

# **[LM2576,](http://www.ti.com/product/lm2576?qgpn=lm2576) [LM2576HV](http://www.ti.com/product/lm2576hv?qgpn=lm2576hv)**

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**LM2576/LM2576HV Series SIMPLE SWITCHER® 3A Step-Down Voltage Regulator**

**Check for Samples: [LM2576,](http://www.ti.com/product/lm2576#samples) [LM2576HV](http://www.ti.com/product/lm2576hv#samples)**

- 
- 
- **• Specified 3A Output Current** version.
- 
- 
- **• 52 kHz Fixed Frequency Internal Oscillator**
- 
- 
- **• Uses Readily Available Standard Inductors** required.
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# **TYPICAL APPLICATION**

(Fixed Output Voltage Versions)

# **<sup>1</sup>FEATURES DESCRIPTION**

**<sup>23</sup>** The LM2576 series of regulators are monolithic **• 3.3V, 5V, 12V, 15V, and Adjustable Output Versions**<br>
integrated circuits that provide all the active functions<br>
for a step-down (buck) switching regulator, capable of<br>
driving 3A load with excellent line and load regulation **France Adjustable Version Output Voltage** driving 3A load with excellent line and load regulation.<br>**Range,1.23V to 37V (57V for HV Version) ±4% These devices are available in fixed output voltages Range,1.23V to 37V (57V for HV Version) ±4%** These devices are available in fixed output voltages **Max Over Line and Load Conditions** of 3.3V, 5V, 12V, 15V, and an adjustable output

**• Wide Input Voltage Range, 40V Up to 60V for** Requiring a minimum number of external components, these regulators are simple to use and include internal frequency compensation and a fixed- **• Requires Only 4 External Components** frequency oscillator.

• TTL Shutdown Capability, Low Power Standby<br>
Mode<br>
• High Efficiency<br>
1990 Mode<br>
1991 Mode<br>
1991 Mode<br>
1991 Mode<br>
1991 Mode<br>
1 **• High Efficiency** heat sink, and in some cases no heat sink is

**•• Thermal Shutdown and Current Limit** A standard series of inductors optimized for use with **Protection**<br>**••• Protection** and **Current Limit** A standard series of inductors optimized for use with **Protection Protection** the LM2576 are available from several different manufacturers. This feature greatly simplifies the **• P+ Product Enhancement Tested** design of switch-mode power supplies.

**APPLICATIONS** Other features include a specified  $\pm$ 4% tolerance on **Simple High-Efficiency Step-Down (Buck)** output voltage within specified input voltages and **• Dogulator** output load conditions, and **±10%** on the oscillator **output load conditions, and ±10% on the oscillator**<br>**Regulator for Linear Regulators** frequency. External shutdown is included, featuring<br>Fire included, featuring<br>Fig. u.A. (typical) standby current. The output switch **• Efficient Pre-Regulator for Linear Regulators** 50 μA (typical) standby current. The output switch **•• On-Card Switching Regulators includes** cycle-by-cycle current limiting, as well as **Positive to Negative Converter (Buck-Boost) • thermal shutdown for full protection under fault conditions.** 



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**INSTRUMENTS** 

Texas

### **Block Diagram**



 $3.3V$  R2 = 1.7k 5V, R2 = 3.1k 12V, R2 = 8.84k 15V, R2 = 11.3k For ADJ. Version  $R1 =$  Open,  $R2 = 0$ Patent Pending





These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

### **ABSOLUTE MAXIMUM RATINGS (1)(2)**



(1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but do not ensured specific performance limits. For ensured specifications and test conditions, see ELECTRICAL [CHARACTERISTICS](#page-5-0) ALL OUTPUT VOLTAGE VERSIONS.

(2) If Military/Aerospace specified devices are required, please contact the TI Sales Office/ Distributors for availability and specifications.

### **OPERATING RATINGS**



### **ELECTRICAL CHARACTERISTICS LM2576-3.3, LM2576HV-3.3**

Specifications with standard type face are for T<sub>J</sub> = 25°C, and those with **boldface type** apply over full Operating Temperature Range.



(1) All limits specified at room temperature (standard type face) and at temperature extremes (bold type face). All room temperature limits are 100% production tested. All limits at temperature extremes are specified via correlation using standard Statistical Quality Control (SQC) methods.

External components such as the catch diode, inductor, input and output capacitors can affect switching regulator system performance. When the LM2576/LM2576HV is used as shown in [Figure](#page-10-0) 21 and [Figure](#page-10-1) 22, system performance will be as shown in [ELECTRICAL](#page-5-0) [CHARACTERISTICS](#page-5-0) ALL OUTPUT VOLTAGE VERSIONS.



