FemtoClock® NG Universal Frequency Translator

ICS840N202I

DATA SHEET

General Description

The ICS840N202I is a highly flexible FemtoClock® NG general purpose, low phase noise Frequency Translator / Synthesizer with alarm and monitoring functions suitable for networking and communications applications. It is able to generate any output frequency in the 1MHz - 250MHz range (see Table 3 for details). A wide range of input reference clocks and a range of low-cost fundamental mode crystal frequencies may be used as the source for the output frequency.

The ICS840N202I has three operating modes to support a very broad spectrum of applications:

1) Frequency Synthesizer
   - Synthesizes output frequencies from a 16MHz - 40MHz fundamental mode crystal.
   - Fractional feedback division is used, so there are no requirements for any specific crystal frequency to produce the desired output frequency with a high degree of accuracy.
2) High-Bandwidth Frequency Translator
   - Applications: PCI Express, Computing, General Purpose
   - Translates any input clock in the 16MHz - 710MHz frequency range into any supported output frequency.
   - This mode has a high PLL loop bandwidth in order to track input reference changes, such as Spread-Spectrum Clock modulation, so it will not attenuate much jitter on the input reference.
3) Low-Bandwidth Frequency Translator
   - Applications: Networking & Communications.
   - Translates any input clock in the 8kHz - 710MHz frequency range into any supported output frequency.
   - This mode supports PLL loop bandwidths in the 10Hz - 580Hz range and makes use of an external crystal to provide significant jitter attenuation.

This device provides two factory-programmed default power-up configurations burned into One-Time Programmable (OTP) memory. The configuration to be used is selected by the CONFIG pin. The two configurations are specified by the customer and are programmed by IDT during the final test phase from an on-hand stock of blank devices. The two configurations may be completely independent of one another.

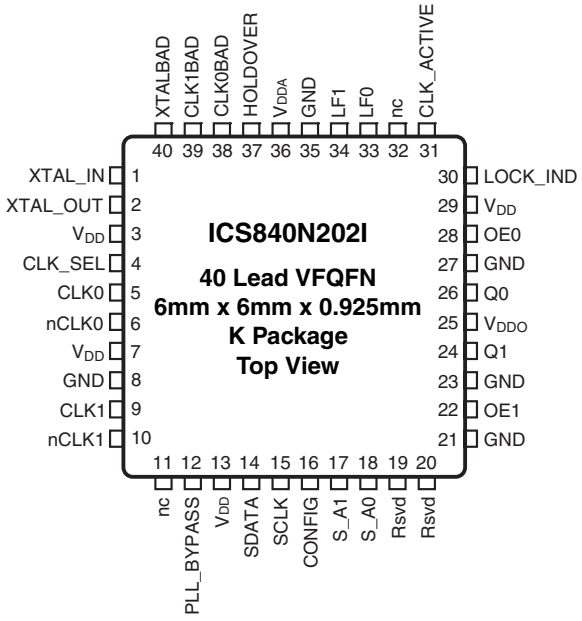
One usage example might be to install the device on a line card with two optional daughter cards: an OC-3 option (configuration 0) requiring a 155.52MHz clock translated from a 19.44MHz input and a Gigabit Ethernet option (configuration 1) requiring a 125MHz clock translated from the same 19.44MHz input reference.

To implement other configurations, these power-up default settings can be overwritten after power-up using the I²C interface and the device can be completely reconfigured. However, these settings would have to be re-written each time the device powers-up.

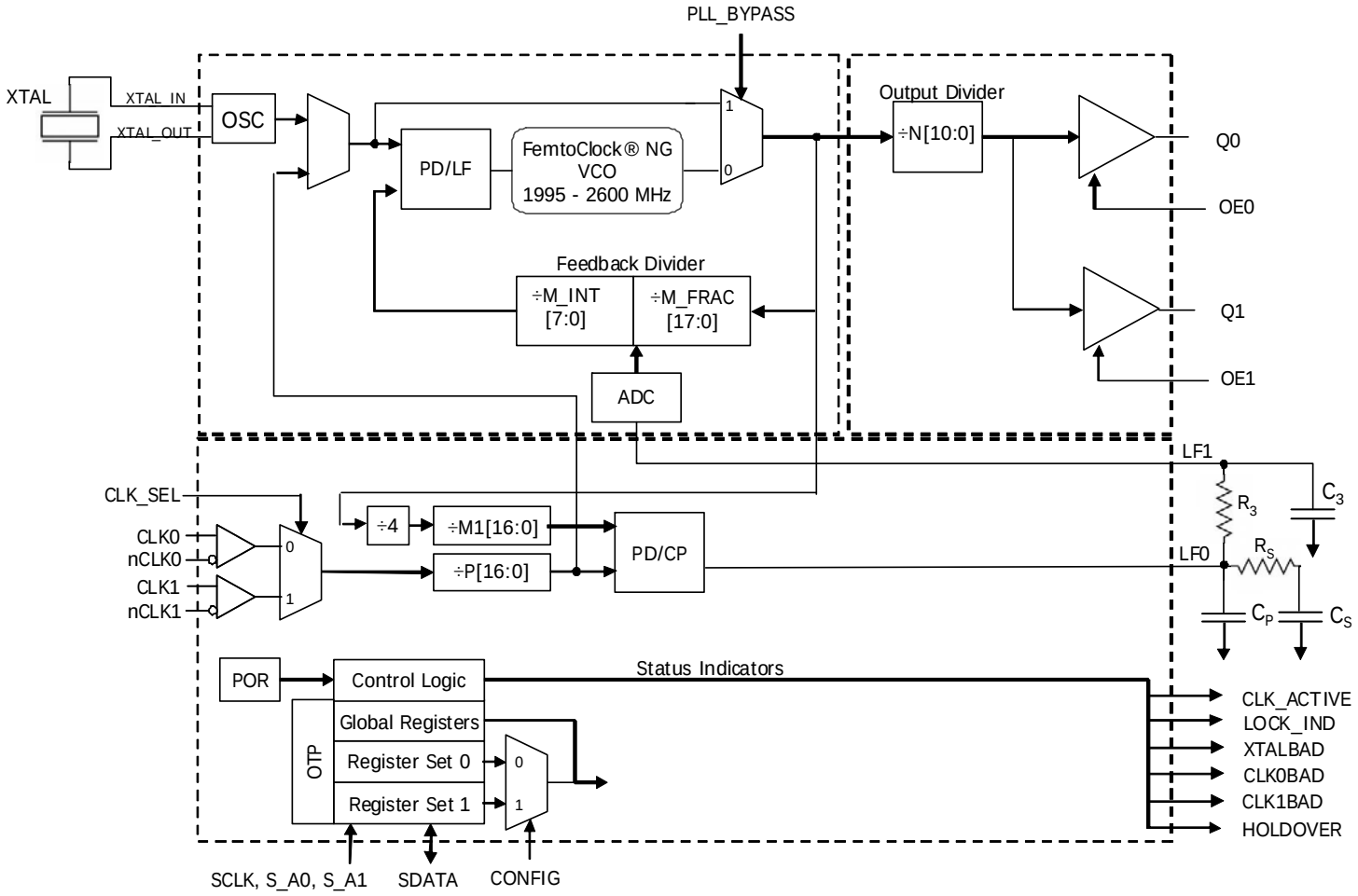
Features

- Fourth generation FemtoClock® NG technology
- Universal Frequency Translator/Frequency Synthesizer
- Two LVCMOS/LVTTL outputs
  - Both outputs may be set to use 2.5V or 3.3V output levels
  - Programmable output frequency: 1.0MHz to 250MHz
- Two differential inputs support the following input types: LVPECL, LVDS, LVHSTL, HCSL
- Input frequency range: 8kHz - 710MHz
- Crystal input frequency range: 16MHz - 40MHz
- Two factory-set register configurations for power-up default state
  - Power-up default configuration pin or register selectable
  - Configurations customized via One-Time Programmable ROM
  - Settings may be overwritten after power-up via I²C
  - I²C Serial interface for register programming
- RMS phase jitter at 125MHz, using a 40MHz crystal (12kHz - 20MHz): 616fs (typical), Low Bandwidth Mode (FracN)
- Output supply voltage modes:
  $V_{DD}/V_{DDA}/V_{DDO}$
  3.3V/3.3V/3.3V
  3.3V/3.3V/2.5V
  2.5V/2.5V/2.5V
- -40°C to 85°C ambient operating temperature
- Lead-free (RoHS 6) packaging

Pin Assignment



Complete Block Diagram



Pin Description and Pin Characteristic Tables

Table 1. Pin Descriptions

Number	Name	Type		Description
1 2	XTAL_IN XTAL_OUT	Input		Crystal oscillator interface designed for 12pF parallel resonant crystals. XTAL_IN (pin 1) is the input and XTAL_OUT (pin 2) is the output.
3, 7, 13, 29	V_{DD}	Power		Core supply pins. All must be either 3.3V or 2.5V.
4	CLK_SEL	Input	Pulldown	Input clock select. Selects the active differential clock input. 0 = CLK0, nCLK0 (default) 1 = CLK1, nCLK1
5	CLK0	Input	Pulldown	Non-inverting differential clock input.
6	nCLK0	Input	Pullup/ Pulldown	Inverting differential clock input. $V_{DD}/2$ default when left floating (set by the internal pullup and pulldown resistors).
8, 21, 23, 27, 35	GND	Power		Power supply pins.
9	CLK1	Input	Pulldown	Non-inverting differential clock input.
10	nCLK1	Input	Pullup/ Pulldown	Inverting differential clock input. $V_{DD}/2$ default when left floating (set by the internal pullup and pulldown resistors).
11, 32	nc	Unused		No connect. These pins are to be left unconnected.
12	PLL_BYPASS	Input	Pulldown	Bypasses the VCXO PLL. 0 = PLL NOT bypassed (default) 1 = PLL Bypassed
14	SDATA	I/O	Pullup	I^2C Data Input/Output. Open drain. LVCMOS/LVTTL Interface Levels.
15	SCLK	Input	Pullup	I^2C Clock Input. LVCMOS/LVTTL Interface Levels.
16	CONFIG	Input	Pulldown	Configuration Pin. Selects between one of two factory programmable pre-set power-up default configurations. The two configurations can have different output/input frequency translation ratios, different PLL loop bandwidths, etc. These default configurations can be overwritten after power-up via I^2C if the user so desires. 0 = Configuration 0 (default) 1 = Configuration 1
17	S_A1	Input	Pulldown	I^2C Address Bit 1. LVCMOS/LVTTL Interface Levels.
18	S_A0	Input	Pulldown	I^2C Address Bit 0. LVCMOS/LVTTL Interface Levels.
19, 20	Rsvd	Reserved		Reserved for future use. Should be left unconnected.
22	OE1	Input	Pullup	Active High Output Enable for Q1. 0 = Output pins high-impedance 1 = Output switching (default)
24	Q1	Output		Clock output. LVCMOS/LVTTL Interface Levels.
25	V_{DDO}	Power		Output supply voltage. Either 2.5V or 3.3V.
26	Q0	Output		Clock output. LVCMOS/LVTTL Interface Levels.
28	OE0	Input	Pullup	Active High Output Enable for Q0. 0 = Output pins high-impedance 1 = Output switching (default)
30	LOCK_IND	Output		Lock Indicator - indicates that the PLL is in a locked condition. LVCMOS/LVTTL interface levels.
31	CLK_ACTIVE	Output		Indicates which of the two differential clock inputs is currently selected. 0 - CLK0, nCLK0 differential input pair 1 - CLK1, nCLK1 differential input pair

Table 1. Pin Descriptions

Number	Name	Type		Description
33, 34	LF0, LF1	Input		Loop filter connection node pins. LF0 is the output. LF1 is the input.
36	V_{DDA}	Power		Analog supply voltage. See Applications section for details on how to connect this pin.
37	HOLDOVER	Output		Alarm output reflecting if the device is in a holdover state. LVCMOS/LVTTL interface levels. 0 = Device is locked to a valid input reference 1 = Device is not locked to a valid input reference
38	CLK0BAD	Output		Alarm output reflecting the state of CLK0. LVCMOS/LVTTL interface levels. 0 = Input Clock 0 is switching within specifications 1 = Input Clock 0 is out of specification
39	CLK1BAD	Output		Alarm output reflecting the state of CLK1. LVCMOS/LVTTL interface levels. 0 = Input Clock 1 is switching within specifications 1 = Input Clock 1 is out of specification
40	XTALBAD	Output		Alarm output reflecting the state of XTAL. LVCMOS/LVTTL interface levels. 0 = crystal is switching within specifications 1 = crystal is out of specification

NOTE: *Pullup and Pulldown* refer to internal input resistors. See Table 2, *Pin Characteristics,* for typical values.

