



Thyristor \ Diode Module

$V_{RRM} = 2 \times 1600 \text{ V}$

$I_{TAV} = 27 \text{ A}$

$V_T = 1.27 \text{ V}$

Phase leg

Part number

MCD26-16io1B



Backside: isolated



Features / Advantages:

- Thyristor for line frequency
- Planar passivated chip
- Long-term stability
- Direct Copper Bonded Al₂O₃-ceramic

Applications:

- Line rectifying 50/60 Hz
- Softstart AC motor control
- DC Motor control
- Power converter
- AC power control
- Lighting and temperature control

Package: TO-240AA

- Isolation Voltage: 4800 V~
- Industry standard outline
- RoHS compliant
- Soldering pins for PCB mounting
- Base plate: DCB ceramic
- Reduced weight
- Advanced power cycling

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| Rectifier | | | Ratings | | | |
|----------------|--|---|-------------------------|------|------|-------------------|
| Symbol | Definition | Conditions | min. | typ. | max. | Unit |
| $V_{RSM/DSM}$ | max. non-repetitive reverse/forward blocking voltage | $T_{VJ} = 25^{\circ}C$ | | | 1700 | V |
| $V_{RRM/DRM}$ | max. repetitive reverse/forward blocking voltage | $T_{VJ} = 25^{\circ}C$ | | | 1600 | V |
| I_{RD} | reverse current, drain current | $V_{R/D} = 1600 V$ | $T_{VJ} = 25^{\circ}C$ | | 100 | μA |
| | | $V_{R/D} = 1600 V$ | $T_{VJ} = 125^{\circ}C$ | | 3 | mA |
| V_T | forward voltage drop | $I_T = 40 A$ | $T_{VJ} = 25^{\circ}C$ | | 1.27 | V |
| | | $I_T = 80 A$ | | | 1.64 | V |
| | | $I_T = 40 A$ | $T_{VJ} = 125^{\circ}C$ | | 1.27 | V |
| | | $I_T = 80 A$ | | | 1.65 | V |
| I_{TAV} | average forward current | $T_C = 85^{\circ}C$ | $T_{VJ} = 125^{\circ}C$ | | 27 | A |
| $I_{T(RMS)}$ | RMS forward current | 180° sine | | | 42 | A |
| V_{T0} | threshold voltage | } for power loss calculation only | $T_{VJ} = 125^{\circ}C$ | | 0.85 | V |
| r_T | slope resistance | | | | 11 | m Ω |
| R_{thJC} | thermal resistance junction to case | | | | 0.88 | K/W |
| R_{thCH} | thermal resistance case to heatsink | | | 0.2 | | K/W |
| P_{tot} | total power dissipation | | $T_C = 25^{\circ}C$ | | 115 | W |
| I_{TSM} | max. forward surge current | $t = 10 ms$; (50 Hz), sine | $T_{VJ} = 45^{\circ}C$ | | 520 | A |
| | | $t = 8,3 ms$; (60 Hz), sine | $V_R = 0 V$ | | 560 | A |