# **ELECTRICAL CHARACTERISTICS LM2576-5.0, LM2576HV-5.0**

Specifications with standard type face are for T<sub>J</sub> = 25°C, and those with [Figure](#page-10-1) 21 and Figure 22 **boldface type** apply over full Operating Temperature Range.



(1) All limits specified at room temperature (standard type face) and at temperature extremes (bold type face). All room temperature limits are 100% production tested. All limits at temperature extremes are specified via correlation using standard Statistical Quality Control (SQC) methods.

(2) External components such as the catch diode, inductor, input and output capacitors can affect switching regulator system performance. When the LM2576/LM2576HV is used as shown in [Figure](#page-10-0) 21 and [Figure](#page-10-1) 22, system performance will be as shown in [ELECTRICAL](#page-5-0) [CHARACTERISTICS](#page-5-0) ALL OUTPUT VOLTAGE VERSIONS.

## **ELECTRICAL CHARACTERISTICS LM2576-12, LM2576HV-12**

Specifications with standard type face are for T<sub>J</sub> = 25°C, and those with **boldface type** apply over full Operating Temperature Range.



(1) All limits specified at room temperature (standard type face) and at temperature extremes (bold type face). All room temperature limits are 100% production tested. All limits at temperature extremes are specified via correlation using standard Statistical Quality Control (SQC) methods.

(2) External components such as the catch diode, inductor, input and output capacitors can affect switching regulator system performance. When the LM2576/LM2576HV is used as shown in [Figure](#page-10-0) 21 and [Figure](#page-10-1) 22, system performance will be as shown in [ELECTRICAL](#page-5-0) [CHARACTERISTICS](#page-5-0) ALL OUTPUT VOLTAGE VERSIONS.



## **ELECTRICAL CHARACTERISTICS LM2576-15, LM2576HV-15**

Specifications with standard type face are for T<sub>J</sub> = 25°C, and those with **boldface type** apply over full Operating Temperature Range.



(1) All limits specified at room temperature (standard type face) and at temperature extremes (bold type face). All room temperature limits are 100% production tested. All limits at temperature extremes are specified via correlation using standard Statistical Quality Control (SQC) methods.

(2) External components such as the catch diode, inductor, input and output capacitors can affect switching regulator system performance. When the LM2576/LM2576HV is used as shown in [Figure](#page-10-0) 21 and [Figure](#page-10-1) 22, system performance will be as shown in [ELECTRICAL](#page-5-0) [CHARACTERISTICS](#page-5-0) ALL OUTPUT VOLTAGE VERSIONS.

## **ELECTRICAL CHARACTERISTICS LM2576-ADJ, LM2576HV-ADJ**

Specifications with standard type face are for T<sub>J</sub> = 25°C, and those with **boldface type** apply over full Operating Temperature Range.



(1) All limits specified at room temperature (standard type face) and at temperature extremes (bold type face). All room temperature limits are 100% production tested. All limits at temperature extremes are specified via correlation using standard Statistical Quality Control (SQC) methods.

(2) External components such as the catch diode, inductor, input and output capacitors can affect switching regulator system performance. When the LM2576/LM2576HV is used as shown in [Figure](#page-10-1) 21 and Figure 22, system performance will be as shown in [ELECTRICAL](#page-5-0) [CHARACTERISTICS](#page-5-0) ALL OUTPUT VOLTAGE VERSIONS.

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# <span id="page-5-0"></span>**ELECTRICAL CHARACTERISTICS ALL OUTPUT VOLTAGE VERSIONS**

Specifications with standard type face are for T<sub>J</sub> = 25°C, and those with **boldface type** apply over full Operating Temperature Range. Unless otherwise specified,  $V_{IN}$  = 12V for the 3.3V, 5V, and Adjustable version,  $V_{IN}$  = 25V for the 12V version, and  $V_{IN}$  $= 30V$  for the 15V version.  $I_{\text{LOAD}} = 500$  mA.