Table 2. Pin Characteristics

Symbol	Parameter		Test Conditions	Minimum	Typical	Maximum	Units
C_{IN}	Input Capacitance	XTAL_IN, XTAL_OUT, PLL_BYPASS, CONFIG, A0, A1, OE0, OE1, SCLK			4		pF
C_{PD}	Power Dissipation Capacitance				8		pF
R_{PULLUP}	Input Pullup Resistor				51		kΩ
$R_{PULLDOWN}$	Input Pulldown Resistor				51		kΩ
R_{OUT}	Output Impedance	Q0, Q1			15		Ω
		CLK_ACTIVE, HOLDOVER, XTALBAD, CLK0BAD, CLK1BAD, LOCK_IND			25		Ω

Functional Description

The ICS840N202I is designed to provide two copies of almost any desired output frequency within its operating range (0.98 - 250MHz) from any input source in the operating range (8kHz - 710MHz). It is capable of synthesizing frequencies from a crystal or crystal oscillator source. The output frequency is generated regardless of the relationship to the input frequency. The output frequency will be exactly the required frequency in most cases. In most others, it will only differ from the desired frequency by a few ppb. IDT configuration software will indicate the frequency error, if any. The ICS840N202I can translate the desired output frequency from one of two input clocks. Again, no relationship is required between the input and output frequencies in order to translate to the output clock rate. In this frequency translation mode, a low-bandwidth, jitter attenuation option is available that makes use of an external fixed-frequency crystal or crystal oscillator to translate from a noisy input source. If the input clock is known to be fairly clean or if some modulation on the input needs to be tracked, then the high-bandwidth frequency translation mode can be used, without the need for the external crystal.

The input clock references and crystal input are monitored continuously and appropriate alarm outputs are raised both as register bits and hard-wired pins in the event of any out-of-specification conditions arising. Clock switching is supported in manual, revertive & non-revertive modes.

The ICS840N202I has two factory-programmed configurations that may be chosen from as the default operating state after reset. This is intended to allow the same device to be used in two different applications without any need for access to the I²C registers. These defaults may be over-written by I²C register access at any time, but those over-written settings will be lost on power-down. Please contact IDT if a specific set of power-up default settings is desired.

Configuration Selection

The ICS840N202I comes with two factory-programmed default configurations. When the device comes out of power-up reset the selected configuration is loaded into operating registers. The ICS840N202I uses the state of the CONFIG pin or CONFIG register bit (controlled by the CFG_PIN_REG bit) to determine which configuration is active. When the output frequency is changed either via the CONFIG pin or via internal registers, the output behavior may not be predictable during the register writing and output settling periods. Devices sensitive to glitches or runt pulses may have to be reset once reconfiguration is complete.

Once the device is out of reset, the contents of the operating registers can be modified by write access from the I²C serial port. Users that have a custom configuration programmed may not require I²C access.

It is expected that the ICS840N202I will be used almost exclusively in a mode where the selected configuration will be used from device power-up without any changes during operation. For example, the device may be designed into a communications line card that supports different I/O modules such as a standard OC-3 module running at 155.52MHz or a (255/237) FEC rate OC-3 module running at 167.332MHz. The different I/O modules would result in a different level on the CONFIG pin which would select different divider ratios within the ICS840N202I for the two different card configurations. Access via I²C would not be necessary for operation using either of the internal configurations.

Operating Modes

The ICS840N202I has three operating modes which are set by the MODE_SEL[1:0] bits. There are two frequency translator modes - low bandwidth and high bandwidth and a frequency synthesizer mode. The device will operate in the same mode regardless of which configuration is active.

Please make use of IDT-provided configuration applications to determine the best operating settings for the desired configurations of the device.

Output Dividers & Supported Output Frequencies

In all 3 operating modes, the output stage behaves the same way, but different operating frequencies can be specified in the two configurations.

The internal VCO is capable of operating in a range anywhere from 1.995GHz - 2.6GHz. It is necessary to choose an integer multiplier of the desired output frequency that results in a VCO operating frequency within that range. The output divider stage N[10:0] is limited to selection of even integers from 10 to 2046. Please refer to Table 3 for the values of N applicable to the desired output frequency.

Table 3. Output Divider Settings & Frequency Ranges

Register Setting	Frequency Divider	Minimum f_{OUT}	Maximum f_{OUT}
Nn[10:0]	N	(MHz)	(MHz)
00000000000 - 0000000100x	2 - 8	Not Supported	
0000000101x	10	199.5	260 (Note 1)
0000000110x	12	166.3	216.7
0000000111x	14	142.5	185.7
0000001000x	16	124.7	162.5
0000001001x	18	110.8	144.4
...	Even N	1995 / N	2600 / N
1111111111x	2046	0.98	1.27

Note 1: using a divider setting of N = 0x00A or 0x00B with a high VCO frequency can result in the CMOS output running faster than its 250MHz maximum operating frequency.

Frequency Synthesizer Mode

This mode of operation allows an arbitrary output frequency to be generated from a fundamental mode crystal input. As can be seen from the block diagram in Figure 1, only the upper feedback loop is used in this mode of operation.

The upper feedback loop supports a delta-sigma fractional feedback divider. This allows the VCO operating frequency to be a non-integer multiple of the crystal frequency. By using an integer multiple only, lower phase noise jitter on the output can be achieved, however the use of the delta-sigma divider logic will provide excellent performance on the output if a fractional divisor is used.

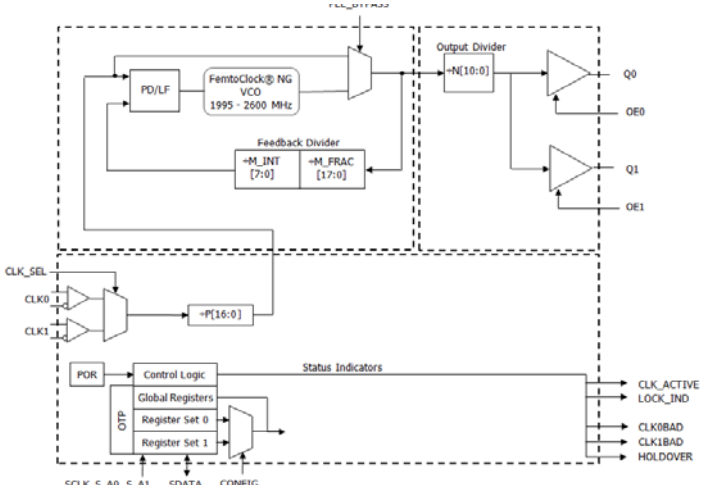


Figure 1. Frequency Synthesizer Mode Block Diagram

High-Bandwidth Frequency Translator Mode

This mode of operation is used to translate one of two input clocks of the same nominal frequency into an output frequency with little jitter attenuation. As can be seen from the block diagram in *Figure 2,* similarly to the Frequency Synthesizer mode, only the upper feedback loop is used.

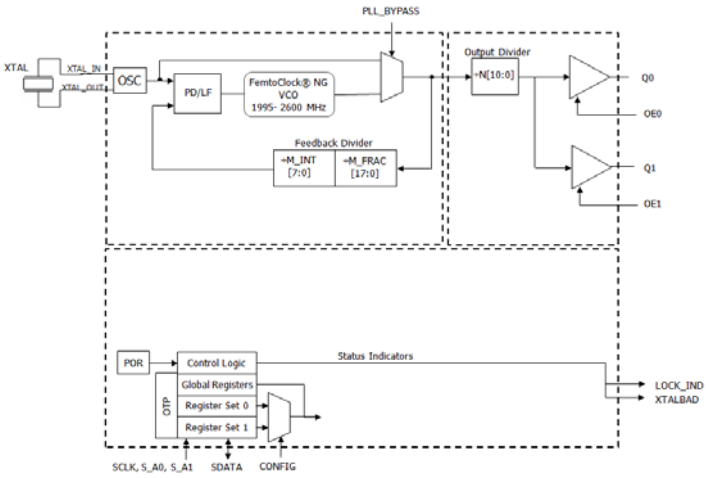


Figure 2. High Bandwidth Frequency Translator Mode Block Diagram

The input reference frequency range is now extended up to 710MHz. A pre-divider stage P is needed to keep the operating frequencies at the phase detector within limits.

Low-Bandwidth Frequency Translator Mode

As can seen from the block diagram in *Figure 3,* this mode involves two PLL loops. The lower loop with the large integer dividers is the low bandwidth loop and it sets the output-to-input frequency translation ratio.This loop drives the upper DCXO loop (digitally controlled crystal oscillator) via an analog-digital converter.

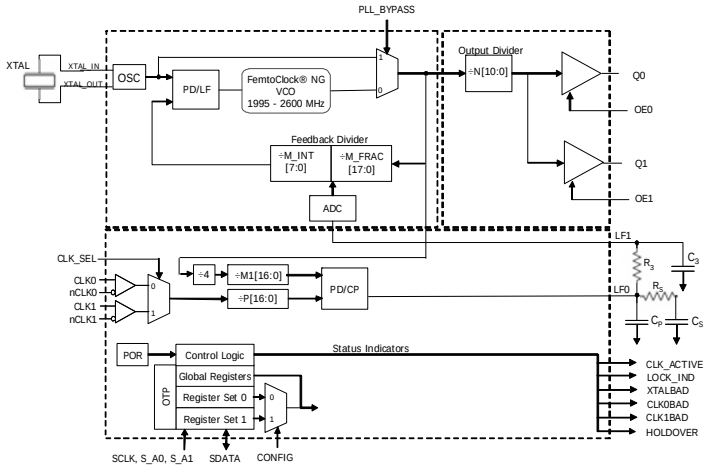


Figure 3. Low Bandwidth Frequency Translator Mode Block Diagram

The phase detector of the lower loop is designed to work with frequencies in the 8kHz - 16kHz range. The pre-divider stage is used to scale down the input frequency by an integer value to achieve a frequency in this range. By dividing down the fed-back VCO operating frequency by the integer divider M1[18:0] to as close as possible to the same frequency, very accurate output frequency translations can be achieved.

Alarm Conditions & Status Bits

The ICS840N202I monitors a number of conditions and reports their status via both output pins and register bits. All alarms will behave as indicated below in all modes of operation, but some of the conditions monitored have no valid meaning in some operating modes. For example, the status of CLK0BAD, CLK1BAD and CLK_ACTIVE are not relevant in Frequency Synthesizer mode. The outputs will still be active and it is left to the user to determine which to monitor and how to respond to them based on the known operating mode.

CLK_ACTIVE - indicates which input clock reference is being used to derive the output frequency.

LOCK_IND - This status is asserted on the pin & register bit when the PLL is locked to the appropriate input reference for the chosen mode of operation. The status bit will not assert until frequency lock has been achieved, but will de-assert once lock is lost.

XTALBAD - indicates if valid edges are being received on the crystal input. Detection is performed by comparing the input to the feedback signal at the upper loop's Phase / Frequency Detector (PFD). If three edges are received on the feedback without an edge on the crystal input, the XTALBAD alarm is asserted on the pin & register bit. Once an edge is detected on the crystal input, the alarm is immediately deasserted.

CLK0BAD - indicates if valid edges are being received on the CLK0 reference input. Detection is performed by comparing the input to the feedback signal at the appropriate Phase / Frequency Detector (PFD). When operating in high-bandwidth mode, the feedback at the upper PFD is used. In low-bandwidth mode, the feedback at the lower PFD is used. If three edges are received on the feedback without an edge on the divided down (÷P) CLK0 reference input, the CLK0BAD alarm is asserted on the pin & register bit. Once an edge is detected on the CLK0 reference input, the alarm is deasserted.

CLK1BAD - indicates if valid edges are being received on the CLK1 reference input. Behavior is as indicated for the CLK0BAD alarm, but with the CLK1 input being monitored and the CLK1BAD output pin & register bits being affected.

HOLDOVER - indicates that the device is not locked to a valid input reference clock. This can occur in Manual switchover mode if the selected reference input has gone bad, even if the other reference input is still good. In automatic mode, this will only assert if both input references are bad.

