage (rising edge of power supply voltage) | +Vdet1 | Same as falling edge (No hysteresis) |
| The way to monitor | Always | One time every second |

The VDD supply voltage monitoring circuit is configured to conduct a sampling operation during an interval of 7.8ms per second to check for a drop in supply voltage below a threshold voltage of 2.1 or 1.35v for the VDSL bit setting of 0 (the default setting) or 1, respectively, in the Control Register 2, thus minimizing supply current requirements as illustrated in the timing chart below. This circuit suspends a sampling operation once the VDET bit is set to 1 in the Control Register 2. The VDD supply voltage monitor is useful for back-up battery checking.



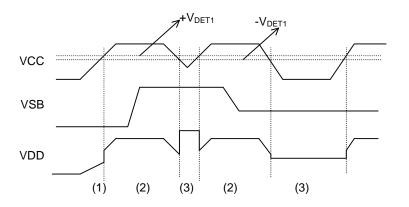
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The VCC supply voltage monitor circuit operates always. When VCC rising over +V_{DET1}, SW1 turns on, and SW2 turns off. And t_{DELAY} after rising VCC, \overline{VDCC} outputs OFF(H). But when oscillation is halt, VCC outputs OFF(H) t_{DELAY} after oscillation starting. When VCC falling beyond -V_{DET1}, SW1 turns off, and SW2 turns on. And \overline{VDCC} outputs "L".



Battery Switch over Circuit

R2061x incorporates three power supply pins, VDD, VCC, and VSB. VDD pin is the power supply pin for internal real time clock circuit. When VCC voltage is lower than $\pm V_{DET1}$, VSB supplies the power to VDD, and when higher than $\pm V_{DET1}$, VCC supplies the power to VDD. The timing chart for VCC, VDD, and VSB is shown following.



- (1) When VSB is 0v and VCC is rising from 0v, VDD follows half of VCC voltage level. After VCC rising over +V_{DET1}, VDD follows VCC voltage level.
- (2) When VCC is higher than $+V_{DET1}$, VDD level is equal to VCC.
- (3) After VCC falling beyond –VDET1, VDD level is equal to VSB.

<Instructions on VSB power-on operation>

To initialize the internal circuit, supply power (+V_{DET1} or more) to the VCC pin while the VSB pin is connected to the power source (Battery). If this initialization is not performed, leakage current may flow into the VSB pin.

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Alarm and Periodic Interrupt

The R2061x incorporates the alarm interrupt circuit and the periodic interrupt circuit that are configured to generate alarm signals and periodic interrupt signals for output from the \overline{INTR} pin as described below.

(1) Alarm Interrupt Circuit

The alarm interrupt circuit is configured to generate alarm signals for output from the INTR, which is driven low (enabled) upon the occurrence of a match between current time read by the time counters (the day-of-week, hour, and minute counters) and alarm time preset by the alarm registers (the Alarm_W registers intended for the day-of-week, hour, and minute digit settings and the Alarm_D registers intended for the hour and minute digit settings).

(2) Periodic Interrupt Circuit

The periodic interrupt circuit is configured to generate either clock pulses in the pulse mode or interrupt signals in the level mode for output from the \overline{INTR} pin depending on the CT2, CT1, and CT0 bit settings in the control register 1.

The above two types of interrupt signals are monitored by the flag bits (i.e. the WAFG, DAFG, and CTFG bits in the Control Register 2) and enabled or disabled by the enable bits (i.e. the WALE, DALE, CT2, CT1, and CT0 bits in the Control Register 1) as listed in the table below.

| | Flag bits | Enable bits |
|-------------------|--------------------|---|
| Alarm_W | WAFG | WALE |
| | (D1 at Address Fh) | (D7 at Address Eh) |
| Alarm_D | DAFG | DALE |
| | (D0 at Address Fh) | (D6 at Address Eh) |
| Peridic interrupt | CTFG | CT2=CT1=CT0=0 |
| | (D2 at Address Fh) | (These bit setting of "0" disable the Periodic Interrupt) |
| | | (D2 to D0 at Address Eh) |

* At power-on, when the WALE, DALE, CT2, CT1, and CT0 bits are set to 0 in the Control Register 1, the INTR pin is driven high (disabled).