- (1) All limits specified at room temperature (standard type face) and at temperature extremes (bold type face). All room temperature limits are 100% production tested. All limits at temperature extremes are specified via correlation using standard Statistical Quality Control (SQC) methods.
- (2) The oscillator frequency reduces to approximately 11 kHz in the event of an output short or an overload which causes the regulated output voltage to drop approximately 40% from the nominal output voltage. This self protection feature lowers the average power dissipation of the IC by lowering the minimum duty cycle from 5% down to approximately 2%.
- (3) Output pin sourcing current. No diode, inductor or capacitor connected to output.
- (4) Feedback pin removed from output and connected to 0V.
- (5) Feedback pin removed from output and connected to +12V for the Adjustable, 3.3V, and 5V versions, and +25V for the 12V and 15V versions, to force the output transistor OFF.
- $V_{IN}$  = 40V (60V for high voltage version).
- (7) Junction to ambient thermal resistance (no external heat sink) for the 5 lead TO-220 package mounted vertically, with ½ inch leads in a socket, or on a PC board with minimum copper area.
- (8) Junction to ambient thermal resistance (no external heat sink) for the 5 lead TO-220 package mounted vertically, with ¼ inch leads soldered to a PC board containing approximately 4 square inches of copper area surrounding the leads.
- (9) If the DDPAK/TO-263 package is used, the thermal resistance can be reduced by increasing the PC board copper area thermally connected to the package. Using 0.5 square inches of copper area,  $\theta_{JA}$  is 50°C/W, with 1 square inch of copper area,  $\theta_{JA}$  is 37°C/W, and with 1.6 or more square inches of copper area,  $\theta_{JA}$  is 32°C/W.

<span id="page-6-0"></span>



(Circuit of [Figure](#page-10-0) 21 and [Figure](#page-10-1) 22)





**EXAS ISTRUMENTS** 

# **TYPICAL PERFORMANCE CHARACTERISTICS (continued)**

(Circuit of [Figure](#page-10-0) 21 and [Figure](#page-10-1) 22)





DUTY CYCLE (%)



## **TYPICAL PERFORMANCE CHARACTERISTICS (continued)**

(Circuit of [Figure](#page-10-0) 21 and [Figure](#page-10-1) 22)



JUNCTION TEMPERATURE (°C) **Figure 16. Figure 17.**

# **TYPICAL PERFORMANCE CHARACTERISTICS (continued)**



If the DDPAK/TO-263 package is used, the thermal resistance can be  $V_{OUT} = 15V$ <br>reduced by increasing the PC board conner area thermally connected. A: Output Pin Voltage, 50V/div reduced by increasing the PC board copper area thermally connected A: Output Pin Voltage, 50V/div<br>to the package, Using 0.5 square inches of copper area  $\theta_{16}$  is B: Output Pin Current, 2A/div to the package. Using 0.5 square inches of copper area,  $\theta_{JA}$  is  $B:$  Output Pin Current, 2A/div  $50^{\circ}$ C/W with 1 square inch of copper area,  $\theta_{JA}$  is 37°C/W and with C: Inductor Current, 2A/div 50°C/W, with 1 square inch of copper area,  $θ_{JA}$  is 37°C/W, and with C: Inductor Current, 2A/div 1.6 or more square inches of copper area,  $θ_{JA}$  is 32°C/W. D: Output Ripple Voltage, 50 mV/div, 1.6 or more square inches of copper area,  $\theta_{JA}$  is 32°C/W.





AC-Coupled **Horizontal Time Base: 5 μs/div Figure 18. Figure 19.**



**Figure 20.**

Texas **NSTRUMENTS** 



### **TEST CIRCUIT AND LAYOUT GUIDELINES**

As in any switching regulator, layout is very important. Rapidly switching currents associated with wiring inductance generate voltage transients which can cause problems. For minimal inductance and ground loops, the length of the leads indicated by heavy lines should be kept as short as possible. Single-point grounding (as indicated) or ground plane construction should be used for best results. When using the Adjustable version, physically locate the programming resistors near the regulator, to keep the sensitive feedback wiring short.



- $L_1$  100 µH, Pulse Eng. PE-92108
- $R_1 2k$ , 0.1%
- $R_2 6.12k$ , 0.1%



<span id="page-10-0"></span>

<span id="page-10-1"></span>



# **LM2576 Series Buck Regulator Design Procedure**





#### **INDUCTOR VALUE SELECTION GUIDES**

(For Continuous Mode Operation)

<span id="page-12-2"></span><span id="page-12-1"></span><span id="page-12-0"></span>

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**ISTRUMENTS** 

**EXAS** 

(For Continuous Mode Operation)







(For Continuous Mode Operation)

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To further simplify the buck regulator design procedure, TI is making available computer design software to be used with the SIMPLE SWITCHER line of switching regulators. **Switchers Made Simple** (Version 3.3) is available on a (3½*″*) diskette for IBM compatible computers from a TI office in your area.