Input Reference Selection and Switching

When operating in Frequency Synthesizer mode, the CLK0 and CLK1 inputs are not used and the contents of this section do not apply. Except as noted below, when operating in either High or Low Bandwidth Frequency Translator mode, the contents of this section apply equally when in either of those modes.

Both input references CLK0 and CLK1 must be the same nominal frequency. These may be driven by any type of clock source, including crystal oscillator modules. A difference in frequency may cause the PLL to lose lock when switching between input references. Please contact IDT for the exact limits for your situation.

The global control bits AUTO_MAN[1:0] dictate the order of priority and switching mode to be used between the CLK0 and CLK1 inputs.

Manual Switching Mode

When the AUTO_MAN[1:0] field is set to Manual via Pin, then the ICS840N202I will use the CLK_SEL input pin to determine which input to use as a reference. Similarly, if set to Manual via Register, then the device will use the CLK_SEL register bit to determine the input reference. In either case, the PLL will lock to the selected reference if there is a valid clock present on that input.

If there is not a valid clock present on the selected input, the ICS840N202I will go into holdover (Low Bandwidth Frequency Translator mode) or free-run (High Bandwidth Frequency Translator mode) state. In either case, the HOLDOVER alarm will be raised. This will occur even if there is a valid clock on the non-selected reference input.

The device will recover from holdover / free-run state once a valid clock is re-established on the selected reference input.

The ICS840N202I will only switch input references on command from the user. The user must either change the CLK_SEL register bit (if in Manual via Register) or CLK_SEL input pin (if in Manual via Pin).

Automatic Switching Mode

When the AUTO_MAN[1:0] field is set to either of the automatic selection modes (Revertive or Non-Revertive), the ICS840N202I determines which input reference it prefers / starts from by the state of the CLK_SEL register bit only. The CLK_SEL input pin is not used in either Automatic switching mode.

When starting from an unlocked condition, the device will lock to the input reference indicated by the CLK_SEL register bit. It will not pay attention to the non-selected input reference until a locked state has been achieved. This is necessary to prevent 'hunting' behavior during the locking phase.

Once the ICS840N202I has achieved a stable lock, it will remain locked to the preferred input reference as long as there is a valid clock on it. If at some point, that clock fails, then the device will automatically switch to the other input reference as long as there is a valid clock there. If there is not a valid clock on either input reference, the ICS840N202I will go into holdover (Low Bandwidth Frequency Translator mode) or free-run (High Bandwidth Frequency Translator mode) state. In either case, the HOLDOVER alarm will be raised.

The device will recover from holdover / free-run state once a valid clock is re-established on either reference input. If clocks are valid on both input references, the device will choose the reference indicated by the CLK_SEL register bit.

If running from the non-preferred input reference and a valid clock returns, there is a difference in behavior between Revertive and Non-revertive modes. In Revertive mode, the device will switch back to the reference indicated by the CLK_SEL register bit even if there is still a valid clock on the non-preferred reference input. In Non-revertive mode, the ICS840N202I will not switch back as long as the non-preferred input reference still has a valid clock on it.

Switchover Behavior of the PLL

Even though the two input references have the same nominal frequency, there may be minor differences in frequency and potentially large differences in phase between them. The ICS840N202I will adjust its output to the new input reference. It will use Phase Slope Limiting to adjust the output phase at a fixed maximum rate until the output phase and frequency are now aligned to the new input reference. Phase will always be adjusted by extending the clock period of the output so that no unacceptably short clock periods are generated on the output ICS840N202I.

Holdover / Free-run Behavior

When both input references have failed (Automatic mode) or the selected input has failed (Manual mode), the ICS840N202I will enter holdover (Low Bandwidth Frequency Translator mode) or free-run (High Bandwidth Frequency Translator mode) state . In both cases, once both input references are lost, the PLL will stop making adjustments to the output phase.

If operating in Low Bandwidth Frequency Translation mode, the PLL will continue to reference itself to the local oscillator and will hold its output phase and frequency in relation to that source. Output stability is determined by the stability of the local oscillator in this case.

However, if operating in High Bandwidth Frequency Translation mode, the PLL no longer has any frequency reference to use and output stability is now determined by the stability of the internal VCO.

If the device is programmed to perform Manual switching, once the selected input reference recovers, the ICS840N202I will switch back to that input reference. If programmed for either Automatic mode, the device will switch back to whichever input reference has a valid clock first.

The switchover that results from returning from holdover or free-run is handled in the same way as a switch between two valid input references as described in the previous section.

Output Configuration

The two outputs of the ICS840N202I both provide the same clock frequency. Both must operate from the same output voltage level of 3.3V or 2.5V, although this output voltage may be less than or equal to the core voltage (3.3V or 2.5V) the rest of the device is operating from. The output voltage level used on the two outputs is supplied on the V_{DDO} pin.

The two outputs can be enabled individually via both register control bits and input pins. When both the OEn register bit and OEn pin are enabled, then the appropriate output is enabled. The OEn register bits default to enabled so that by default the outputs can be directly controlled by the input pins. Similarly, the input pins are provisioned with weak pull-ups so that if they are left unconnected, the output state can be directly controlled by the register bits. When the output is in the disabled state, it will show a high impedance condition.

Serial Interface Configuration Description

The ICS840N202I has an I²C-compatible configuration interface to access any of the internal registers (Table 4D) for frequency and PLL parameter programming. The ICS840N202I acts as a slave device on the I²C bus and has the address 0b11011xx, where xx is set by the values on the S_A0 & S_A1 pins (see Table 4A for details). The interface accepts byte-oriented block write and block read operations. An address byte (P) specifies the register address (Table 4D) as the byte position of the first register to write or read. Data bytes (registers) are accessed in sequential order from the lowest to the highest byte (most significant bit first, see table 4B, 4C). Read and write block transfers can be stopped after any complete byte transfer. It is recommended to terminate I²C the read or write transfer after accessing byte #23.

For full electrical I²C compliance, it is recommended to use external pull-up resistors for SDATA and SCLK. The internal pull-up resistors have a size of 50kΩ typical.

Note: if a different device slave address is desired, please contact IDT.

Table 4A. I²C Device Slave Address

1	1	0	1	1	S_A1	S_A0	R/W

Table 4B. Block Write Operation

Bit	1	2:8	9	10	11:18	19	20:27	28	29-36	37	...	...	...
Description	START	Slave Address	W (0)	ACK	Address Byte (P)	ACK	Data Byte (P)	ACK	Data Byte (P+1)	ACK	Data Byte ...	ACK	STOP
Length (bits)	1	7	1	1	8	1	8	1	8	1	8	1	1

Table 4C. Block Read Operation

Bit	1	2:8	9	10	11:18	19	20	21:27	28	29	30:37	38	39-46	47	...	...	...
Description	START	Slave Address	W (0)	ACK	Address Byte (P)	ACK	Repeated START	Slave Address	R (1)	ACK	Data Byte (P)	ACK	Data Byte (P+1)	ACK	Data Byte ...	ACK	STOP
Length (bits	1	7	1	1	8	1	1	7	1	1	8	1	8	1	8	1	1

Register Descriptions

Please consult IDT for configuration software and/or programming guides to assist in selection of optimal register settings for the desired configurations.

Table 4D. I²C Register Map

Register	Binary Register Address	Register Bit							
		D7	D6	D5	D4	D3	D2	D1	D0
0	00000	MFRAC0[17]	MFRAC0[16]	MFRAC0[15]	MFRAC0[14]	MFRAC0[13]	MFRAC0[12]	MFRAC0[11]	MFRAC0[10]
1	00001	MFRAC1[17]	MFRAC1[16]	MFRAC1[15]	MFRAC1[14]	MFRAC1[13]	MFRAC1[12]	MFRAC1[11]	MFRAC1[10]
2	00010	MFRAC0[9]	MFRAC0[8]	MFRAC0[7]	MFRAC0[6]	MFRAC0[5]	MFRAC0[4]	MFRAC0[3]	MFRAC0[2]
3	00011	MFRAC1[9]	MFRAC1[8]	MFRAC1[7]	MFRAC1[6]	MFRAC1[5]	MFRAC1[4]	MFRAC1[3]	MFRAC1[2]
4	00100	MFRAC0[1]	MFRAC0[0]	MINT0[7]	MINT0[6]	MINT0[5]	MINT0[4]	MINT0[3]	MINT0[2]
5	00101	MFRAC1[1]	MFRAC1[0]	MINT1[7]	MINT1[6]	MINT1[5]	MINT1[4]	MINT1[3]	MINT1[2]
6	00110	MINT0[1]	MINT0[0]	P0[16]	P0[15]	P0[14]	P0[13]	P0[12]	P0[11]
7	00111	MINT1[1]	MINT1[0]	P1[16]	P1[15]	P1[14]	P1[13]	P1[12]	P1[11]
8	01000	P0[10]	P0[9]	P0[8]	P0[7]	P0[6]	P0[5]	P0[4]	P0[3]
9	01001	P1[10]	P1[9]	P1[8]	P1[7]	P1[6]	P1[5]	P1[4]	P1[3]
10	01010	P0[2]	P0[1]	P0[0]	M1_0[16]	M1_0[15]	M1_0[14]	M1_0[13]	M1_0[12]
11	01011	P1[2]	P1[1]	P1[0]	M1_1[16]	M1_1[15]	M1_1[14]	M1_1[13]	M1_1[12]
12	01100	M1_0[11]	M1_0[10]	M1_0[9]	M1_0[8]	M1_0[7]	M1_0[6]	M1_0[5]	M1_0[4]
13	01101	M1_1[11]	M1_1[10]	M1_1[9]	M1_1[8]	M1_1[7]	M1_1[6]	M1_1[5]	M1_1[4]
14	01110	M1_0[3]	M1_0[2]	M1_0[1]	M1_0[0]	N0[10]	N0[9]	N0[8]	N0[7]
15	01111	M1_1[3]	M1_1[2]	M1_1[1]	M1_1[0]	N1[10]	N1[9]	N1[8]	N1[7]
16	10000	N0[6]	N0[5]	N0[4]	N0[3]	N0[2]	N0[1]	N0[0]	BW0[6]
17	10001	N1[6]	N1[5]	N1[4]	N1[3]	N1[2]	N1[1]	N1[0]	BW1[6]
18	10010	BW0[5]	BW0[4]	BW0[3]	BW0[2]	BW0[1]	BW0[0]	Rsvd	Rsvd
19	10011	BW1[5]	BW1[4]	BW1[3]	BW1[2]	BW1[1]	BW1[0]	Rsvd	Rsvd
20	10100	MODE_SEL[1]	MODE_SEL[0]	CONFIG	CFG_PIN_REG	OE1	OE0	Rsvd	Rsvd
21	10101	CLK_SEL	AUTO_MAN[1]	AUTO_MAN[0]	0	ADC_RATE[1]	ADC_RATE[0]	LCK_WIN[1]	LCK_WIN[0]
22	10110	1	0	1	0	0	0	0	0
23	10111	CLK_ACTIVE	HOLDOVER	CLK1BAD	CLK0BAD	XTAL_BAD	LOCK_IND	Rsvd	Rsvd

Register Bit Color Key

Configuration 0 Specific Bits
Configuration 1 Specific Bits
Global Control & Status Bits

The register bits described in Table 4E are duplicated, with one set applying for Configuration 0 and the other for Configuration 1. The functions of the bits are identical, but only apply when the configuration they apply to is enabled. Replace the lowercase n in the bit field description with 0 or 1 to find the field's location in the bitmap in Table 4D.

Table 4E. Configuration-Specific Control Bits

Register Bits	Function
Pn[16:0]	Reference Pre-Divider for Configuration n.
M1_n[16:0]	Integer Feedback Divider in Lower Feedback Loop for Configuration n.
M_INTn[7:0]	Feedback Divider, Integer Value in Upper Feedback Loop for Configuration n.
M_FRACn[17:0]	Feedback Divider, Fractional Value in Upper Feedback Loop for Configuration n.
Nn[10:0]	Output Divider for Configuration n.
BWn[6:0]	Internal Operation Settings for Configuration n. Please use IDT ICS840N202I Configuration Software to determine the correct settings for these bits for the specific configuration. Alternatively, please consult with IDT directly for further information on the functions of these bits.The function of these bits is explained in Tables 4J and 4K.