* When two types of interrupt signals are output simultaneously from the INTR pin, the output from the INTR pin becomes an OR waveform of their negative logic.

| Example: Combined | Output to INTR Pin Under Control of |
|--------------------|-------------------------------------|
| Alarm_D | and Periodic Interrupt |
| | |
| Alarm_D | |
| Periodic Interrupt | |
| INTR | |

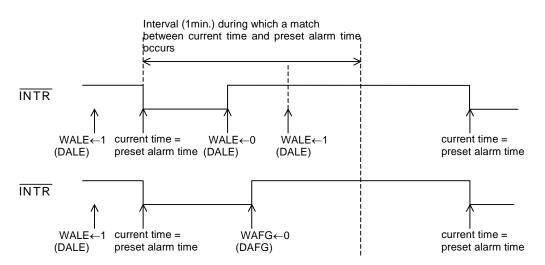
In this event, which type of interrupt signal is output from the \overline{INTR} pin can be confirmed by reading the DAFG, and CTFG bit settings in the Control Register 2.

Alarm Interrupt

The alarm interrupt circuit is controlled by the enable bits (i.e. the WALE and DALE bits in the Control Register 1) and the flag bits (i.e. the WAFG and DAFG bits in the Control Register 2). The enable bits can be used to enable this circuit when set to 1 and to disable it when set to 0. When intended for reading, the flag bits can be used to monitor alarm interrupt signals. When intended for writing, the flag bits will cause no event when set to 1 and will drive high (disable) the alarm interrupt circuit when set to 0.

The enable bits will not be affected even when the flag bits are set to 0. In this event, therefore, the alarm interrupt circuit will continue to function until it is driven low (enabled) upon the next occurrence of a match between current time and preset alarm time.

The alarm function can be set by presetting desired alarm time in the alarm registers (the Alarm_W Registers for the day-of-week digit settings and both the Alarm_W Registers and the Alarm_D Registers for the hour and minute digit settings) with the WALE and DALE bits once set to 0 and then to 1 in the Control Register 1. Note that the WALE and DALE bits should be once set to 0 in order to disable the alarm interrupt circuit upon the coincidental occurrence of a match between current time and preset alarm time in the process of setting the alarm function.



After setting WALE(DALW) to 0, Alarm registers is set to current time, and WALE(DALE) is set to 1, INTR will be not driven to "L" immediately, INTR will be driven to "L" at next alarm setting time.

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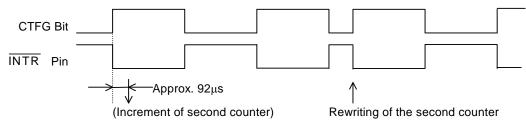
• Periodic Interrupt

Setting of the periodic selection bits (CT2 to CT0) enables periodic interrupt to the CPU. There are two waveform modes: pulse mode and level mode. In the pulse mode, the output has a waveform duty cycle of around 50%. In the level mode, the output is cyclically driven low and, when the CTFG bit is set to 0, the output is return to High (OFF).

| CT2 | CT1 | CT0 | Description | | |
|-----|-----|-----|-------------------|---|-----------|
| | | | Wave form mode | Interrupt Cycle and Falling Timing | |
| 0 | 0 | 0 | - | OFF(H) | (Default) |
| 0 | 0 | 1 | - | Fixed at "L" | |
| 0 | 1 | 0 | Pulse Mode *1) | 2Hz(Duty50%) | |
| 0 | 1 | 1 | Pulse Mode *1) | 1Hz(Duty50%) | |
| 1 | 0 | 0 | Level Mode *2) | Once per 1 second (Synchronized with Second counter increment) | |
| 1 | 0 | 1 | Level Mode *2) | Once per 1 minute (at 00 seconds of every Minute) | |
| 1 | 1 | 0 | Level Mode *2) | Once per hour (at 00 minutes and 00 Seconds of every hour) | |
| 1 | 1 | 1 | Level Mode *2) | Once per month (at 00 hours, 00 minutes, and 00 seconds of first day of every month) | |

*1) Pulse Mode:

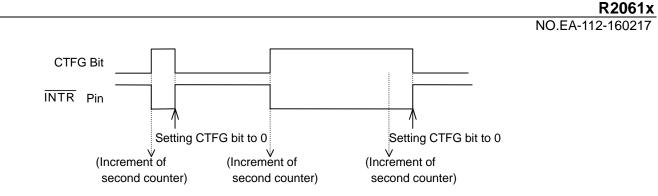
2-Hz and 1-Hz clock pulses are output in synchronization with the increment of the second counter as illustrated in the timing chart below.