**EXAS ISTRUMENTS** 

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### **Table 1. Diode Selection Guide**

<span id="page-15-0"></span>

### **Table 2. Inductor Selection by Manufacturer's Part Number**

<span id="page-15-1"></span>

(1) Schott Corporation, (612) 475-1173, 1000 Parkers Lake Road, Wayzata, MN 55391.

(2) Pulse Engineering, (619) 674-8100, P.O. Box 12235, San Diego, CA 92112.

(3) Renco Electronics Incorporated, (516) 586-5566, 60 Jeffryn Blvd. East, Deer Park, NY 11729.



# **APPLICATION HINTS**

# **INPUT CAPACITOR (CIN)**

To maintain stability, the regulator input pin must be bypassed with at least a 100 μF electrolytic capacitor. The capacitor's leads must be kept short, and located near the regulator.

If the operating temperature range includes temperatures below −25°C, the input capacitor value may need to be larger. With most electrolytic capacitors, the capacitance value decreases and the ESR increases with lower temperatures and age. Paralleling a ceramic or solid tantalum capacitor will increase the regulator stability at cold temperatures. For maximum capacitor operating lifetime, the capacitor's RMS ripple current rating should be greater than

1.2  $\times \left(\frac{\text{t}_{\text{ON}}}{T}\right) \times \text{I}_{\text{LOAD}}$ where  $\frac{t_{ON}}{T} = \frac{V_{OUT}}{V_{IN}}$  for a buck regulator and  $\frac{t_{ON}}{T} = \frac{|V_{OUT}|}{|V_{OUT}| + V_{IN}}$  for a buck-boost regulator.

(1)

# <span id="page-16-0"></span>**INDUCTOR SELECTION**

All switching regulators have two basic modes of operation: continuous and discontinuous. The difference between the two types relates to the inductor current, whether it is flowing continuously, or if it drops to zero for a period of time in the normal switching cycle. Each mode has distinctively different operating characteristics, which can affect the regulator performance and requirements.

The LM2576 (or any of the SIMPLE SWITCHER family) can be used for both continuous and discontinuous modes of operation.

The inductor value selection guides in [Figure](#page-12-0) 23 through [Figure](#page-12-2) 27 were designed for buck regulator designs of the continuous inductor current type. When using inductor values shown in the inductor selection guide, the peak-to-peak inductor ripple current will be approximately 20% to 30% of the maximum DC current. With relatively heavy load currents, the circuit operates in the continuous mode (inductor current always flowing), but under light load conditions, the circuit will be forced to the discontinuous mode (inductor current falls to zero for a period of time). This discontinuous mode of operation is perfectly acceptable. For light loads (less than approximately 300 mA) it may be desirable to operate the regulator in the discontinuous mode, primarily because of the lower inductor values required for the discontinuous mode.

The selection guide chooses inductor values suitable for continuous mode operation, but if the inductor value chosen is prohibitively high, the designer should investigate the possibility of discontinuous operation. The computer design software **Switchers Made Simple** will provide all component values for discontinuous (as well as continuous) mode of operation.

Inductors are available in different styles such as pot core, toriod, E-frame, bobbin core, and so on, as well as different core materials, such as ferrites and powdered iron. The least expensive, the bobbin core type, consists of wire wrapped on a ferrite rod core. This type of construction makes for an inexpensive inductor, but since the magnetic flux is not completely contained within the core, it generates more electromagnetic interference (EMI). This EMI can cause problems in sensitive circuits, or can give incorrect scope readings because of induced voltages in the scope probe.

The inductors listed in the selection chart include ferrite pot core construction for AIE, powdered iron toroid for Pulse Engineering, and ferrite bobbin core for Renco.

An inductor should not be operated beyond its maximum rated current because it may saturate. When an inductor begins to saturate, the inductance decreases rapidly and the inductor begins to look mainly resistive (the DC resistance of the winding). This will cause the switch current to rise very rapidly. Different inductor types have different saturation characteristics, and this should be kept in mind when selecting an inductor.

The inductor manufacturer's data sheets include current and energy limits to avoid inductor saturation.

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### <span id="page-17-0"></span>**INDUCTOR RIPPLE CURRENT**

When the switcher is operating in the continuous mode, the inductor current waveform ranges from a triangular to a sawtooth type of waveform (depending on the input voltage). For a given input voltage and output voltage, the peak-to-peak amplitude of this inductor current waveform remains constant. As the load current rises or falls, the entire sawtooth current waveform also rises or falls. The average DC value of this waveform is equal to the DC load current (in the buck regulator configuration).

