TOSHIBA Bi-CMOS Integrated Circuit Silicon Monolithic

TB6642FG

Full-Bridge DC Motor Driver IC

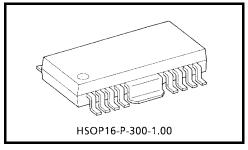
The TB6642FG is a full-bridge DC motor driver with MOS output transistors.

The low ON-resistance MOS process and PWM control enables driving DC motors with high thermal efficiency.

Four operating modes are selectable via IN1 and IN2: clockwise (CW), counterclockwise (CCW), Short Brake and Stop.

Features

- Power supply voltage: 50 V (max)
- Output current: 4.5 A (max)
- Direct PWM control
- CW/CCW/Short Brake/Stop modes
- Overcurrent shutdown circuit (ISD)
- Overcurrent detection threshold control
- Overcurrent detection time control
- Overvoltage shutdown circuit (VSD)
- Thermal shutdown circuit (TSD)
- Undervoltage lockout circuit (UVLO)
- · Dead time for preventing shoot-through current
- Selectable release of TSD,ISD



Weight: 0.5 g (typ.)

Note: The following conditions apply to solderability:

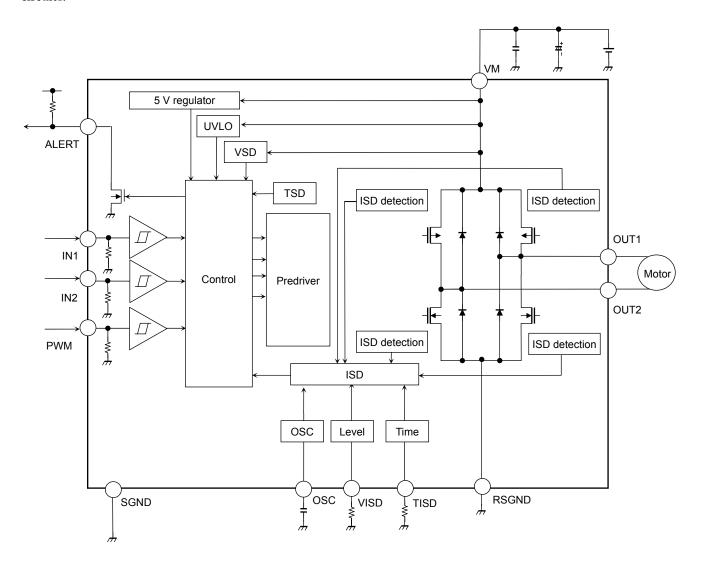
About solderability, following conditions were confirmed

- (1) Use of Sn-37Pb solder Bath
 - solder bath temperature: 230°C
 - dipping time: 5 seconds
 - the number of times: once
 - use of R-type flux
- (2) Use of Sn-3.0Ag-0.5Cu solder Bath
 - solder bath temperature: 245°C
 - dipping time: 5 seconds
 - the number of times: once
 - use of R-type flux

Block Diagram (application circuit example)

The application circuits shown in this document are provided for reference purposes only. Thorough evaluation is required, especially at the mass production design stage.

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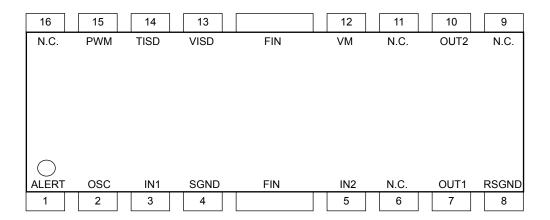


Pin Functions

| Pin No. | Pin Name | Functional Description |
|---------|----------|---|
| 1 | ALERT | Error detection output pin |
| 2 | OSC | Capacitor pin for controlling release of ISD,TSD |
| 3 | IN1 | Control signal input pin 1 |
| 4 | SGND | Small signal ground pin |
| 5 | IN2 | Control signal input pin 2 |
| 6 | N.C. | No-connect |
| 7 | OUT1 | Output pin 1 |
| 8 | RSGND | Power ground pin/ Detection resistor pin for PWM constant-current control |
| 9 | N.C. | No-connect |
| 10 | OUT2 | Output pin 2 |
| 11 | N.C. | No-connect |
| 12 | VM | Power supply voltage pin |
| 13 | VISD | Resistor pin for overcurrent detection threshold control |
| 14 | TISD | Resistor pin for overcurrent detection time control |
| 15 | PWM | PWM input pin |
| 16 | N.C. | No-connect |
| _ | FIN | Pin-fin heat sink (Note) |