In the pulse mode, the increment of the second counter is delayed by approximately 92 μ s from the falling edge of clock pulses. Consequently, time readings immediately after the falling edge of clock pulses may appear to lag behind the time counts of the real-time clocks by approximately 1 second. Rewriting the second counter will reset the other time counters of less than 1 second, driving the INTR pin low.

*2) Level Mode:

Periodic interrupt signals are output with selectable interrupt cycle settings of 1 second, 1 minute, 1 hour, and 1 month. The increment of the second counter is synchronized with the falling edge of periodic interrupt signals. For example, periodic interrupt signals with an interrupt cycle setting of 1 second are output in synchronization with the increment of the second counter as illustrated in the timing chart below.



*1), *2) When the oscillation adjustment circuit is used, the interrupt cycle will fluctuate once per 20sec. as follows:

Pulse Mode: The "L" period of output pulses will increment or decrement by a maximum of ± 3.784 ms. For example, 1-Hz clock pulses will have a duty cycle of 50 ± 0.3784 %.

Level Mode: A periodic interrupt cycle of 1 second will increment or decrement by a maximum of ±3.784ms.

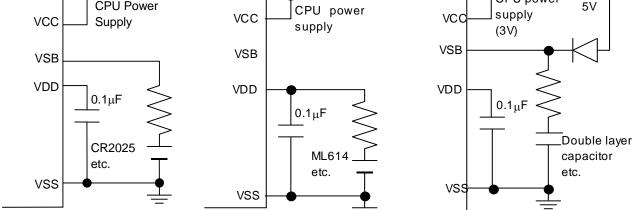
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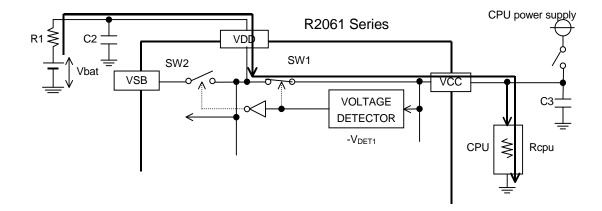
Typical Applications

• Typical Power Circuit Configurations

The case of back-up by primary battery (Charging voltage is equal to CPU power supply voltage) The case of back-up by capacitor or secondary battery (Charging voltage is equal to CPU power supply voltage) The case of back-up by capacitor or secondary battery (Charging voltage is not equal to CPU power supply voltage) CPU power Supply CPU power



VDD pin cannot be connected to any additional heavy load components such as SRAM. And VDD pin must be connected C2, and C2 should be over 0.1μ F.



When secondary battery or double layer capacitor connects to VDD pin, after CPU power supply turning off, secondary battery discharges through the root above figure. If R1 is much smaller than CPU impedance (Rcpu), VCC voltage keeps higher than -VDET1, and SW1 keeps on. Therefore R1 must be specified by following formula.

R1 > Rcpu x (Vbat - (-VDET1)) / (-VDET1)

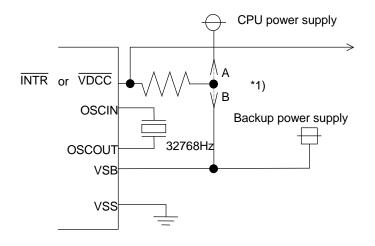
R1 is specified by back-up battery or double layer capacitor, too. Please check the data sheet for back-up devices.

• Connection of CIN pin

Please connect capacitor over $0.1 \mu F$ between CIN and VSS pin.

• Connection of $\overline{\text{INTR}}$ and $\overline{\text{VDCC}}$ Pin

The INTR and VDCC pins follow the N-channel open drain output logic and contains no protective diode on the power supply side. As such, it can be connected to a pull-up resistor of up to 5.5 volts regardless of supply voltage.