If the load current drops to a low enough level, the bottom of the sawtooth current waveform will reach zero, and the switcher will change to a discontinuous mode of operation. This is a perfectly acceptable mode of operation. Any buck switching regulator (no matter how large the inductor value is) will be forced to run discontinuous if the load current is light enough.

## **OUTPUT CAPACITOR**

An output capacitor is required to filter the output voltage and is needed for loop stability. The capacitor should be located near the LM2576 using short pc board traces. Standard aluminum electrolytics are usually adequate, but low ESR types are recommended for low output ripple voltage and good stability. The ESR of a capacitor depends on many factors, some which are: the value, the voltage rating, physical size and the type of construction. In general, low value or low voltage (less than 12V) electrolytic capacitors usually have higher ESR numbers.

The amount of output ripple voltage is primarily a function of the ESR (Equivalent Series Resistance) of the output capacitor and the amplitude of the inductor ripple current  $(\Delta I_{\text{IND}})$ . See [INDUCTOR](#page-17-0) RIPPLE CURRENT.

The lower capacitor values (220 μF–1000 μF) will allow typically 50 mV to 150 mV of output ripple voltage, while larger-value capacitors will reduce the ripple to approximately 20 mV to 50 mV.

Output Ripple Voltage =  $(\Delta I_{IND})$  (ESR of C<sub>OUT</sub>) (2)

To further reduce the output ripple voltage, several standard electrolytic capacitors may be paralleled, or a higher-grade capacitor may be used. Such capacitors are often called "high-frequency," "low-inductance," or "low-ESR." These will reduce the output ripple to 10 mV or 20 mV. However, when operating in the continuous mode, reducing the ESR below  $0.03Ω$  can cause instability in the regulator.

Tantalum capacitors can have a very low ESR, and should be carefully evaluated if it is the only output capacitor. Because of their good low temperature characteristics, a tantalum can be used in parallel with aluminum electrolytics, with the tantalum making up 10% or 20% of the total capacitance.

The capacitor's ripple current rating at 52 kHz should be at least 50% higher than the peak-to-peak inductor ripple current.

## **CATCH DIODE**

Buck regulators require a diode to provide a return path for the inductor current when the switch is off. This diode should be located close to the LM2576 using short leads and short printed circuit traces.

Because of their fast switching speed and low forward voltage drop, Schottky diodes provide the best efficiency, especially in low output voltage switching regulators (less than 5V). Fast-Recovery, High-Efficiency, or Ultra-Fast Recovery diodes are also suitable, but some types with an abrupt turn-off characteristic may cause instability and EMI problems. A fast-recovery diode with soft recovery characteristics is a better choice. Standard 60 Hz diodes (e.g., 1N4001 or 1N5400, and so on) are also **not suitable.** See [Table](#page-15-0) 1 for Schottky and "soft" fast-recovery diode selection guide.

## **OUTPUT VOLTAGE RIPPLE AND TRANSIENTS**

The output voltage of a switching power supply will contain a sawtooth ripple voltage at the switcher frequency, typically about 1% of the output voltage, and may also contain short voltage spikes at the peaks of the sawtooth waveform.

The output ripple voltage is due mainly to the inductor sawtooth ripple current multiplied by the ESR of the output capacitor. (See INDUCTOR [SELECTION\)](#page-16-0)



The voltage spikes are present because of the the fast switching action of the output switch, and the parasitic inductance of the output filter capacitor. To minimize these voltage spikes, special low inductance capacitors can be used, and their lead lengths must be kept short. Wiring inductance, stray capacitance, as well as the scope probe used to evaluate these transients, all contribute to the amplitude of these spikes.

An additional small LC filter (20 μH & 100 μF) can be added to the output (as shown in [Figure](#page-21-0) 33) to further reduce the amount of output ripple and transients. A 10  $\times$  reduction in output ripple voltage and transients is possible with this filter.

#### **FEEDBACK CONNECTION**

The LM2576 (fixed voltage versions) feedback pin must be wired to the output voltage point of the switching power supply. When using the adjustable version, physically locate both output voltage programming resistors near the LM2576 to avoid picking up unwanted noise. Avoid using resistors greater than 100 kΩ because of the increased chance of noise pickup.