Note: Since the pin-fin is provided for discharging heat, the thermal design must be considered on the PCB designing. (The fin is installed on the second surface of the chip and electrified; therefore it must be insulated or earthed to the ground.)

Pin Assignment (top view)



Absolute Maximum Ratings (Note) (Ta = 25°C)

| Characteristics | Symbol | Rating | Unit |
|--------------------------|----------------------|---------------|------|
| Power supply voltage | VM | 50 | V |
| Output voltage | VO | 50 (Note 1) | V |
| Output current 1 | I _O peak1 | 4.5 (Note 2) | Α |
| Output current 2 | I _O peak2 | 4.0 (Note 3) | Α |
| Input voltage | V_{IN} | -0.3 to 5.5 | V |
| ALERT pin output voltage | V _{ALERT} | 5.5 | V |
| ALERT pin output current | I _{ALERT} | 5 | mA |
| Power dissipation | P_{D} | 0.89 (Note 4) | W |
| Operating temperature | T _{opr} | -40 to 85 | °C |
| Storage temperature | T _{stg} | –55 to 150 | °C |

Note: The absolute maximum ratings of a semiconductor device are a set of ratings that must not be exceeded, even for a moment. Do not exceed any of these ratings.

Exceeding the rating (s) may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion.

Please use the TB6642FG within the specified operating ranges.

Note 1: OUT1, OUT2

Note 2: The absolute maximum output current rating of 4.5 A must be kept for OUT1 and OUT2 when VM \leq 36 V.

Note 3: The absolute maximum output current rating of 4.0 A must be kept for OUT1 and OUT2 when VM >36 V.

Note 4: IC only

Operating Ranges

| Characteristics | Symbol | Rating | Unit |
|-----------------|-----------------------|---------------------------------------|------|
| Supply voltage | VM _{opr} | 10 to 45 | V |
| PWM frequency | f _{PWM} | Up to 100 | kHz |
| Output current | I _O (Ave.) | Up to 1.5 (Note 5) (given as a guide) | Α |

Note 5: $T_a = 25$ °C, the TB6642FG is mounted on the PCB (70 mm × 70 mm × 1.6 mm), double-sided, Cu thickness: 50 μ m, Cu dimension: 67%).

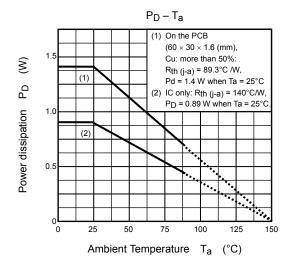
*: The average output current shall be increased or decreased depending on usage conditions such as ambient temperature and IC mounting method).

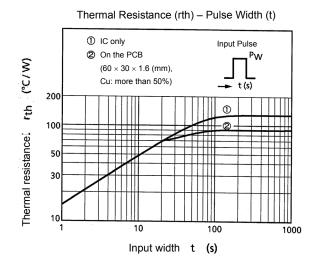
Use the average output current so that the junction temperature of 150° C (T_{j}) and the absolute maximum output current rating of 4.5 A or 4.0 A are not exceeded.