| | | $t = 10 ms$; (50 Hz), sine | $T_{VJ} = 125^{\circ}C$ | | 440 | A |
| | | $t = 8,3 ms$; (60 Hz), sine | $V_R = 0 V$ | | 475 | A |
| I^2t | value for fusing | $t = 10 ms$; (50 Hz), sine | $T_{VJ} = 45^{\circ}C$ | | 1.35 | kA ² s |
| | | $t = 8,3 ms$; (60 Hz), sine | $V_R = 0 V$ | | 1.31 | kA ² s |
| | | $t = 10 ms$; (50 Hz), sine | $T_{VJ} = 125^{\circ}C$ | | 970 | A ² s |
| | | $t = 8,3 ms$; (60 Hz), sine | $V_R = 0 V$ | | 940 | A ² s |
| C_J | junction capacitance | $V_R = 400 V$ $f = 1 MHz$ | $T_{VJ} = 25^{\circ}C$ | | 22 | pF |
| P_{GM} | max. gate power dissipation | $t_p = 30 \mu s$ | $T_C = 125^{\circ}C$ | | 10 | W |
| | | $t_p = 300 \mu s$ | | | 5 | W |
| P_{GAV} | average gate power dissipation | | | | 0.5 | W |
| $(di/dt)_{cr}$ | critical rate of rise of current | $T_{VJ} = 125^{\circ}C$; $f = 50 Hz$ repetitive, $I_T = 45 A$ | | | 150 | A/ μs |
| | | $t_p = 200 \mu s$; $di_G/dt = 0.45 A/\mu s$; $I_G = 0.45 A$; $V = \frac{2}{3} V_{DRM}$ non-repet., $I_T = 27 A$ | | | 500 | A/ μs |
| $(dv/dt)_{cr}$ | critical rate of rise of voltage | $V = \frac{2}{3} V_{DRM}$ $R_{GK} = \infty$; method 1 (linear voltage rise) | $T_{VJ} = 125^{\circ}C$ | | 1000 | V/ μs |
| V_{GT} | gate trigger voltage | $V_D = 6 V$ | $T_{VJ} = 25^{\circ}C$ | | 1.5 | V |
| | | | $T_{VJ} = -40^{\circ}C$ | | 1.6 | V |
| I_{GT} | gate trigger current | $V_D = 6 V$ | $T_{VJ} = 25^{\circ}C$ | | 100 | mA |
| | | | $T_{VJ} = -40^{\circ}C$ | | 200 | mA |
| V_{GD} | gate non-trigger voltage | $V_D = \frac{2}{3} V_{DRM}$ | $T_{VJ} = 125^{\circ}C$ | | 0.2 | V |
| I_{GD} | gate non-trigger current | | | | 10 | mA |
| I_L | latching current | $t_p = 10 \mu s$ | $T_{VJ} = 25^{\circ}C$ | | 450 | mA |
| | | $I_G = 0.45 A$; $di_G/dt = 0.45 A/\mu s$ | | | | |
| I_H | holding current | $V_D = 6 V$ $R_{GK} = \infty$ | $T_{VJ} = 25^{\circ}C$ | | 200 | mA |
| t_{gd} | gate controlled delay time | $V_D = \frac{1}{2} V_{DRM}$ | $T_{VJ} = 25^{\circ}C$ | | 2 | μs |
| | | $I_G = 0.45 A$; $di_G/dt = 0.45 A/\mu s$ | | | | |
| t_q | turn-off time | $V_R = 100 V$; $I_T = 20 A$; $V = \frac{2}{3} V_{DRM}$ $di/dt = 10 A/\mu s$ $dv/dt = 20 V/\mu s$ $t_p = 200 \mu s$ | $T_{VJ} = 100^{\circ}C$ | | 150 | μs |