## **ON /OFF INPUT**

For normal operation, the  $\overline{ON}$  /OFF pin should be grounded or driven with a low-level TTL voltage (typically below 1.6V). To put the regulator into standby mode, drive this pin with a high-level TTL or CMOS signal. The  $\overline{ON}$  /OFF pin can be safely pulled up to +V<sub>IN</sub> without a resistor in series with it. The  $\overline{ON}$  /OFF pin should not be left open.

### **GROUNDING**

To maintain output voltage stability, the power ground connections must be low-impedance (see [Figure](#page-10-0) 21 and [Figure](#page-10-1) 22). For the 5-lead TO-220 and DDPAK/TO-263 style package, both the tab and pin 3 are ground and either connection may be used, as they are both part of the same copper lead frame.

### **HEAT SINK/THERMAL CONSIDERATIONS**

In many cases, only a small heat sink is required to keep the LM2576 junction temperature within the allowed operating range. For each application, to determine whether or not a heat sink will be required, the following must be identified:

- 1. Maximum ambient temperature (in the application).
- 2. Maximum regulator power dissipation (in application).
- 3. Maximum allowed junction temperature (125°C for the LM2576). For a safe, conservative design, a temperature approximately 15°C cooler than the maximum temperatures should be selected.
- 4. LM2576 package thermal resistances  $\theta_{JA}$  and  $\theta_{JC}$ .

Total power dissipated by the LM2576 can be estimated as follows:

$$
P_D = (V_{IN})(I_Q) + (V_O/V_{IN})(I_{LOAD})(V_{SAT})
$$

where

- $I<sub>O</sub>$  (quiescent current) and  $V<sub>SAT</sub>$  can be found in TYPICAL PERFORMANCE [CHARACTERISTICS](#page-6-0) shown previously,
- $V_{IN}$  is the applied minimum input voltage,  $V_{O}$  is the regulated output voltage,
- and  $I_{\text{LOAD}}$  is the load current. (3)

The dynamic losses during turn-on and turn-off are negligible if a Schottky type catch diode is used.

When no heat sink is used, the junction temperature rise can be determined by the following:

 $\Delta T_J = (P_D) (\theta_{JA})$  (4)

To arrive at the actual operating junction temperature, add the junction temperature rise to the maximum ambient temperature.

 $T_J = \Delta T_J + T_A$  (5)

If the actual operating junction temperature is greater than the selected safe operating junction temperature determined in step 3, then a heat sink is required.



 $\Delta T_{J} = (P_{D}) ( \theta_{JC} + \theta_{interface} + \theta_{Heat sink})$  (6)

<span id="page-19-0"></span>The operating junction temperature will be:

 $T_J = T_A + \Delta T_J$ 

As in [Equation](#page-19-0) 14, if the actual operating junction temperature is greater than the selected safe operating junction temperature, then a larger heat sink is required (one that has a lower thermal resistance).

Included on the **Switcher Made Simple** design software is a more precise (non-linear) thermal model that can be used to determine junction temperature with different input-output parameters or different component values. It can also calculate the heat sink thermal resistance required to maintain the regulators junction temperature below the maximum operating temperature.

# **Additional Applications**

### **INVERTING REGULATOR**

[Figure](#page-19-1) 28 shows a LM2576-12 in a buck-boost configuration to generate a negative 12V output from a positive input voltage. This circuit bootstraps the regulator's ground pin to the negative output voltage, then by grounding the feedback pin, the regulator senses the inverted output voltage and regulates it to −12V.

For an input voltage of 12V or more, the maximum available output current in this configuration is approximately 700 mA. At lighter loads, the minimum input voltage required drops to approximately 4.7V.

The switch currents in this buck-boost configuration are higher than in the standard buck-mode design, thus lowering the available output current. Also, the start-up input current of the buck-boost converter is higher than the standard buck-mode regulator, and this may overload an input power source with a current limit less than 5A. Using a delayed turn-on or an undervoltage lockout circuit (described in NEGATIVE BOOST [REGULATOR](#page-20-0)) would allow the input voltage to rise to a high enough level before the switcher would be allowed to turn on.

Because of the structural differences between the buck and the buck-boost regulator topologies, the buck regulator design procedure section can not be used to select the inductor or the output capacitor. The recommended range of inductor values for the buck-boost design is between 68 μH and 220 μH, and the output capacitor values must be larger than what is normally required for buck designs. Low input voltages or high output currents require a large value output capacitor (in the thousands of micro Farads).