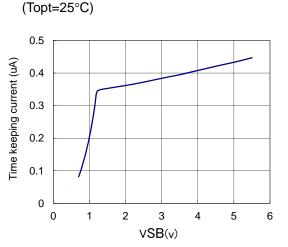


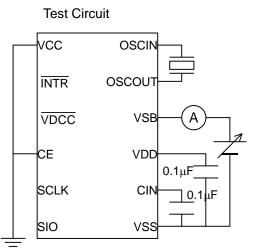
- *1) Depending on whether the INTR and VDCC pins are to be used during battery backup, it should be connected to a pull-up resistor at the following different positions:
- (1) Position A in the left diagram when it is not to be used during battery backup.
- (2) Position B in the left diagram when it is to be used during battery backup.

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Typical Characteristics

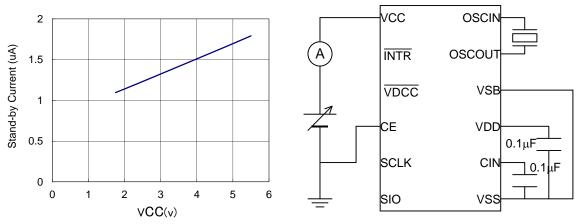
• Time keeping current (IsB) vs. Supply voltage (VsB)





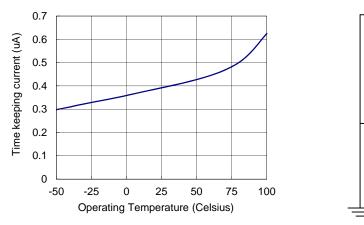
• Stand-by current (Icc) vs. Supply voltage (Vcc)

(Topt=25°C)



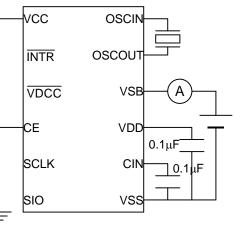
• Time keeping current (ISB) vs. Operating Temperature (Topt)

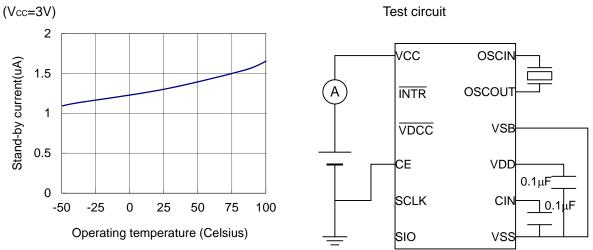




Test circuit

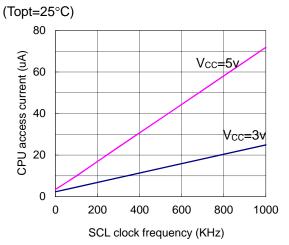
Test circuit



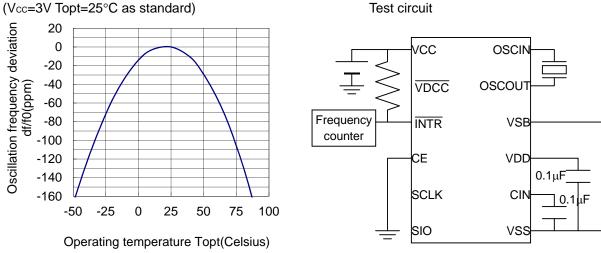


• Stand-by current (Icc) vs. Operating Temperature (Topt)

• CPU access current vs. SCLK clock frequency (kHz)



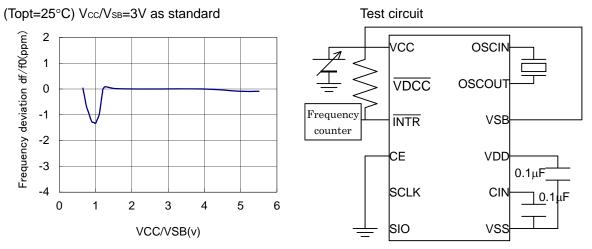
• Oscillation frequency deviation (∆f/f0) vs. Operating temperature (Topt)