| Package TO-240AA | | | | Ratings | | | |
|------------------|--|----------------------|-------------------------------------|---------|------|------|--|
| Symbol | Definition | Conditions | min. | typ. | max. | Unit | |
| I_{RMS} | RMS current | per terminal | | | 200 | A | |
| T_{VJ} | virtual junction temperature | | -40 | | 125 | °C | |
| T_{op} | operation temperature | | -40 | | 100 | °C | |
| T_{stg} | storage temperature | | -40 | | 125 | °C | |
| Weight | | | | | 81 | g | |
| M_D | mounting torque | | 2.5 | | 4 | Nm | |
| M_T | terminal torque | | 2.5 | | 4 | Nm | |
| $d_{Spp/App}$ | creepage distance on surface striking distance through air | terminal to terminal | 13.0 | 9.7 | | mm | |
| $d_{Spb/Apb}$ | | terminal to backside | 16.0 | 16.0 | | mm | |
| V_{ISOL} | isolation voltage | t = 1 second | | 4800 | | V | |
| | | t = 1 minute | 50/60 Hz, RMS; $I_{ISOL} \leq 1$ mA | 4000 | | V | |



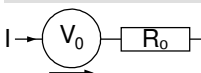
| Ordering | Ordering Number | Marking on Product | Delivery Mode | Quantity | Code No. |
|----------|-----------------|--------------------|---------------|----------|----------|
| Standard | MCD26-16io1B | MCD26-16io1B | Box | 36 | 500955 |

| Similar Part | Package | Voltage class |
|----------------|-------------|---------------|
| MCMA35PD1600TB | TO-240AA-1B | 1600 |
| MCMA50PD1600TB | TO-240AA-1B | 1600 |

Equivalent Circuits for Simulation

* on die level

$T_{VJ} = 125^{\circ}\text{C}$



Thyristor

| | | | |
|--------------|--------------------|------|----|
| $V_{0\ max}$ | threshold voltage | 0.85 | V |
| $R_{0\ max}$ | slope resistance * | 9.8 | mΩ |



Outlines TO-240AA



General tolerance: DIN ISO 2768 class „c“



Optional accessories for modules

Keyed gate/cathode twin plugs with wire length = 350 mm, gate = white, cathode = red
Type ZY 200L (L = Left for pin pair 4/5) UL 758, style 3751



Thyristor



Fig. 1 Surge overload current I_{TSM} , I_{FSM} : Crest value, t : duration



Fig. 2 I^2dt versus time (1-10 ms)



Fig. 3 Max. forward current at case temperature



Fig. 4 Power dissipation vs. on-state current & ambient temperature (per thyristor or diode)



Fig. 5 Gate trigger characteristics



Fig. 6 Three phase rectifier bridge: Power dissipation versus direct output current and ambient temperature

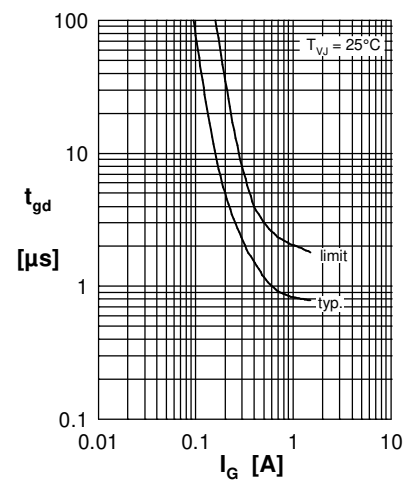


Fig. 7 Gate trigger delay time



Rectifier



Fig. 8 Three phase AC-controller: Power dissipation versus RMS output current and ambient temperature



R_{thJC} for various conduction angles d:

| d | R_{thJC} [K/W] |
|------|------------------|
| DC | 0.88 |
| 180° | 0.92 |
| 120° | 0.95 |
| 60° | 0.98 |
| 30° | 1.01 |

Constants for Z_{thJC} calculation:

| i | R_{thi} [K/W] | t_i [s] |
|---|-----------------|-----------|
| 1 | 0.019 | 0.0031 |
| 2 | 0.029 | 0.0216 |
| 3 | 0.832 | 0.1910 |

Fig. 9 Transient thermal impedance junction to case (per thyristor/diode)



R_{thJK} for various conduction angles d:

| d | R_{thJK} [K/W] |
|------|------------------|
| DC | 1.08 |
| 180° | 1.12 |
| 120° | 1.15 |
| 60° | 1.18 |
| 30° | 1.21 |

Constants for Z_{thJK} calculation:

| i | R_{thi} [K/W] | t_i [s] |
|---|-----------------|-----------|
| 1 | 0.019 | 0.0031 |
| 2 | 0.029 | 0.0216 |
| 3 | 0.832 | 0.1910 |
| 4 | 0.200 | 0.4500 |

Fig. 10 Transient thermal impedance junction to heatsink (per thyristor/diode)

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