The peak inductor current, which is the same as the peak switch current, can be calculated from the following formula:

$$
I_p \approx \frac{I_{LOAD} (V_{IN} + |V_O|)}{V_{IN}} + \frac{V_{IN} |V_O|}{V_{IN} + |V_O|} \times \frac{1}{2L_1 f_{osc}}
$$

where

• 
$$
f_{osc} = 52 \text{ kHz}
$$
 (8)

<span id="page-19-1"></span>Under normal continuous inductor current operating conditions, the minimum  $V_{IN}$  represents the worst case. Select an inductor that is rated for the peak current anticipated.





(7)



Also, the maximum voltage appearing across the regulator is the absolute sum of the input and output voltage. For a −12V output, the maximum input voltage for the LM2576 is +28V, or +48V for the LM2576HV.

The **Switchers Made Simple** (version 3.0) design software can be used to determine the feasibility of regulator designs using different topologies, different input-output parameters, different components, and so on.

#### <span id="page-20-0"></span>**NEGATIVE BOOST REGULATOR**

Another variation on the buck-boost topology is the negative boost configuration. The circuit in [Figure](#page-20-1) 29 accepts an input voltage ranging from −5V to −12V and provides a regulated −12V output. Input voltages greater than −12V will cause the output to rise above −12V, but will not damage the regulator.



Typical Load Current 400 mA for  $V_{IN} = -5.2V$ 750 mA for  $V_{IN} = -7V$ Heat sink may be required.

#### **Figure 29. Negative Boost**

<span id="page-20-1"></span>Because of the boosting function of this type of regulator, the switch current is relatively high, especially at low input voltages. Output load current limitations are a result of the maximum current rating of the switch. Also, boost regulators can not provide current limiting load protection in the event of a shorted load, so some other means (such as a fuse) may be necessary.

#### **UNDERVOLTAGE LOCKOUT**

In some applications it is desirable to keep the regulator off until the input voltage reaches a certain threshold. An undervoltage lockout circuit which accomplishes this task is shown in [Figure](#page-20-2) 30, while [Figure](#page-21-1) 31 shows the same circuit applied to a buck-boost configuration. These circuits keep the regulator off until the input voltage reaches a predetermined level.

$$
V_{TH} \approx V_{Z1} + 2V_{BE}(Q1)
$$



<span id="page-20-2"></span>Complete circuit not shown.



# **[LM2576,](http://www.ti.com/product/lm2576?qgpn=lm2576) [LM2576HV](http://www.ti.com/product/lm2576hv?qgpn=lm2576hv)**







Complete circuit not shown (see [Figure](#page-19-1) 28).

**Figure 31. Undervoltage Lockout for Buck-Boost Circuit**

### <span id="page-21-1"></span>**DELAYED STARTUP**

The ON /OFF pin can be used to provide a delayed startup feature as shown in [Figure](#page-21-2) 32. With an input voltage of 20V and for the part values shown, the circuit provides approximately 10 ms of delay time before the circuit begins switching. Increasing the RC time constant can provide longer delay times. But excessively large RC time constants can cause problems with input voltages that are high in 60 Hz or 120 Hz ripple, by coupling the ripple into the ON /OFF pin.

### **ADJUSTABLE OUTPUT, LOW-RIPPLE POWER SUPPLY**

A 3A power supply that features an adjustable output voltage is shown in [Figure](#page-21-0) 33. An additional L-C filter that reduces the output ripple by a factor of 10 or more is included in this circuit.



Complete circuit not shown.

**Figure 32. Delayed Startup**

<span id="page-21-2"></span>

<span id="page-21-0"></span>



#### **DEFINITION OF TERMS**

- **BUCK REGULATOR**A switching regulator topology in which a higher voltage is converted to a lower voltage. Also known as a step-down switching regulator.
- **BUCK-BOOST REGULATOR**A switching regulator topology in which a positive voltage is converted to a negative voltage without a transformer.
- **DUTY CYCLE (D)**Ratio of the output switch's on-time to the oscillator period.

 $D = \frac{t_{ON}}{T} = \frac{V_{OUT}}{V_{IN}}$ for buck regulator for buck-boost regulator  $D = \frac{t_{ON}}{T} = \frac{|V_O|}{|V_O| + V_{IN}}$ 

**CATCH DIODE OR CURRENT STEERING DIODE**The diode which provides a return path for the load current when the LM2576 switch is OFF.