Test circuit

NO.EA-112-160217

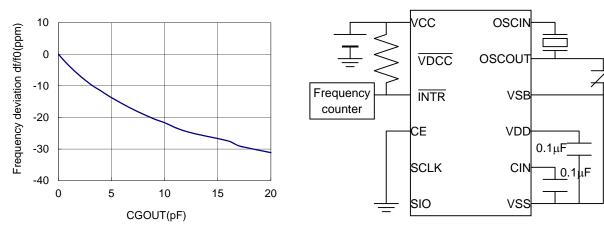
Frequency deviation (Δf/f0) vs. Supply voltage (VsB/Vcc)



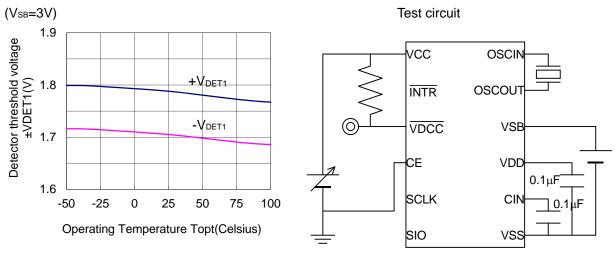
Frequency deviation (∆f/f0) vs. CGOUT

(Topt=25°C, Vcc=3V)CGOUT=0pF as standard



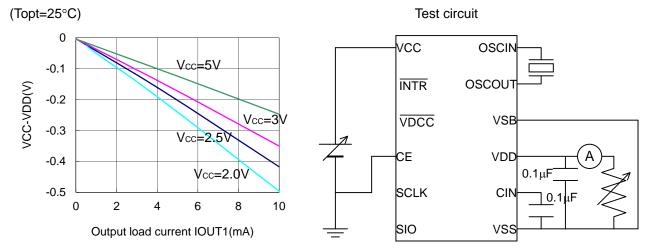


• Detector threshold voltage (+VDET1/-VDET1) vs. Operating temperature (Topt) (R2061K01, R2061L01)

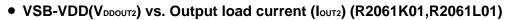


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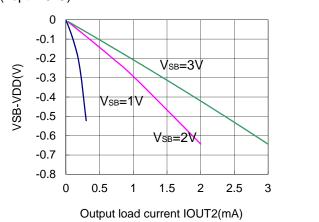
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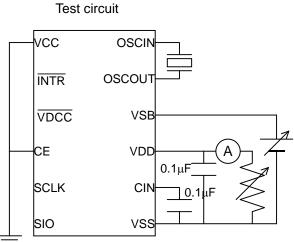


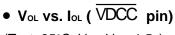
• VCC-VDD(VDDOUT1) vs. Output load current (IOUT1) (R2061K01,R2061L01)

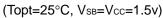


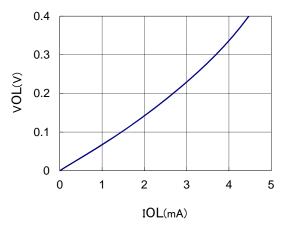
(Topt=25°C)

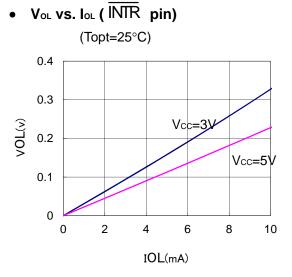










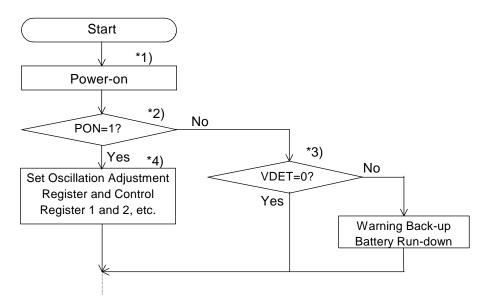


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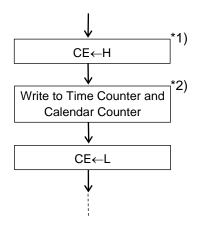
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Typical Software-based Operations