Electrical Characteristics (unless otherwise specified, $T_a = 25$ °C, VM = 24 V)

| Cha | aracteristics | Symbol | Test Condition | Min | Тур. | Max | Unit | |
|-------------------------|------------------------------|-------------------------|-----------------------------------|-----|------|------|------|--|
| | | I _{CC1} | Stop mode | _ | 3 | 8 | | |
| Power supply of | Power supply current | | CW/CCW mode | _ | 3 | 8 | mA | |
| | | | Short Brake mode | _ | 3 | 8 | | |
| | Input voltage | V _{INH} | | 2 | _ | 5.5 | | |
| Control circuit | input voltage | V _{INL} | | 0 | _ | 0.8 | V | |
| IN1 pin, IN2 pin, | Hysteresis voltage | V _{IN (HYS)} | | _ | 0.4 | _ | | |
| PWM pin | Input current | l _{INH} | V _{IN} = 5 V | _ | 50 | 75 | μА | |
| | | I _{INL} | V _{IN} = 0 V | _ | _ | 5 | | |
| PWM frequency | | f _{PWM} | Duty: 50 % | _ | 100 | _ | kHz | |
| PWM minimum pulse width | | f _{PWM (TW)} | (given as a guide only) | 1 | _ | _ | μS | |
| | Output ON resistance | R _{ON} (U + L) | I _O = 3 A | _ | 0.55 | 0.9 | Ω | |
| | Output leakage current | I _{L (U)} | VM = 50 V, V _{OUT} = 0 V | -2 | _ | _ | μА | |
| OUT1 pin, OUT2 pin | | I _{L (L)} | VM = V _{OUT} = 50 V | _ | _ | 2 | | |
| 0012 piii | Diode forward voltage | V _{F (U)} | I _O = 3 A | _ | 1.3 | 1.7 | V | |
| | | V _{F (L)} | I _O = -3 A | _ | 1.3 | 1.7 | | |
| ALERT pin | Output fall time voltage | V _{AL} (LO) | I _{ALERT} = 1 mA | _ | _ | 0.4 | V | |
| | Output leakage current | I _{AL (LE)} | V _{ALERT} = 5.5 V | _ | _ | 2 | μА | |
| OSC charge/di | OSC charge/discharge current | | | 4.5 | 9 | 13.5 | μА | |

Thermal Performance Characteristics





I/O Equivalent Circuits

The equivalent circuit diagrams may be simplified or some parts of them may be omitted for explanatory purposes.

| Pin No. | I/O Signal | I/O Internal Circuit |
|--------------------|---|--|
| IN1 (3) IN2 (5) | Digital input L: 0.8 V (max) H: 2 V (min) | IN1 (IN2) Φ (typ.) Q (cd, dx) Q (cd, dx) |
| PWM (15) | Digital input L: 0.8 V (max) H: 2 V (min) | 100 kg (typ.) |
| ALERT (1) | Open-drain output An externally attached pull-up resistor enalbes the High output. H (High-impedance): Abnormal operation (When the UVLO, TSD, VSD and/or ISD is activated) L: Normal operation | ALERT |
| OSC (2) | The pin connects a capacitor for controlling release of ISD, TSD | osc |
| VISD (13) | The pin connects a resistor controlling overcurrent detection threshold. | VISD |
| TISD (14) | The pin connects a resistor controlling overcurrent detection time. | TISD |

| Pin No. | I/O Signal | I/O Internal Circuit |
|------------------------------------|--|---------------------------------|
| OUT1 (7) OUT2 (10) RSGND (8) | The RSGND pin must be connected to a resistor for detection when it is used in the PWM constant-current control; it must be earthed to the ground, otherwise. Utmost care must be taken for designing the pin-arrangement pattern because a large current flows through these pins. | OUT1 (OUT2) OUT1 (OUT2) RSGND |

Functional Description

The equivalent circuit diagrams may be simplified or some parts of them may be omitted for explanatory purposes.

Timing charts may be simplified for explanatory purposes.

1. Input/Output Functions

| Input | | | Output | | | |
|-------|-----|-----|--------|---------|---------------------------------------|--|
| IN1 | IN2 | PWM | OUT1 | OUT2 | Mode | |
| Н | Н | Н | L | L | - Short brake | |
| 11 | | L | L | L | | |
| ı | Н | Н | L | Н | CW/CCW | |
| L | | L | L | L | Short brake | |
| Н | | Н | Н | L | CCW/CW | |
| П | | | L | L | Short brake | |
| 1 | L | Н | OFF | /LI; 7) | Stop (a release of TSD and/or ISD) | |
| L | | L | OFF | (Hi-Z) | | |