Table 4F. Global Control Bits

Register Bits	Function
MODE_SEL[1:0]	PLL Mode Select 00 = Low Bandwidth Frequency Translator 01 = Frequency Synthesizer 10 = High Bandwidth Frequency Translator 11 = High Bandwidth Frequency Translator
CFG_PIN_REG	Configuration Control. Selects whether the configuration selection function is under pin or register control. 0 = Pin Control 1 = Register Control
CONFIG	Configuration Selection. Selects whether the device uses the register configuration set 0 or 1. This bit only has an effect when the CFG_PIN_REG bit is set to 1 to enable register control.
OE0	Output Enable Control for Output 0. Both this register bit and the corresponding Output Enable pin OE0 must be asserted to enable the Q0 output. 0 = Output Q0 disabled 1 = Output Q0 under control of the OE0 pin
OE1	Output Enable Control for Output 1. Both this register bit and the corresponding Output Enable pin OE1 must be asserted to enable the Q1 output. 0 = Output Q1 disabled 1 = Output Q1 under control of the OE1 pin
Rsvd	Reserved bits - user should write a '0' to these bit positions if a write to these registers is needed
AUTO_MAN[1:0]	Selects how input clock selection is performed. 00 = Manual Selection via pin only 01 = Automatic, non-revertive 10 = Automatic, revertive 11 = Manual Selection via register only
CLK_SEL	In manual clock selection via register mode, this bit will command which input clock is selected. In the automatic modes, this indicates the primary clock input. In manual selection via pin mode, this bit has no effect. 0 = CLK0 1 = CLK1
ADC_RATE[1:0]	Sets the ADC sampling rate in Low-Bandwidth Mode as a fraction of the crystal input frequency. 00 = Crystal Frequency / 16 01 = Crystal Frequency / 8 10 = Crystal Frequency / 4 (recommended) 11 = Crystal Frequency / 2
LCK_WIN[1:0]	Sets the width of the window in which a new reference edge must fall relative to the feedback edge: 00 = 2usec (recommended), 01 = 4usec, 10 = 8usec, 11 = 16usec

Table 4G. Global Status Bits

Register Bits	Function
CLK0BAD	Status Bit for input clock 0. This function is mirrored in the CLK0BAD pin. 0 = input CLK0 is good 1 = input CLK0 is bad. Self clears when input clock returns to good status
CLK1BAD	Status Bit for input clock 1. This function is mirrored in the CLK1BAD pin. 0 = input CLK1 is good 1 = input CLK1 is bad. Self clears when input clock returns to good status
XTALBAD	Status Bit. This function is mirrored on the XTALBAD pin. 0 = crystal input good 1 = crystal input bad. Self-clears when the XTAL clock returns to good status
LOCK_IND	Status bit. This function is mirrored on the LOCK_IND pin. 0 = PLL unlocked 1 = PLL locked
HOLDOVER	Status Bit. This function is mirrored on the HOLDOVER pin. 0 = Input to phase detector is within specifications and device is tracking to it 1 = Phase detector input not within specifications and DCXO is frozen at last value
CLK_ACTIVE	Status Bit. Indicates which input clock is active. Automatically updates during fail-over switching. Status also indicated on CLK_ACTIVE pin.

Table 4J. BW[6:0] Bits

Mode	BW[6]	BW[5]	BW[4]	BW[3]	BW[2]	BW[1]	BW[0]
Synthesizer Mode	PLL2_LF[1]	PLL2_LF[0]	DSM_ORD	DSM_EN	PLL2_CP[1]	PLL2_CP[0]	PLL2_LOW_ICP
High-Bandwidth Mode	PLL2_LF[1]	PLL2_LF[0]	DSM_ORD	DSM_EN	PLL2_CP[1]	PLL2_CP[0]	PLL2_LOW_ICP
Low-Bandwidth Mode	ADC_GAIN[3]	ADC_GAIN[2]	ADC_GAIN[1]	ADC_GAIN[0]	PLL1_CP[1]	PLL1_CP[0]	PLL2_LOW_ICP

Table 4K. Functions of Fields in BW[6:0]

Register Bits	Function
PLL2_LF[1:0]	Sets loop filter values for upper loop PLL in Frequency Synthesizer & High-Bandwidth modes. Defaults to setting of 00 when in Low Bandwidth Mode. See Table 4L for settings.
DSM_ORD	Sets Delta-Sigma Modulation to 2nd (0) or 3rd order (1) operation.
DSM_EN	Enables Delta-Sigma Modulator. 0 = Disabled - feedback in integer mode only 1 = Enabled - feedback in fractional mode
PLL2_CP[1:0]	Upper loop PLL charge pump current settings: 00 = 173µA (defaults to this setting in Low Bandwidth Mode) 01 = 346µA 10 = 692µA 11 = reserved
PLL2_LOW_ICP	Reduces Charge Pump current by 1/3RD to reduce bandwidth variations resulting from higher feedback register settings or high VCO operating frequency (>2.4GHz).
ADC_GAIN[3:0]	Gain setting for ADC in Low Bandwidth Mode.
PLL1_CP[1:0]	Lower loop PLL charge pump current settings (lower loop is only used in Low Bandwidth Mode): 00 = 800µA 01 = 400µA 10 = 200µA 11 = 100µA

Table 4L. Upper Loop (PLL2) Bandwidth Settings

Desired Bandwidth	PLL2_CP	PLL2ICP	PLL2_LF
Frequency Synthesizer Mode			
200kHz	00	1	00
400kHz	01	1	01
800kHz	10	1	10
2MHz	10	1	11
High Bandwidth Frequency Translator Mode			
200kHz	00	1	00
400kHz	01	1	01
800kHz	10	1	10
4MHz	10	0	11
Low Bandwidth Frequency Translator Mode			
200kHz	00		00

NOTE: To achieve 4MHz bandwidth, reference to the phase detector should be 80MHz.

Absolute Maximum Ratings

NOTE: Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These ratings are stress specifications only. Functional operation of product at these conditions or any conditions beyond those listed in the *DC Characteristics or AC Characteristics* is not implied. Exposure to absolute maximum rating conditions for extended periods may affect product reliability.

Item	Rating
Supply Voltage, V_{DD}	3.63V
Inputs, V_I XTAL_IN Other Input	 0V to 2V -0.5V to V_{DD} + 0.5V
Outputs, V_O (LVCMOS)	-0.5V to V_{DDO} + 0.5V
Outputs, SDATA	10mA
Package Thermal Impedance, θ_{JA}	32.4°C/W (0 mps)
Storage Temperature, T_{STG}	-65°C to 150°C

DC Electrical Characteristics

Table 5A. Power Supply DC Characteristics, $V_{DD} = V_{DDO} = 3.3V±5\%$, T_A = -40°C to 85°C

Symbol	Parameter	Test Conditions	Minimum	Typical	Maximum	Units
V_{DD}	Core Supply Voltage		3.135	3.3	3.465	V
V_{DDA}	Analog Supply Voltage		3.135	3.3	3.465	V
V_{DDO}	Output Supply Voltage		3.135	3.3	3.465	V
$I_{DD} + I_{DDO}$	Power + Output Supply Current	Outputs Unloaded			289	mA
I_{DDA}	Analog Supply Current				31	mA

Table 5B. Power Supply DC Characteristics, $V_{DD} = 3.3V±5\%$, $V_{DDO} = 2.5V±5\%$, T_A = -40°C to 85°C

Symbol	Parameter	Test Conditions	Minimum	Typical	Maximum	Units
V_{DD}	Core Supply Voltage		3.135	3.3	3.465	V
V_{DDA}	Analog Supply Voltage		3.135	3.3	3.465	V
V_{DDO}	Output Supply Voltage		2.375	2.5	2.625	V
$I_{DD} + I_{DDO}$	Power + Output Supply Current	Outputs Unloaded			288	mA
I_{DDA}	Analog Supply Current				31	mA

Table 5C. Power Supply DC Characteristics, $V_{DD} = V_{DDO} = 2.5V±5\%$, T_A = -40°C to 85°C

Symbol	Parameter	Test Conditions	Minimum	Typical	Maximum	Units
V_{DD}	Core Supply Voltage		2.375	2.5	2.625	V
V_{DDA}	Analog Supply Voltage		2.375	2.5	2.625	V
V_{DDO}	Output Supply Voltage		2.375	2.5	2.625	V
$I_{DD} + I_{DDO}$	Power + Output Supply Current	Outputs Unloaded			275	mA
I_{DDA}	Analog Supply Current				29	mA

Table 5D. LVCMOS/LVTTL DC Characteristics, T_A = -40°C to 85°C

Symbol	Parameter		Test Conditions	Minimum	Typical	Maximum	Units
V_{IH}	Input High Voltage		V_{DD} = 3.3V	2		V_{DD} + 0.3	V
			V_{DD} = 2.5V	1.7		V_{DD} + 0.3	V
V_{IL}	Input Low Voltage		V_{DD} = 3.3V	-0.3		0.8	V
			V_{DD} = 2.5V	-0.3		0.7	V
I_{IH}	Input High Current	CLK_SEL, CONFIG, PLL_BYPASS, S_A[0:1]	V_{DD} = V_{IN} = 3.465V or 2.625V			150	µA
		OE0, OE1, SCLK, SDATA	V_{DD} = V_{IN} = 3.465V or 2.625V			5	µA
I_{IL}	Input Low Current	CLK_SEL, CONFIG, PLL_BYPASS, S_A[0:1]	V_{DD} = 3.465V or 2.625V, V_{IN} = 0V	-5			µA
		OE0, OE1, SCLK, SDATA	V_{DD} = 3.465V or 2.625V, V_{IN} = 0V	-150			µA
V_{OH}	Output High Voltage	XTALBAD, CLK0BAD, CLK1BAD, CLK_ACTIVE, SDATA, HOLDOVER, LOCK_IND	V_{DDO} = 3.465V, I_{OH} = -8mA	2.6			V
			V_{DDO} = 2.625V, I_{OH} = -8mA	1.8			V
		Q0, Q1	V_{DDO} = 3.465V, I_{OH} = -12mA	2.6			V
			V_{DDO} = 2.625V, I_{OH} = -12mA	1.8			V
V_{OL}	Output Low Voltage	XTALBAD, CLK0BAD, CLK1BAD, CLK_ACTIVE, SDATA, HOLDOVER, LOCK_IND	V_{DDO} = 3.465V or 2.625V, I_{OH} = 8mA			0.5	V
		Q0, Q1	V_{DDO} = 3.465V or 2.625V, I_{OH} = 12mA			0.5	V

Table 5E. Differential DC Characteristics, V_{DD} = V_{DDO} = 3.3V ± 5% or 2.5V ± 5%, T_A = -40°C to 85°C

Symbol	Parameter		Test Conditions	Minimum	Typical	Maximum	Units
I_{IH}	Input High Current	CLK0, nCLK0, CLK1, nCLK1	V_{DD} = V_{IN} = 3.465V or 2.625V			150	µA
I_{IL}	Input Low Current	CLK0, CLK1	V_{DD} = 3.465V or 2.625V, V_{IN} = 0V	-5			µA
		nCLK0, nCLK1	V_{DD} = 3.465V or 2.625V, V_{IN} = 0V	-150			µA
V_{PP}	Peak-to-Peak Voltage; NOTE 1			0.15		1.3	V
V_{CMR}	Common Mode Input Voltage; NOTE 1, 2			GND + 0.5		V_{DD} – 1.0	V

NOTE 1: V_{IL} should not be less than -0.3V. V_{IH} should not be greater than V_{DD}.
NOTE 2: Common mode voltage is defined as the crosspoint.

Table 6. Input Frequency Characteristics, $V_{DD} = V_{DDO} = 3.3V±5\%$ or $2.5V±5\%$, or $V_{DD} = 3.3V±5\%$, $V_{DDO} = 2.5V±5\%$, T_A = -40°C to 85°C

Symbol	Parameter		Test Conditions	Minimum	Typical	Maximum	Units
f_{IN}	Input Frequency	XTAL_IN, XTAL_OUT NOTE 1		16		40	MHz
		CLK0, nCLK0, CLK1, nCLK1	High Bandwidth Mode	16		710	MHz
			Low Bandwidth Mode	0.008		710	MHz
		SCLK				5	MHz

NOTE 1: For the input crystal and CLKx, nCLKx frequency range, the M value must be set for the VCO to operate within the 1995MHz to 2600MHz range.