Initialization at Power-on



- *1) After power-on from 0 volt, the process of internal initialization require a time span on 1sec, so that access should be done after VDCC turning to OFF(H).
- *2) The PON bit setting of 0 in the Control Register 1 indicates power-on from backup battery and not from 0v. For further details, see "P.39 Power-on Reset, Oscillation Halt Sensing, and Supply Voltage Monitoring •PON, XST, and VDET ".
- *3) This step is not required when the supply voltage monitoring circuit is not used.
- *4) This step involves ordinary initialization including the Oscillation Adjustment Register and interrupt cycle settings, etc.
- Writing of Time and Calendar Data

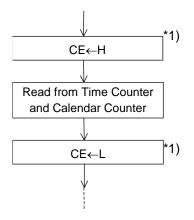


- *1) When writing to clock and calendar counters, do not insert CE=L until all times from second to year have been written to prevent error in writing time. (Detailed in "P.31
 •Considerations in Reading and Writing Time Data under special condition".
- *2) Any writing to the second counter will reset divider units lower than the second digits.

The R2061x may also be initialized not at power-on but in the process of writing time and calendar data.

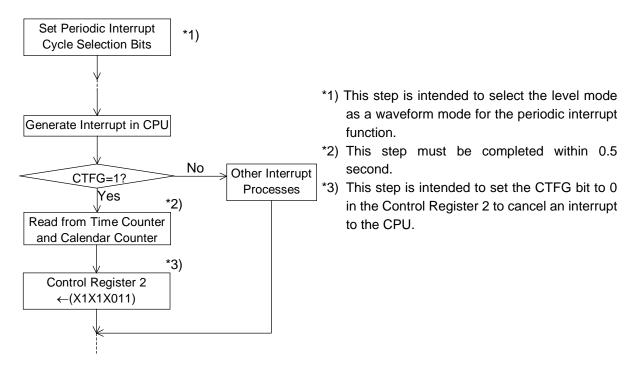
• Reading Time and Calendar Data

(1) Ordinary Process of Reading Time and Calendar Data



*1) When reading to clock and calendar counters, do not insert CE=L until all times from second to year have been read to prevent error in reading time. (Detailed in "P.31
•Considerations in Reading and Writing Time Data under special condition".

(2) Basic Process of Reading Time and Calendar Data with Periodic Interrupt Function

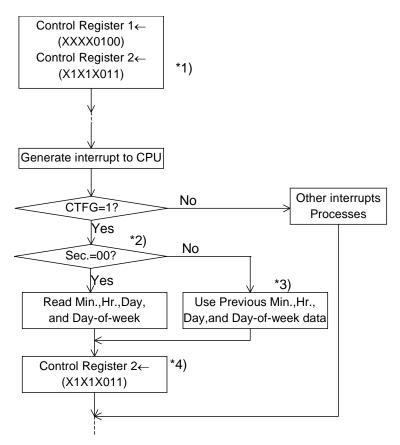


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(3) Applied Process of Reading Time and Calendar Data with Periodic Interrupt Function

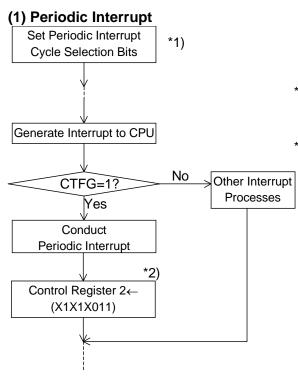
Time data need not be read from all the time counters when used for such ordinary purposes as time count indication. This applied process can be used to read time and calendar data with substantial reductions in the load involved in such reading.

For Time Indication in "Day-of-Month, Day-of-week, Hour, Minute, and Second" Format:



- *1) This step is intended to select the level mode as a waveform mode for the periodic interrupt function.
- *2) This step must be completed within 0.5 sec.
- *3) This step is intended to read time data from all the time counters only in the first session of reading time data after writing time data.
- *4) This step is intended to set the CTFG bit to 0 in the Control Register 2 to cancel an interrupt to the CPU.