2. Protective Operation Alert Output (ALERT)

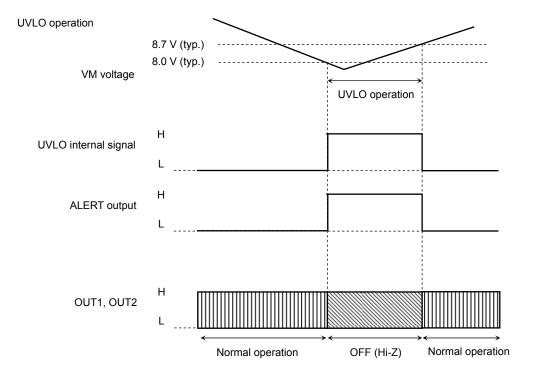
The ALERT pin behaves as an open-drain output and provides a high-impedance state on output being pulled up by a resistor externally wired.

The output is Low when the TB6642FG performs a normal operation (in which state the operational mode is selectable through the IN1 pin and IN2 pin among CW, CCW, Short Brake and Stop modes.). In any other cases (in which state the thermal shutdown circuit (TSD), overcurrent shutdown circuit (ISD), overvoltage shutdown circuit (VSD) and/or undervoltage lockout (UVLO) is activated), the output is High. Driving both the IN1 pin and IN2 pin Low allows a release of the shutdown operations; the TB6642FG resumes the normal operations.

3. Undervoltage Lockout Circuit (UVLO)

The TB6642FG incorporates an undervoltage lockout circuit. When the supply voltage drops under 8 V (typ.), all the outputs are turned off (Hi-Z).

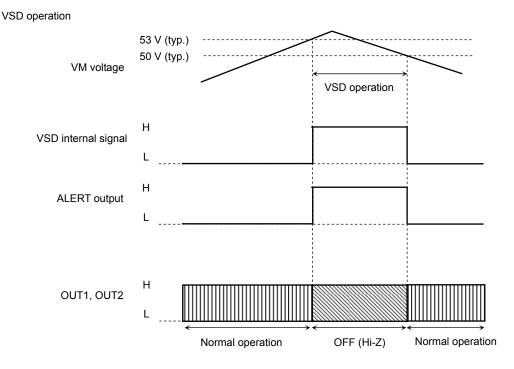
The UVLO circuit has a hysteresis of 0.7 V (typ.); the TB6642FG resumes the normal operation at 8.7 V (typ.).



4. Overvoltage Shutdown Circuit (VSD)

The TB6642FG incorporates an overvoltage shutdown circuit. If the supply voltage exceeds 53 V (typ.), all the outputs are turned off (Hi-Z).

The VSD circuit has a hysteresis of 3 V (typ.); the TB6642FG resumes the normal operation at 50 V (typ.).



Note: The VSD circuit is activated if the absolute maximum voltage rating is violated. Note that the circuit is provided as an auxiliary only and does not necessarily provide the IC with a perfect protection from any kind of damages.

5. Thermal Shutdown Circuit (TSD)

The TB6642FG incorporates a thermal shutdown circuit. If the junction temperature (T_j) exceeds 170°C (typ.), all the outputs are turned off (Hi-Z).

Stop time is determined by oscillation frequency of OSC capacitor.

Example of formula: OSC frequency: fosc = 8/ (Cosc [F] $\times 10^6$) [Hz] (typ.)

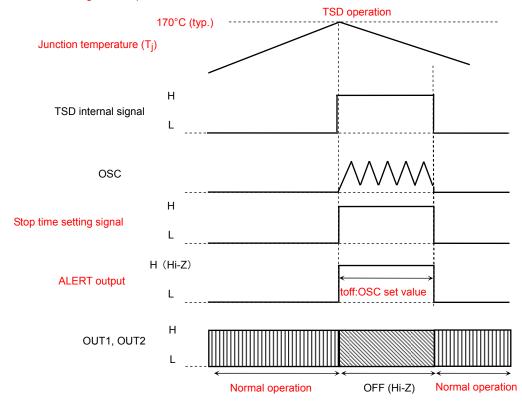
Stop time: toff = 5.17/ fosc [s] (typ.)