Table 7. Crystal Characteristics

Parameter	Test Conditions	Minimum	Typical	Maximum	Units
Mode of Oscillation		Fundamental			
Frequency		16		40	MHz
Load Capacitance (C_L)			12		pF
Equivalent Series Resistance (ESR)				100	Ω
Shunt Capacitance				7	pF

AC Electrical Characteristics

Table 8. AC Characteristics, $V_{DD} = V_{DDO} = 3.3V±5\%$ or 2.5V±5%, or $V_{DD} = 3.3V±5\%$, $V_{DDO} = 2.5V±5\%$, T_A = -40°C to 85°C

Symbol	Parameter		Test Conditions	Minimum	Typical	Maximum	Units
f_{OUT}	Output Frequency			0.98		250	MHz
*t*jit(Ø)	RMS Phase Jitter (Random); NOTE 1		LBW Mode, 40MHz XTAL, f_{IN} = 25MHz, f_{OUT} = 125MHz, Integration Range: 12kHz – 20MHz		616	865	fs
*t*jit(cc)	Cycle-to-Cycle Jitter; NOTE 2, 3		Frequency Synthesizer Mode			35	ps
			Frequency Translator Mode			40	ps
*t*jit(per)	RMS Period Jitter; NOTE 3				1.4	4.5	ps
*t*sk(o)	Output Skew; NOTE 2					50	ps
t_R / t_F	Output Rise/Fall Time; NOTE 3	Q0, Q1	20% to 80%	100		750	ps
odc	Output Duty Cycle: NOTE 3	Q0, Q1	$f_{OUT} \leq$ 125MHz	45		55	%
		Q0, Q1	125MHz < $f_{OUT} \leq$ 200MHz	40		60	%
		Q0, Q1	f_{OUT} > 200MHz	37		63	%
t_{SET}	Output Re-configuration Settling Time		from falling edge of the 8th SCLK for a register change		200		ns
			from edge on CONFIG pin		10		ns

NOTE: Electrical parameters are guaranteed over the specified ambient operating temperature range, which is established when the device is mounted in a test socket with maintained transverse airflow greater than 500 lfpm. The device will meet specifications after thermal equilibrium has been reached under these conditions.

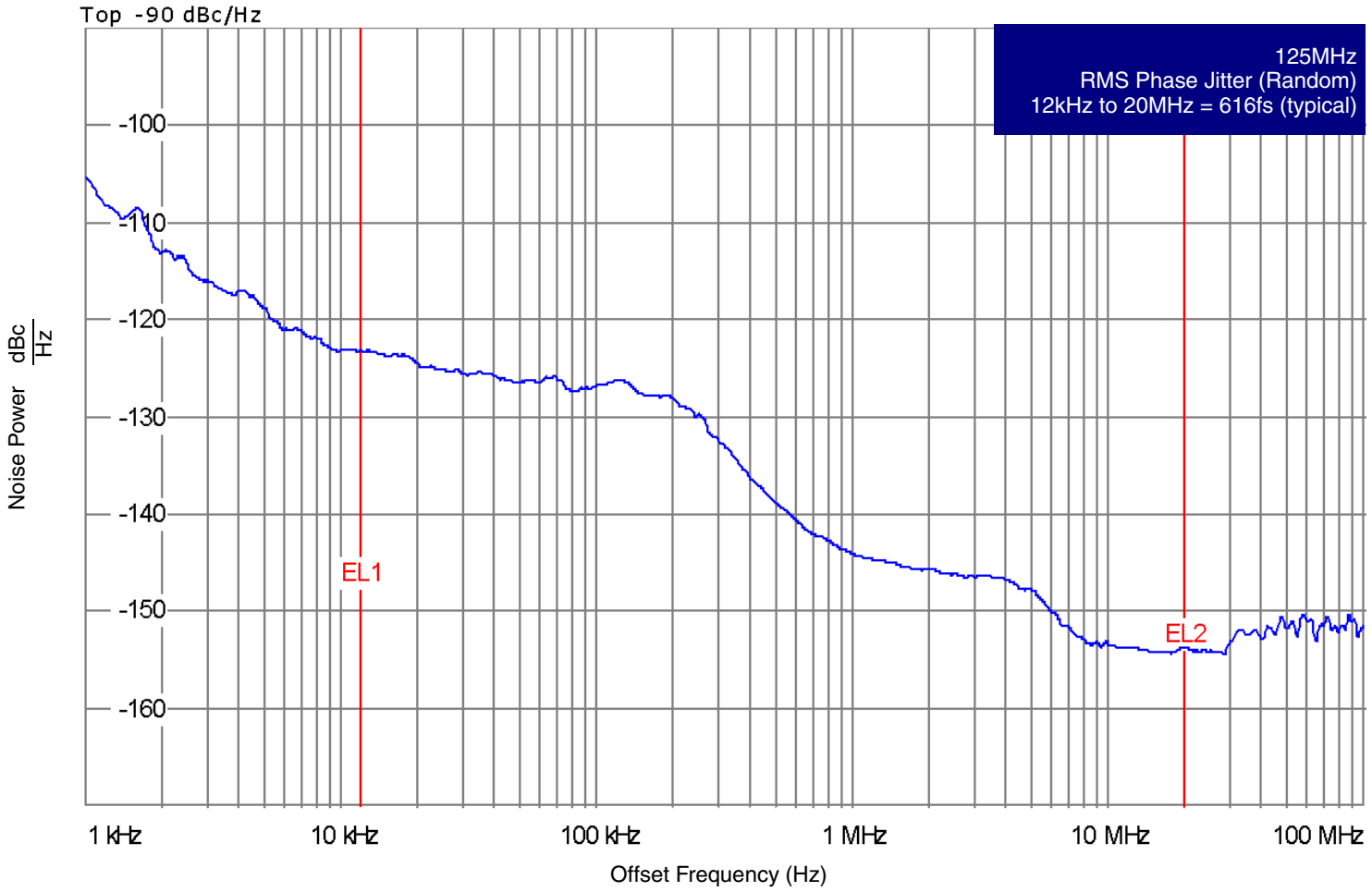
NOTE: Above AC characteristics are measured with crystal C_L = 12pF.

NOTE 1: RMS phase jitter measured with crystal C_L = 12pF.

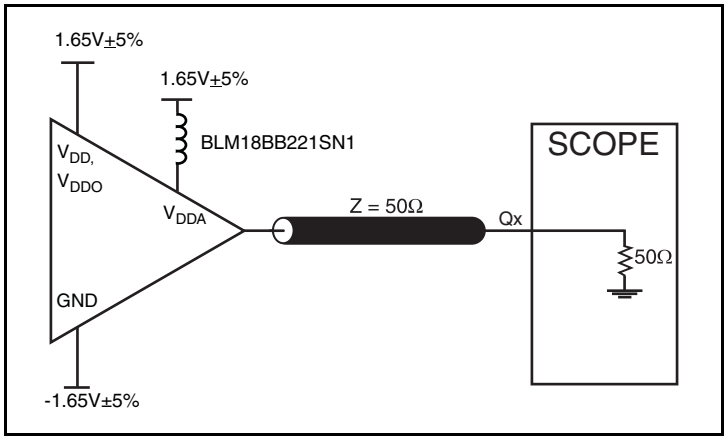
NOTE 2: This parameter is defined in accordance with JEDEC Standard 65.

NOTE 3: Measurements are collected with the following output frequencies: 15MHz, 38.88MHz, 50MHz, 68.88MHz, 125MHz, 132.61MHz, 156.25MHz, 161.1328125MHz, 200MHz, 233.33MHz, 250MHz.

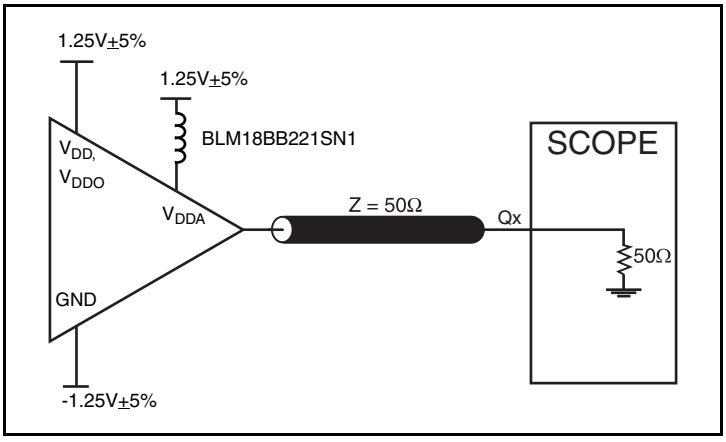
Typical Phase Noise at 125MHz (LBW Mode)



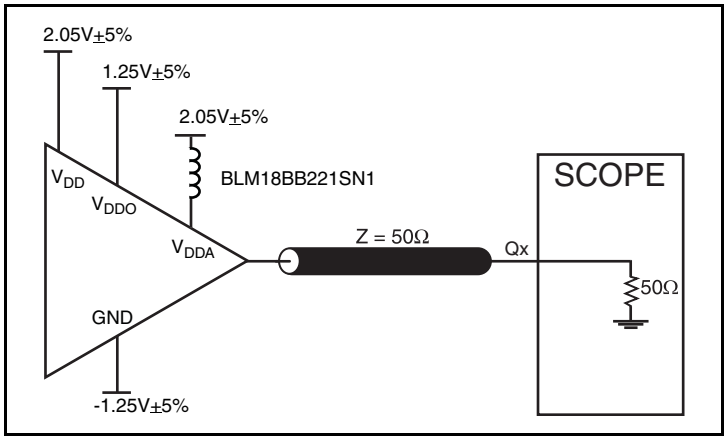
Parameter Measurement Information



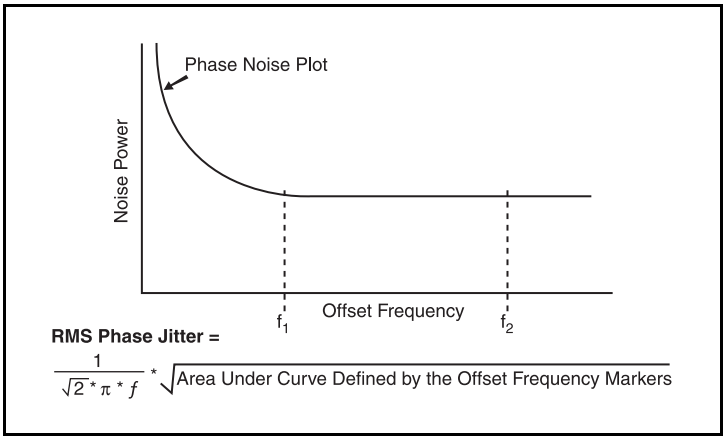
3.3 Core/3.3V LVCMOS Output Load Test Circuit



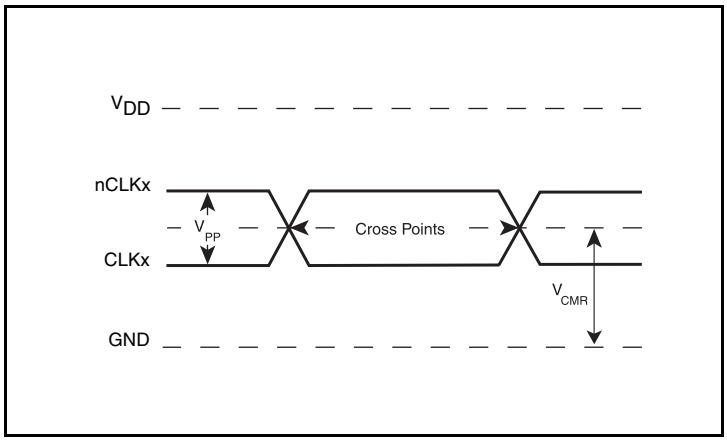
2.5 Core/2.5V LVCMOS Output Load Test Circuit