**EFFICIENCY (η)**The proportion of input power actually delivered to the load.

$$
\eta = \frac{P_{OUT}}{P_{IN}} = \frac{P_{OUT}}{P_{OUT} + P_{LOSS}}
$$

(10)

(9)

**CAPACITOR EQUIVALENT SERIES RESISTANCE (ESR)**The purely resistive component of a real capacitor's impedance (see [Figure](#page-22-0) 34). It causes power loss resulting in capacitor heating, which directly affects the capacitor's operating lifetime. When used as a switching regulator output filter, higher ESR values result in higher output ripple voltages.

$$
\underbrace{\hspace{2.5cm}}_{ESR}\underbrace{\hspace{2.5cm}}_{ESL}\underbrace{\hspace{2.5cm}}_{ESL}\underbrace{\hspace{2.5cm}}_{C}
$$

**Figure 34. Simple Model of a Real Capacitor**

Most standard aluminum electrolytic capacitors in the 100  $\mu$ F–1000  $\mu$ F range have 0.5 $\Omega$  to 0.1Ω ESR. Higher-grade capacitors ("low-ESR", "high-frequency", or "low-inductance") in the 100 μF–1000 μF range generally have ESR of less than 0.15Ω.

- <span id="page-22-0"></span>**EQUIVALENT SERIES INDUCTANCE (ESL)**The pure inductance component of a capacitor (see [Figure](#page-22-0) 34). The amount of inductance is determined to a large extent on the capacitor's construction. In a buck regulator, this unwanted inductance causes voltage spikes to appear on the output.
- **OUTPUT RIPPLE VOLTAGE**The AC component of the switching regulator's output voltage. It is usually dominated by the output capacitor's ESR multiplied by the inductor's ripple current ( $Δ_{IND}$ ). The peak-topeak value of this sawtooth ripple current can be determined by reading the [INDUCTOR](#page-17-0) RIPPLE [CURRENT](#page-17-0) section.
- **CAPACITOR RIPPLE CURRENT**RMS value of the maximum allowable alternating current at which a capacitor can be operated continuously at a specified temperature.
- **STANDBY QUIESCENT CURRENT (I<sub>STBY</sub>)** Supply current required by the LM2576 when in the standby mode (ON /OFF pin is driven to TTL-high voltage, thus turning the output switch OFF).
- **INDUCTOR RIPPLE CURRENT (ΔI<sub>IND</sub>)**The peak-to-peak value of the inductor current waveform, typically a sawtooth waveform when the regulator is operating in the continuous mode (vs. discontinuous mode).
- **CONTINUOUS/DISCONTINUOUS MODE OPERATION**Relates to the inductor current. In the continuous mode, the inductor current is always flowing and never drops to zero, vs. the discontinuous mode, where the inductor current drops to zero for a period of time in the normal switching cycle.
- **INDUCTOR SATURATION**The condition which exists when an inductor cannot hold any more magnetic flux. When an inductor saturates, the inductor appears less inductive and the resistive component dominates. Inductor current is then limited only by the DC resistance of the wire and the available source current.
- **OPERATING VOLT MICROSECOND CONSTANT (E•Top)**The product (in VoIt•μs) of the voltage applied to the inductor and the time the voltage is applied. This  $\mathsf{E}\text{-}\mathsf{T}_\mathsf{op}$  constant is a measure of the energy handling capability of an inductor and is dependent upon the type of core, the core area, the number of turns, and the duty cycle.

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#### **Connection Diagrams**

(XX indicates output voltage option.)



<span id="page-23-0"></span>**Figure 37. Bent, Staggered Leads 5-Lead TO-220 (T) Package LM2576T-XX Flow LB03 or LM2576HVT-XX Flow LB03 See Package Number NDH0005D**

## **REVISION HISTORY**









# **PACKAGING INFORMATION**





# **PACKAGE OPTION ADDENDUM**





# **PACKAGE OPTION ADDENDUM**







**(1)** The marketing status values are defined as follows:

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**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

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**OBSOLETE:** TI has discontinued the production of the device.

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**(3)** MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

**(4)** There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

**(5)** Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.



# **PACKAGE OPTION ADDENDUM**

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# **QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**





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\*All dimensions are nominal

# NDH0005D



# **MECHANICAL DATA**

# KTT0005B



# NEB0005B



KC (R-PSFM-T5)

PLASTIC FLANGE-MOUNT PACKAGE



NOTES:

- A. All linear dimensions are in inches (millimeters).
- This drawing is subject to change without notice. **B.**  $\mathbb{C}.$
- All lead dimensions apply before solder dip.
- The center lead is in electrical contact with the mounting tab. D.
- $\overline{\mathbb{R}}$  These features are optional.
- $\overbrace{\text{F}}$  Thermal pad contour optional within these dimensions.



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