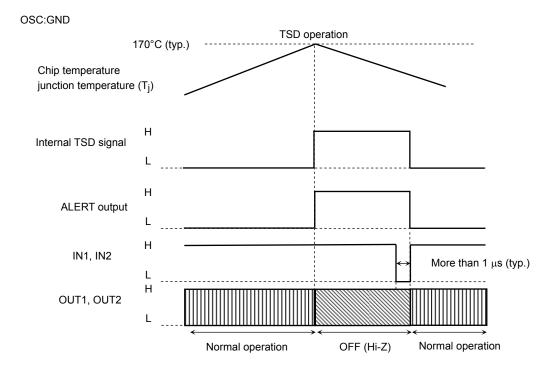
OSC terminal should be connected to the GND in order not to recover the operation automatically after thermal shut down.

Driving both the IN1 pin and IN2 pin Low allows a release of the shutdown operation; the TB6642FG resumes the normal operation.

 $TSD = 170^{\circ}C \text{ (typ.)}$

<OSC: Connecting to the capacitor>





Note: The TSD circuit is activated if the absolute maximum junction temperature rating (T_j) of 150°C is violated. Note that the circuit is provided as an auxiliary only and does not necessarily provide the IC with a perfect protection from any kind of damages.

6. Overcurrent Shutdown Circuit (ISD)

The TB6642FG incorporates overcurrent shutdown (ISD) circuits monitoring the current that flows through each of all the four output power transistors.

The detection time threshold is programmable through the VISD pin with a pull-up resistor. If the overcurrent flowing through any one of the ISD circuit flows beyond the detected time threshold, all the outputs are turned off (Hi-Z).

The detection time threshold is controllable through the external resistor of the TISD pin.

The operation recovers after stop time (toff). Stop time is determined by oscillation frequency of OSC capacitor. Example of formula: OSC frequency: fosc = 8/ (Cosc [F] \times 10⁶) [Hz] (typ.) Stop time: toff = 5.17/ fosc [s] (typ.)

OSC terminal should be open in order not to recover the operation automatically after over current shut down.

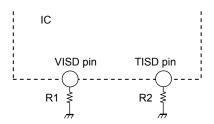
Driving both the IN1 pin and IN2 pin Low allows a release of the shutdown operations; the TB6642FG resumes the normal operation.

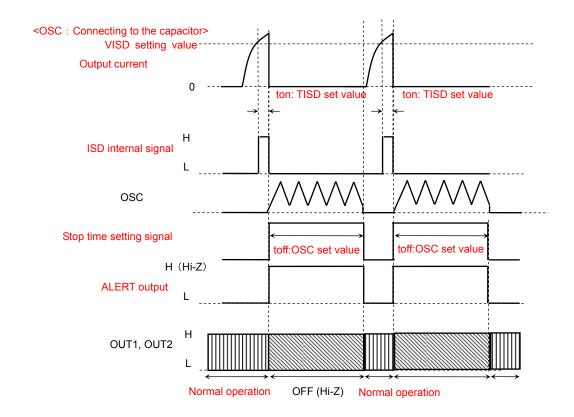
• Detection current threshold of the external resistor, R1, of the VISD pin

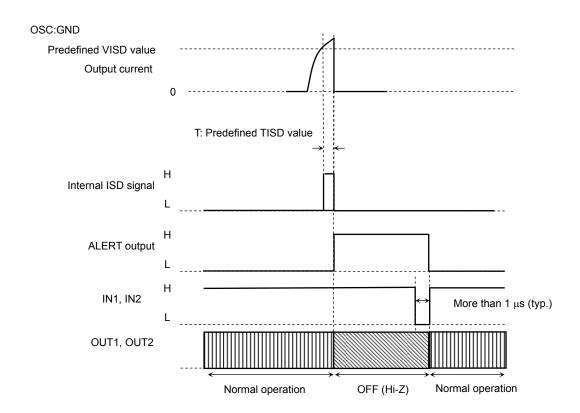
10 kΩ: 6.3 A (typ.) 20 kΩ: 4.2A (typ.) 30 kΩ: 3.1 A (typ.)