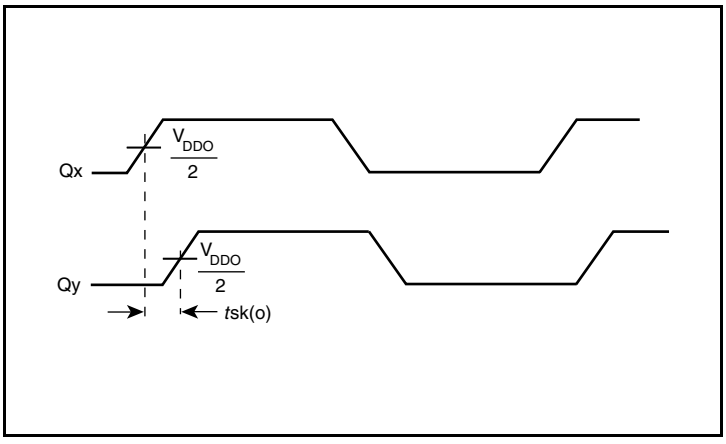
3.3 Core/2.5V LVCMOS Output Load Test Circuit



RMS Phase Jitter

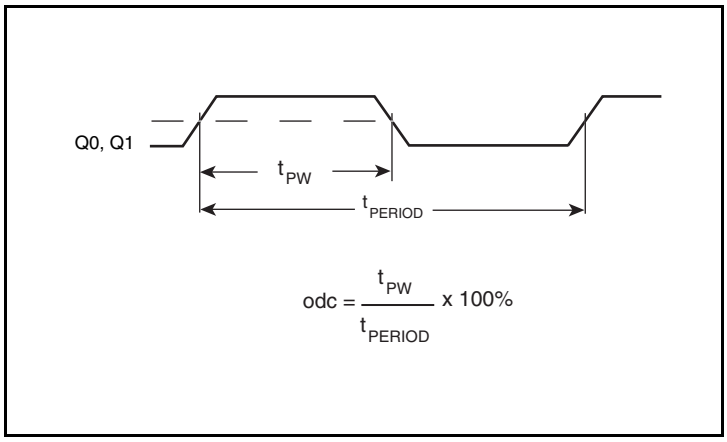


Differential Input Levels

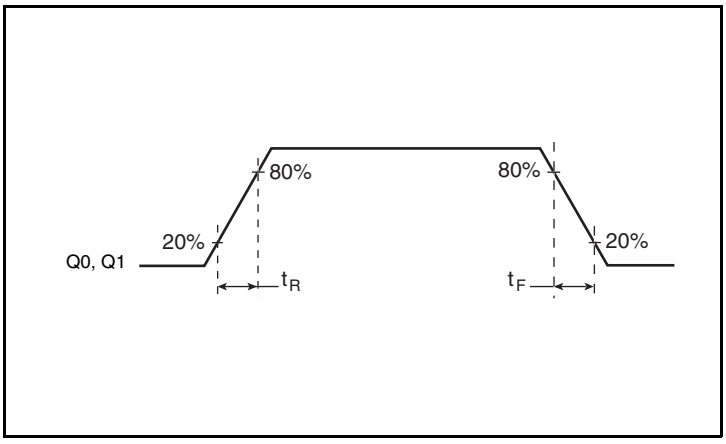


Output Skew

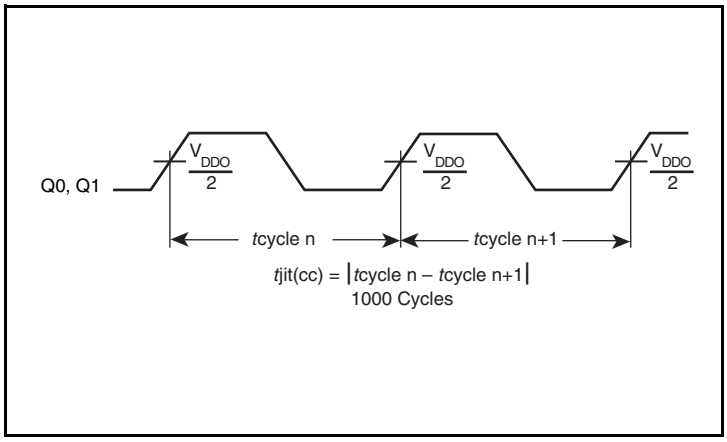
Parameter Measurement Information, continued



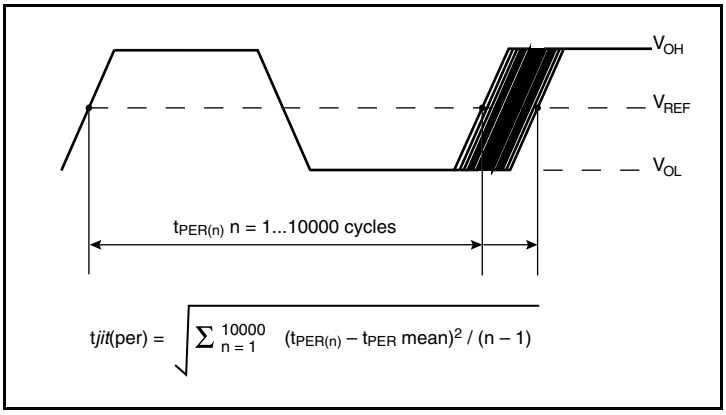
Single-Ended Output Duty Cycle/Output Pulse Width/Period



Single-Ended Output Rise/Fall Time



Cycle-to-Cycle Jitter



RMS Period Jitter

Applications Information

Recommendations for Unused Input and Output Pins

Inputs:

Crystal Inputs

For applications not requiring the use of the crystal oscillator input, both XTAL_IN and XTAL_OUT can be left floating. Though not required, but for additional protection, a 1kΩ resistor can be tied from XTAL_IN to ground.

CLKx/nCLKx Inputs

For applications not requiring the use of either differential input, both CLKx and nCLKx can be left floating. Though not required, but for additional protection, a 1kΩ resistor can be tied from CLKx to ground. It is recommended that CLKx, nCLKx be left unconnected in frequency synthesizer mode.

LVCMOS Control Pins

All control pins have internal pull-up or put-down resistors; additional resistance is not required but can be added for additional protection. A 1kΩ resistor can be used.

Outputs:

LVCMOS Outputs

The unused LVCMOS outputs can be left floating. There should be no trace attached.

Recommended Values for Low-Bandwidth Mode Loop Filter

External loop filter components are not needed in Frequency Synthesizer or High-Bandwidth modes. In Low-Bandwidth mode, the loop filter structure and components shown in *Figure 8* is recommended. Please consult IDT if other values are needed.

Wiring the Differential Input to Accept Single-Ended Levels

Figure 4 shows how a differential input can be wired to accept single ended levels. The reference voltage $V_{REF} = V_{DD}/2$ is generated by the bias resistors R1 and R2. The bypass capacitor (C1) is used to help filter noise on the DC bias. This bias circuit should be located as close to the input pin as possible. The ratio of R1 and R2 might need to be adjusted to position the V_{REF} in the center of the input voltage swing. For example, if the input clock swing is 2.5V and V_{DD} = 3.3V, R1 and R2 value should be adjusted to set V_{REF} at 1.25V. The values below are for when both the single ended swing and V_{DD} are at the same voltage. This configuration requires that the sum of the output impedance of the driver (Ro) and the series resistance (Rs) equals the transmission line impedance. In addition, matched termination at the input will attenuate the signal in half. This can be done in one of two ways. First, R3 and R4 in parallel should equal the transmission line impedance. For most 50Ω applications, R3 and R4 can be 100Ω. The values of the resistors can be increased to reduce the loading for slower and weaker LVCMOS driver. When using single-ended signaling, the noise rejection benefits of differential signaling are reduced. Even though the differential input can handle full rail LVCMOS signaling, it is recommended that the amplitude be reduced. The datasheet specifies a lower differential amplitude, however this only applies to differential signals. For single-ended applications, the swing can be larger, however V_{IL} cannot be less than -0.3V and V_{IH} cannot be more than V_{DD} + 0.3V. Though some of the recommended components might not be used, the pads should be placed in the layout. They can be utilized for debugging purposes. The datasheet specifications are characterized and guaranteed by using a differential signal.

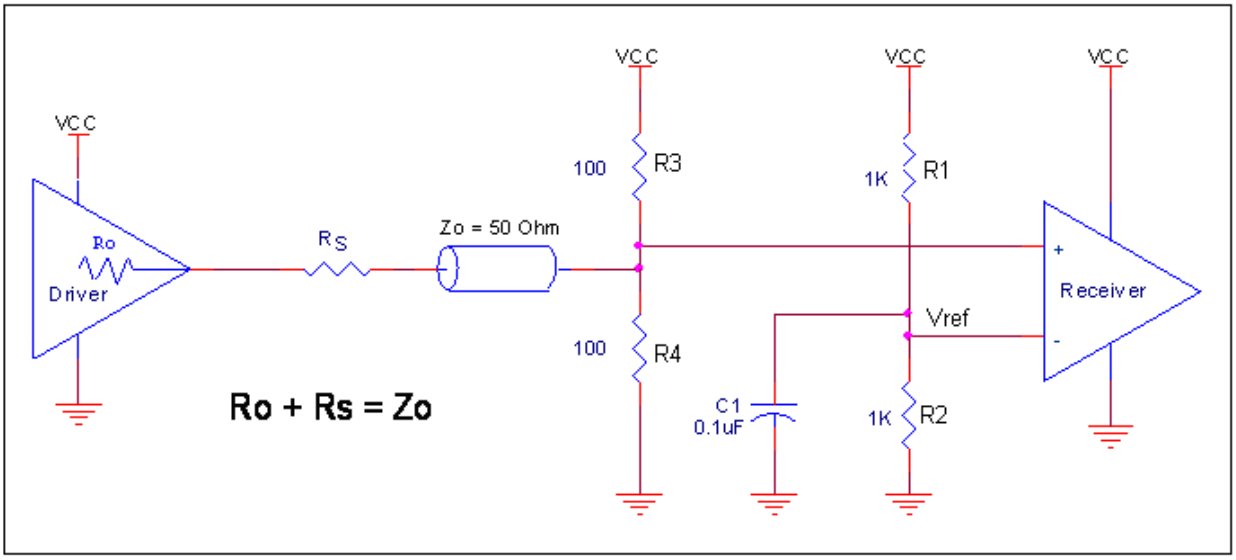


Figure 4. Recommended Schematic for Wiring a Differential Input to Accept Single-ended Levels

Overdriving the XTAL Interface

The XTAL_IN input can be overdriven by an LVCMOS driver or by one side of a differential driver through an AC coupling capacitor. The XTAL_OUT pin can be left floating. The amplitude of the input signal should be between 500mV and 1.8V and the slew rate should not be less than 0.2V/nS. For 3.3V LVCMOS inputs, the amplitude must be reduced from full swing to at least half the swing in order to prevent signal interference with the power rail and to reduce internal noise. *Figure 5A* shows an example of the interface diagram for a high speed 3.3V LVCMOS driver. This configuration requires that the sum of the output impedance of the driver (Ro) and the series resistance (Rs) equals the transmission line impedance. In addition, matched termination at the crystal input will attenuate the signal in half. This can be done in one of two ways. First, R1 and R2 in parallel should equal the transmission line impedance. For most 50Ω applications, R1 and R2 can be 100Ω. This can also be accomplished by removing R1 and changing R2 to 50Ω. The values of the resistors can be increased to reduce the loading for a slower and weaker LVCMOS driver. *Figure 5B* shows an example of the interface diagram for an LVPECL driver. This is a standard LVPECL termination with one side of the driver feeding the XTAL_IN input. It is recommended that all components in the schematics be placed in the layout. Though some components might not be used, they can be utilized for debugging purposes. The datasheet specifications are characterized and guaranteed by using a quartz crystal as the input.