Interrupt Process

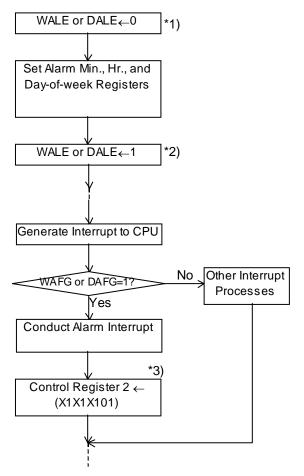


- *1) This step is intended to select the level mode as a waveform mode for the periodic interrupt function.
- *2) This step is intended to set the CTFG bit to 0 in the Control Register 2 to cancel an interrupt to the CPU.

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(2) Alarm Interrupt



- *1) This step is intended to once disable the alarm interrupt circuit by setting the WALE or DALE bits to 0 in anticipation of the coincidental occurrence of a match between current time and preset alarm time in the process of setting the alarm interrupt function.
- *2) This step is intended to enable the alarm interrupt function after completion of all alarm interrupt settings.
- *3) This step is intended to once cancel the alarm interrupt function by writing the settings of "X,1,X, 1,X,1,0,1" and "X,1,X,1,X,1,1,0" to the Alarm_W Registers and the Alarm_D Registers, respectively.

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Sales & Support Offices

RICOH ELECTRONIC DEVICES CO., LTD. Higashi-Shinagawa Office (International Sales) 3-32-3, Higashi-Shinagawa, Shinagawa-ku, Tokyo 140-8655, Japan Phone: +81-3-5479-2857 Fax: +81-3-5479-0502

RICOH EUROPE (NETHERLANDS) B.V. Semiconductor Support Centre Prof. W.H. Keesomlaan 1, 1183 DJ Amstelveen, The Netherlands Phone: +31-20-5474-309

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RICOH ELECTRONIC DEVICES KOREA CO., LTD. 3F, Haesung Bldg, 504, Teheran-ro, Gangnam-gu, Seoul, 135-725, Korea Phone: +82-2-2135-5700 Fax: +82-2-2051-5713

RICOH ELECTRONIC DEVICES SHANGHAI CO., LTD. ai 201203

Room 403, No.2 Building, No.690 Bibo Road, Pu Dong People's Republic of China Phone: +86-21-5027-3200 Fax: +86-21-5027-3299

RICOH ELECTRONIC DEVICES CO., LTD.

Taipei office Room 109, 10F-1, No.51, Hengyang Rd., Taipei City, Taiwan (R.O.C.) Phone: +886-2-2313-1621/1622 Fax: +886-2-2313-1623

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Общество с ограниченной ответственностью «МосЧип» ИНН 7719860671 / КПП 771901001 Адрес: 105318, г.Москва, ул.Щербаковская д.З, офис 1107

Данный компонент на территории Российской Федерации

Вы можете приобрести в компании MosChip.

Для оперативного оформления запроса Вам необходимо перейти по данной ссылке:

http://moschip.ru/get-element

Вы можете разместить у нас заказ для любого Вашего проекта, будь то серийное производство или разработка единичного прибора.

В нашем ассортименте представлены ведущие мировые производители активных и пассивных электронных компонентов.

Нашей специализацией является поставка электронной компонентной базы двойного назначения, продукции таких производителей как XILINX, Intel (ex.ALTERA), Vicor, Microchip, Texas Instruments, Analog Devices, Mini-Circuits, Amphenol, Glenair.

Сотрудничество с глобальными дистрибьюторами электронных компонентов, предоставляет возможность заказывать и получать с международных складов практически любой перечень компонентов в оптимальные для Вас сроки.

На всех этапах разработки и производства наши партнеры могут получить квалифицированную поддержку опытных инженеров.

Система менеджмента качества компании отвечает требованиям в соответствии с ГОСТ Р ИСО 9001, ГОСТ РВ 0015-002 и ЭС РД 009

Офис по работе с юридическими лицами:

105318, г.Москва, ул.Щербаковская д.3, офис 1107, 1118, ДЦ «Щербаковский»

Телефон: +7 495 668-12-70 (многоканальный)

Факс: +7 495 668-12-70 (доб.304)

E-mail: info@moschip.ru

Skype отдела продаж: moschip.ru moschip.ru_4

moschip.ru_6 moschip.ru_9