• Detection time threshold of the external resistor, R2, of the TISD pin

 $10 \text{ k}\Omega$: 1.6 μs (typ.) $20 \text{ k}\Omega$: 2.8 μs (typ.) $100 \text{ k}\Omega$: 12.4 μs (typ.)







Note: The ISD circuit is activated if the absolute maximum current rating is violated. Note that the circuit is provided as an auxiliary only and does not necessarily provide the IC with a perfect protection from damages due to overcurrent caused by power fault, ground fault, load-short and the like.

12

7. Direct PWM Control

The motor rotation speed is controllable by the PWM input sent through the PWM pin.

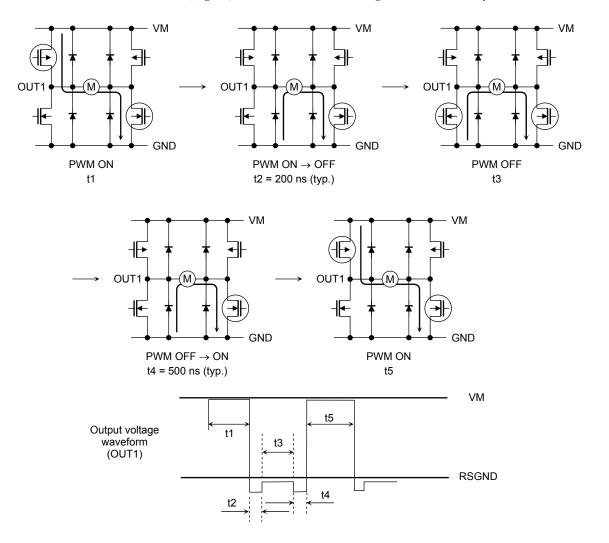
It is also possible to control the motor rotation speed by sending in the PWM signal through not the PWM pin but the IN1 and IN2 pins.

When the motor drive is controlled by the PWM input, the TB6642FG repeats operating in Normal Operation mode and Short Brake mode alternately.

For preventing the shoot-through current in the output circuit caused by the upper and lower power transistors being turned on simultaneously, the dead time is internally generated at the time the upper and lower power transistors switches between on and off.

This eliminates the need of inserting Off time externally; thus the PWM control with synchronous rectification is enabled.

Note that inserting Off time externally is not required on operation mode changes between CW and CCW, and CW (CCW) and Short Brake, again, because of the dead time generated internally.

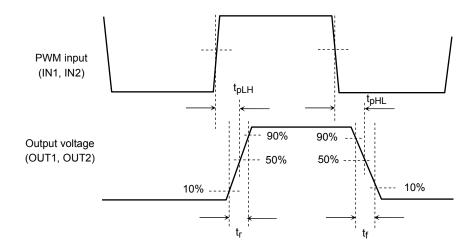




8. Output Circuit

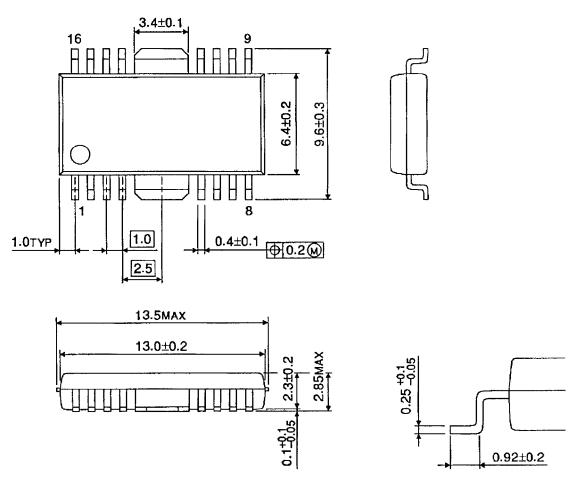
The switching characteristics of the output transistors of the OUT1 and OUT2 pins are as shown below:

| Characteristic | Value | Unit |
|------------------|------------|------|
| t _{pLH} | 650 (typ.) | |
| t _{pHL} | 450 (typ.) | ns |
| t _r | 90 (typ.) | 113 |
| t _f | 130 (typ.) | |



Package Dimensions

HSOP16-P-300-1.00 Unit: mm



Weight: 0.5 g (typ.)