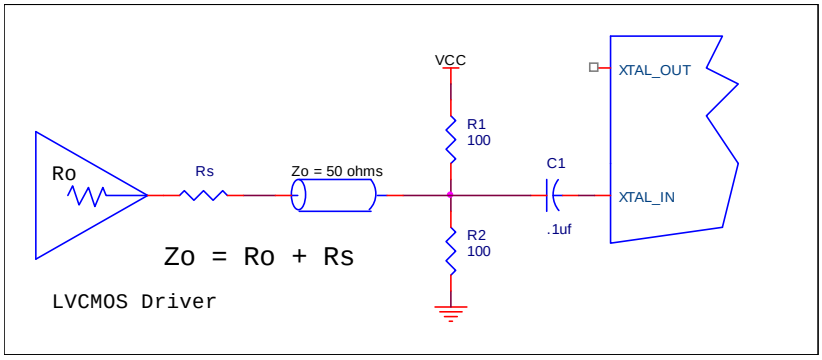


Figure 5A. General Diagram for LVCMOS Driver to XTAL Input Interface

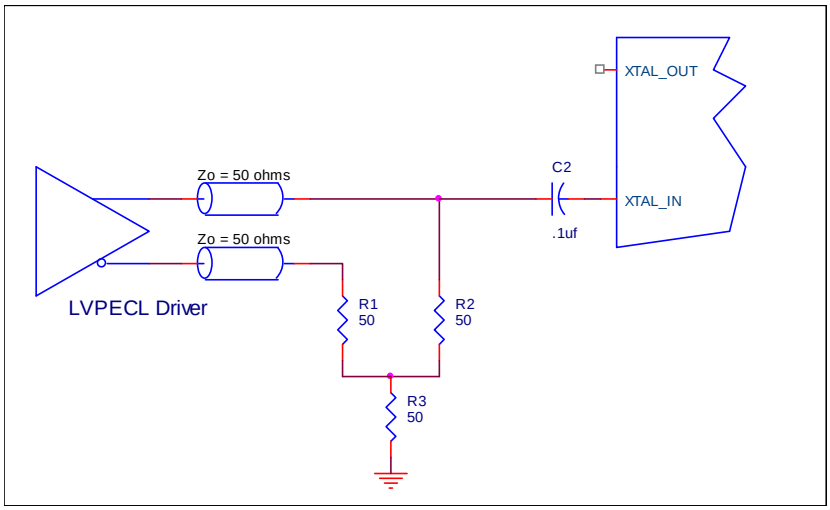


Figure 5B. General Diagram for LVPECL Driver to XTAL Input Interface

Differential Clock Input Interface

The CLK /nCLK accepts LVDS, LVPECL, LVHSTL, HCSL and other differential signals. Both V_{SWING} and V_{OH} must meet the V_{PP} and V_{CMR} input requirements. *Figures 6A to 6E* show interface examples for the CLK/nCLK input driven by the most common driver types. The input interfaces suggested here are examples only. Please consult with the vendor of the driver component to confirm the driver termination requirements. For example, in Figure 7A, the input termination applies for IDT open emitter LVHSTL drivers. If you are using an LVHSTL driver from another vendor, use their termination recommendation.

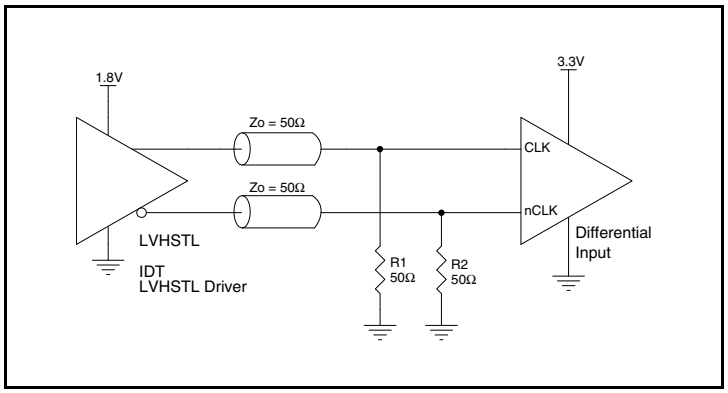


Figure 6A. CLK/nCLK Input Driven by an IDT Open Emitter LVHSTL Driver

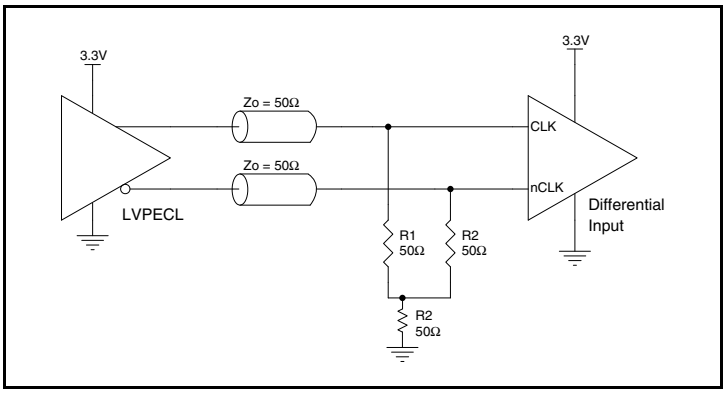


Figure 6B. CLK/nCLK Input Driven by a 3.3V LVPECL Driver

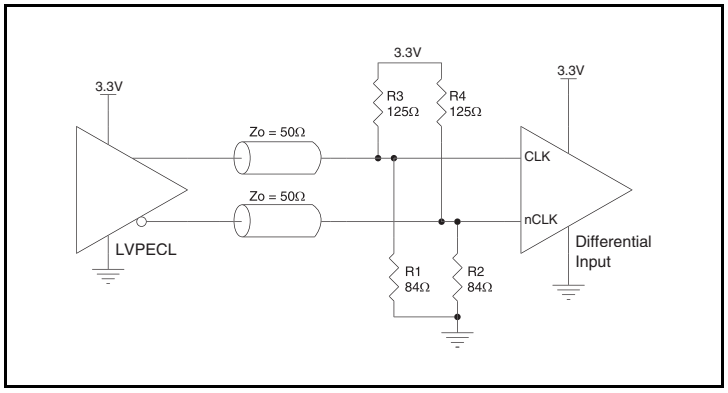


Figure 6C. CLK/nCLK Input Driven by a 3.3V LVPECL Driver

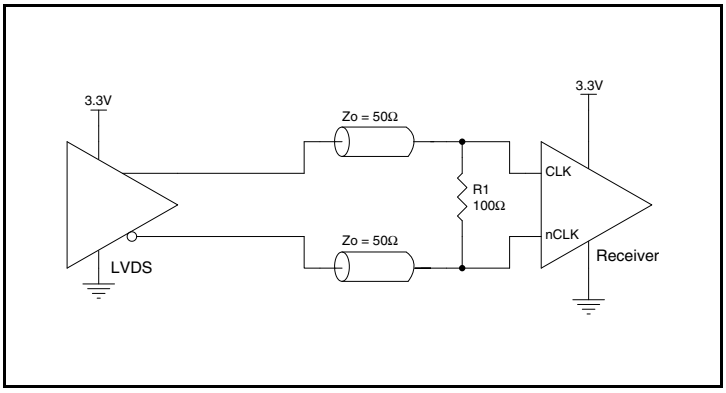


Figure 6D. CLK/nCLK Input Driven by a 3.3V LVDS Driver

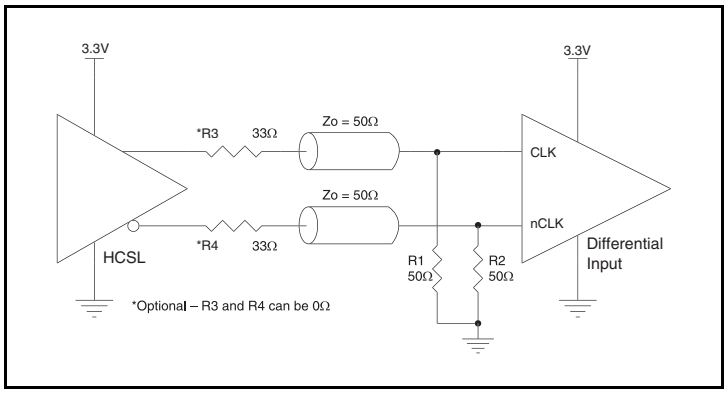


Figure 6E. CLK/nCLK Input Driven by a 3.3V HCSL Driver

VFQFN EPAD Thermal Release Path

In order to maximize both the removal of heat from the package and the electrical performance, a land pattern must be incorporated on the Printed Circuit Board (PCB) within the footprint of the package corresponding to the exposed metal pad or exposed heat slug on the package, as shown in *Figure 7*. The solderable area on the PCB, as defined by the solder mask, should be at least the same size/shape as the exposed pad/slug area on the package to maximize the thermal/electrical performance. Sufficient clearance should be designed on the PCB between the outer edges of the land pattern and the inner edges of pad pattern for the leads to avoid any shorts.

While the land pattern on the PCB provides a means of heat transfer and electrical grounding from the package to the board through a solder joint, thermal vias are necessary to effectively conduct from the surface of the PCB to the ground plane(s). The land pattern must be connected to ground through these vias. The vias act as “heat pipes”. The number of vias (i.e. “heat pipes”) are application specific and dependent upon the package power dissipation as well as electrical conductivity requirements. Thus, thermal and electrical analysis and/or testing are recommended to determine the minimum number needed. Maximum thermal and electrical performance is achieved when an array of vias is incorporated in the land pattern. It is recommended to use as many vias connected to ground as possible. It is also recommended that the via diameter should be 12 to 13mils (0.30 to 0.33mm) with 1oz copper via barrel plating. This is desirable to avoid any solder wicking inside the via during the soldering process which may result in voids in solder between the exposed pad/slug and the thermal land. Precautions should be taken to eliminate any solder voids between the exposed heat slug and the land pattern. Note: These recommendations are to be used as a guideline only. For further information, please refer to the Application Note on the Surface Mount Assembly of Amkor’s Thermally/ Electrically Enhance Leadframe Base Package, Amkor Technology.

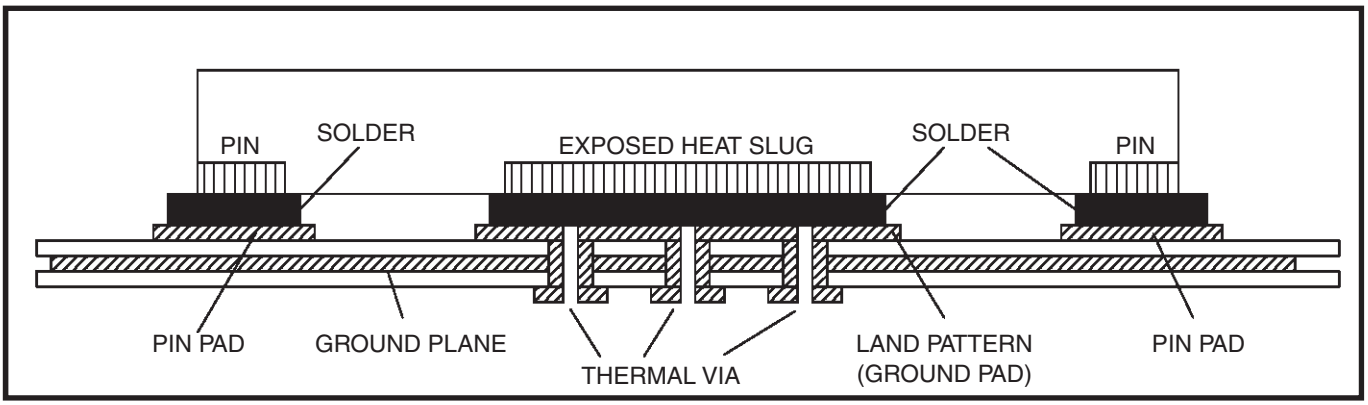


Figure 7. P.C. Assembly for Exposed Pad Thermal Release Path – Side View (drawing not to scale)