Notes on Contents

1. Block Diagrams

Some of the functional blocks, circuits, or constants in the block diagram may be omitted or simplified for explanatory purposes.

2. Equivalent Circuits

The equivalent circuit diagrams may be simplified or some parts of them may be omitted for explanatory purposes.

3. Timing Charts

Timing charts may be simplified for explanatory purposes.

4. Application Circuits

The application circuits shown in this document are provided for reference purposes only. Thorough evaluation is required, especially at the mass production design stage.

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5. Test Circuits

Components in the test circuits are used only to obtain and confirm the device characteristics. These components and circuits are not guaranteed to prevent malfunction or failure from occurring in the application equipment.

IC Usage Considerations

Notes on Handling of ICs

- (1) The absolute maximum ratings of a semiconductor device are a set of ratings that must not be exceeded, even for a moment. Do not exceed any of these ratings.
 Exceeding the rating(s) may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion.
- (2) Use an appropriate power supply fuse to ensure that a large current does not continuously flow in case of over current and/or IC failure. The IC will fully break down when used under conditions that exceed its absolute maximum ratings, when the wiring is routed improperly or when an abnormal pulse noise occurs from the wiring or load, causing a large current to continuously flow and the breakdown can lead smoke or ignition. To minimize the effects of the flow of a large current in case of breakdown, appropriate settings, such as fuse capacity, fusing time and insertion circuit location, are required.
- (3) If your design includes an inductive load such as a motor coil, incorporate a protection circuit into the design to prevent device malfunction or breakdown caused by the current resulting from the inrush current at power ON or the negative current resulting from the back electromotive force at power OFF. IC breakdown may cause injury, smoke or ignition.

 Use a stable power supply with ICs with built-in protection functions. If the power supply is unstable, the protection function may not operate, causing IC breakdown. IC breakdown may cause injury, smoke or ignition.
- (4) Do not insert devices in the wrong orientation or incorrectly.
 - Make sure that the positive and negative terminals of power supplies are connected properly. Otherwise, the current or power consumption may exceed the absolute maximum rating, and exceeding the rating(s) may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion.

16

In addition, do not use any device that is applied the current with inserting in the wrong orientation or incorrectly even just one time.

Points to Remember on Handling of ICs

(1) Over Current Protection Circuit

Over current protection circuits (referred to as current limiter circuits) do not necessarily protect ICs under all circumstances. If the Over current protection circuits operate against the over current, clear the over current status immediately.

Depending on the method of use and usage conditions, such as exceeding absolute maximum ratings can cause the over current protection circuit to not operate properly or IC breakdown before operation. In addition, depending on the method of use and usage conditions, if over current continues to flow for a long time after operation, the IC may generate heat resulting in breakdown.

(2) Thermal Shutdown Circuit

Thermal shutdown circuits do not necessarily protect ICs under all circumstances. If the thermal shutdown circuits operate against the over temperature, clear the heat generation status immediately. Depending on the method of use and usage conditions, such as exceeding absolute maximum ratings can cause the thermal shutdown circuit to not operate properly or IC breakdown before operation.

(3) Heat Radiation Design

In using an IC with large current flow such as power amp, regulator or driver, please design the device so that heat is appropriately radiated, not to exceed the specified junction temperature (T_j) at any time and condition. These ICs generate heat even during normal use. An inadequate IC heat radiation design can lead to decrease in IC life, deterioration of IC characteristics or IC breakdown. In addition, please design the device taking into considerate the effect of IC heat radiation with peripheral components.

(4) Back-EMF

When a motor rotates in the reverse direction, stops or slows down abruptly, a current flow back to the motor's power supply due to the effect of back-EMF. If the current sink capability of the power supply is small, the device's motor power supply and output pins might be exposed to conditions beyond maximum ratings. To avoid this problem, take the effect of back-EMF into consideration in system design.

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