Schematic Layout

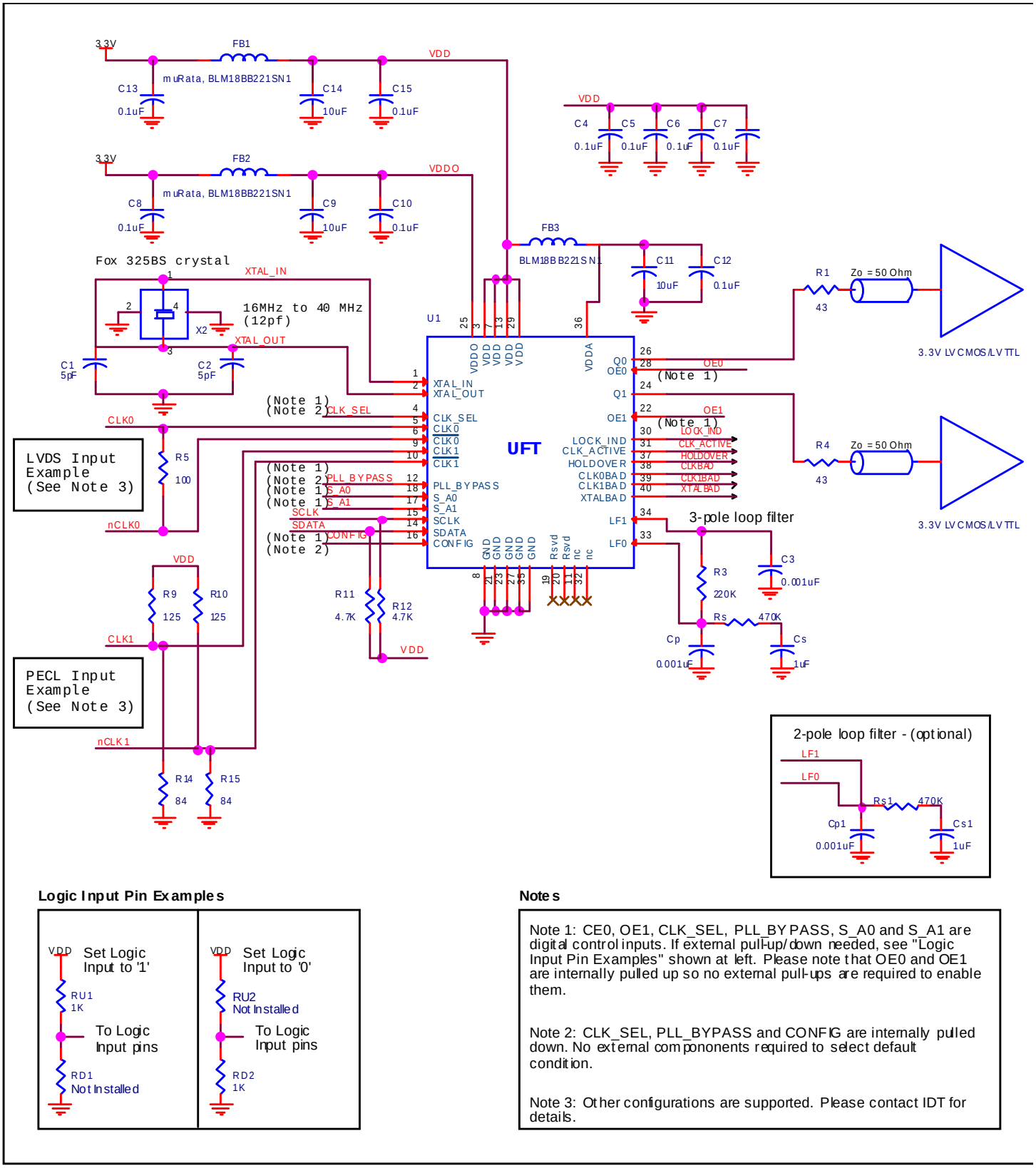
Figure 8 (next page) shows an example of the ICS840N202I UFT application schematic. Input and output terminations shown are intended as examples only and may not represent the exact user configuration. In this example, the device is operated at V_{DD} = 3.3V. To use the 2.5V CMOS output option, please refer to the section "Output Configuration". A 12pF parallel resonant 16MHz to 40MHz crystal is used in this example, though different crystal frequencies may be used. The load capacitance C1= 5pF and C2 = 5pF are recommended for frequency accuracy, but these may be adjusted for different board layouts. If different crystal types are used, please consult IDT for recommendations.

It is recommended that the loop filter components be laid out for the 3-pole option which can be adjusted for additional spur reduction and also allow for a 2-pole filter by setting R3 to 0 ohms and not populating C3.

As with any high speed analog circuitry, the power supply pins are vulnerable to noise. To achieve optimum jitter performance, power supply isolation is required. The ICS840N202I UFT provides separate power supplies to isolate from coupling into the internal PLL.

In order to achieve the best possible filtering, it is recommended that the placement of the filter components be on the device side of the PCB as close to the power pins as possible. If space is limited, the 0.1uF capacitor in each power pin filter should be placed on the device side of the PCB and the other components can be placed on Power supply filter recommendations are a general guideline to be used for reducing external noise from coupling into the devices. The filter performance is designed for wide range of noise frequencies. This low-pass filter starts to attenuate noise at approximately 10kHz. If a specific frequency noise component is known, such as switching power supply frequencies, it is recommended that component values be adjusted and if required, additional filtering be added. Additionally, good general design practices for power plane voltage stability suggests adding bulk capacitances in the local area of all devices.

The schematic example focuses on functional connections and is not configuration specific. Refer to the pin description and functional tables in the datasheet to ensure the logic control inputs are properly set. the opposite side.



Logic Input Pin Examples

Notes

Note 1: CE0, OE1, CLK_SEL, PLL_BYPASS, S_A0 and S_A1 are digital control inputs. If external pull-up/down needed, see "Logic Input Pin Examples" shown at left. Please note that OE0 and OE1 are internally pulled up so no external pull-ups are required to enable them.

Note 2: CLK_SEL, PLL_BYPASS and CONFIG are internally pulled down. No external compononents required to select default condition.

Note 3: Other configurations are supported. Please contact IDT for details.

Figure 8. ICS840N202I Application Schematic

Power Considerations

This section provides information on power dissipation and junction temperature for the ICS840N202I.
Equations and example calculations are also provided.

1. Power Dissipation.

The total power dissipation for the ICS840N202I is the sum of the core power plus the power dissipated into the load.
The following is the power dissipation for V_{DD}= 3.3V + 5% = 3.465V, which gives worst case results.

- Power $(core)_{MAX} = V_{DD\_MAX} * (I_{DD} + I_{DDO}) + I_{DDA}$ = 3.465V * 320mA = **1108.8mW**

LVCMOS Output Power Dissipation

- Output Impedance R_{OUT} Power Dissipation due to Loading 50Ω to $V_{DDO}/2$
  Output Current $I_{OUT} = V_{DDO\_MAX} / [2 * (50Ω + R_{OUT})]$ = 3.465V / [2 * (50Ω + 15Ω)] = **26.65mA**
- Power Dissipation on the R_{OUT} per LVCMOS output
  Power $(R_{OUT}) = R_{OUT} * (I_{OUT})^2$ = 15Ω * (26.65mA)^2 = **10.65mW per output**
- Total Power (R_{OUT}) = 10.65mW * 2 = **21.3mW**

Total Power Dissipation

- **Total Power**
  = Power (core) + Total Power (R_{OUT})
  = 1108.8mW + 21.3mW **= 1130.1mW**

2. Junction Temperature.

Junction temperature, Tj, is the temperature at the junction of the bond wire and bond pad directly affects the reliability of the device. The maximum recommended junction temperature is 125°C. Limiting the internal transistor junction temperature, Tj, to 125°C ensures that the bond wire and bond pad temperature remains below 125°C.

The equation for Tj is as follows: $Tj = \theta_{JA} * Pd\_total + T_A$

Tj = Junction Temperature

θ_{JA} = Junction-to-Ambient Thermal Resistance

Pd_total = Total Device Power Dissipation (example calculation is in section 1 above)

T_A = Ambient Temperature

In order to calculate junction temperature, the appropriate junction-to-ambient thermal resistance θ_{JA} must be used. Assuming no air flow and a multi-layer board, the appropriate value is 32.4°C/W per Table 9 below.

Therefore, Tj for an ambient temperature of 85°C with all outputs switching is:

85°C + 1.130W * 32.4°C/W = 121.6°C. This is below the limit of 125°C.

This calculation is only an example. Tj will obviously vary depending on the number of loaded outputs, supply voltage, air flow and the type of board (multi-layer).

Table 9. Thermal Resistance θ_{JA} for 40 Lead VFQFN, Forced Convection

θ_{JA} by Velocity			
Meters per Second	**0**	**1**	**2.5**
Multi-Layer PCB, JEDEC Standard Test Boards	32.4°C/W	25.7°C/W	23.4°C/W

Reliability Information

Table 10. θ_{JA} vs. Air Flow Table for a 40 Lead VFQFN

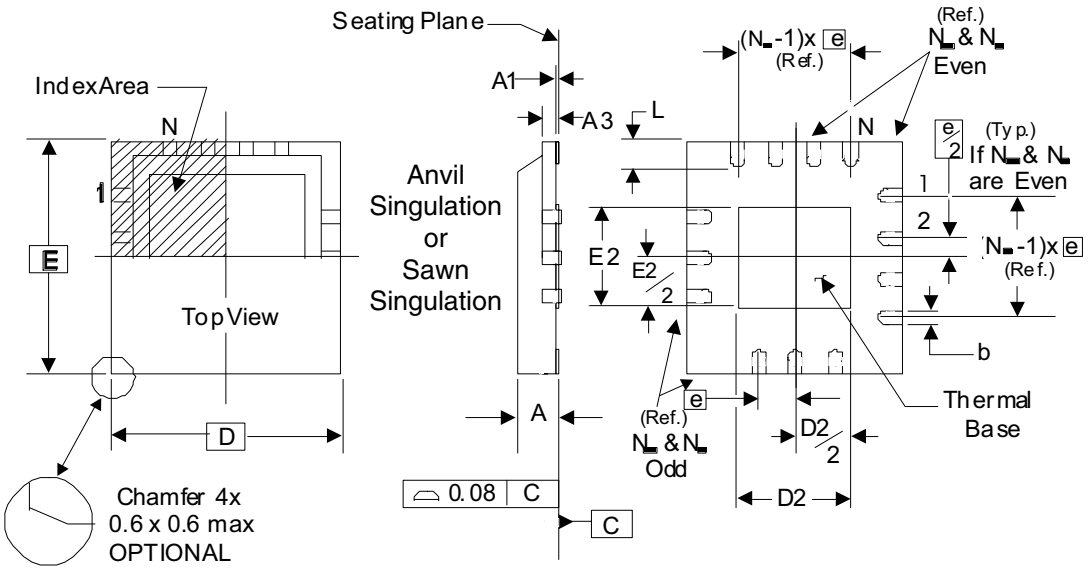
θ_{JA} vs. Air Flow			
Meters per Second	**0**	**1**	**2.5**
Multi-Layer PCB, JEDEC Standard Test Boards	32.4°C/W	25.7°C/W	23.4°C/W

Transistor Count

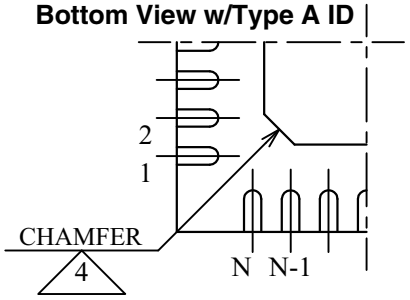
The transistor count for ICS840N202I is: 50,462

Package Outline and Package Dimensions

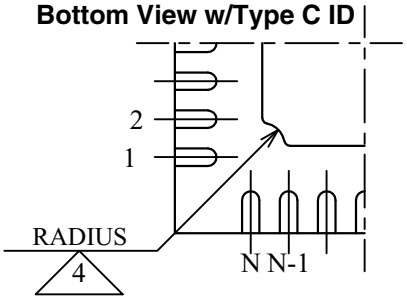
Package Outline - K Suffix for 40 Lead VFQFN



Bottom View w/Type A ID



Bottom View w/Type C ID



There are 2 methods of indicating pin 1 corner at the back of the VFQFN package:

1. Type A: Chamfer on the paddle (near pin 1)
2. Type C: Mouse bite on the paddle (near pin 1)

Table 11. Package Dimensions

JEDEC Variation: VJJD-2/-5 All Dimensions in Millimeters		
Symbol	**Minimum**	**Maximum**
N	40	
A	0.80	1.00
A1	0	0.05
A3	0.25 Ref.	
b	0.18	0.30
N_D & N_E	10	
D & E	6.00 Basic	
D2 & E2	4.55	4.75
e	0.50 Basic	
L	0.30	0.50

Reference Document: JEDEC Publication 95, MO-220

NOTE: The following package mechanical drawing is a generic drawing that applies to any pin count VFQFN package. This drawing is not intended to convey the actual pin count or pin layout of this device. The pin count and pinout are shown on the front page. The package dimensions are in Table 11.

Ordering Information

Table 12. Ordering Information

Part/Order Number	Marking	Package	Shipping Packaging	Temperature
840N202CKI-dddLF	ICS0202CIddd	“Lead-Free” 40 Lead VFQFN	Tray	-40°C to +85°C
840N202CKI-dddLFT	ICS0202CIddd	“Lead-Free” 40 Lead VFQFN	Tape & Reel	-40°C to +85°C

NOTE: For the specific -ddd order codes, refer to *FemtoClock NG Universal Frequency Translator Ordering Product Information* document.

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